

RUIZHE SHI

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Education

University of Washington, Seattle, USA

Feb. 2024 – Present

Research Visitor at Paul G. Allen School of Computer Science

Tsinghua University, Beijing, China

Sept. 2021 – Present

Undergraduate at Special Pilot Class in Computer Science (Yao class)

Overall GPA: 3.93/4.00

- Major: *Computer Science and Technology*
- Minor: *Chinese Language and Literature*

Publications

(★ indicates equal contribution.)

[2] Ruizhe Shi*, Yuyao Liu*, Yanjie Ze, Simon S. Du, Huazhe Xu.

Unleashing the Power of Pre-trained Language Models for Offline Reinforcement Learning.

International Conference on Learning Representations, 2024.

[1] Yanjie Ze, Yuyao Liu*, Ruizhe Shi*, Jiaxin Qin, Zhecheng Yuan, Jiashun Wang, Huazhe Xu.

H-InDex: Visual Reinforcement Learning with Hand-Informed Representations for Dexterous Manipulation.

Annual Conference on Neural Information Processing Systems, 2023.

Research Experience

Language Model Alignment

Dec. 2023 – Present

Supervised by Prof. Simon S. Du

Paul G. Allen School of Computer Science, University of Washington

Theory of Transformer in Reinforcement Learning

Nov. 2023 – Jan. 2024

Supervised by Prof. Huazhe Xu

IIIS, Tsinghua University

- Second-authored work submitted to **ICML 2024**, under review (rating: 556).

Language Model for Reinforcement Learning

June 2023 – Sept. 2023

Supervised by Prof. Huazhe Xu

IIIS, Tsinghua University

- We leverage the power of pre-trained Language Models for low-level motion control in offline reinforcement learning. First-authored work accepted by **ICLR 2024**.
- We demonstrate the superiority of LaMo over DT-based and value-based offline RL algorithms. Specifically, we find that LaMo could successfully handle the challenging low-data regime while DT could not. This highlights the great potential of our cross-domain pre-training for sequential modeling.

Visual Reinforcement Learning

Mar. 2023 – May 2023

Supervised by Prof. Huazhe Xu

IIIS, Tsinghua University

- We propose H-InDex, a hand-informed visual representation for dexterous manipulation with reinforcement learning. Second-authored work accepted by **NeurIPS 2023**.
- We show the effectiveness of our framework on 12 challenging visual dexterous manipulation tasks, comparing with recent strong foundation models such as VC-1. Our study has offered valuable insights into the application of pre-trained models for dexterous manipulation, by exploring the direct application of a 3D human hand pose estimation model

Awards & Honors

Jiang Nanxiang Scholarship

Nov. 2023

Tsinghua University

top scholarship; 1 student per major

China National Endeavor Scholarship

Oct. 2022

Beijing Education Bureau

1 student per major

Xue Tang Scholarship of Tsinghua University

Oct. 2021 – Present

Tsinghua University

First Prize in College Student Mathematics Competition (Beijing)

Oct. 2022

Chinese Mathematical Society

First Prize in National High School's Mathematics Competition of China (Jiangsu)

Oct. 2020

Chinese Mathematical Society

top 20

Service

Workshop Program Committee

FMDM 2023 at NeurIPS

Oct. 2023

Online

Drop-in Tutoring for STEM Courses

Volunteering at Tsinghua University

Oct. 2022 – Present

Beijing, China

I have 157 hours of officially recorded volunteering work.

Selected Courses

Mathematics and Theory: Calculus (**A**⁺), Linear Algebra (**A**), Abstract Algebra (**A**), Introduction to Complex Analysis (**A**), Probability and Statistics (**A**), Introduction to Optimization Theory (**A**), Theory of Computation (**A**), Physics of Information (**A**);

Programming and AI: Introduction to Programming in C/C++ (**A**⁺), Intelligent Unmanned System (**A**⁺), Type-safe Modern System Practice (**A**), Machine Learning (**A**), Artificial Intelligence: Principles and Techniques (**A**), Natural Language Processing (**A**).

Technical Skills

Programming Skills: Python, C/C++, L^AT_EX, Bash, Scala, Matlab.

Language Skills: Chinese Mandarin (native), English (CET-6, TOEFL 104 [R30/L26/S23/W25]).