```
# Hilios v18 - Dark Sector Physics
# === PART 1: IMPORTS & PARAMETERS ===
import numpy as np
import cupy as cp
import time
import h5py
import os
import matplotlib.pyplot as plt
import matplotlib.gridspec as gridspec
from IPython.display import display, clear_output
sim_params = {
 # Simulation Control
 "NUM STEPS": 50000,
 "VIS_INTERVAL": 100,
 "DT": 1e-5,
 "GRID SIZE": 401,
 # RDU Physics Constants
 "G RDU": 0.05,
 "K_S": 1.0,
 "C ACCRETION DRAG": 0.1,
 "ACCRETION_RADIUS": 15.0,
 "C_DYN_FRICTION": 0.01,
 # Knoechelman Mechanism Constants
 "A CONST": 1.2,
 "N SENSITIVITY": 0.5,
 "C_UNIFY": 1.5e-5,
 "K ROT": 3.0,
 "C BALANCE": 423.0,
 "TACHYON MASS": 0.001,
 # Supernova & Magnetar Parameters
 "SUPERNOVA_SHELL_PARTICLES": 200,
 "SUPERNOVA EJECTION VELOCITY": 0.5,
 "REMNANT MASS FRACTION": 0.2,
 "MAGNETAR_STRENGTH": 500.0,
 "GAS CHARGE": 0.05,
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# Dark Strong Force Parameters
  "DARK_FORCE_STRENGTH": 0.01, # Epsilon_DS: The overall strength
  "REPULSION RADIUS": 2.5, #r 0: The distance where the force turns repulsive
  # Particle Population
  "gas particle count": 8000,
  "star population": {"G-Star": 1200, "BD": 800, "WD": 500, "NS": 300, "Magnetar": 10},
  "NUM TACHYONS": 5000,
  # Output Control
  "OUTPUT_FILENAME": "hilios_v18_final_state.h5",
  "OUTPUT DIR": "/content/drive/MyDrive/RDU Sims/"
}
# === PART 2: CUDA KERNELS ===
merger kernel = cp.RawKernel(r"""
extern "C" global
void merger kernel(float* pos, float* vel, float* mass, float* radius, int* is consumed, int
num particles.
          int* merger_log, int* merger_log_count, int max_log_size) {
  int i = blockDim.x * blockldx.x + threadldx.x;
  if (i >= num particles || is consumed[i] == 1) return;
  for (int j = i + 1; j < num particles; ++j) {
    if (is_consumed[j] == 1) continue;
    float dx = pos[i*3+0] - pos[i*3+0];
    float dy = pos[i*3+1] - pos[j*3+1];
    float dz = pos[i*3+2] - pos[j*3+2];
    float dist sq = dx*dx + dy*dy + dz*dz;
    float combined_radius = radius[i] + radius[j];
    if (dist_sq < combined_radius * combined_radius) {</pre>
      int survivor idx = (mass[i] >= mass[j]) ? i : j;
      int consumed_idx = (mass[i] >= mass[j]) ? j : i;
      if (atomicCAS(&is_consumed[consumed_idx], 0, 1) == 0) {
         float m survivor = mass[survivor idx];
         float m consumed = mass[consumed idx];
         float total_mass = m_survivor + m_consumed;
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vel[survivor_idx*3+0] = (m_survivor * vel[survivor_idx*3+0] + m_consumed *
vel[consumed_idx*3+0]) / total_mass;
          vel[survivor idx*3+1] = (m survivor * vel[survivor idx*3+1] + m consumed *
vel[consumed idx*3+1]) / total mass;
          vel[survivor_idx*3+2] = (m_survivor * vel[survivor_idx*3+2] + m_consumed *
vel[consumed idx*3+2]) / total mass;
          atomicAdd(&mass[survivor idx], m consumed);
          radius[survivor idx] = cbrtf(powf(radius[survivor idx], 3) + powf(radius[consumed idx],
3));
          int log_idx = atomicAdd(merger_log_count, 1);
          if (log idx < max log size) {
            merger_log[log_idx * 2 + 0] = survivor_idx;
             merger log[log idx * 2 + 1] = consumed idx;
          }
       }
    }
""", 'merger kernel')
stellar evolution kernel = cp.RawKernel(r"""
extern "C" global
void stellar_evolution_kernel(int* particle_types, float* lifetimes, int* event_flags, int n, float dt) {
  int i = blockDim.x* blockldx.x + threadldx.x;
  if (i \ge n \mid | lifetimes[i] \le 0) return;
  lifetimes[i] -= dt;
