

SMART HOME AUTOMATION

1. INTRODUCTION

1.1 OBJECTIVES AND GOALS

Objectives

- Design the wireless mesh for IoT in Home.
- With this project we try to make a smart home in which we include some sensor which make our day-to-day life easy and safe.
- To discover answers to questions through the application of scientific procedures.

Goal

- To find out the way to control household appliances using Arduino and Sensors.
- The basic aim of Home automation is to control or monitor signals from different appliances, or basic services.
- To use smart way such as smartphone to control or monitor the home automation system.

1.2 APPLICATIONS

- The most common applications of home automation are **lighting control, door opening, kitchen appliances**, and many more.
- It close and open the gate when ever the person is detected nearby.
- It buzzes the alarm when gas is detected in home which is the safety application of our smart home automation.
- Our project is also design to save energy as a person can say to switch on or off the light whenever he wants so that he/she don't have to stand up from his/her place to do the action.
- Same with Air Conditioner.
- Our project is made for hand free technology as we have a voice controller in our application.

1.3 FEATURE

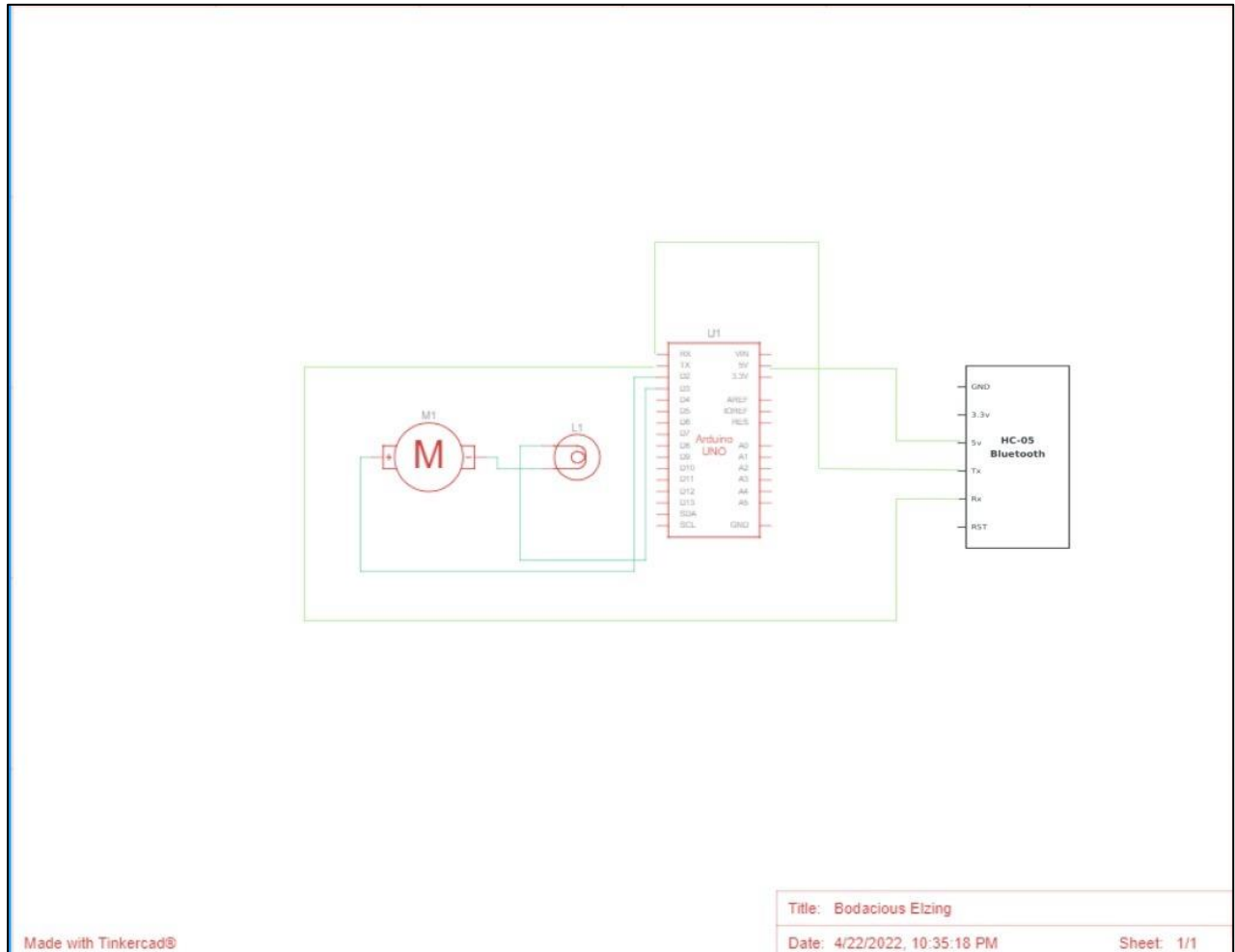
- Advanced home network, you've probably heard of the "Internet of Things" by now.
- Remote access. When most people talk about smart homes, what they really mean is remote access to one's home systems.
- Advanced security, smoke sensor in kitchen appliances.
- Lighting control, automated door treatments.
- Distributed audio.

