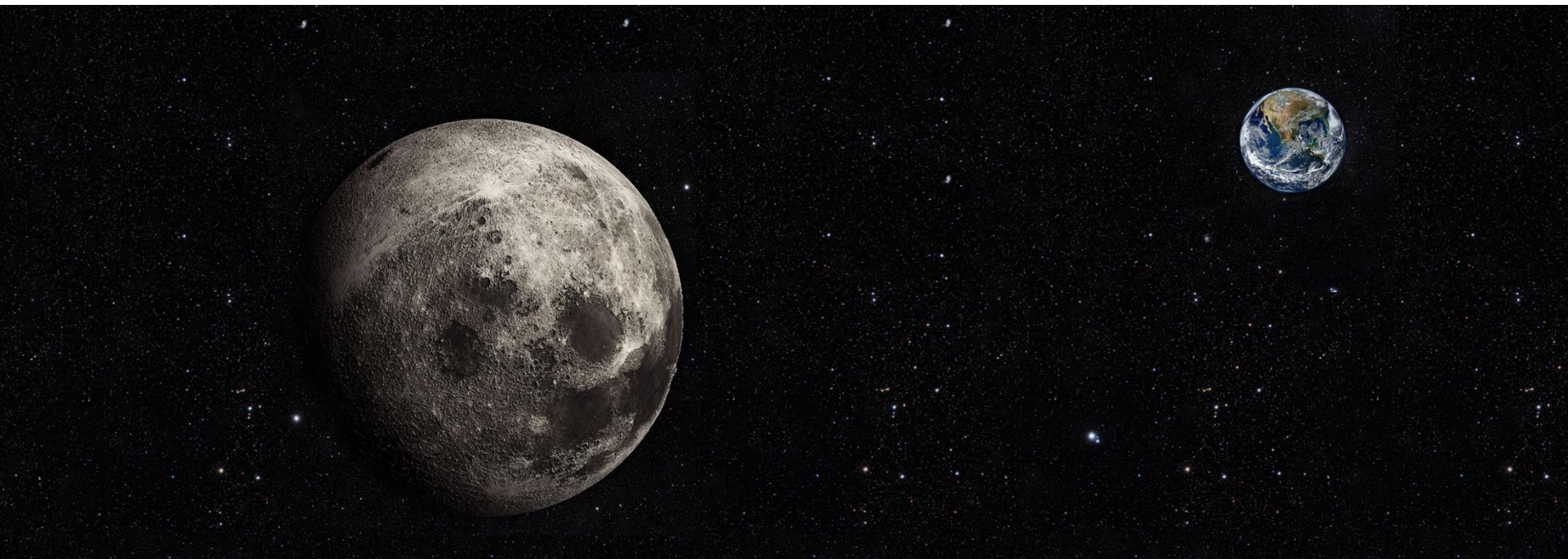


# Blast Off into the Future of Autonomy in Space



PROF. GRACE X. GAO



# New Era for Exploring the Moon

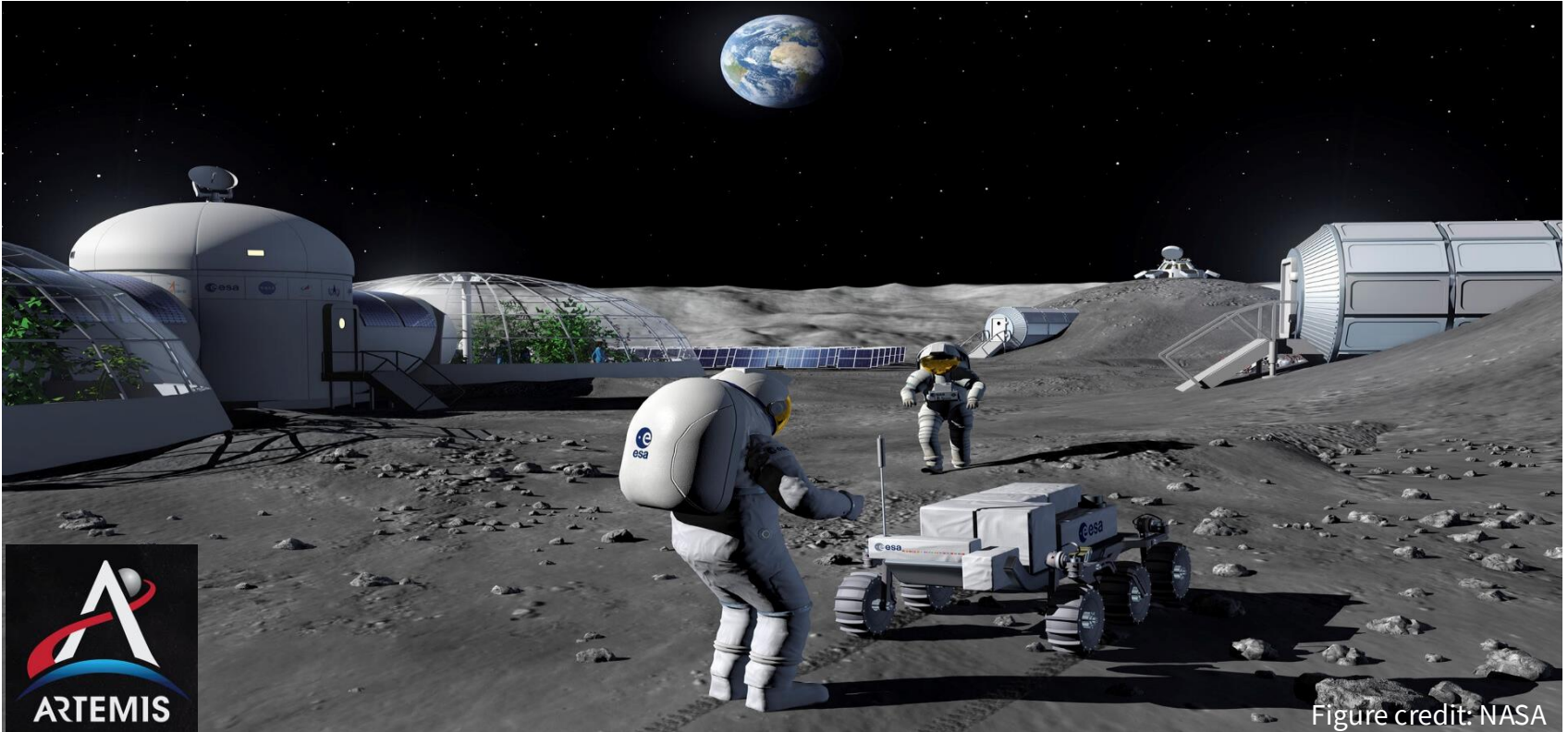


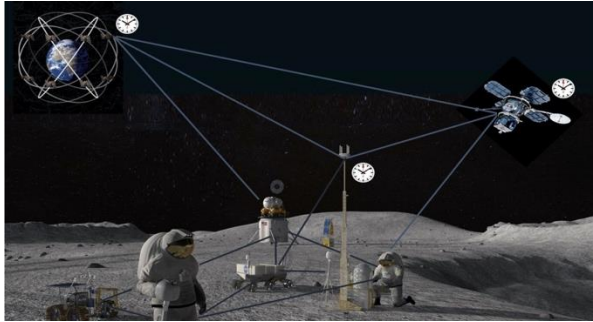
Figure credit: NASA

# Blast Off into the Future of Autonomy in Space: Technical Trends

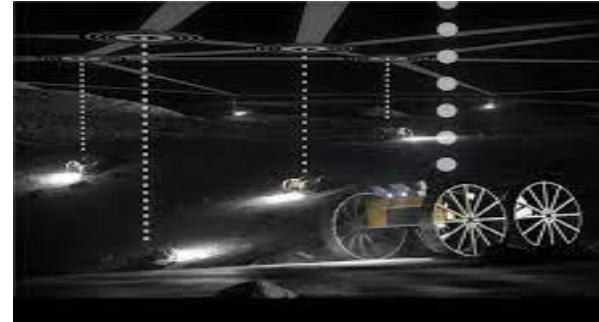


- Building infrastructure (e.g. WiFi, GPS, power plant, base station)