  if (lifetimes[i] <= 0) {
     if (particle_types[i] == 2) {
       particle_types[i] = 4;
       event flags[i] = 1;
  }
""", 'stellar evolution kernel')
knoechelman kernel = cp.RawKernel(r"""
extern "C" global
void knoechelman kernel(const float* positions, float* velocities, float* masses, const float*
radii, const float* spins,
               int* particle_types, int* is_consumed, int* event_flags, int n, float A, float N_sens,
float C_unify,
               float k_rot, float C_balance, float G_rdu, float tachyon_mass) {
```

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int i = blockDim.x* blockldx.x + threadldx.x:
  if (i >= n || is_consumed[i] == 1 || particle_types[i] == 0 || particle_types[i] >= 10) return;
  float drc_pos_x = positions[0], drc_pos_y = positions[1], drc_pos_z = positions[2];
  float drc radius = radii[0];
  float dx = positions[i*3+0] - drc pos x;
  float dy = positions[i*3+1] - drc pos y;
  float dz = positions[i*3+2] - drc pos z;
  float dist_sq = dx*dx + dy*dy + dz*dz;
  if (dist_sq < (radii[i] + drc_radius) * (radii[i] + drc_radius)) {</pre>
     if (atomicExch(&is_consumed[i], 1) == 0) {
       float drc mass = masses[0];
       float drc_spin_mag = sqrtf(spins[0]*spins[0] + spins[1]*spins[1] + spins[2]*spins[2]);
       float I over Imax proxy = fminf(1.0f, drc spin mag / 100.0f);
       float drc_density = (drc_radius > 0) ? drc_mass / (4.1887f * drc_radius * drc_radius *
drc_radius): 0.0f;
       float phi U = C unify * (drc mass * drc density) * expf(k rot * I over Imax proxy);
       float consumed_mass = masses[i];
       float omega R = A * powf(phi U / fmaxf(consumed mass, 1e-9f), N sens);
       float e_trap = (drc_radius > 0) ? G_rdu * (drc_mass * drc_mass) / drc_radius : 1e9f;
       float xi = (e_trap > 0) ? C_balance * (omega_R * omega_R) / e_trap : 0.0f;
       if (xi > 1.0f) {
          particle_types[i] = 11;
          velocities[i*3+0] *= 50.0f;
          velocities[i*3+1] *= 50.0f;
          velocities[i*3+2] *= 50.0f;
       } else {
          particle_types[i] = 10;
          velocities[i*3+0] *= 5.0f;
          velocities[i*3+1] *= 5.0f;
          velocities[i*3+2] *= 5.0f;
       masses[i] = tachyon_mass;
       event_flags[i] = 2;
  }
""", 'knoechelman kernel')
deposit_mass_kernel = cp.RawKernel(r"""
extern "C" global void deposit mass kernel(const float* positions, const float* masses,
float* grid, int n, int gs) {
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int i = blockDim.x * blockldx.x + threadldx.x:
  if (i \ge n) return;
  int x = (int)positions[i*3+0], y = (int)positions[i*3+1], z = (int)positions[i*3+2];
  if (x \ge 0 \&\& x < gs \&\& y \ge 0 \&\& y < gs \&\& z \ge 0 \&\& z < gs)
     atomicAdd(&grid[x*gs*gs + y*gs + z], masses[i]);
  }
}
""", 'deposit mass kernel')
update chronos kernel = cp.RawKernel(r"""
extern "C" __global__ void update_chronos_kernel(float* C_n_plus_1, const float* C_n, const
float* C n minus 1, const float* source term, int gs, float dt, float K S, float G) {
  int x = blockldx.x * blockDim.x + threadldx.x, y = blockldx.y * blockDim.y + threadldx.y, z =
blockldx.z * blockDim.z + threadldx.z;
  if (x \ge gs || y \ge gs || z \ge gs) return;
  if (x > 0 \&\& x < gs - 1 \&\& y > 0 \&\& y < gs - 1 \&\& z > 0 \&\& z < gs - 1) {
     int idx = x*gs*gs + y*gs + z;
     float laplacian = K S * (C n[idx+gs*gs] + C n[idx-gs*gs] + C n[idx+gs] + C n[idx-gs] +
C_n[idx+1] + C_n[idx-1] - 6.0f * C_n[idx]);
     float source = -G * source term[idx];
