

Blast Off into the Future of Autonomy in Space



PROF. GRACE X. GAO



New Era for Exploring the Moon

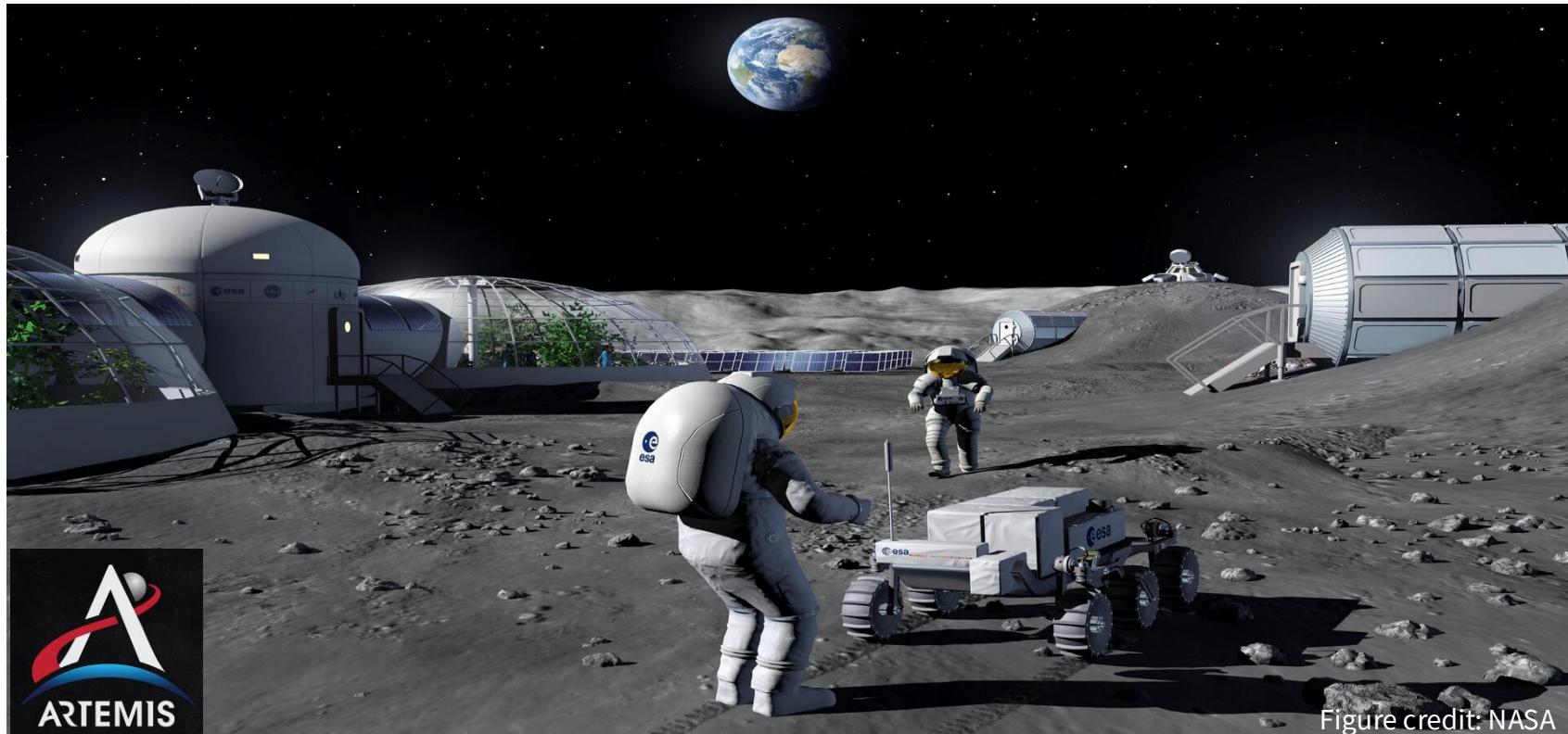


Figure credit: NASA

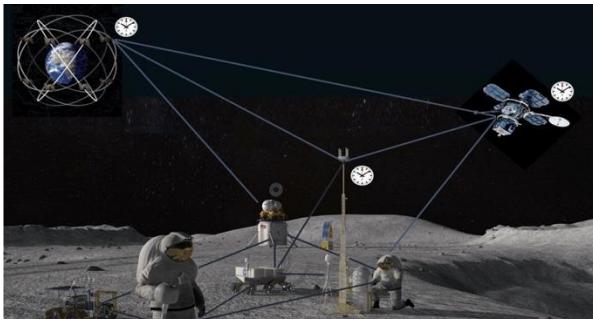


Blast Off into the Future of Autonomy in Space: Technical Trends

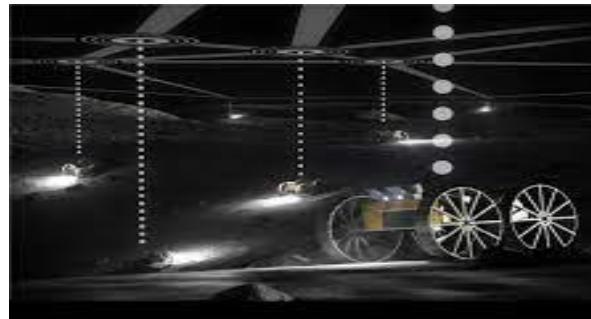


- Building infrastructure (e.g. WiFi, GPS, power plant, base station)
- Collaborative intelligence (e.g. swarm robots, satellite swarms)
- Long-range autonomy
- AI for space

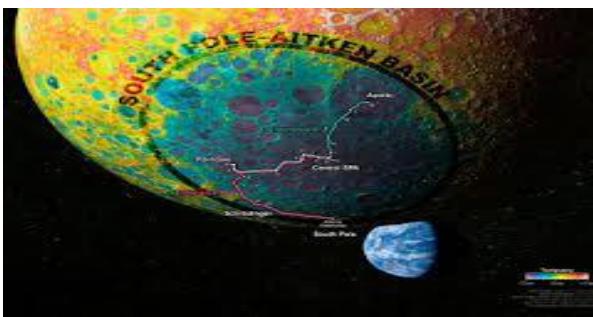
Example Projects in the Stanford NAV Lab