- Collaborative intelligence (e.g. swarm robots, satellite swarms)
- Long-range autonomy
- AI for space

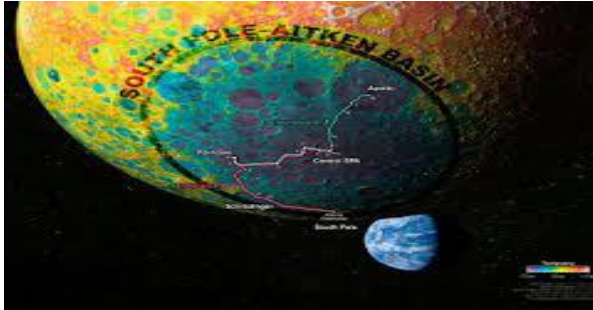
# Example Projects in the Stanford NAV Lab



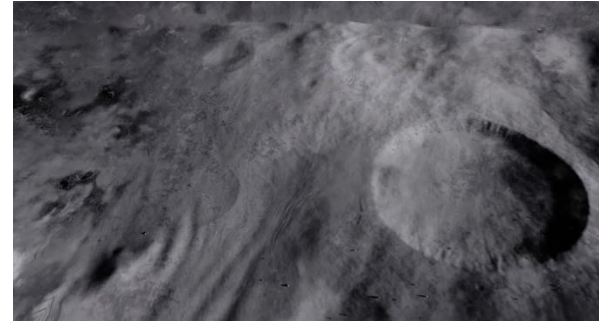
“GPS” for the Moon



Moon Rover Swarm: CADRE Mission

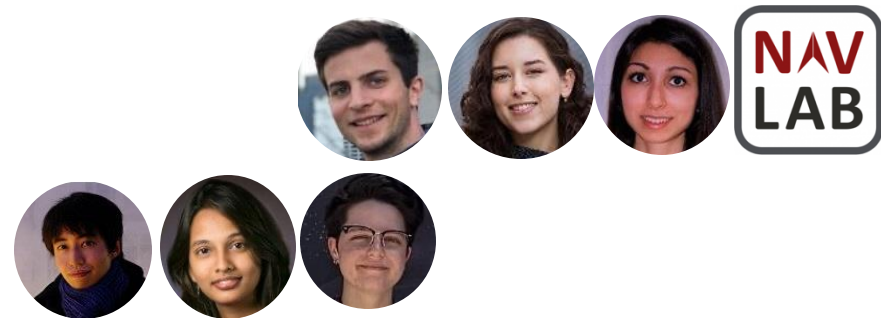
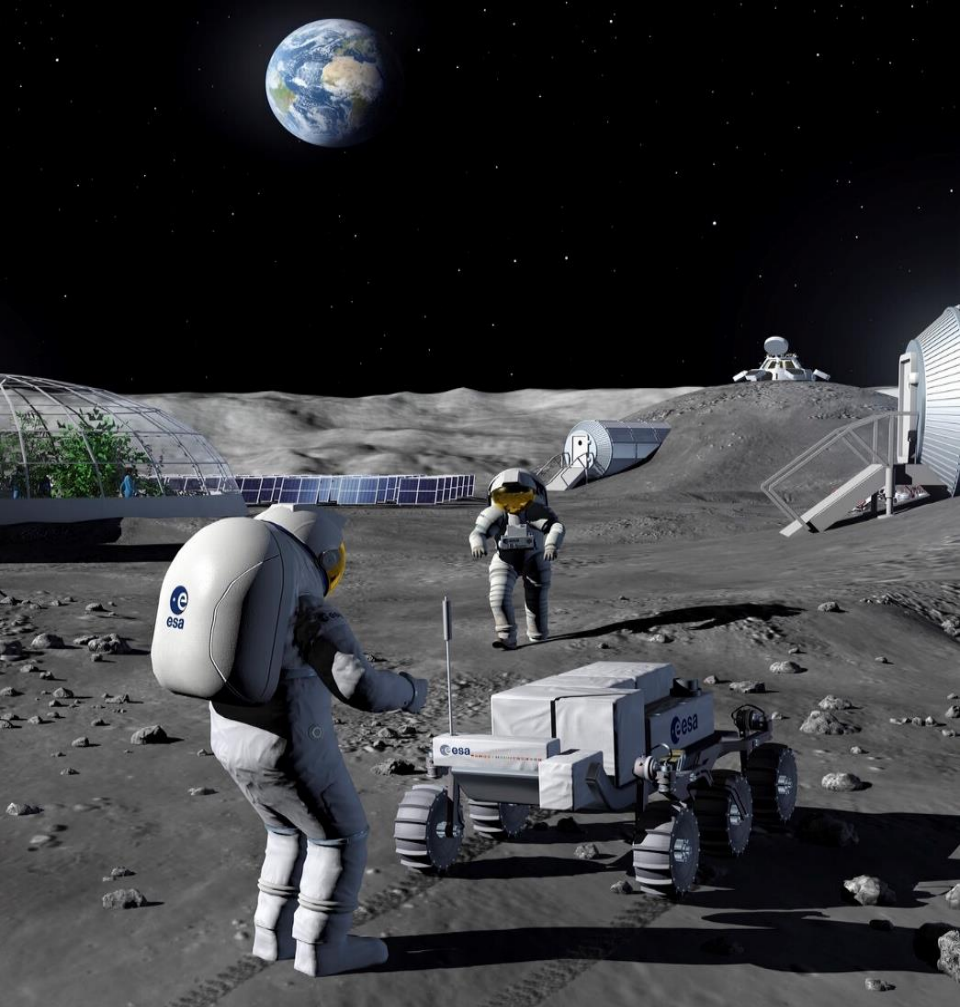


