

Construction of coarse approximations for a Schrödinger problem with highly oscillating potential

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Outline

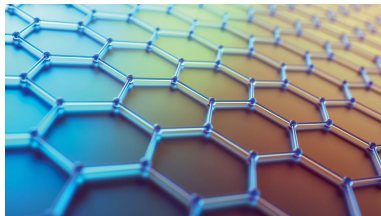
- 1 An inverse multiscale problem
 - Reminder about inverse problems
 - Homogenization theory
 - Our objectives
- 2 Recovering an effective potential
- 3 Recovering an H^1 -approximation

Inverse Problem : A new paradigm

Let Ω be a bounded open of \mathbb{R}^d .

Direct problem : For a given operator \mathcal{L} and RHS f , find u that satisfies

$$\begin{cases} \mathcal{L}u = \left(\sum_{i,j} a_{ij}(\cdot) \partial_{i,j} + \sum_i b_i(\cdot) \partial_i + c(\cdot) \right) u = f & \text{in } \Omega, \\ u = 0 & \text{on } \partial\Omega. \end{cases} \quad (1)$$



Inverse Problem : A new paradigm

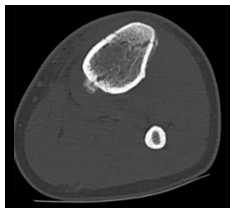
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Direct problem : For a given operator \mathcal{L} and RHS f , find u that satisfies (1).

Inverse problem : Assume the map $f \rightarrow u$ solution to (1) is known.

"Find" \mathcal{L} such that (1) is satisfied.

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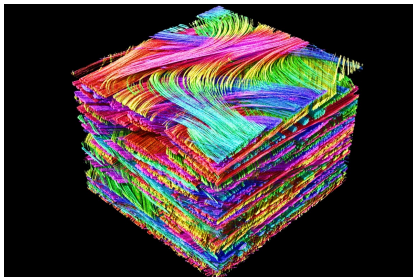
Inverse Problem : A new paradigm

Inverse problems

- have been widely studied ([Calderón problem](#), 1980)
- may involve more complexity (e.g. partial measurements available, finite number of available measurements, ...).
- are **(very) HARD** to solve ! (existence/uniqueness/stability issues...)

Multiscale Context

Our study focuses on **multiscale** systems (e.g. composite materials, lungs). Such systems naturally leads to **ill-posed inverse problems** (see [Lions05]).



Multiscale Context : ill-posed inverse problem

Consider the problem oscillating at the *small length scale* ε

$$\mathcal{L}_\varepsilon u_\varepsilon = (-\Delta + \varepsilon^{-1} V(\varepsilon^{-1} \cdot)) u_\varepsilon = f \text{ in } \Omega, \quad u_\varepsilon = 0 \text{ on } \partial\Omega,$$

with potential **periodic** V such that $\langle V \rangle = 0$, and RHS $f \in L^2(\Omega)$.

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*Homogenization theory*¹ assesses the existence of a limit equation when $\varepsilon \rightarrow 0$.

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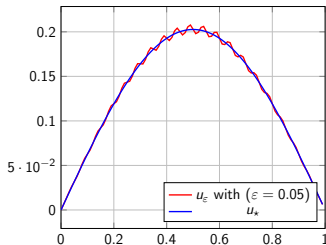
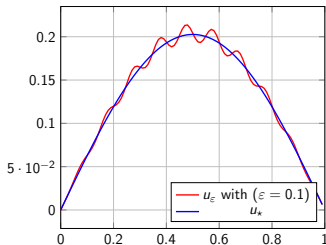
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Multiscale Context : ill-posed inverse problem

Issue : in the limit $\varepsilon \rightarrow 0$, the quantity u_ε is very close to u_\star , whereas the operator we seek to reconstruct, \mathcal{L}_ε , is very different from \mathcal{L}_\star , its homogenized version.

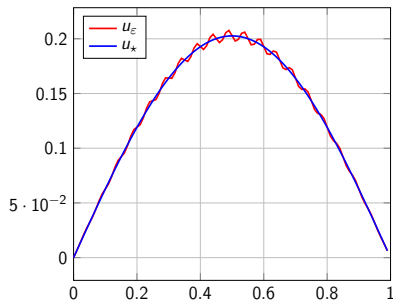
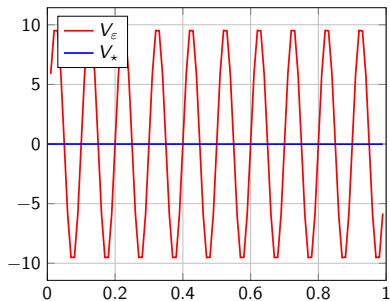


Figure: Two similar solutions associated to two very distinct potentials

An Inverse Multiscale Problem

How to tackle such problems ?