2. DESIGN

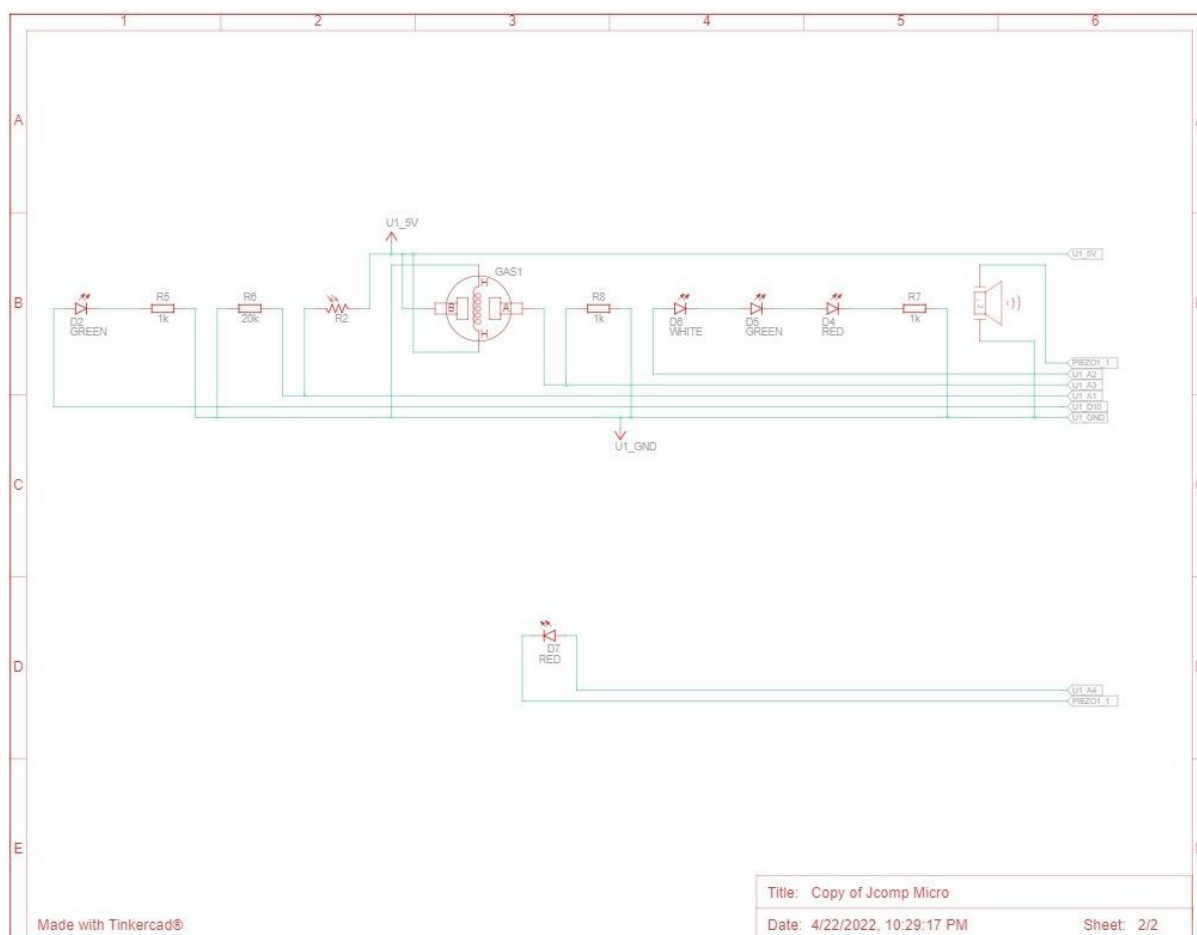
2.1 Block Diagram

2.2 Snapshots - Project

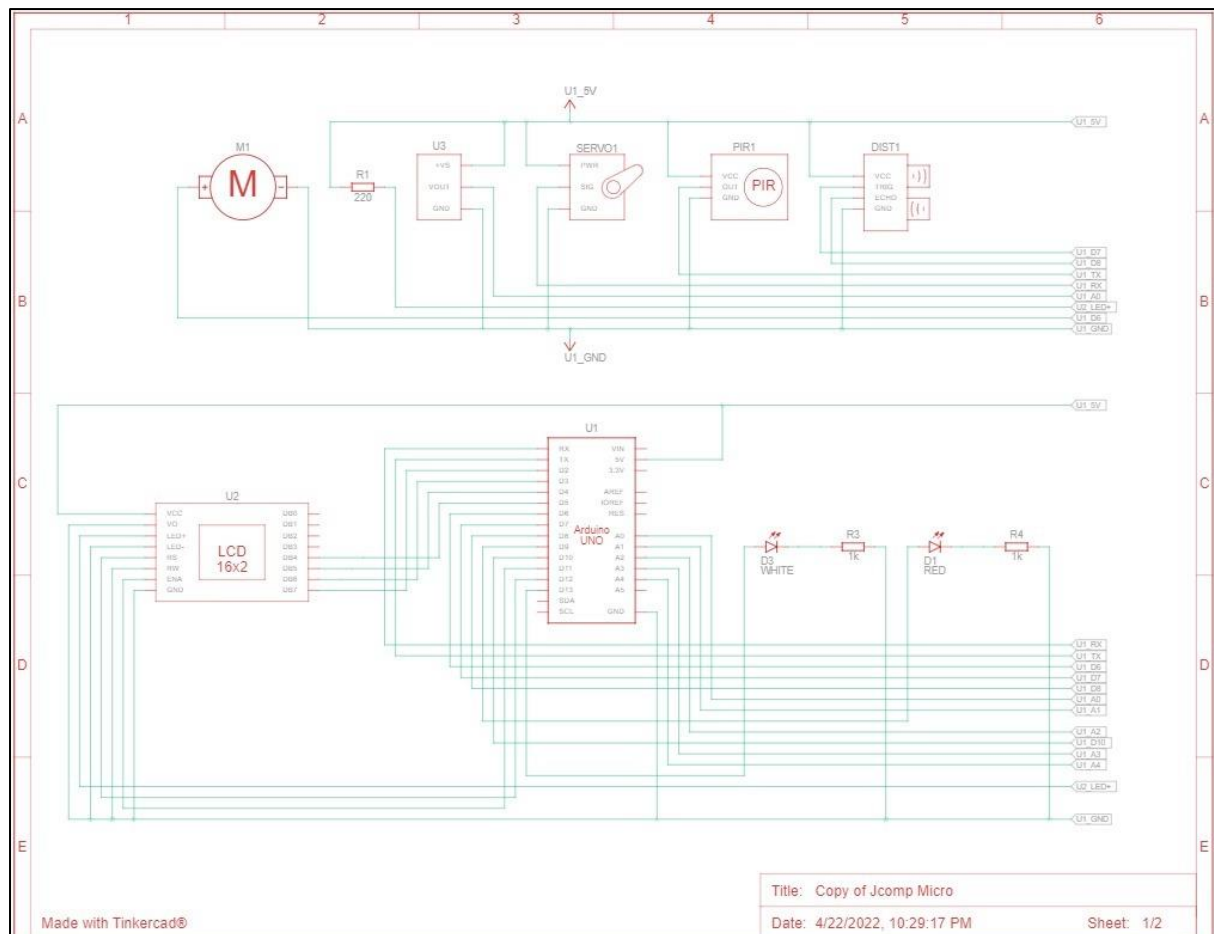