Long-Range Moon Rover:  
Endurance Mission Concept



Neural Moon Surface Maps

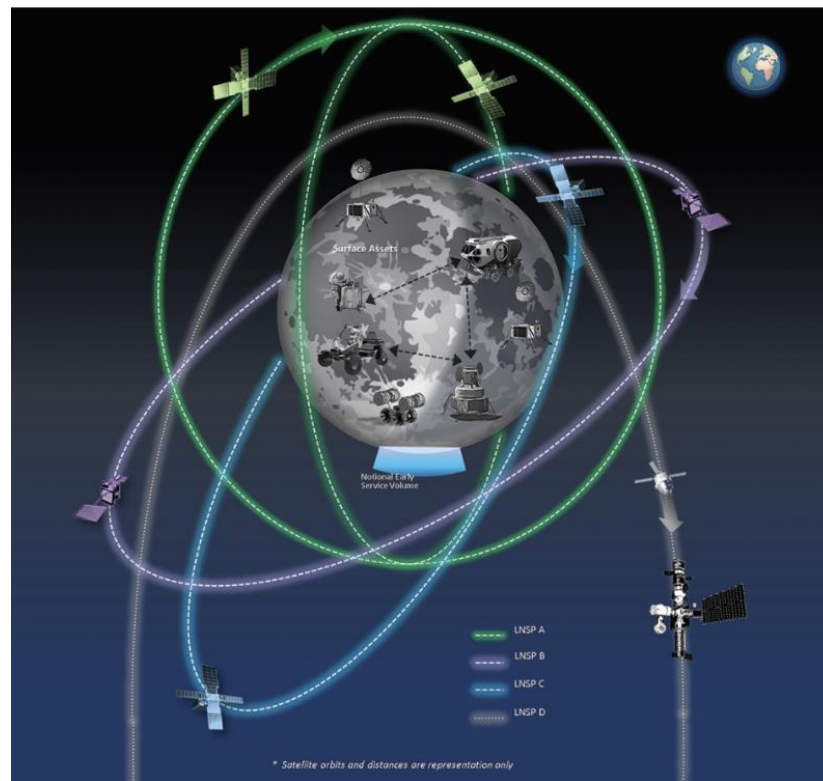




## “GPS” for the Moon

# LunaNet

- Satellite network around the moon for navigation and communication
- Joint effort by
  - US NASA
  - European ESA
  - Japanese JAXA
  - + Korea
  - + India

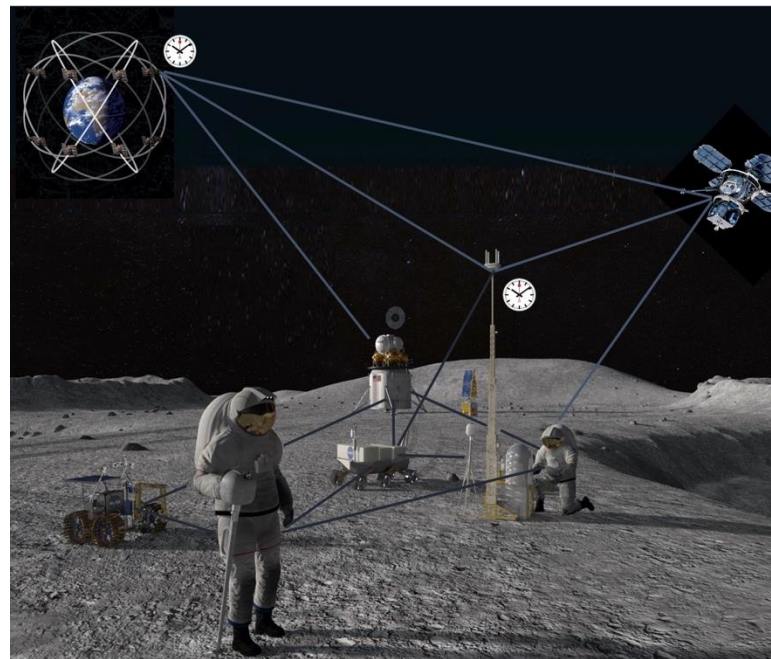


**Can we have a GPS-like system for the Moon, but with a much lower cost?**

# Lunar Navigation Satellite System



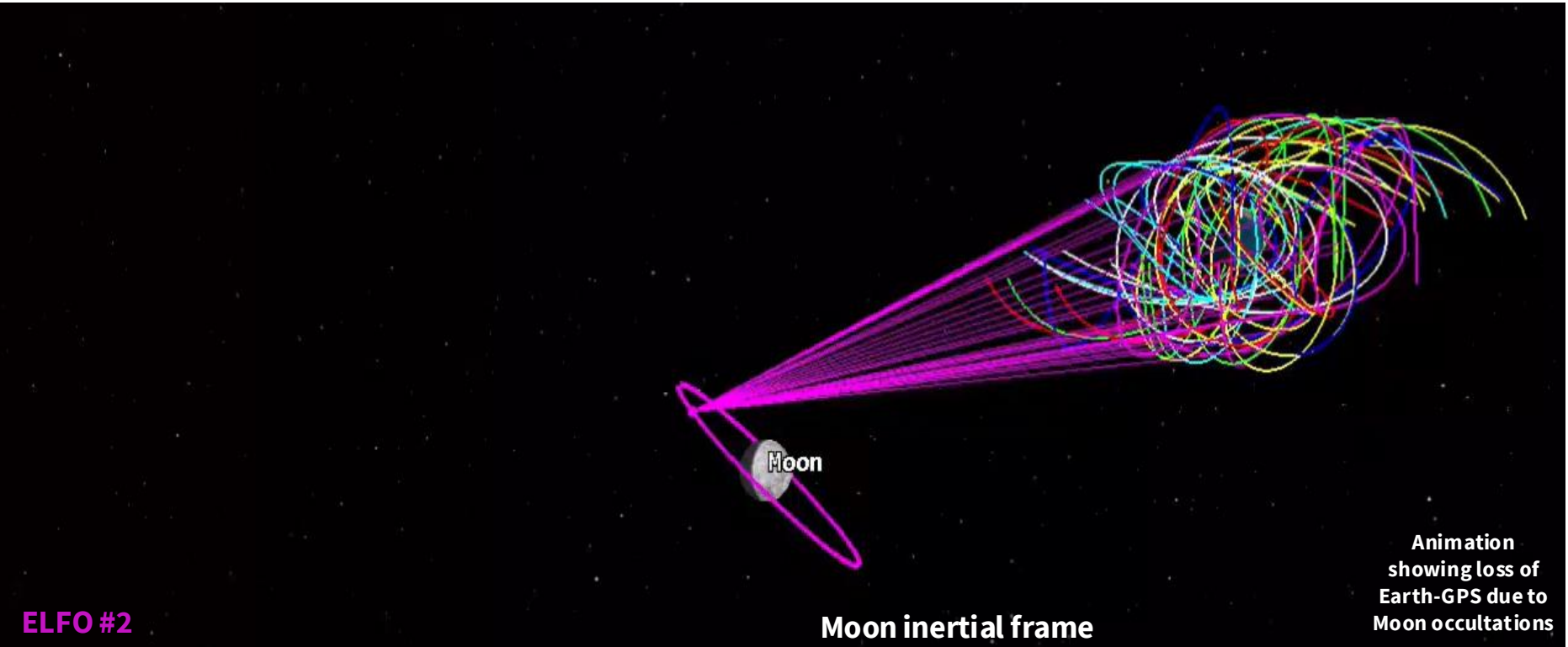
- Smaller satellites
  - as small as a shoe box
  - vs. terrestrial GPS satellites: as large as a truck
- Cheaper clocks
  - a thousand times cheaper than the atomic clocks on today's GPS satellites