     C n plus 1[idx] = 2.0f * C n[idx] - C n minus 1[idx] + dt * dt * (laplacian + source);
  }
""", 'update_chronos_kernel')
generate b field kernel = cp.RawKernel(r"""
extern "C" __global__ void generate_b_field_kernel(float* b_field_grid, const float* positions,
const float* spins, const int* particle types, int n, int gs, float b strength) {
  int x = blockldx.x * blockDim.x + threadIdx.x, y = blockldx.y * blockDim.y + threadIdx.y, z =
blockldx.z * blockDim.z + threadIdx.z;
  if (x \ge gs || y \ge gs || z \ge gs) return;
  int grid idx = (x*g*g*g* + y*g* + z)*3;
  float bx = 0.0f, by = 0.0f, bz = 0.0f;
  for (int i = 0; i < n; ++i) {
     if (particle types[i] == 7) { // Magnetar
        float mx = positions[i*3+0], my = positions[i*3+1], mz = positions[i*3+2];
        float rx = (float)x - mx, ry = (float)y - my, rz = (float)z - mz;
        float dist sq = rx*rx + ry*ry + rz*rz;
        if (dist_sq > 1e-6f) {
          float strength = b_strength / (dist_sq * sqrtf(dist_sq));
          float sx = spins[i*3+0], sy = spins[i*3+1], sz = spins[i*3+2];
          float smag = sqrtf(sx*sx + sy*sy + sz*sz);
          if (smag > 1e-6f) {
             bx += strength * sx / smag;
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by += strength * sy / smag;
             bz += strength * sz / smag;
          }
       }
     }
  b field_grid[grid_idx+0] = bx;
  b_field_grid[grid_idx+1] = by;
  b_field_grid[grid_idx+2] = bz;
""", 'generate b field kernel')
force kernel = cp.RawKernel(r"""
extern "C" __global__
void force kernel(
  float* accelerations, const float* positions, const float* velocities, const float* masses,
  const int* particle_types, const float* chronos_field, const float* b_field_grid,
  int n, int gs, float C drag, float R drag, float C friction, float q,
  float dsf_strength, float dsf_radius) {
  int i = blockldx.x * blockDim.x + threadldx.x;
  if (i \ge n) return;
  float px = positions[i*3+0], py = positions[i*3+1], pz = positions[i*3+2];
  float ax = 0.0f, ay = 0.0f, az = 0.0f;
  int x = (int)px, y = (int)py, z = (int)pz;
  // Force from Chronos Field Gradient
  if (x > 0 \&\& x < gs - 1 \&\& y > 0 \&\& y < gs - 1 \&\& z > 0 \&\& z < gs - 1) {
     ax = -(chronos_field[(x+1)*gs*gs+y*gs+z] - chronos_field[(x-1)*gs*gs+y*gs+z]) / 2.0f;
     ay = -(chronos_field[x*gs*gs+(y+1)*gs+z] - chronos_field[x*gs*gs+(y-1)*gs+z]) / 2.0f;
     az = -(chronos field[x*qs*qs+y*qs+(z+1)] - chronos field[x*qs*qs+y*qs+(z-1)]) / 2.0f;
  }
  int p_type = particle_types[i];
  // Gas-specific forces
  if (p type == 1) {
     // Lorentz force for charged gas
     if (x \ge 0 \&\& x < gs \&\& y \ge 0 \&\& y < gs \&\& z \ge 0 \&\& z < gs)
        int b idx = (x*gs*gs + y*gs + z) * 3;
        float bx = b_field_grid[b_idx+0], by = b_field_grid[b_idx+1], bz = b_field_grid[b_idx+2];
        float vx = velocities[i*3+0], vy = velocities[i*3+1], vz = velocities[i*3+2];
        ax += q * (vy * bz - vz * by);
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ay += q * (vz * bx - vx * bz);
        az += q * (vx * by - vy * bx);
     // Accretion drag near the center
     float d_{sq_c} = (50.5f - px)*(50.5f - px) + (50.5f - py)*(50.5f - py) + (50.5f - pz)*(50.5f - pz);
     if (d_sq_c < R_drag * R_drag) {
        ax -= C_drag * velocities[i*3+0];
       ay -= C_drag * velocities[i*3+1];
        az -= C_drag * velocities[i*3+2];
    }
  }
  // Dynamical Friction for massive objects
  if (masses[i] > 10.0) {
     float v_sq = velocities[i*3+0]*velocities[i*3+0] + velocities[i*3+1]*velocities[i*3+1] +