→ Voice Enhanced Smart Home Automation



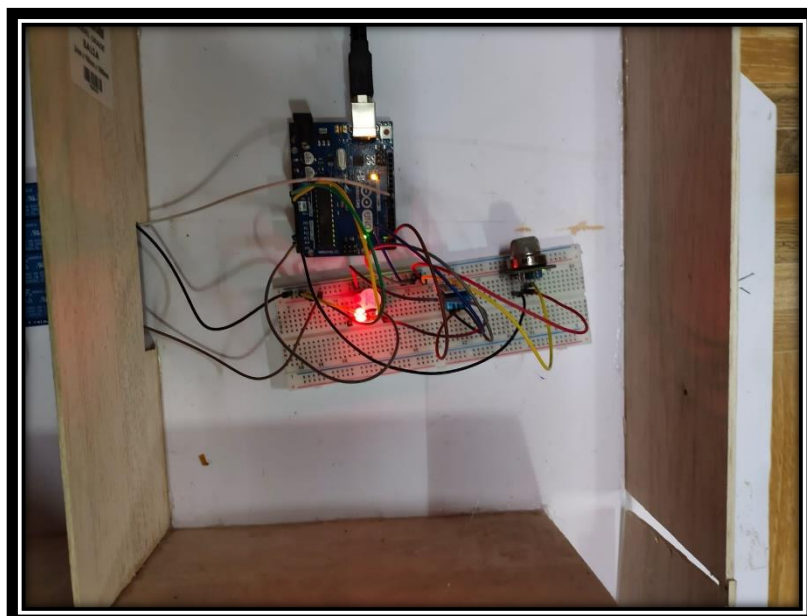
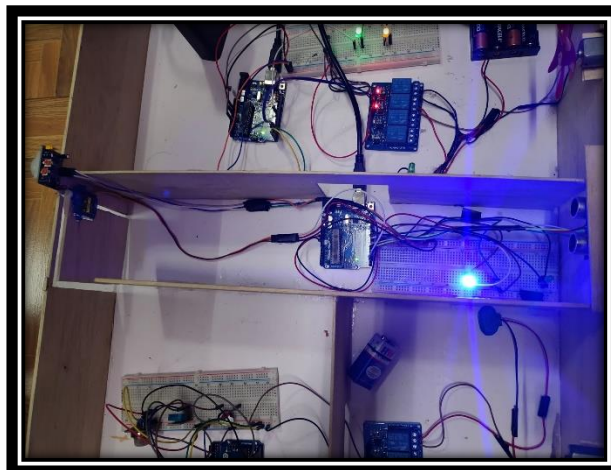
