# REAL TIME 2D POSE ESTIMATION



#### Presented by

B141755

B141349

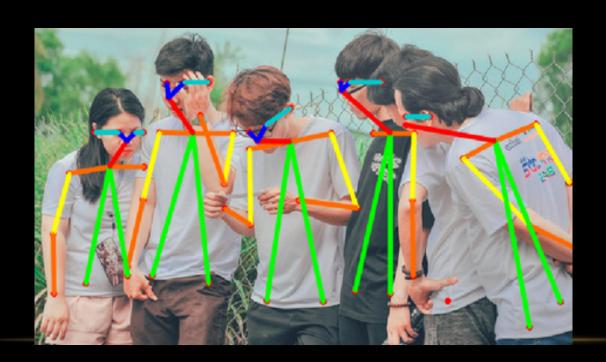
B141475

#### AGENDA

- Introduction
- Dataset used
- Architecture
- Requirements
- Libraries used
- Model used
- Applications
- Output screenshots
- Conclusion

#### INTRODUCTION

Pose Estimation is predicting the body part or joint positions of a person from an image or a video.

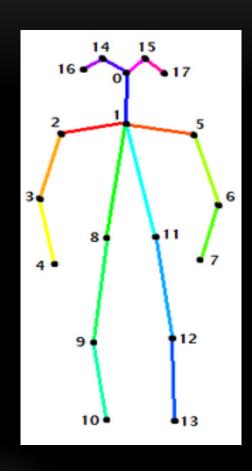


#### **DATASET USED**

■ We have used COCO Dataset (Common object in context dataset)

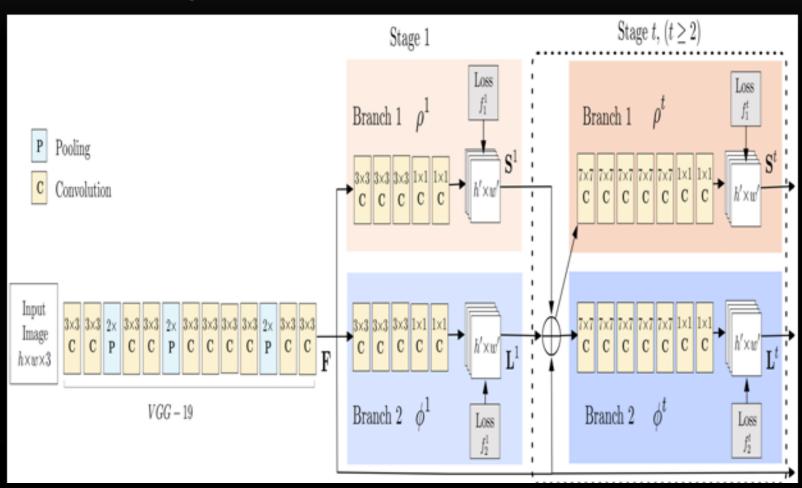
330 k Images

 250,000 people trained with 18 key-points



# **ARCHITECTURE**

The model takes input as color image of size w\*h and produces key points for each person in the image.



# **CONTINUE...**



- Confidence maps
- Part affinity fields

#### **REQUIREMENTS**

- Ubuntu(64bint) / windows(64bit).
- Python 3.6 .
- Create Environment.
- Activate Environment.
- Install required libraries.

#### LIBRARIES USED

- Open cv
- Sliding window
- SciPy
- Matplotlib
- Tensorflow

#### **LIBRARIES USED**

- Numpy
- Argparse
- Logging
- Time

#### **MODEL USED**

☐ Tensorflow offers various pre-trained models.

Inception

Mobilenet

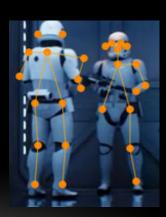
Resnet

### **APPLICATIONS**

Activity recognition



☐ Training robots



# **OUTPUT SCREENSHOTS**



Object detection



Keypoints identification For single person

# **OUTPUT SCREENSHOTS**

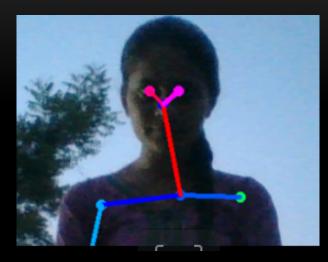


Keypoint identification For multiperson



Pose estimation

# **OUTPUT SCREENSHOTS**



Pose estimation



Pose estimation For multi person

#### CONCLUSION

■ Real time multi-person 2D pose estimation is a key component in enabling machines to have an understanding of people in images and videos.

# THANK YOU!