General approach :

- **Direct Inversion** (see [Uhlmann13]),
- **Perturbation** (see [Ammari08]),

Approach based on homogenization (see [Nolen12]):

- **Features Determination** (see [Engquist14]),
- **Regularization at order 0**, identifying effective quantity (see [Ammari16, Caiazzo20]),
- **Regularization at order 1**, beyond effective quantity : H^1 reconstruction (see [Garnier23, LeBris18]).
- **Inverse Homogenization** (see [Cherkaev01])

Our Approach

Consider the Schrödinger problem (2) involving a periodic potential V :

$$\mathcal{L}_\varepsilon u_\varepsilon = (-\Delta + \varepsilon^{-1} V(\varepsilon^{-1} \cdot)) u_\varepsilon = f \text{ in } \Omega, \quad u_\varepsilon = 0 \text{ on } \partial\Omega. \quad (2)$$

From the knowledge of solutions u_ε for various rhs f , our aim is:

- 1 to propose a numerical methodology to build an **effective operator** $\overline{\mathcal{L}}$ approaching \mathcal{L}_ε with satisfying L^2 error on the solutions,

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Our strategy

- is inspired by homogenization theory,
- does not rely on classical hypothesis for homogenization (such as periodicity) which may be too restrictive in practical situations,
- can be adapted to a wide range of other elliptic equations (see [LeBris18]),
- is valid outside the regime of homogenization (i.e. $\varepsilon \rightarrow 0$).

Recovering an effective potential

Let $\overline{V} \in \mathbb{R}$ be a *constant* potential, and $\overline{u} = u(\overline{V}, f)$ be the solution to (3) with RHS $f \in L^2(\Omega)$.

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The quality of the approximation of \mathcal{L}_ε by $\overline{\mathcal{L}}$ can be quantified through the functional

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Hence we can **minimize** the **worst case scenario** with the optimization problem

$$\inf_{\overline{V} \in \mathbb{R}} \sup_{\|f\|_{L^2(\Omega)}=1} \|u_\varepsilon(f) - u(\overline{V}, f)\|_{L^2(\Omega)}^2$$

The choice of an $L^2(\Omega)$ norm is reminiscent of the fact that $\|u_\varepsilon - u_\star\|_{L^2(\Omega)}$ tends to 0 with ε .

Recovering an effective potential

Practical considerations : To recover a **quadratic** optimization problem in \overline{V} , we consider the slightly different problem (4)

$$I_\varepsilon = \inf_{\overline{V} \in \mathbb{R}} \sup_{\|f\|_{L^2(\Omega)}=1} \|(-\Delta)^{-1} (-\Delta + \overline{V}) (u_\varepsilon(f) - \overline{u}(f))\|_{L^2(\Omega)}^2. \quad (4)$$

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Theoretical considerations :

Proposition (Asymptotic consistency, periodic case)

Consider the problem (4). In the periodic setting, we have

$$\lim_{\varepsilon \rightarrow 0} I_\varepsilon = 0. \quad (5)$$

Furthermore, for $\varepsilon > 0$ fixed (sufficiently small), there exists a unique minimizer $\overline{V}_\varepsilon^0 \in \mathbb{R}$. The following convergence holds :

$$\lim_{\varepsilon \rightarrow 0} \overline{V}_\varepsilon^0 = V_\star. \quad (6)$$

A consistency result

$$\text{Let } \Phi_\varepsilon(\bar{V}) = \sup_{\|f\|_{L^2(\Omega)}=1} \|(-\Delta)^{-1} (-\Delta + \bar{V}) (u_\varepsilon(f) - \bar{u}(f))\|_{L^2(\Omega)}^2.$$

Lemma

In the periodic setting, we have

$$\lim_{\varepsilon \rightarrow 0} \Phi_\varepsilon(V_\star) = 0.$$

Lemma

For ε sufficiently small, the functional Φ_ε is continuous and convex.