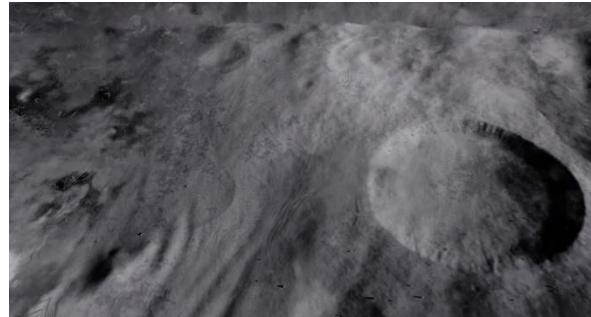
"GPS" for the Moon



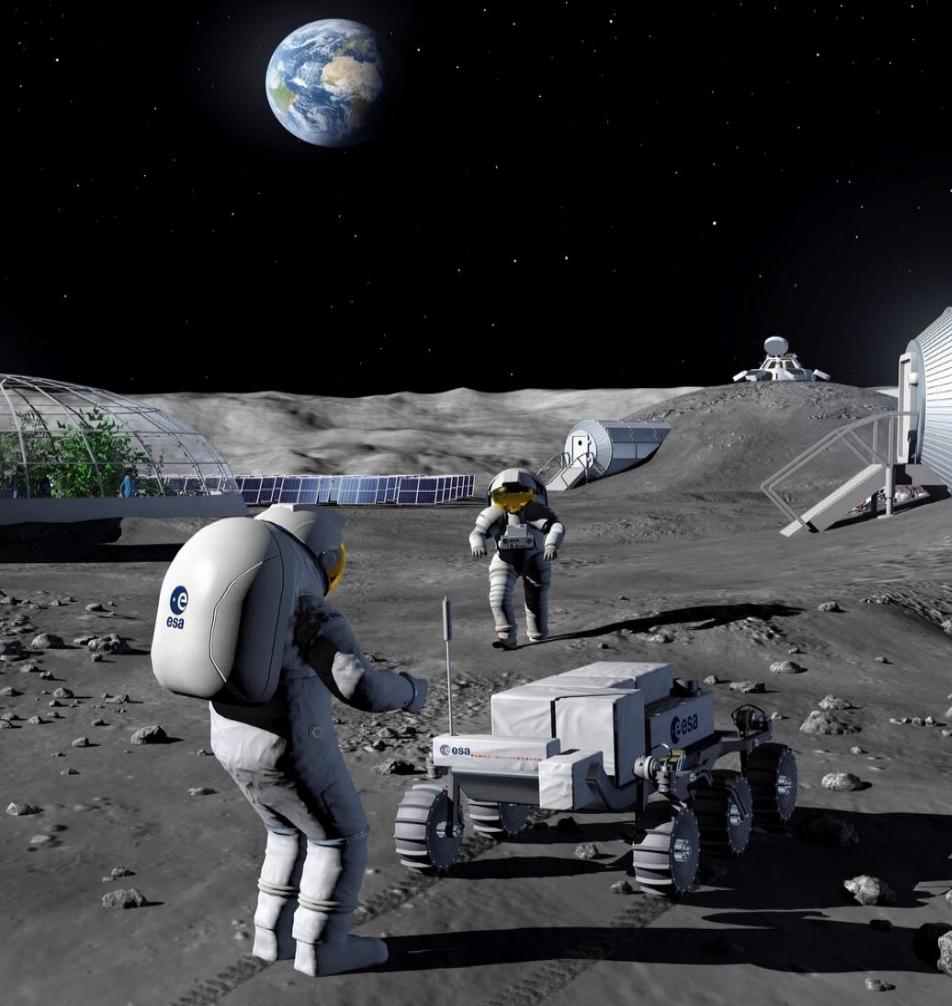
Moon Rover Swarm: CADRE Mission



Long-Range Moon Rover:
Endurance Mission Concept



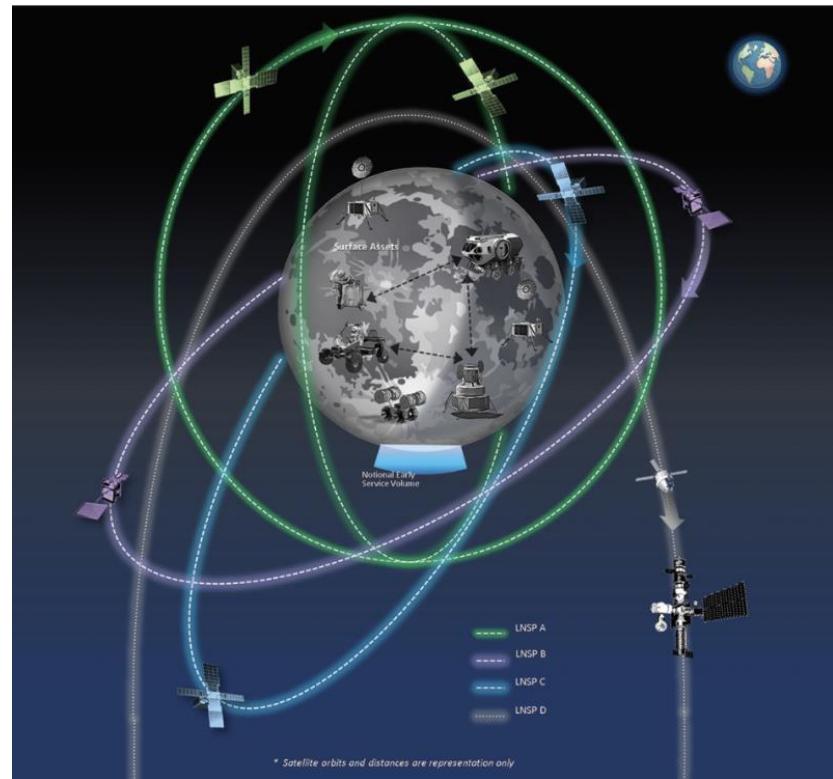
Neural Moon Surface Maps



“GPS” for the Moon

LunaNet

- Satellite network around the moon for navigation and communication
- Joint effort by
 - US NASA
 - European ESA
 - Japanese JAXA
 - + Korea
 - + India