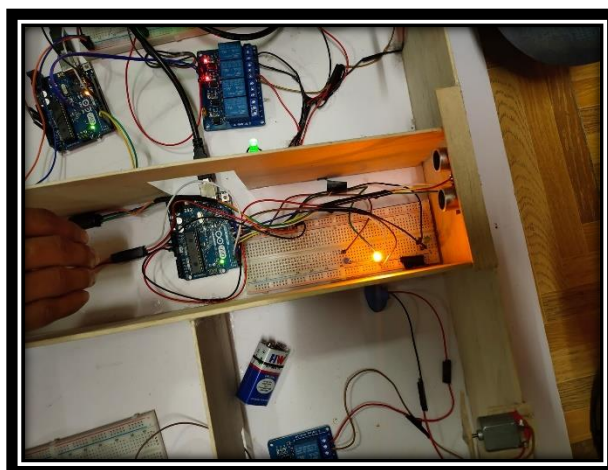
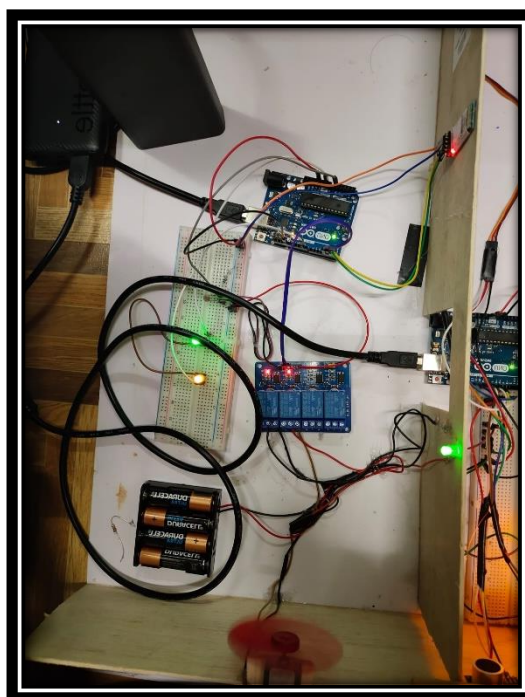
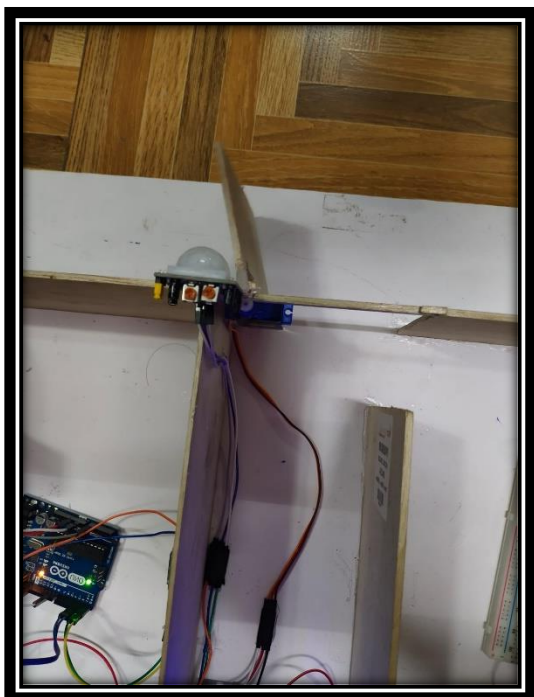
→ Humidity