velocities[i*3+2]*velocities[i*3+2];
     if (v_sq > 0.1f) {
       float f_mag = C_friction * masses[i] / v_sq;
       ax -= f_mag * velocities[i*3+0];
       ay -= f_mag * velocities[i*3+1];
       az -= f_mag * velocities[i*3+2];
  }
  // Dark Strong Force between Tachyons
  if (p type >= 10) {
     for (int j = 0; j < n; ++j) {
        if (i == j || particle_types[j] < 10) continue;
        float dx = px - positions[j*3+0], dy = py - positions[j*3+1], dz = pz - positions[j*3+2];
        float r_sq = dx^*dx + dy^*dy + dz^*dz;
        if (r_sq > 1e-6f \& r_sq < 25.0f) {
          float r = sqrtf(r sq);
          float r0_over_r_6 = powf(dsf_radius / r, 6.0f);
          float r0_over_r_12 = r0_over_r_6 * r0_over_r_6;
          float force_mag = (12.0f * dsf_strength / r) * (r0_over_r_12 - r0_over_r_6);
          ax += force_mag * (dx / r) / masses[i];
          ay += force_mag * (dy / r) / masses[i];
          az += force_mag * (dz / r) / masses[i];
       }
     }
  }
  accelerations[i*3+0] = ax;
  accelerations[i*3+1] = ay;
```

```
accelerations[i*3+2] = az;
}
""", 'force kernel')
# === PART 3: DATA INITIALIZATION & GPU TRANSFER ===
print("Initializing Hilios v18...");
star counts = sim params["star population"];
num stars = sum(star counts.values())
num baryons = sim params["gas particle count"] + num stars + 1; # +1 for DRC
num_tachyons = sim_params["NUM_TACHYONS"]
total particles = num baryons + num tachyons;
gs = sim_params["GRID_SIZE"]
positions cpu = np.zeros((total particles, 3), dtype=np.float32);
velocities cpu = np.zeros((total particles, 3), dtype=np.float32)
masses cpu = np.ones(total particles, dtype=np.float32);
radii cpu = np.ones(total particles, dtype=np.float32) * 0.5
is consumed cpu = np.zeros(total particles, dtype=np.int32);
spin cpu = np.zeros((total particles, 3), dtype=np.float32)
particle_type_cpu = np.zeros(total_particles, dtype=np.int32);
lifetimes cpu = np.zeros(total particles, dtype=np.float32)
print(f"Creating {total_particles} particles...");
# Dark Resonator Core (DRC)
particle_type_cpu[0] = 0;
masses cpu[0] = 50000.0;
radii cpu[0] = 2.0
spin_cpu[0] = [0, 0, 100.0];
positions_cpu[0] = [gs / 2, gs / 2, gs / 2];
# Accretion Disk
disk indices = slice(1, num baryons)
num disk particles = num baryons - 1;
radius = np.random.uniform(gs * 0.1, gs * 0.5, num disk particles);
angle = np.random.uniform(0, 2 * np.pi, num_disk_particles);
z pos = np.random.uniform(-gs * 0.04, gs * 0.04, num disk particles)
positions_cpu[disk_indices, 0] = gs / 2 + radius * np.cos(angle);
positions cpu[disk indices, 1] = gs / 2 + radius * np.sin(angle)
positions cpu[disk indices, 2] = gs / 2 + z pos;
orbital v = np.sqrt(sim params["G RDU"] * masses cpu[0] / radius)
velocities cpu[disk indices, 0] = -orbital_v * np.sin(angle);
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velocities cpu[disk indices, 1] = orbital v * np.cos(angle)
# Populate particle types in the disk
start idx = 1:
particle type cpu[start idx:start idx + sim params["gas particle count"]] = 1; # Gas
start idx += sim params["gas particle count"]
type map = {"G-Star": 2, "BD": 3, "WD": 4, "NS": 5, "Magnetar": 7};
label map = {v: k for k, v in type map.items()}
label map[0] = "DRC";
label map[1] = "Gas"
for star type, count in star counts.items():
  end_idx = start_idx + count
  particle type cpu[start idx:end idx] = type map[star type]
  if star type == "NS":
     lifetimes_cpu[start_idx:end_idx] = np.random.uniform(0.1, sim_params["NUM STEPS"] *
sim params["DT"])
  start idx = end idx