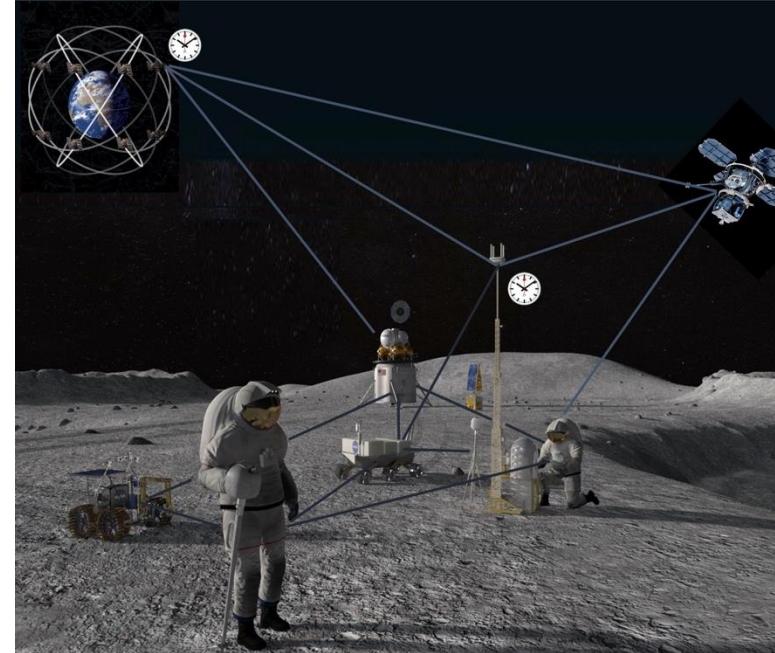


**Can we have a GPS-like system for the
Moon, but with a much lower cost?**

Lunar Navigation Satellite System

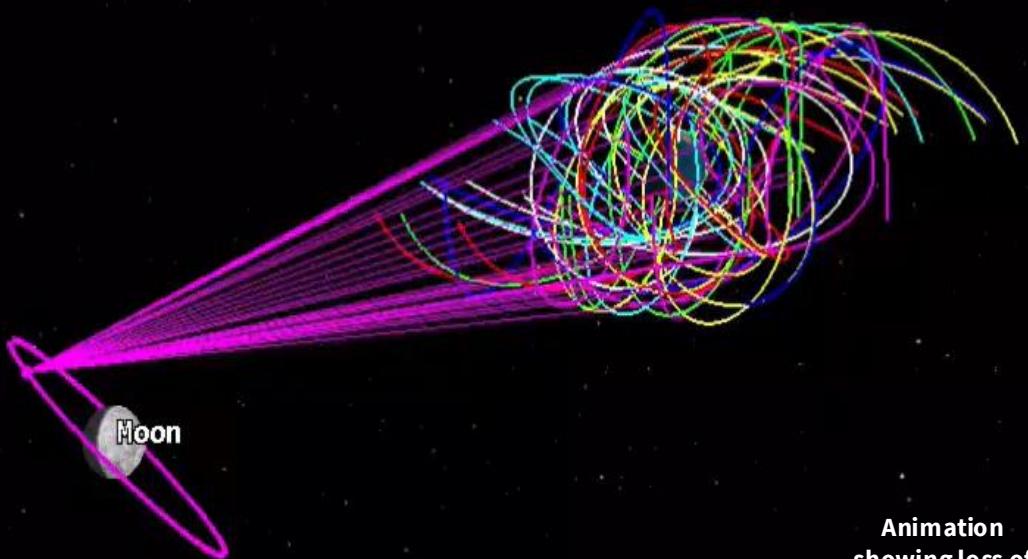


- Smaller satellites
 - as small as a shoe box
 - vs. terrestrial GPS satellites: as large as a truck
- Cheaper clocks
 - a thousand times cheaper than the atomic clocks on today's GPS satellites



Key idea: Use terrestrial GPS for lunar navigation satellite clock and ephemeris corrections

