## ASSIGNMENT 5 21/03/25

NAME: SHRESTH SONKAR

REGNO: 20214272

GROUP : CS8D

TOPIC : FORMAL METHOD

CODE : CS-18201

```
# Q1 Implement a Kripke Structure in Python and verify
Computation Tree Logic (CTL) properties.
class KripkeStructure:
    def __init__(self):
        self.states = set()
        self.transitions = {}
        self.labeling = {}
    def add_state(self, state, labels=set()):
        self.states.add(state)
        self.transitions[state] = set()
        self.labeling[state] = labels
    def add transition(self, state from, state to):
        if state_from in self.states and state_to in
self.states:
            self.transitions[state from].add(state to)
    def satisfies(self, state, prop):
        return prop in self.labeling.get(state, set())
def EX(kripke, prop):
    result = set()
    for state in kripke.states:
        if any(kripke.satisfies(next state, prop) for
next state in kripke.transitions[state]):
            result.add(state)
    return result
def AX(kripke, prop):
    result = set()
    for state in kripke.states:
        if kripke.transitions[state] and all(
                kripke.satisfies(next state, prop) for
next state in kripke.transitions[state]):
            result.add(state)
    return result
def EG(kripke, prop):
    result = set()
    for state in kripke.states:
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visited, stack = set(), [state]
        while stack:
             s = stack.pop()
             if s in visited:
                 continue
             visited.add(s)
             if not kripke.satisfies(s, prop):
             stack.extend(kripke.transitions[s])
         else:
             result.add(state)
    return result
def test kripke structure():
    ks = KripkeStructure()
    ks.add_state("s0", {"a"})
    ks.add state("s1", {"b"})
    ks.add_state("s2", {"a", "b"})
                              "s1")
    ks.add transition("s0",
    ks.add_transition("s1",
                              "s2")
    ks.add_transition("s2", "s0")
    print("EX(b):", EX(ks, "b"))
    print("AX(b):", AX(ks, "b"))
print("EG(a):", EG(ks, "a"))
test_kripke_structure()
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# Q2 Develop a Python-based Linear Temporal Logic (LTL)
model checker for verifying safety and liveness
properties.
import networkx as nx
class LTLModelChecker:
    def __init__(self, transition_system):
        self.transition system = transition system
    def check_safety(self, atomic_proposition):
        for state in self.transition_system.nodes():
            if atomic proposition not in
self.transition_system.nodes[state]['labels']:
                return False, state
        return True, None
    def check liveness(self, atomic proposition):
        satisfying_states = [state for state in
self.transition system.nodes() if
                             atomic_proposition in
self.transition system.nodes[state]['labels']]
        return satisfying states if satisfying states
else None
ts = nx.DiGraph()
ts.add nodes from([
    ("s0", {"labels": {"p"}}),
    ("s1", {"labels": {"q"}}),
])
ts.add edges from([("s0", "s1"), ("s1", "s0")])
checker = LTLModelChecker(ts)
safety_result, safety_state = checker.check_safety("p")
liveness result = checker.check liveness("q")
print("Safety holds:" if safety result else f"Safety
fails at {safety_state}")
print(f"Liveness holds in states: {liveness result}" if
liveness_result else "Liveness fails")
```

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* python3 q2.py
Safety fails at s1
Liveness holds in states: ['s1']

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# Q3 Model a state transition system and check for
deadlock freedom using model checking.
class StateTransitionSystem:
   def init (self):
        self.transitions = {}
    def add_state(self, state):
        if state not in self.transitions:
            self.transitions[state] = []
    def add_transition(self, from_state, to_state):
        if from_state not in self.transitions:
            self.add state(from_state)
        if to_state not in self.transitions:
            self.add state(to state)
        self.transitions[from state].append(to state)
    def check deadlock freedom(self):
        deadlocks = [state for state in
self.transitions if not self.transitions[state]]
        if deadlocks:
            print("Deadlock detected in states:",
deadlocks)
            return False
        else:
            print("System is deadlock-free.")
```

## return True

```
sts = StateTransitionSystem()
sts.add_transition("S1", "S2")
sts.add_transition("S2", "S3")
sts.add_transition("S3", "S4")
sts.add_transition("S4", "S2")
sts.check_deadlock_freedom()
```

# Q4 Implement a property verification tool using CTL for a given transition system.

from itertools import product

```
class TransitionSystem:
    def __init__(self, states, transitions,
initial_states, atomic_props, labeling):
        self.states = states
        self.transitions = transitions
        self.initial_states = initial_states
        self.atomic_props = atomic_props
```