Key idea: Use terrestrial GPS for lunar navigation satellite clock and ephemeris corrections



# Loss of Earth-GPS due to Occultation



ELFO #2

# LuGRE: Lunar GNSS Receiver Experiment



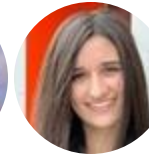
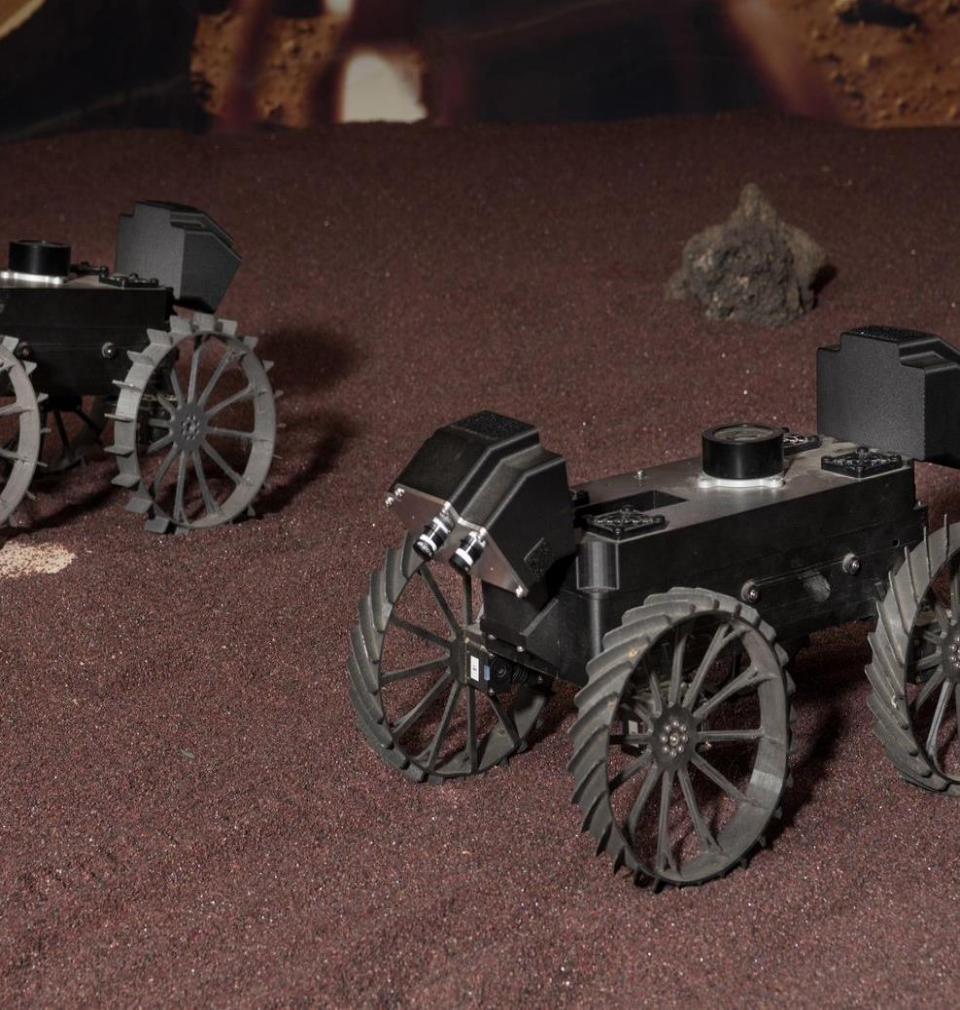
- **LuGRE:** a payload onboard Firefly Aerospace Blue Ghost Mission 1, launched on **Jan 15, 2025**.
  - Collaboration among NASA, ASI, and Qascom SRL
- Catches GPS Signal From 205,674 miles (331,000 km) Away, sets distance record.
- Demonstrated the feasibility of using Earth GNSS signals



# Moonshot 2.0: Blast Off into the Future of Autonomy in Space



- Building infrastructure (e.g. WiFi, GPS, power plant, base station)
- Collaborative intelligence (e.g. swarm robots)
- Long-range autonomy
- AI for space