Loss of Earth-GPS due to Occultation



Moon inertial frame

Animation
showing loss of
Earth-GPS due to
Moon occultations

LuGRE: Lunar GNSS Receiver Experiment



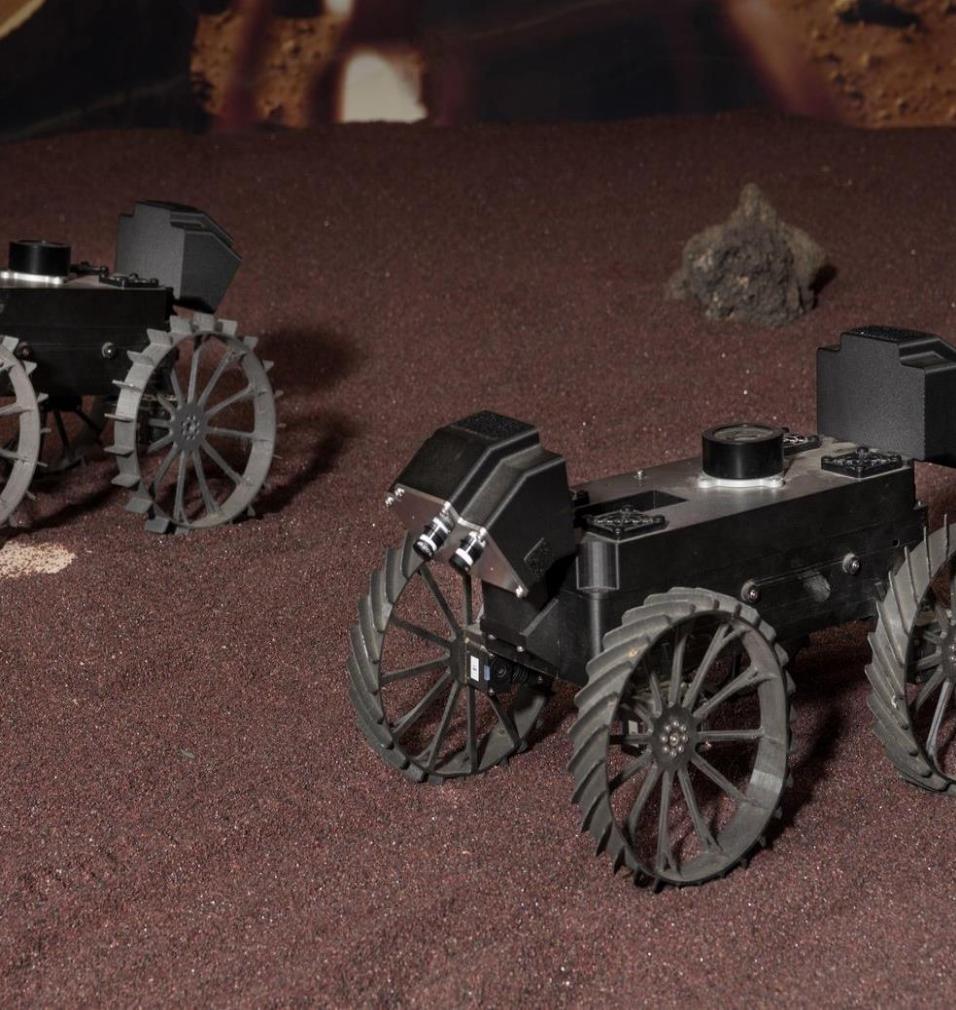
- **LuGRE:** a payload onboard Firefly Aerospace Blue Ghost Mission 1, launched on **Jan 15, 2025**.
 - Collaboration among NASA, ASI, and Qascom SRL
- Catches GPS Signal From 205,674 miles (331,000 km) Away, sets distance record.
- Demonstrated the feasibility of using Earth GNSS signals



Moonshot 2.0: Blast Off into the Future of Autonomy in Space



- Building infrastructure (e.g. WiFi, GPS, power plant, base station)
- Collaborative intelligence (e.g. swarm robots)
- Long-range autonomy
- AI for space