```
self.labeling = labeling
    def get_successors(self, state):
        return self.transitions.get(state, [])
class CTLModelChecker:
    def __init__(self, transition_system):
        self.ts = transition system
    def check_property(self, formula):
        return self.evaluate(formula,
self.ts.initial states)
    def evaluate(self, formula, states):
        if formula.startswith("EX"):
            subformula = formula[2:].strip()
            return self.ex(subformula, states)
        elif formula.startswith("EF"):
            subformula = formula[2:].strip()
            return self.ef(subformula, states)
        elif formula.startswith("EG"):
            subformula = formula[2:].strip()
            return self.eq(subformula, states)
        elif formula.startswith("AX"):
            subformula = formula[2:].strip()
            return self.ax(subformula, states)
        elif formula.startswith("AF"):
            subformula = formula[2:].strip()
            return self.af(subformula, states)
        elif formula.startswith("AG"):
            subformula = formula[2:].strip()
            return self.ag(subformula, states)
        else:
            return {s for s in states if formula in
self.ts.labeling.get(s, [])}
    def ex(self, formula, states):
        sat_states = self.evaluate(formula,
self.ts.states)
        return {s for s in states if any(succ in
sat_states for succ in self.ts.get_successors(s))}
    def ax(self, formula, states):
```

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sat states = self.evaluate(formula,
self.ts.states)
        return {s for s in states if all(succ in
sat_states for succ in self.ts.get_successors(s))}
    def ef(self, formula, states):
        sat states = set()
        stack = list(self.evaluate(formula,
self.ts.states))
        while stack:
            s = stack.pop()
            if s not in sat_states:
                sat states.add(s)
                stack.extend([pred for pred in
self.ts.states if s in self.ts.get successors(pred)])
        return sat states.intersection(states)
    def af(self, formula, states):
        sat_states = self.evaluate(formula,
self.ts.states)
        unsat states = set(self.ts.states) - sat states
        result = set(states)
        while True:
            new_result = {s for s in result if all(succ
in result for succ in self.ts.get_successors(s))}
            if new result == result:
                break
            result = new result
        return result
    def eg(self, formula, states):
        sat_states = self.evaluate(formula,
self.ts.states)
        result = set()
        stack = [s for s in sat states if all(succ in
sat states for succ in self.ts.get successors(s))]
        while stack:
            s = stack.pop()
            if s not in result:
                result.add(s)
                stack.extend(
                    [pred for pred in self.ts.states if
pred in sat states and s in
self.ts.get successors(pred)])
        return result.intersection(states)
```

```
def ag(self, formula, states):
        return states.intersection(self.ts.states -
self.ef(f"!({formula})", self.ts.states))
if __name__ == "__main__":
    states = {"s0", "s1", "s2", "s3"}
    transitions = {"s0": ["s1", "s2"], "s1": ["s3"],
"s2": ["s3"], "s3": []}
    initial states = {"s0"}
    atomic_props = {"p"}
    labeling = {"s0": set(), "s1": {"p"}, "s2": set(),
"s3": {"p"}}
    ts = TransitionSystem(states, transitions,
initial_states, atomic_props, labeling)
    checker = CTLModelChecker(ts)
    formula = "EF p"
    result = checker.check_property(formula)
    print(f"States satisfying {formula}: {result}")
```

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- python3 q4.py
States satisfying EF p: {'s0'}

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```

```
# Q5 Verify fairness conditions in a concurrent system
using temporal logic.
class SystemModel:
    def __init__(self):
        self.states = []
        self.transitions = {}
        self.current_state = None
    def add state(self, state):
        self.states.append(state)
        self.transitions[state] = []
    def add_transition(self, from_state, to_state):
        if from state in self.states and to state in
self.states:
self.transitions[from state].append(to state)
    def set initial state(self, state):
        if state in self.states:
            self.current state = state
    def get reachable states (self, state,
visited=None):
        if visited is None:
            visited = set()
        if state in visited:
            return visited
        visited.add(state)
        for next_state in self.transitions.get(state,
[]):
            self.get reachable states(next state,
visited)
        return visited
class TemporalLogicChecker:
    Ostaticmethod
    def globally(system, condition):
        visited =
system.get_reachable_states(system.current_state)
        return all(condition(state) for state in
visited)
```

```
Ostaticmethod
    def eventually(system, condition):
        visited =
system.get_reachable_states(system.current_state)
        return any(condition(state) for state in
visited)
    Ostaticmethod
    def fairness condition(system, request condition,
grant condition):
        visited =
system.get_reachable_states(system.current_state)
        for state in visited:
            if request_condition(state):
                if not any(grant condition(next state)
for next state in visited):
                    return False
        return True
system = SystemModel()
system.add state("idle")
system.add state("request")
system.add state("critical")
system.add transition("idle", "request")
system.add_transition("request", "critical")
system.add_transition("critical", "idle")
system.set initial state("idle")
request_condition = lambda state: state == "request"
grant_condition = lambda state: state == "critical"
fairness result =
TemporalLogicChecker.fairness condition(system,
request condition, grant condition)
print("Fairness Condition Holds?" , fairness_result)
```