→ Door Sensor and Hallway Lights



2.3 Results



3. SOFTWARE ANALYSIS

3.1 Coding

→ Voice Enhanced Home Automation

```
String s;
int Lawn_Light=A0;
int Lawn_Lights=9;
void setup() {
  pinMode(2,OUTPUT);
  pinMode(3,OUTPUT);
  Serial.begin(9600);
  pinMode(Lawn_Light,INPUT);
  // digitalWrite(3,HIGH);
  //digitalWrite(2,HIGH);
}
void Fan_switch(String s){
  if(s.equalsIgnoreCase("Jarvis AC on")){
    Serial.println("Yes Boss, switching Fan on");
    digitalWrite(2,LOW);
  }
  else if(s.equalsIgnoreCase("Jarvis AC off")){
    Serial.println("Yes Boss, switching Fan off");
    digitalWrite(2,HIGH);
  }
}

void Light_switch(String s){
  if(s.equalsIgnoreCase("Jarvis Light on")){
    Serial.println("Yes Boss, switching Lights on");
```

```
        digitalWrite(3,LOW);
    }
    else if(s.equalsIgnoreCase("Jarvis Light off")){
        Serial.println("Yes Boss, switching Lights off");
        digitalWrite(3,HIGH);
    }

}

void Lawn_Light_Control(){
    int s=(255./1023.)*analogRead(Lawn_Light);
    Serial.println(s);
    analogWrite(Lawn_Lights,255-s);
    delay(1000);
}

void loop() {

    Lawn_Light_Control();
    s=Serial.readString();
    Fan_switch(s);
    Light_switch(s);
    Serial.println(s);

}
```