Moon Rover Swarm: CADRE Mission

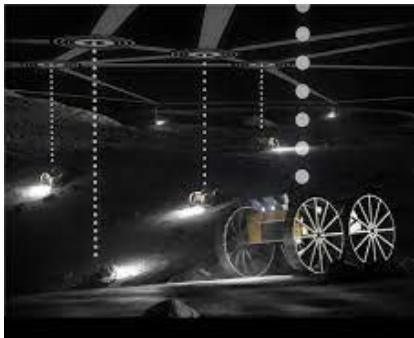


CADRE

Cooperative Autonomous Distributed Robotic Exploration



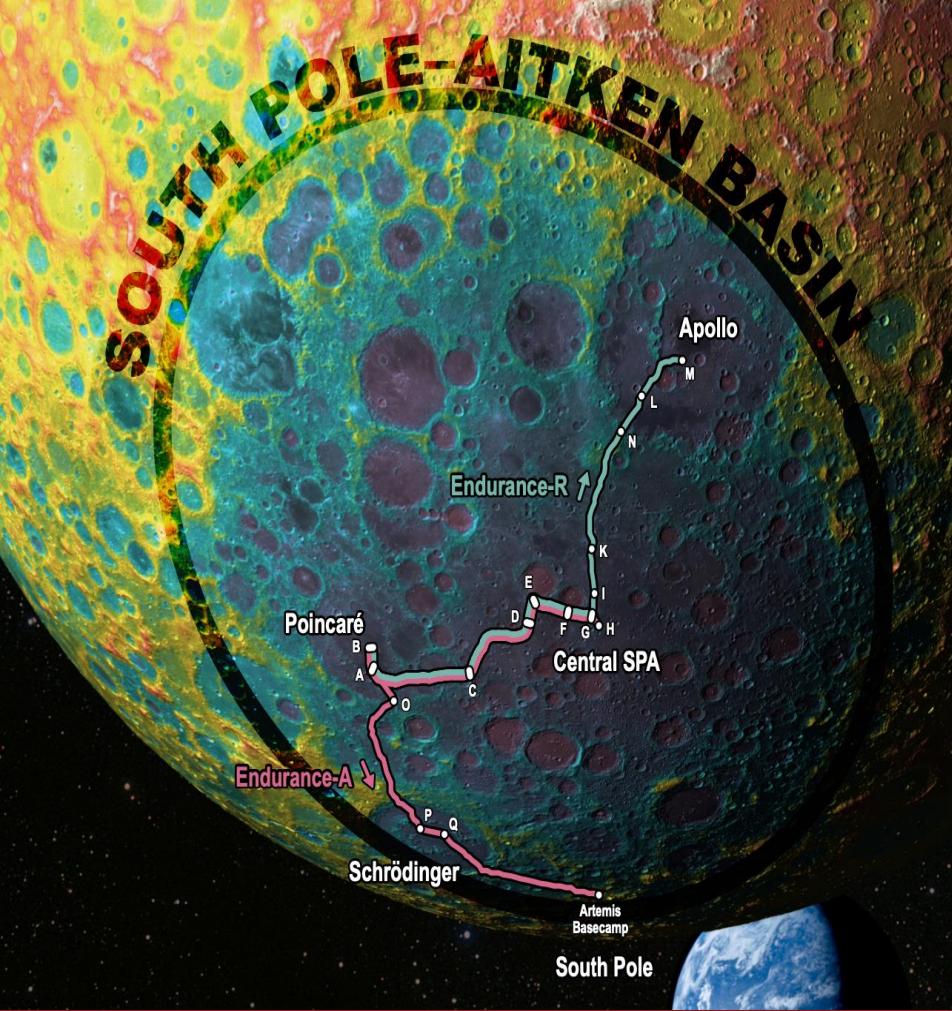
Robot Swarm Navigation



Moonshot 2.0: Blast Off into the Future of Autonomy in Space

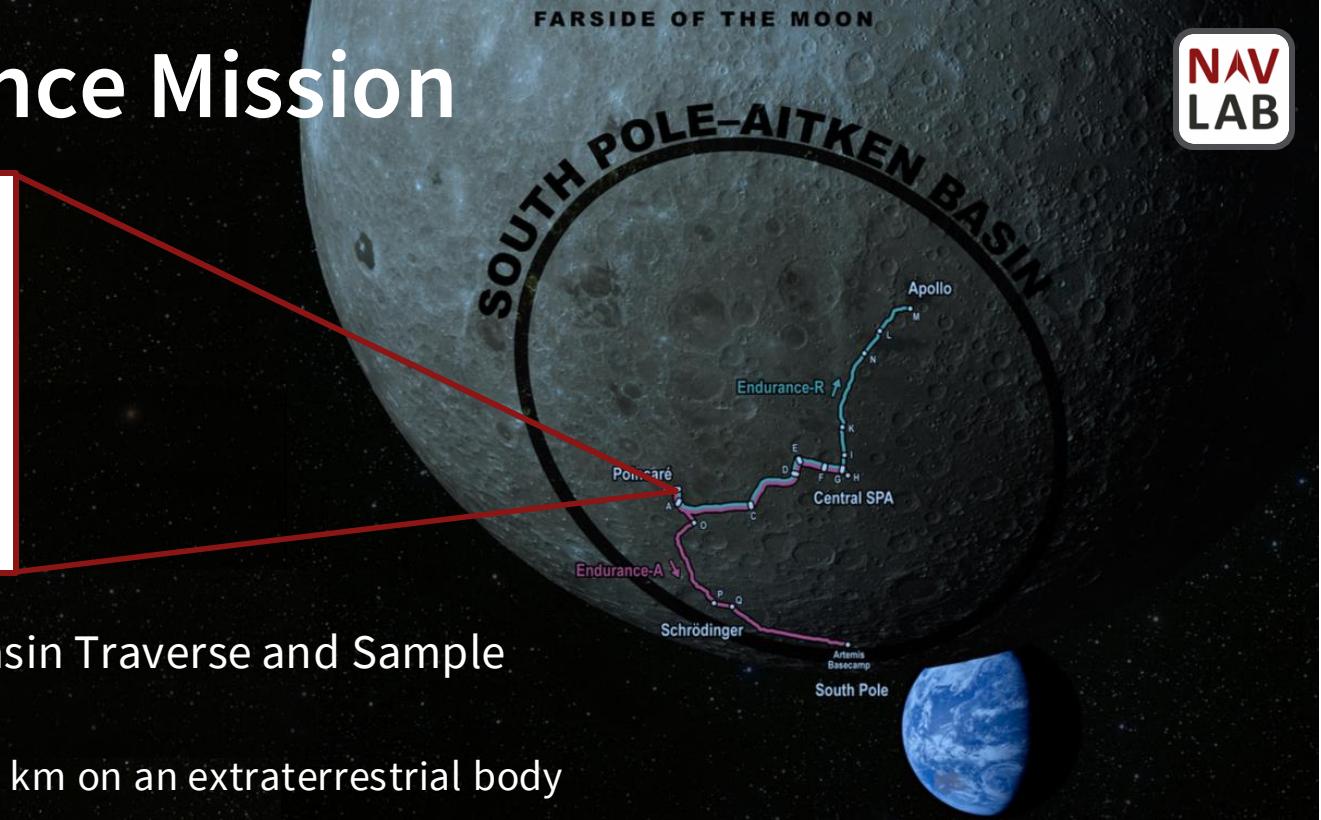
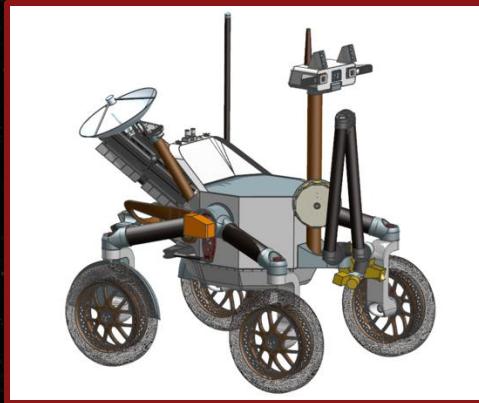


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Long-Range Moon Rover: Endurance Mission Concept

NASA Endurance Mission

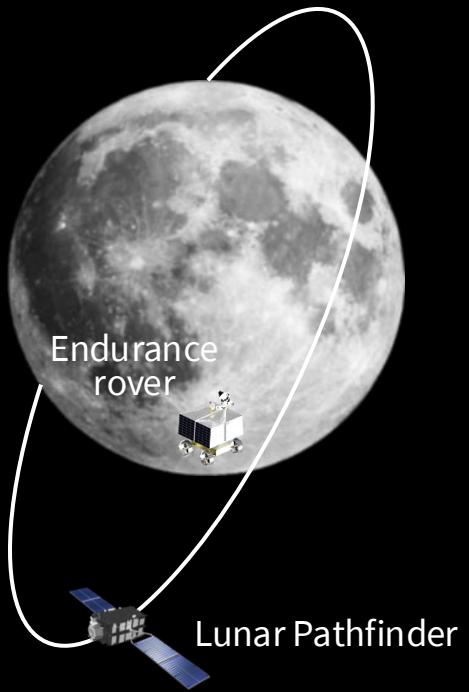


Lunar South Pole-Aitken Basin Traverse and Sample Return Rover

- First rover to traverse 2000 km on an extraterrestrial body
- *Launch:* ~2030s
- *Mission:* Collect 12 samples along its traverse and return samples to Artemis astronauts

Earth image: Apollo 11 / NASA / JSC,
Moon topography: LRO LOLA,
Moon image mosaic: LRO WAC / LRO LOLA /
NASA's Scientific Visualization Studio,
Sky: Taurus / NSF NOIRLab / Akira Fujii,
Composited by James Tuttle Keane.