# Moon Rover Swarm: CADRE Mission

# CADRE

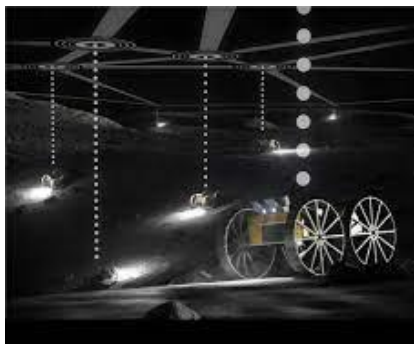


Cooperative Autonomous Distributed Robotic Exploration





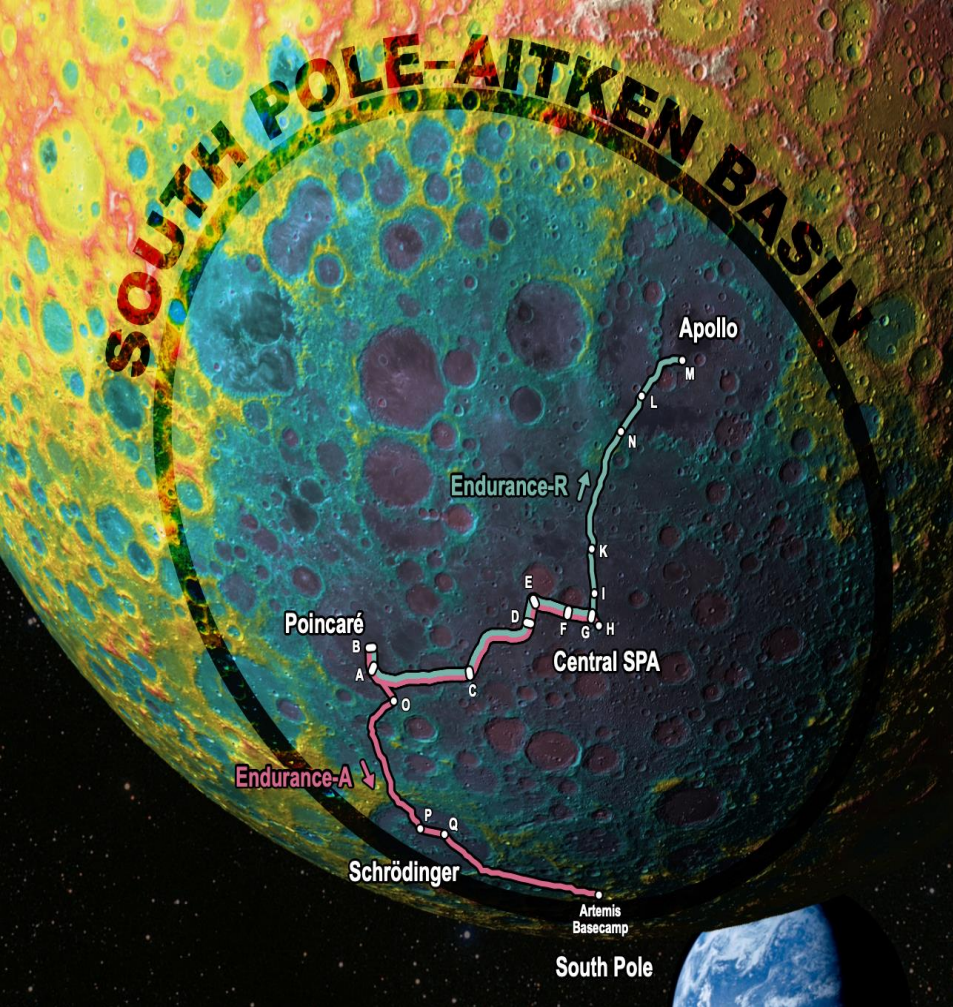
# Robot Swarm Navigation



# Moonshot 2.0: Blast Off into the Future of Autonomy in Space



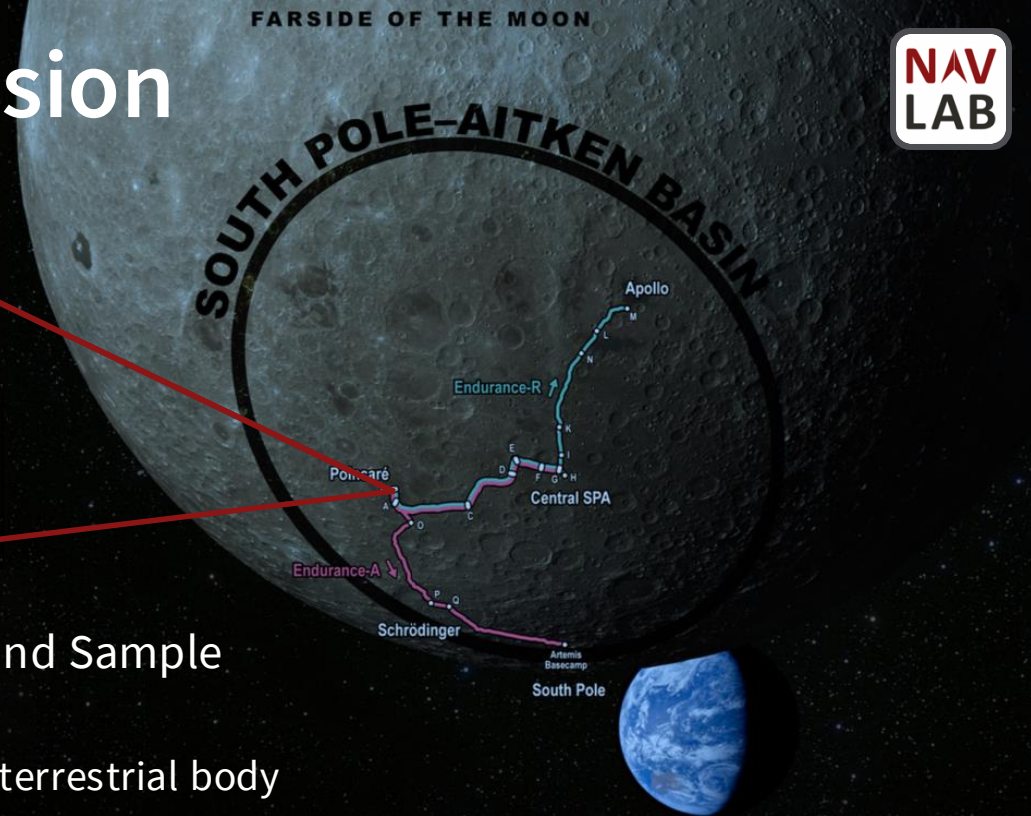
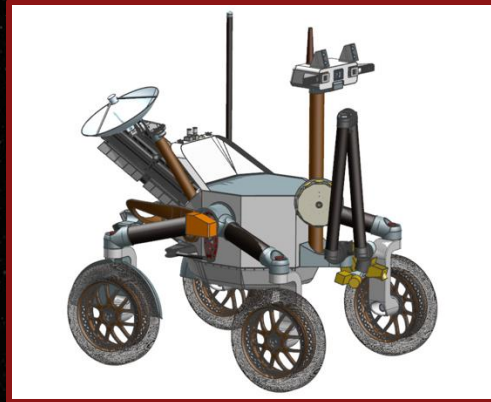
- Building infrastructure (e.g. WiFi, GPS, power plant, base station)
- Collaborative intelligence (e.g. swarm robots)
- Long-range autonomy
- AI for space