# --- NEW: Assign physically-based masses to stars ---
print("Assigning star masses...");
mass map = {
  2: 1.0, # G-Star (Solar mass)
  3: 0.06, # BD (Brown Dwarf, e.g., 60 Jupiter masses)
  4: 0.9, # WD (White Dwarf)
  5: 1.8, # NS (Neutron Star)
  7: 2.0 # Magnetar
# Loop through all baryonic particles to set star masses
for i in range(1, num baryons):
  p type = particle type cpu[i]
  if p type in mass map:
    # Assign the mapped mass, with a small random variation
     masses_cpu[i] = mass_map[p_type] + np.random.uniform(-0.05, 0.05)
# Ensure gas particles remain at mass 1.0
gas_mask = (particle_type_cpu == 1)
masses_cpu[gas_mask] = 1.0
# Tachyons
tachyon_indices = slice(num_baryons, total_particles);
positions cpu[tachyon indices] = np.random.rand(num tachyons, 3) * gs
velocities cpu[tachyon indices] = (np.random.rand(num tachyons, 3) - 0.5) * 100;
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particle type cpu[tachyon indices] = 10
masses_cpu[tachyon_indices] = sim_params["TACHYON_MASS"] # Also assign tachyon mass
print("Transferring data to GPU...");
positions gpu = cp.asarray(positions cpu);
velocities gpu = cp.asarray(velocities cpu)
masses gpu = cp.asarray(masses cpu);
radii gpu = cp.asarray(radii cpu);
is consumed gpu = cp.asarray(is consumed cpu)
spin gpu = cp.asarray(spin cpu);
particle_type_gpu = cp.asarray(particle_type_cpu);
lifetimes gpu = cp.asarray(lifetimes cpu)
# Initialize GPU arrays
accelerations_gpu = cp.empty_like(positions_gpu);
event_flags_gpu = cp.zeros(total_particles, dtype=cp.int32)
chronos field n minus 1 = cp.zeros((gs, gs, gs), dtype=cp.float32);
chronos_field_n = cp.zeros((gs, gs, gs), dtype=cp.float32)
chronos field n plus 1 = cp.zeros((gs, gs, gs), dtype=cp.float32);
source_term_gpu = cp.zeros((gs, gs, gs), dtype=cp.float32)
b_field_grid = cp.zeros((gs, gs, gs, 3), dtype=cp.float32)
# Merger logging setup
MAX_MERGERS_PER_STEP = 100;
merger log gpu = cp.zeros((MAX MERGERS PER STEP, 2), dtype=cp.int32);
merger log count gpu = cp.zeros(1, dtype=cp.int32)
print("Initialization complete.")
# === PART 4: LIVE SCIENCE DASHBOARD ===
fig = plt.figure(figsize=(16, 12));
fig.patch.set facecolor('#0d0d0d');
dashboard_gs = gridspec.GridSpec(2, 4, height_ratios=[3, 1.2])
ax_main = fig.add_subplot(dashboard_gs[0, :], projection='3d');
ax hist baryon = fig.add subplot(dashboard qs[1, 0])
ax_hist_tachyon = fig.add_subplot(dashboard_gs[1, 1]);
ax_angular_momentum = fig.add_subplot(dashboard_gs[1, 2])
ax log = fig.add subplot(dashboard gs[1, 3]);
plt.subplots_adjust(wspace=0.3, hspace=0.5)
# UPDATED Dashboard Function
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```
def update dashboard(step, positions, velocities, particle types, masses, ang mom history,
event_log_list):
  # --- Clear all axes for redrawing ---
  for ax in [ax main, ax hist baryon, ax hist tachyon, ax angular momentum, ax log]:
     ax.cla()
  # --- Main 3D Plot ---
  ax main.set facecolor('black')
  ax main.set title(f'Galaxy State at Step {step}', color='white', fontsize=16)
  type color map = {0: "magenta", 1: "#333333", 2: "yellow", 3: "orange", 4: "white", 5: "cyan",
7: "lime", 10: "red", 11: "purple"}
  type size map = {0: 200, 1: 2, 2: 15, 3: 10, 4: 12, 5: 20, 7: 25, 10: 5, 11: 5}
  unique types = np.unique(particle types)
  for p_type in unique_types:
     mask = (particle_types == p_type)
     marker = "*" if p type == 0 else "o"
     alpha = 0.1 if p_type == 1 or p_type >= 10 else 1.0
     ax main.scatter(positions[mask, 0], positions[mask, 1], positions[mask, 2],