The Existing Lunar Landscape

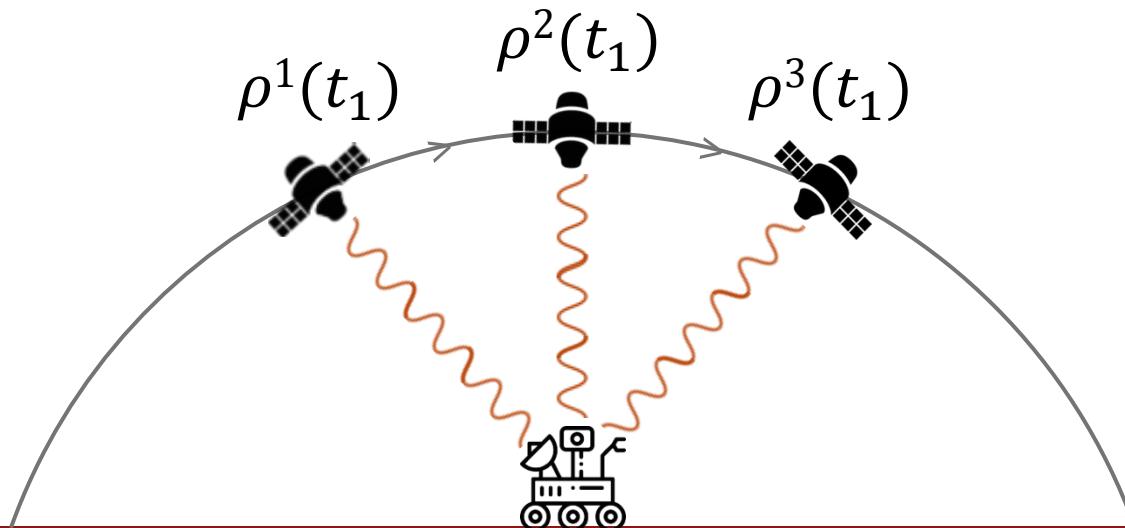


Lunar Pathfinder Satellite

- Data Relay Satellite
- in elliptical lunar frozen orbit (ELFO)
- *Service: ~2025 - 2033*

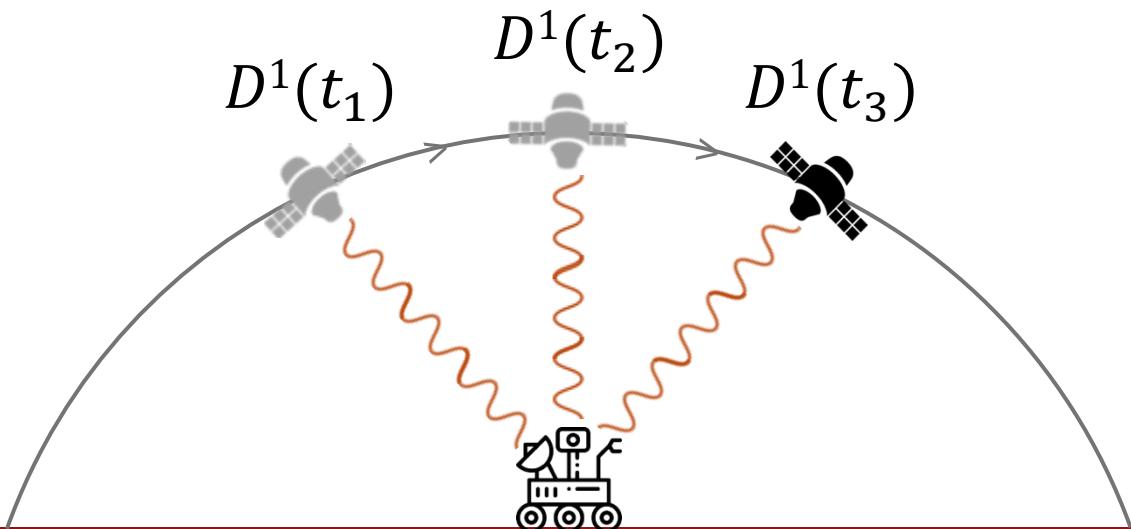
Desired and Traditional Scenario

- ***Multiple satellites*** – instantaneous localization (with at least 4 satellites)
- ***Navigation payload*** – obtain pseudorange measurements for trilateration