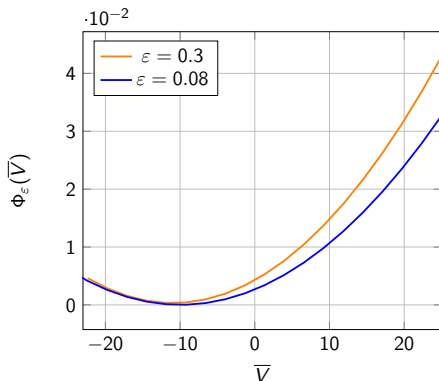


Figure: Convexity of Φ_ε .

Numerical results

We use an alternating direction algorithm in 2D ($\Omega = [0, 1]^2$) using the potential

$$V(x, y) = \pi^2 \sqrt{8} (\sin(2\pi x) + \sin(2\pi y)).$$

We approximate the supremum by a maximization over the first eigenmodes of $(-\Delta)$ -operator. In practice, a *single* mode is sufficient in order to find the *single* coefficient \overline{V} .

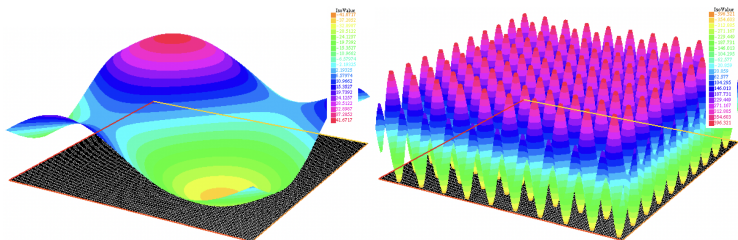


Figure: Potential V and Oscillating Potential $V_\epsilon = \epsilon^{-1} V(\epsilon^{-1} \cdot)$.

Numerical results

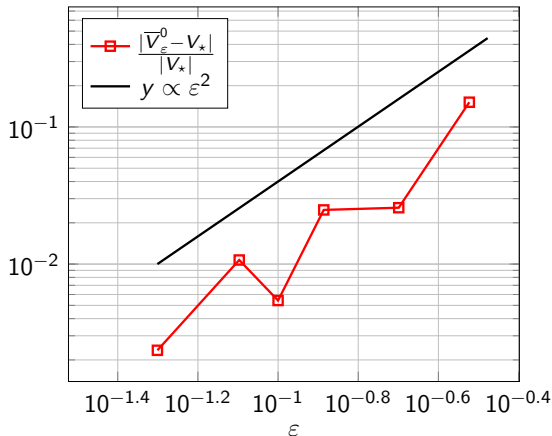


Figure: Error between the homogenized potential V_* and the effective potential $\overline{V}_\varepsilon^0$ as a function of ε .

Numerical results

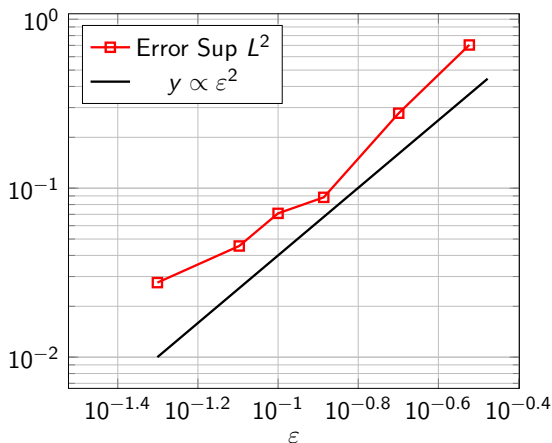


Figure: Error $\sup_{f \in \text{Span}_{1 \leq p \leq 10}(f_p)} \left(\frac{\|u_\varepsilon(f) - u(\bar{V}_\varepsilon^0, f)\|_{L^2(\Omega)}}{\|u_\varepsilon(f)\|_{L^2(\Omega)}} \right)$ as a function of ε . (\bar{V}_ε^0 computed with $P = 3$)

Recovering an H^1 -approximation

In the periodic setting, homogenization theory assesses that u_ε converges to u_\star strongly in $L^2(\Omega)$, but only **weakly in $H^1(\Omega)$** . We wish to recover within our strategy a satisfying $H^1(\Omega)$ approximation. The strategy consisting in considering the problem (7) is a dead-end.

$$I_\varepsilon^{H^1} = \inf_{\overline{V} \in \mathbb{R}} \sup_{\|f\|_{L^2(\Omega)}=1} \|u_\varepsilon(f) - u(\overline{V}, f)\|_{H^1(\Omega)}. \quad (7)$$

How can we go further ?