c=type color map.get(p type), s=type size map.get(p type), alpha=alpha, marker=marker)
  plot_limit = sim_params["GRID SIZE"]
  ax main.set(xlim=(0, plot limit), ylim=(0, plot limit), zlim=(0, plot limit))
  for axis in [ax_main.xaxis, ax_main.yaxis, ax_main.zaxis]:
     axis.pane.fill = False
     axis.line.set color('grey')
     axis.set tick params(colors='grey')
  # --- Baryon Mass Histogram ---
  baryon mask = (particle types < 10) & (particle types > 0)
  ax hist baryon.hist(masses[baryon mask], bins=50, color='cyan', alpha=0.7) # Increased
bins
  ax hist baryon.set title('Baryon Mass Dist.', color='white')
  ax hist baryon.set facecolor('#1a1a1a')
  ax hist baryon.tick params(colors='grey')
  # --- Tachyon Velocity Histogram ---
  tachyon_mask = (particle_types >= 10)
  if np.any(tachyon mask):
    tachyon speeds = np.linalg.norm(velocities[tachyon mask], axis=1)
     ax_hist_tachyon.hist(tachyon_speeds, bins=20, color='red', alpha=0.7)
  ax hist tachyon.set title('Tachyon Speed Dist.', color='white')
  ax hist tachyon.set facecolor('#1a1a1a')
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```
ax hist tachyon.tick params(colors='grey')
  # --- Angular Momentum Plot ---
  steps_plotted = range(0, len(ang_mom_history) * sim_params["VIS_INTERVAL"],
sim_params["VIS_INTERVAL"])
  if len(steps_plotted) > 1:
    ax angular momentum.plot(steps plotted, ang mom history, color='lime')
  ax angular momentum.set title('Ang. Momentum', color='white')
  ax angular momentum.set facecolor('#1a1a1a')
  ax angular momentum.tick params(colors='grey')
  # --- Event Log ---
  ax log.set title('Event Log', color='white')
  ax_log.set_facecolor('#1a1a1a')
  ax log.set xticks([])
  ax_log.set_yticks([])
  ax_log.text(0.05, 0.95, '\n'.join(event_log_list[-5:]), transform=ax_log.transAxes,
color='lightgreen', fontsize=10, va='top', family='monospace')
  # --- Display Update ---
  display(fig)
  clear_output(wait=True)
# === PART 5: DATA SAVING FUNCTION ===
def save_final_state(filepath, pos_gpu, vel_gpu, types_gpu, masses_gpu, spin_gpu):
  print(f"\nSaving final simulation state to: {filepath}");
  try:
    os.makedirs(os.path.dirname(filepath), exist_ok=True)
    pos_host = cp.asnumpy(pos_gpu);
    vel host = cp.asnumpy(vel gpu);
    types_host = cp.asnumpy(types_gpu)
    masses host = cp.asnumpy(masses gpu);
    spin_host = cp.asnumpy(spin_gpu)
    with h5py.File(filepath, 'w') as f:
      p_group = f.create_group('particles')
      p group.create dataset('positions', data=pos host);
      p_group.create_dataset('velocities', data=vel_host)
      p group.create dataset('types', data=types host);
      p group.create dataset('masses', data=masses host)
      p_group.create_dataset('spins', data=spin_host)
    print("Save complete.")
  except Exception as e:
```

```
print(f"--- ERROR: Could not save file. ---\n{e}")
# === PART 6: MAIN SIMULATION LOOP ===
print(f"Starting Hilios v18 with {total particles} particles...")
threads per block = 256;
blocks_per_grid_1d = (total_particles + threads_per_block - 1) // threads_per_block
event log = ["Sim Initialized..."]
angular momentum history = []
for step in range(sim_params["NUM_STEPS"]):
  # --- Merger Detection ---
  merger_log_count_gpu.fill(0)
  merger kernel((blocks per grid 1d,), (threads per block,),
         (positions_gpu, velocities_gpu, masses_gpu, radii_gpu, is_consumed_gpu,
total_particles, merger_log_gpu, merger_log_count_gpu, MAX_MERGERS_PER_STEP))
  num mergers = int(merger log count gpu.get().item())