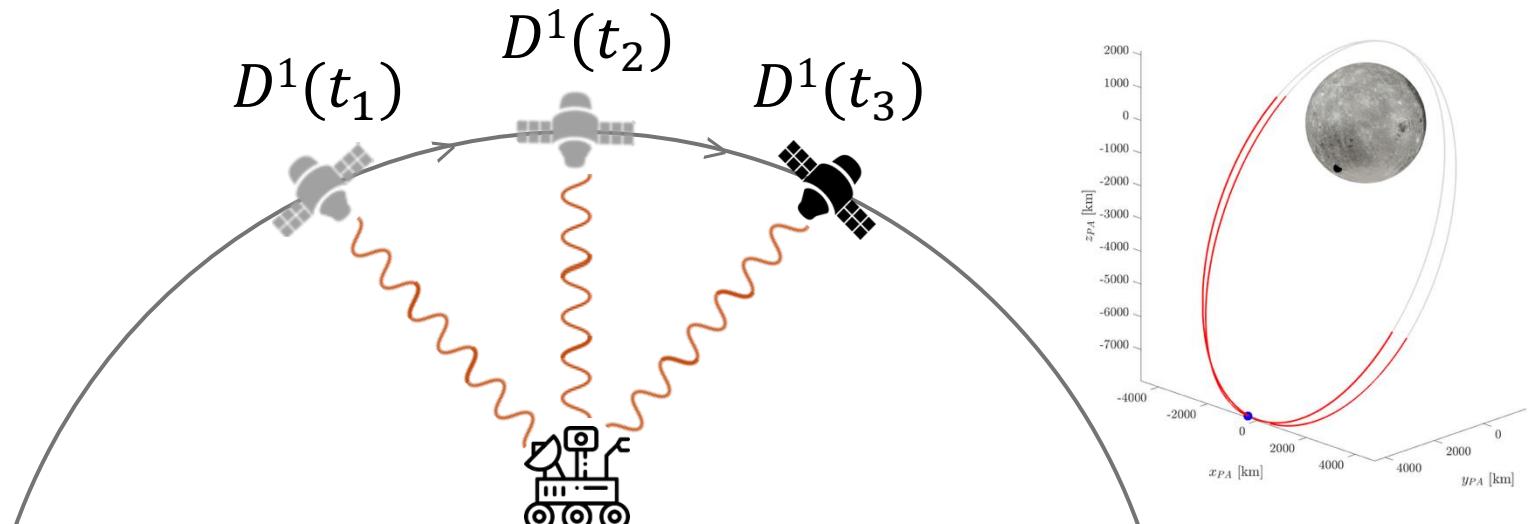
Our Scenario

- *Single satellite*
- *No navigation payload*



Key Ideas

- **Single satellite** – measurements over time \rightarrow multiple virtual satellites
- **No navigation payload** – use Doppler shift observables to obtain pseudorange rate measurements