# Long-Range Moon Rover: Endurance Mission Concept



# NASA Endurance Mission

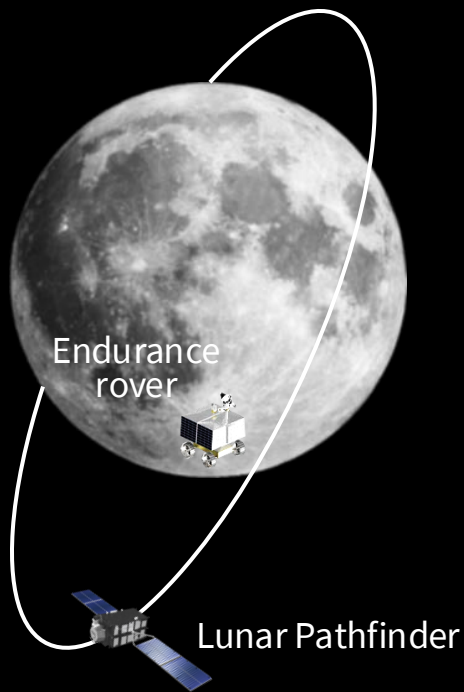


## Lunar South Pole-Aitken Basin Traverse and Sample Return Rover

- First rover to traverse 2000 km on an extraterrestrial body
- *Launch: ~2030s*
- *Mission: Collect 12 samples along its traverse and return samples to Artemis astronauts*

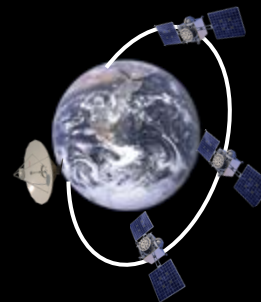
Earth image: Apollo 11 / NASA / JSC.  
Moon topography: LRO LOLA.  
Moon image mosaic: LRO WAC / LRO LOLA /  
NASA's Scientific Visualization Studio.  
Sky: Taurus / NSF NOIRLab / Akira Fujii.  
Composited by James Tuttle Keane.

# The Existing Lunar Landscape



## Lunar Pathfinder Satellite

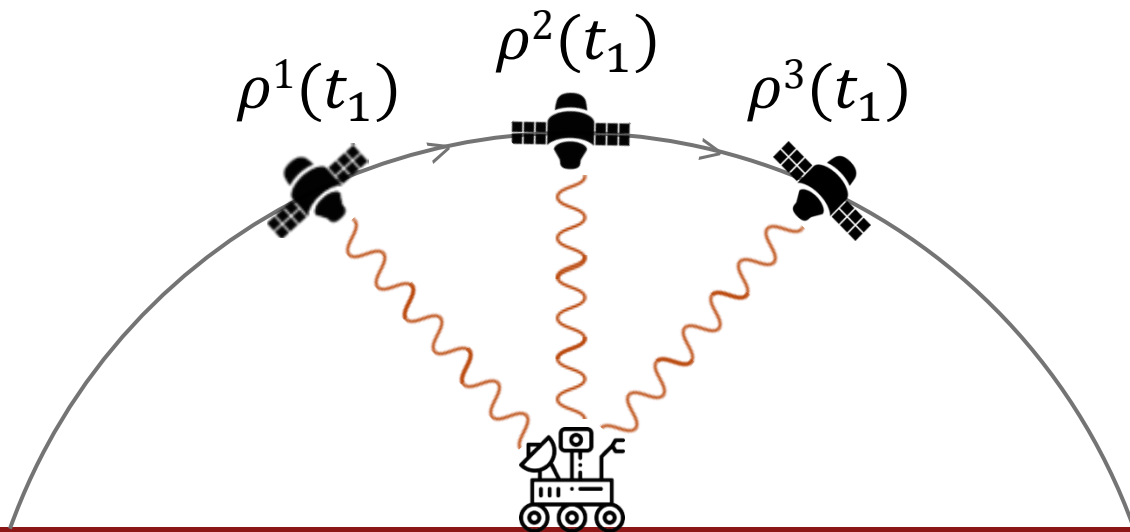
- Data Relay Satellite
- in elliptical lunar frozen orbit (ELFO)
- *Service: ~2025 - 2033*





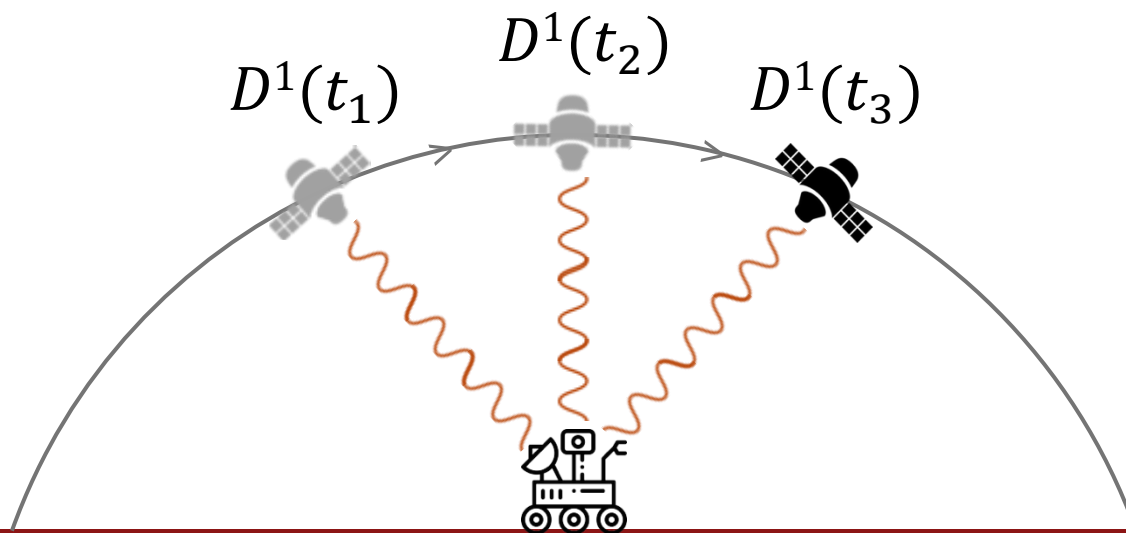
# Desired and Traditional Scenario

- **Multiple satellites** – instantaneous localization (with at least 4 satellites)
- **Navigation payload** – obtain pseudorange measurements for trilateration