  # FIX: Cap the number of mergers to the maximum we can log to prevent crashes.
  num mergers = min(num mergers, MAX MERGERS PER STEP)
  if num mergers > 0:
    merger events = cp.asnumpy(merger log gpu[:num mergers]);
    involved_indices = merger_events.flatten()
    involved types = cp.asnumpy(particle type gpu[involved indices]).reshape(num mergers,
2)
    for i in range(num mergers):
      survivor_name = label_map.get(involved_types[i, 0], "Unk");
      consumed_name = label_map.get(involved_types[i, 1], "Unk")
      event log.append(f"MERGER @ {step}: {survivor name} + {consumed name}")
  # --- Chronos Field Update ---
  source term gpu.fill(0)
  deposit_mass_kernel((blocks_per_grid_1d,), (threads_per_block,),
             (positions_gpu, masses_gpu, source_term_gpu, total_particles, gs))
  threads per_block_3d = (8, 8, 8);
  blocks_per_grid_3d = ((gs + 7) // 8, (gs + 7) // 8, (gs + 7) // 8)
  # FIX: Corrected syntax for 3D kernel calls
  update_chronos_kernel(blocks_per_grid_3d, threads_per_block_3d,
              (chronos field n plus 1, chronos field n, chronos field n minus 1,
source_term_gpu, gs, sim_params["DT"], sim_params["K_S"], sim_params["G_RDU"]))
```

```
chronos_field_n, chronos_field_n_minus_1 = chronos_field_n_plus_1, chronos_field_n
  # --- B-Field Generation ---
  b field grid.fill(0)
  # FIX: Corrected syntax for 3D kernel calls
  generate b field kernel(blocks per grid 3d, threads per block 3d,
                (b_field_grid, positions_gpu, spin_gpu, particle_type_gpu, total_particles, gs,
sim_params["MAGNETAR_STRENGTH"]))
  # --- Force Calculation & Integration ---
  force_kernel((blocks_per_grid_1d,), (threads_per_block,),
          (accelerations gpu, positions gpu, velocities gpu, masses gpu, particle type gpu,
chronos_field_n.ravel(), b_field_grid, total_particles, gs, sim_params["C_ACCRETION DRAG"],
sim params["ACCRETION RADIUS"], sim_params["C_DYN_FRICTION"],
sim_params["GAS_CHARGE"], sim_params["DARK_FORCE_STRENGTH"],
sim_params["REPULSION_RADIUS"]))
  velocities_gpu += accelerations_gpu * sim_params["DT"];
  positions gpu += velocities gpu * sim params["DT"]
  # --- Stellar Evolution & Supernovae ---
  event flags gpu.fill(0)
  stellar evolution kernel((blocks per grid 1d,), (threads per block,),
                 (particle_type_gpu, lifetimes_gpu, event_flags_gpu, total_particles,
sim params["DT"]))
  if cp.any(event flags gpu == 1):
    supernova_indices_gpu = cp.where(event_flags_gpu == 1)[0]
    if supernova_indices_gpu.size > 0:
       log_message = f"SUPERNOVA @ {step}: {supernova_indices_gpu.size} star(s)
exploded!";
       event_log.append(log_message)
       supernova_positions = cp.asnumpy(positions_gpu[supernova_indices_gpu]);
       supernova_masses = cp.asnumpy(masses_gpu[supernova_indices_gpu])
       new particles pos, new particles vel, new particles mass, new particles type,
new_particles_radius, new_particles_lifetimes, new_particles_spins = [], [], [], [], [], [], []
       for i in range(supernova_indices_gpu.size):
         pos, original mass = supernova positions[i], supernova masses[i]
         remnant mass = original mass * sim params["REMNANT MASS FRACTION"]
         new particles pos.append(pos);
         new particles vel.append([0, 0, 0]);
         new particles mass.append(remnant mass)
```

```
if original_mass > 2.5:
            new particles type.append(7) # Magnetar
         else:
            new particles type.append(5) # Neutron Star
         new particles radius.append(0.01);
         new particles lifetimes.append(1e18);
         new particles spins.append([0, 0, 0])
         shell particles = sim params["SUPERNOVA SHELL PARTICLES"];
         ejection_vel = sim_params["SUPERNOVA_EJECTION_VELOCITY"]
         mass per shell particle = (original mass * (1.0 -
sim_params["REMNANT_MASS_FRACTION"])) / shell_particles
         for _ in range(shell_particles):
            theta, phi = np.arccos(2 * np.random.rand() - 1), np.random.uniform(0, 2 * np.pi)
            vx, vy, vz = ejection vel * np.sin(theta) * np.cos(phi), ejection vel * np.sin(theta) *
np.sin(phi), ejection_vel * np.cos(theta)
            new particles pos.append(pos);
            new particles vel.append([vx, vy, vz]);