Moonshot 2.0: Blast Off into the Future of Autonomy in Space

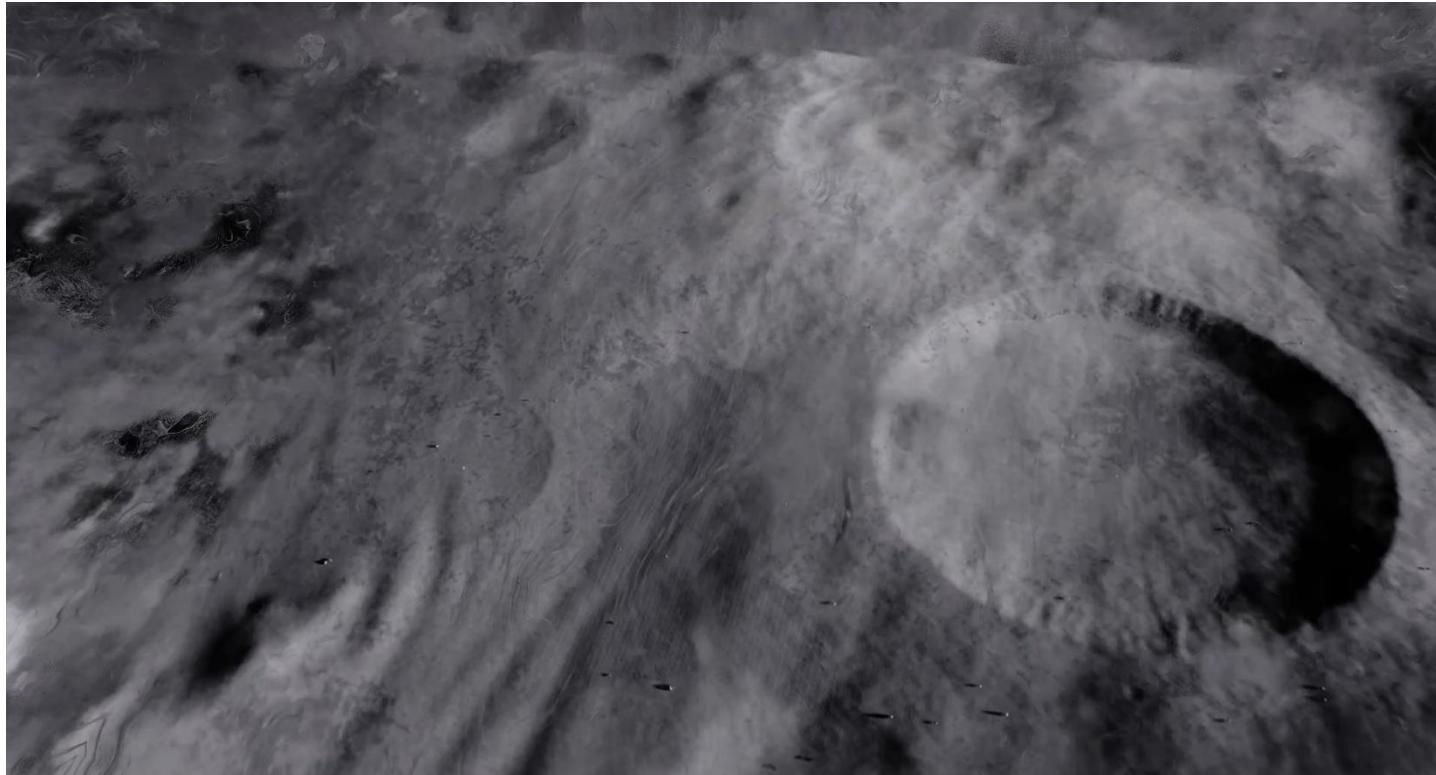


- Building infrastructure (e.g. WiFi, GPS, power plant, base station)
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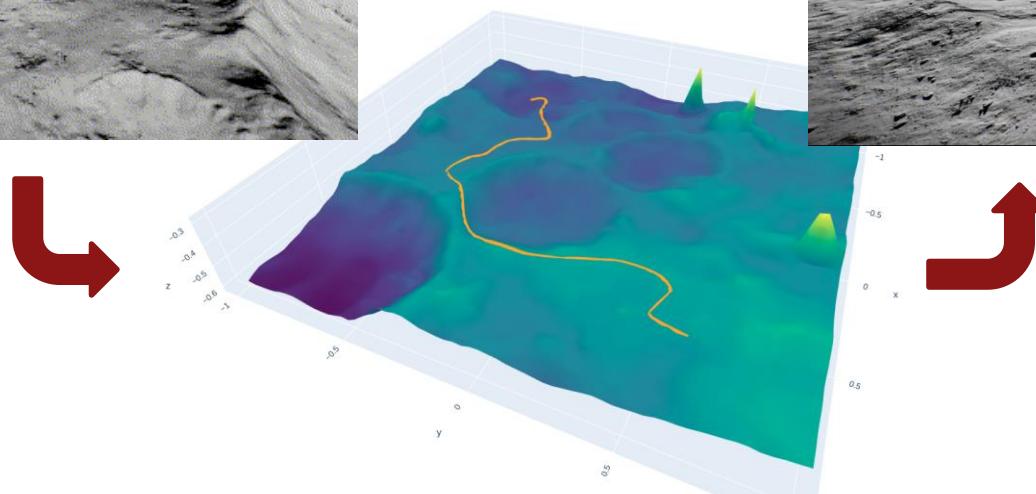
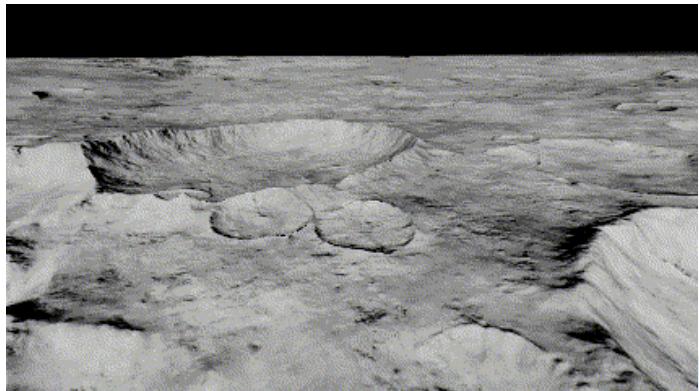


Neural Map for the Moon

Neural Map for the Moon

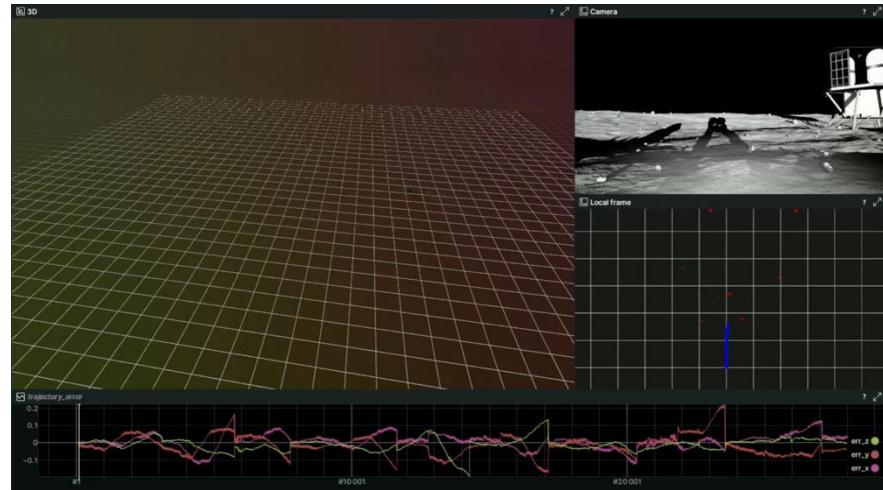


Example Moon Surface Path Planning

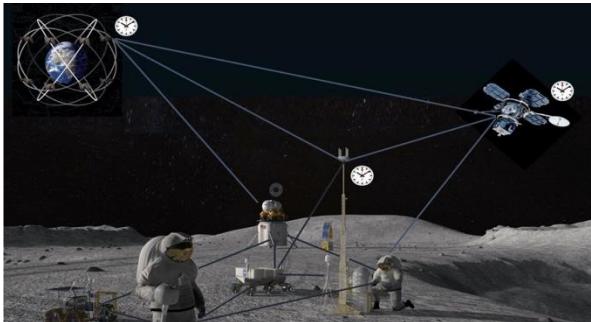


NASA Lunar Autonomy Challenge

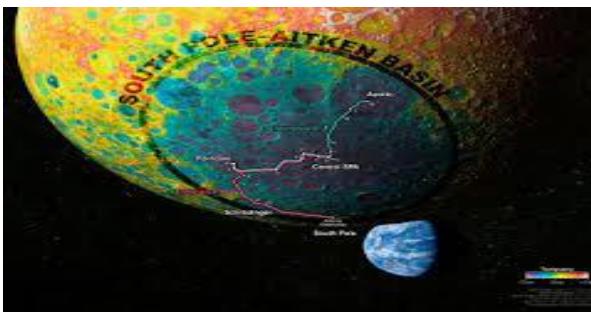
- A six-month long competition, finished on May 15, 2025
- Using a digital twin of NASA's In-Situ Resource Utilization Pilot Excavator (IPEx)
- Our NAV Lab won 1st place



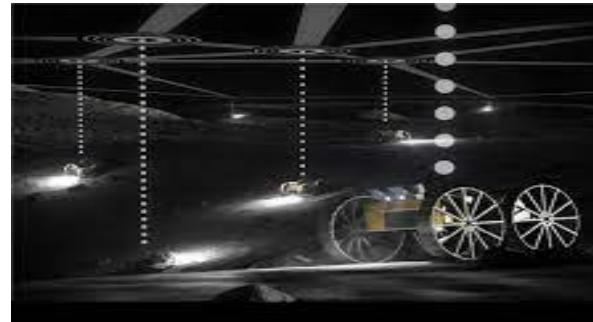
Summary of Projects in the Stanford NAV Lab



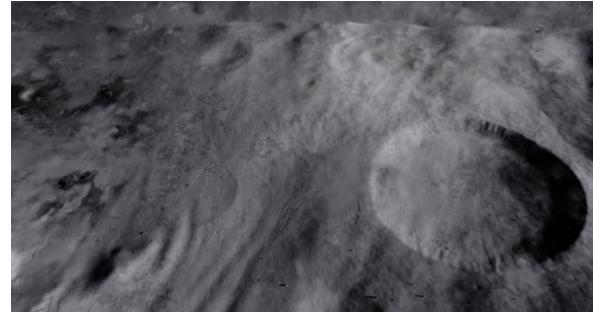
“GPS” for the Moon



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Neural Moon Surface Maps

Thank You!



Stanford University