# Our Scenario

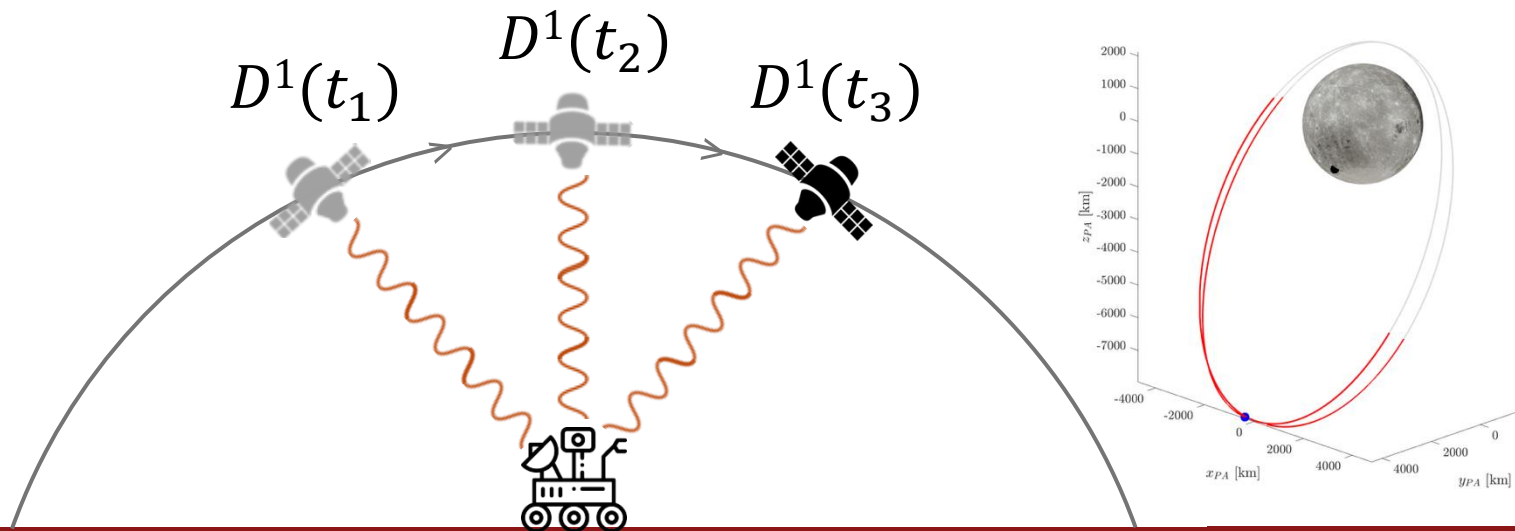
- *Single satellite*
- *No navigation payload*



# Key Ideas



- **Single satellite** – measurements over time -> multiple virtual satellites
- **No navigation payload** – use Doppler shift observables to obtain pseudorange rate measurements



# Moonshot 2.0: Blast Off into the Future of Autonomy in Space



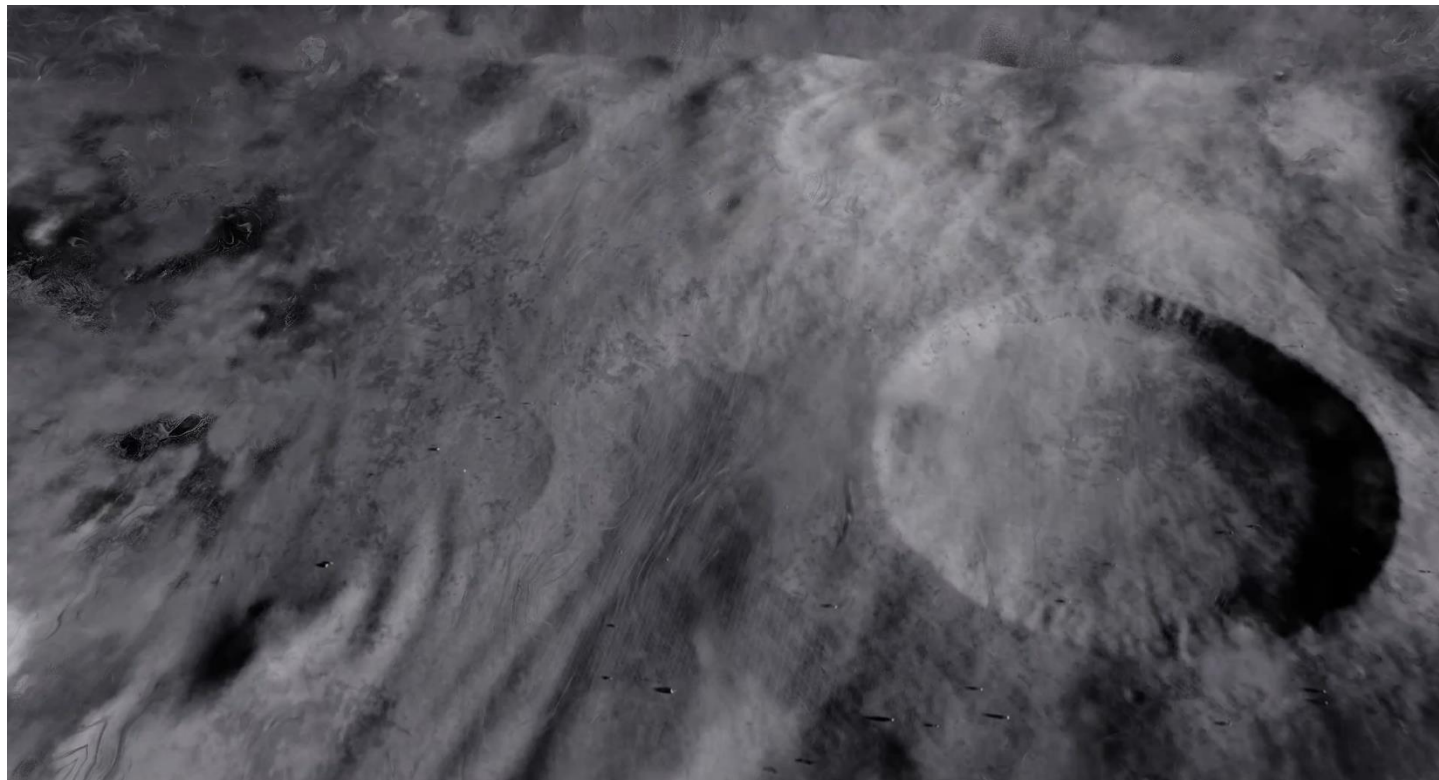
- Building infrastructure (e.g. WiFi, GPS, power plant, base station)
- Collaborative intelligence (e.g. swarm robots)
- Long-range autonomy
- AI for space