            new_particles_mass.append(mass_per_shell_particle)
            new particles type.append(1); # Gas
            new particles radius.append(0.001);
            new_particles_lifetimes.append(1e18);
            new particles spins.append([0, 0, 0])
       # Remove original stars and add new remnants and shell particles
       keep mask = (event flags gpu != 1)
       positions_gpu, velocities_gpu, masses_gpu, radii_gpu, is_consumed_gpu, spin_gpu,
particle type gpu, lifetimes gpu = \
         positions gpu[keep mask], velocities gpu[keep mask], masses gpu[keep mask],
radii_gpu[keep_mask], is_consumed_gpu[keep_mask], spin_gpu[keep_mask],
particle_type_gpu[keep_mask], lifetimes_gpu[keep_mask]
       num new particles = len(new particles pos)
       new_pos_gpu = cp.asarray(np.array(new_particles_pos));
       new vel gpu = cp.asarray(np.array(new particles vel));
       new_mass_gpu = cp.asarray(np.array(new_particles_mass))
       new_type_gpu = cp.asarray(np.array(new_particles_type), dtype=cp.int32);
       new radius gpu = cp.asarray(np.array(new particles radius));
       new_lifetimes_gpu = cp.asarray(np.array(new_particles_lifetimes));
       new spins gpu = cp.asarray(np.array(new spins gpu))
       new_consumed_gpu = cp.zeros(num_new_particles, dtype=cp.int32)
```

```
positions_gpu = cp.vstack([positions_gpu, new_pos_gpu]);
       velocities gpu = cp.vstack([velocities gpu, new vel gpu]);
       masses_gpu = cp.hstack([masses_gpu, new_mass_gpu])
       radii gpu = cp.hstack([radii gpu, new radius gpu]);
       is_consumed_gpu = cp.hstack([is_consumed_gpu, new_consumed_gpu]);
       spin gpu = cp.vstack([spin gpu, new spins gpu])
       particle_type_gpu = cp.hstack([particle_type_gpu, new_type_gpu]);
       lifetimes_gpu = cp.hstack([lifetimes_gpu, new_lifetimes_gpu])
       # Update particle count and kernel launch parameters
       total particles = positions gpu.shape[0];
       event flags gpu = cp.zeros(total particles, dtype=cp.int32)
       blocks_per_grid_1d = (total_particles + threads_per_block - 1) // threads_per_block
  # --- Knoechelman Mechanism ---
  knoechelman_kernel((blocks_per_grid_1d,), (threads_per_block,),
             (positions gpu, velocities gpu, masses gpu, radii gpu, spin gpu,
particle_type_gpu, is_consumed_gpu, event_flags_gpu, total_particles,
              sim params["A CONST"], sim params["N SENSITIVITY"],
sim_params["C_UNIFY"], sim_params["K_ROT"], sim_params["C_BALANCE"],
sim_params["G_RDU"], sim_params["TACHYON_MASS"]))
  if cp.any(event flags gpu == 2):
    num_events = int(cp.sum(event_flags_gpu == 2).get().item());
    event log.append(f"TRANSFORMATION @ {step}: {num events} particle(s) converted.")
  # --- Visualization ---
  if step > 0 and step % sim_params["VIS_INTERVAL"] == 0:
    active_mask = (is_consumed_gpu == 0)
    pos_host = cp.asnumpy(positions_gpu[active_mask]);
    vel host = cp.asnumpy(velocities gpu[active mask]);
    types_host = cp.asnumpy(particle_type_gpu[active_mask])
    masses_host = cp.asnumpy(masses_gpu[active_mask])
    # Calculate Angular Momentum
    if pos host.shape[0] > 1:
       # Center positions relative to the DRC (particle 0)
       rel_pos = pos_host[1:] - pos_host[0]
       # Get masses for non-DRC particles
       rel masses = masses host[1:]
       # Get velocities for non-DRC particles
       rel vel = vel host[1:]
       # Calculate angular momentum for each particle (L = r \times p = m * (r \times v))
```

```
L_vectors = rel_masses[:, np.newaxis] * np.cross(rel_pos, rel_vel)
     # Total angular momentum is the sum of individual vectors
     L total vector = np.sum(L vectors, axis=0)
     # Magnitude of the total angular momentum
     L_total_mag = np.linalg.norm(L_total_vector)
     angular_momentum_history.append(L_total_mag)
   else:
     angular_momentum_history.append(0)
   # UPDATED Function Call
   update_dashboard(step, pos_host, vel_host, types_host, masses_host,
angular_momentum_history, event_log)
print("Simulation Finished.")
# === PART 7: FINAL SAVE ===
save_final_state(os.path.join(sim_params["OUTPUT_DIR"],
sim params["OUTPUT FILENAME"]),
         positions_gpu, velocities_gpu, particle_type_gpu, masses_gpu, spin_gpu)
```