→ Hmidity

```
#include <DHT.h>

#define Type DHT11

int sensePin=2;

DHT HT(sensePin,Type);

float humidty;

float tempC;

float tempF;


int val;

int fanPin=9;


//Gas Sensor

int gas_sensor=A3;

int INDICATOR=A4;

void setup() {

    pinMode(fanPin,OUTPUT);

    HT.begin();

    delay(500);


    pinMode(INDICATOR, OUTPUT);

    pinMode(gas_sensor, INPUT);

    Serial.begin(9600);

}

void Gas_sensor()

{

    val=analogRead(gas_sensor);

    if(val>105){

        digitalWrite(INDICATOR, HIGH);
```

```
    }  
    else  
    {  
        digitalWrite(INDICATOR, LOW);  
        Serial.println(analogRead(gas_sensor));  
    }  
}  
  
void loop() {  
    // put your main code here, to run repeatedly:  
  
    humidity=HT.readHumidity();  
    tempC=HT.readTemperature();  
    tempF=HT.readTemperature(true);  
  
    Serial.print("Humidity: ");  
    Serial.print(humidity);  
    Serial.print(" TempC: ");  
    Serial.print(tempC);  
    Serial.print("C TempF: ");  
    Serial.print(tempF);  
    Serial.println("F ");  
    if(humidity>=80){  
        digitalWrite(fanPin,LOW);  
        delay(2000);  
    }  
    else{  
        digitalWrite(fanPin,HIGH);  
    }  
    Gas_sensor();  
    delay(1000);  
}
```

→ Door Sensor and Hallway lights

```
#include <Servo.h>
```

```
Servo myservo;
```

```
int pirPin = 2;
```

```
int pirStat = 0;
```

```
int pos = 0;
```

```
int ultra_trig=7;
```

```
int ultra_echo=8;
```

```
int RED_passage=9;
```

```
int GREEN_passage=10;
```

```
int WHITE_passage=13;
```

```
int PIR_sense=1;
```

```
Servo myServo;
```

```
int duration;
```

```
float cm;
```

```
void setup() {
```

```
    pinMode(pirPin, INPUT);
```

```
    myservo.attach(3);
```

```
    Serial.begin(9600);
```

```
    pinMode(ultra_echo, INPUT);
```

```
    pinMode(ultra_trig, OUTPUT);
```

```
    pinMode(RED_passage, OUTPUT);
```

```
    pinMode(GREEN_passage, OUTPUT);
```

```
    pinMode(WHITE_passage, OUTPUT);
```

```
    Serial.begin(9600);
```

```
}
```

```
void Door(){
    pirStat = digitalRead(pirPin);
    if (pirStat == HIGH) {
        Serial.println("OPENING THE DOOR");
        for (pos = 90; pos >= 0; pos -= 1) {
            myservo.write(pos);
            delay(15);
        }
        delay(1000);
        for (pos = 0; pos <= 110; pos += 1) {
            myservo.write(pos);
            delay(15);
        }
    }
    else {
    }
}

void Passage_Light(){
    digitalWrite(ultra_trig,HIGH);
    delayMicroseconds(10);
    digitalWrite(ultra_trig,LOW);
    duration=pulseIn(ultra_echo,HIGH);
    cm=duration*0.034/2;
    Serial.println(cm);
    if(cm>35){
        digitalWrite(RED_passage,HIGH);
        digitalWrite(GREEN_passage,LOW);
        digitalWrite(WHITE_passage,LOW);
    }
}
```

```
else if(cm>10){
    digitalWrite(GREEN_passage,HIGH);
    digitalWrite(RED_passage,LOW);
    digitalWrite(WHITE_passage,LOW);
}
else{
    digitalWrite(WHITE_passage,HIGH);
    digitalWrite(GREEN_passage,LOW);
    digitalWrite(RED_passage,LOW);
}
//lcd.print(cm);
delay(500);
}

void loop() {
    Door();
    Passage_Light();

}
```

4. CONCLUSION AND FUTURE WORK

4.1 Result, Conclusion and Inference

Result:

We successfully run our project “SMART HOME AUTOMATION” and got the output as we wanted and all the components are working fine.

Conclusion:

Hence, we can say that the Arduino Board can be used perfectly without any problems occurring in between for Home Automation.

Inference:

The team truly believes that home automation is the next big step in the lives of consumers. The technology is available, most homes have a WiFi service, most consumers have smartphones.

4.2 Future Work and Cost

Future Work:

To ensure that the prototype created during this project can achieve its maximum potential, there are a number of improvements and changes that can be implemented. Also, the problems encountered throughout this project should be addressed. Foremost, the most prominent would be the Raspberry Pi working as a central unit connecting the consumer to devices in his/her home. Therefore looking into a two way communication between the Raspberry Pi and the device.

Cost:

As per project done, for one home around 5-6K rupees is invested. But as we go on large scale platform, the components required can be available in cheaper side, additionally there will be in need of work force.