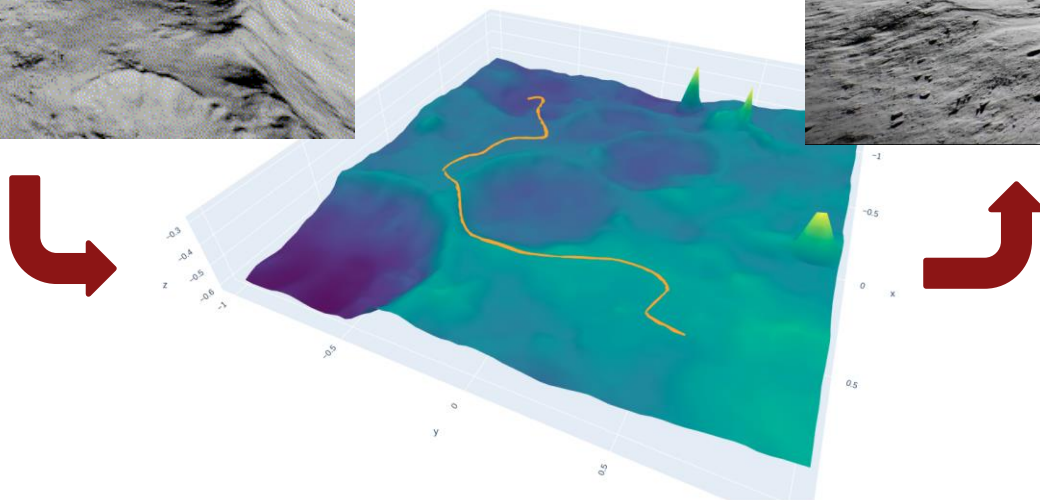
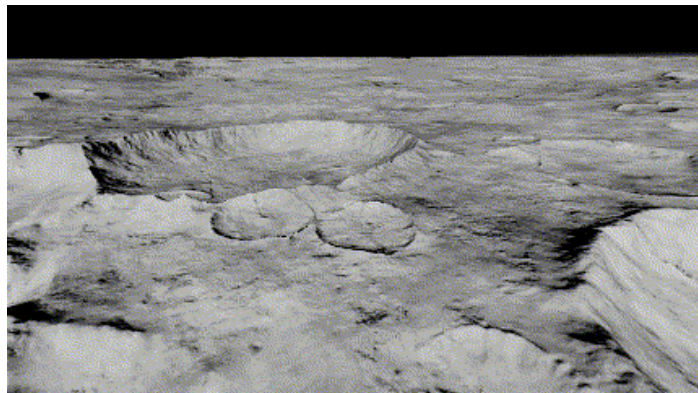
## Neural Map for the Moon



# Neural Map for the Moon



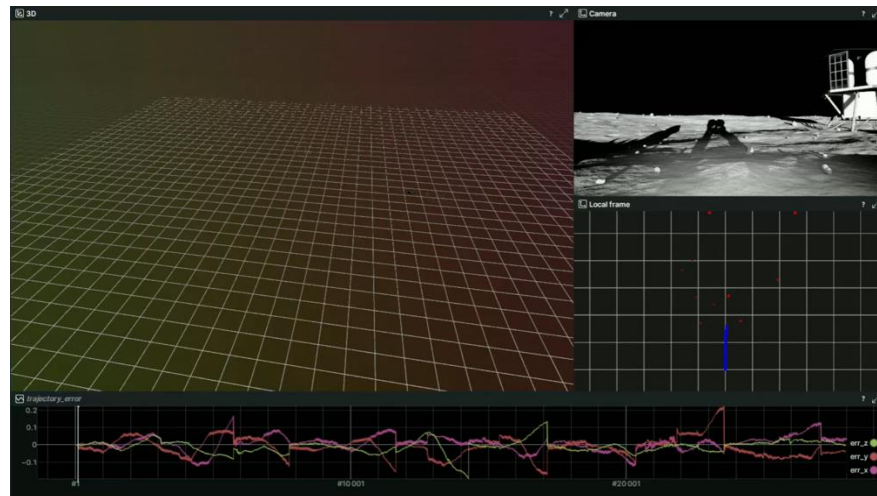
# Example Moon Surface Path Planning



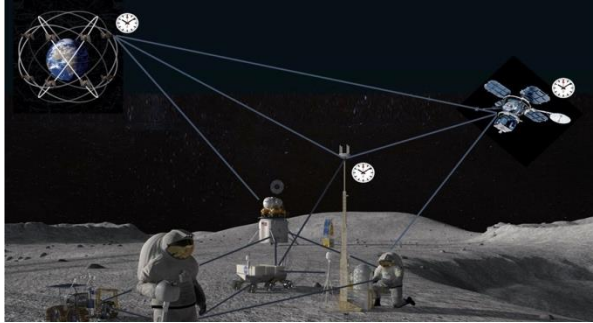
# NASA Lunar Autonomy Challenge



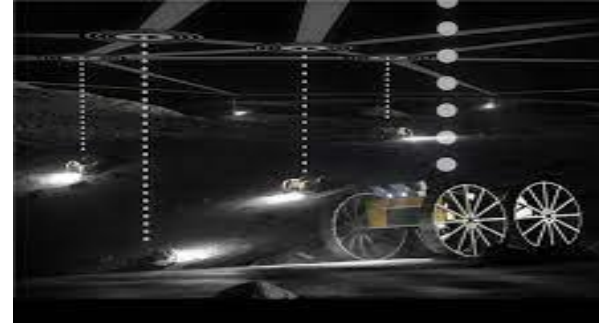
- A six-month long competition, finished on May 15, 2025
- Using a digital twin of NASA's In-Situ Resource Utilization Pilot Excavator (IPEX)
- Our NAV Lab won 1st place



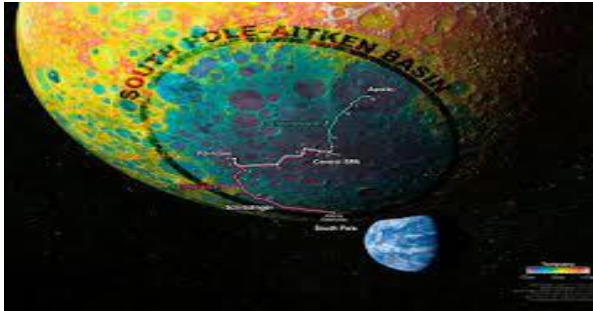
# Summary of Projects in the Stanford NAV Lab



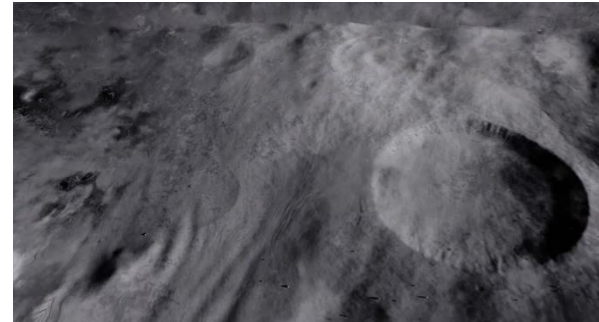
“GPS” for the Moon



Moon Rover Swarm: CADRE Mission



Long-Range Moon Rover:  
Endurance Mission Concept



Neural Moon Surface Maps



# Thank You!

