

Ruizhe Shi

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Education

Tsinghua University, Beijing, China

Sept. 2021 – Present

Undergraduate at Special Pilot Class in Computer Science (*Yao class*)

- Major: Computer Science and Technology
- Minor: Chinese Language and Literature

GPA 3.93/4.00

GPA 4.00/4.00

University of Washington, Seattle, USA

Feb. 2024 – July 2024

Research Visitor at Paul G. Allen School of Computer Science

Publications

(* indicates equal contribution.)

- [5] (**Manuscript**) Ruizhe Shi*, Runlong Zhou*, Simon S. Du. *To be released soon.*
- [4] (**NeurIPS 2024**) Ruizhe Shi, Yifang Chen, Yushi Hu, Alisa Liu, Hannaneh Hajishirzi, Noah A. Smith, Simon S. Du. “Decoding-Time Language Model Alignment with Multiple Objectives”.[\[link\]](#)
- [3] (**ICML 2024**) Chenhao Lu, Ruizhe Shi*, Yuyao Liu*, Kaizhe Hu, Simon S. Du, Huazhe Xu. “Rethinking Transformers in Solving POMDPs”.[\[link\]](#)
- [2] (**ICLR 2024**) Ruizhe Shi*, Yuyao Liu*, Yanjie Ze, Simon S. Du, Huazhe Xu. “Unleashing the Power of Pre-trained Language Models for Offline Reinforcement Learning”.[\[link\]](#)
- [1] (**NeurIPS 2023**) Yanjie Ze, Yuyao Liu*, Ruizhe Shi*, Jiaxin Qin, Zhecheng Yuan, Jiashun Wang, Huazhe Xu. “H-InDex: Visual Reinforcement Learning with Hand-Informed Representations for Dexterous Manipulation”.[\[link\]](#)

Research Experience

DPO Theory

May 2024 – Present

Supervised by Prof. Simon S. Du

CSE, University of Washington

- Submitted to **ICLR 2025**, under review.

Multi-Objective Language Model Alignment

Dec. 2023 – May 2024

Supervised by Prof. Simon S. Du

CSE, University of Washington

- We propose a training-free, simple yet effective decoding-time algorithm for multi-objective alignment of language models, with optimality guarantees. First-authored work accepted by **NeurIPS 2024**.
- We exploit a common form among a family of f -divergence regularized alignment approaches (such as PPO, DPO, and their variants) to identify a closed-form solution by Legendre transform, and derive an efficient decoding strategy. Theoretically, we show why existing approaches can be sub-optimal even in natural settings and obtain optimality guarantees for our method.

Representation Theory of Transformer for Decision-Making

Nov. 2023 – Jan. 2024

Supervised by Prof. Huazhe Xu

IIIS, Tsinghua University

- We challenge the common wisdom and prove theoretically and empirically that Transformers are not suitable for Partially Observable RL, while advocating Linear RNN as a promising alternative. Second-authored work accepted by **ICML 2024**.
- We establish that regular languages, which Transformers struggle to model, are reducible to POMDPs. This poses a significant challenge for Transformers in learning POMDP-specific inductive biases, due to their lack of inherent recurrence found in other models like RNNs, with empirical results highlighting the sub-optimal performance of the Transformer and considerable strength of LRU.

Tuning Language Model for Decision-Making

June 2023 – Sept. 2023

Supervised by Prof. Huazhe Xu

IIIS, Tsinghua University

- We leverage the power of pre-trained Language Models for low-level motion control in offline reinforcement learning. First-authored work accepted by **ICLR 2024**.
- We demonstrate the superiority of LaMo over DT-based and value-based offline RL algorithms. Specifically, we find that LaMo could successfully handle the challenging low-data regime while DT could not. This highlights the great potential of our cross-domain pre-training for sequential modeling.

Visual Representation for Reinforcement Learning

Mar. 2023 – May 2023

Supervised by Prof. Huazhe Xu

IIIS, Tsinghua University

- We propose H-InDex, a hand-informed visual representation for dexterous manipulation with reinforcement learning. Second-authored work accepted by **NeurIPS 2023**.
- We show the effectiveness of our framework on 12 challenging visual dexterous manipulation tasks, comparing with recent strong foundation models such as VC-1. Our study has offered valuable insights into the application of pre-trained models for dexterous manipulation, by exploring the direct application of a 3D human hand pose estimation model

Awards & Honors

Yao Award (Silver Medal)

IIIS, Tsinghua University

Sept. 2024

top scholarship; 3 students institute-wide

Jiang Nanxiang Scholarship

Tsinghua University

Nov. 2023

top scholarship; 1 student per major

China National Endeavor Scholarship

Beijing Education Bureau

Oct. 2022

1 student per major

First Prize in College Student Mathematics Competition

Chinese Mathematical Society

Oct. 2022

First Prize in National High School's Mathematics Competition of China

Chinese Mathematical Society

Oct. 2020

top 20

Service

Conference Reviewer

NeurIPS 2024

July 2024

Online

Workshop Program Committee

FMDM 2023 at NeurIPS [\[link\]](#)

Oct. 2023

Online

Teaching Assistant

Natural Language Processing

Sept. 2024 – Jan. 2025(expected)

Tsinghua University

Drop-in Tutoring

STEM Courses

Oct. 2022 – July 2024

Tsinghua University

*I have **157** hours of officially recorded volunteering work.*

Selected Courses

Mathematics and Theory: Calculus (**A**⁺), Linear Algebra (**A**), Abstract Algebra (**A**), Introduction to Complex Analysis (**A**), Probability and Statistics (**A**), Basic Topology (**93**), Introduction to Optimization (**A**), Theory of Computation (**A**), Physics of Information (**A**);

Programming and AI: Introduction to Programming in C/C++ (**A**⁺), Intelligent Unmanned System (**A**⁺), Type-safe Modern System Practice (**A**), Machine Learning (**A**), Artificial Intelligence: Principles and Techniques (**A**), Natural Language Processing (**A**).

Technical Skills

Programming Skills: Python, C/C++, L^AT_EX, Bash, Scala, Matlab.

Language Skills: Chinese Mandarin (native), English (CET-6, TOEFL 104 [R30/L26/S23/W25]).