Recovering an H^1 -approximation

An essential tool in homogenization is the [corrector](#). For our Schrödinger equation (2), it is the periodic solution to (8), denoted w .

$$\Delta w = V \tag{8}$$

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Homogenization theory assesses that $u_{\varepsilon,1} = u_{\star}(1 + \varepsilon w(\varepsilon^{-1}\cdot))$ is a good H^1 approximation of solution u_{ε} . Hence, we have :

$$\nabla u_{\varepsilon}(x) = \nabla u_{\star}(x) + u_{\star}(x)(\nabla w) \left(\frac{x}{\varepsilon} \right) + o_{L^2}(\varepsilon)$$

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Inspired by this statement, we define $\overline{C}_{\varepsilon}^0$, an approximation of $(\nabla w)(\varepsilon^{-1}\cdot)$, as the minimizer of (9).

$$I_{\varepsilon}^{corr} = \inf_{\overline{C} \in \mathbb{P}^0} \sup_{\|f\|_{L^2}=1} \|\nabla u_{\varepsilon}(f) - \nabla u(\overline{V}_{\varepsilon}, f) - u(\overline{V}_{\varepsilon}, f) \overline{C}\|_{L^2(\Omega)}^2. \quad (9)$$

where $u(\overline{V}_{\varepsilon}, f)$ is to be understood as an approximation of $u_{\star}(f)$ (which holds since $\overline{V}_{\varepsilon} \approx V_{\star}$).

Numerical results

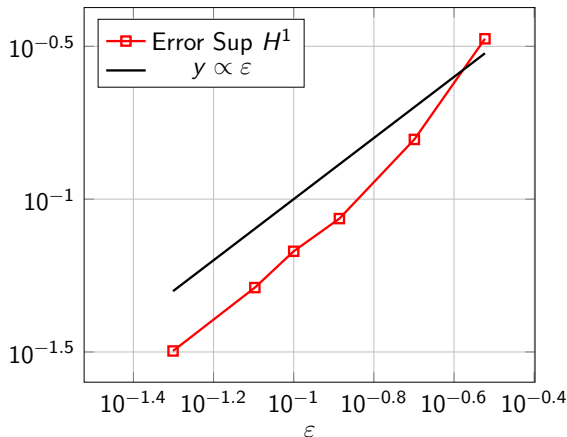








Figure: H^1 maximal error $\sup_{f \in \text{Span}_{1 \leq p \leq 10}(f_p)} \left(\frac{\|\nabla u_\varepsilon(f) - \nabla u(\bar{V}_\varepsilon^0, f) - u(\bar{V}_\varepsilon^0, f) \bar{C}_\varepsilon^0\|_{L^2(\Omega/\partial\Omega)}}{\|\nabla u_\varepsilon(f)\|_{L^2(\Omega/\partial\Omega)}} \right)$ as a function of ε . (\bar{V}_ε^0 and \bar{C}_ε^0 computed with $P = 3$)

In progress :

- **Robustness analysis** : what happens if the data is blurred/perturbed/deteriorated/... ?
- Exploring **other type of data** : starting from the knowledge of macroscopic data (e.g. energy $\int_{\Omega} |\nabla u_{\varepsilon}|^2 + V_{\varepsilon} u_{\varepsilon}^2$) instead of microscopic ones.

Thank you !

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Supremum or Maximum ?

For small ε , homogenization assesses $u_\varepsilon(f) \rightarrow u_\star(f)$ in $L^2(\Omega)$. Hence for all $f \in L^2(\Omega)$, we have

$$\|(-\Delta)^{-1}(-\Delta + \overline{V})(u_\varepsilon(f) - \overline{u}(f))\|_{L^2(\Omega)}^2 \rightarrow \underbrace{\|(-\Delta)^{-1}(-\Delta + \overline{V})(u_\star(f) - \overline{u}(f))\|_{L^2(\Omega)}^2}_{= \int_{\Omega} \mathcal{H}_\star^{\overline{V}}(f) f}.$$

The study of $\mathcal{H}_\star^{\overline{V}}$ shows that it has the same eigenvalues (in the same order) as $-\Delta$.

Hence the supremum is well approximated by a maximization on the first eigenmodes :

$$\sup_{f \in L^2(\Omega)} \frac{\int_{\Omega} \mathcal{H}_\star^{\overline{V}}(f) f}{\|f\|_{L^2(\Omega)}^2} \approx \max_{f \in \text{Span}(\phi_p)_{p=1}^P} \frac{\int_{\Omega} \mathcal{H}_\star^{\overline{V}}(f) f}{\|f\|_{L^2(\Omega)}^2}$$