

Vectorization :

→ Basically used to get rid of explicit folders in your code
 → crucial in deep learning since we're using large datasets.

lets see an example

task $z = w^T x + b$

we can do this computation directly using vectors, or by looping through values:

Non vectorized approach

$z = 0$

for i in range(n, x)

$z += w[i] * x[i]$

$z += b$

vectorized approach

$z = \underbrace{np.dot(w, x)}_{w^T x} + b$

$w^T x$

$+b$

written in C

numpy is faster coz it does SIMD parallel processing

→ towards data science / how fast - numpy really is

5 to 100 times faster

faster / easier → 1.5 ms

Slower / convoluted
474 ms

code run

Conclusion : whenever possible, avoid running for loops

functions discussed

$np.exp(v)$

$1/v$

$np.log(v)$

$v * 2$

$np.max(v, 0)$

Vectorized Logistic Regression:

(I) $z = np.dot(w.T, x) + b$



$A = \sigma(z)$

$z = [z^{(1)} \ z^{(2)} \ z^{(3)} \dots z^{(m)}] = w^T X + \underbrace{[b \ b \ b \ b \dots]}_{1 \times m} = [w^T x^{(1)} + b] \ [w^T x^{(2)} + b] \dots [w^T x^{(m)} + b]$

Broadcasting in python is a real no.

Vectorized Grad. Descent Computation:

(II) $dZ = A - Y = [a^{(1)} - y^{(1)} \ a^{(2)} - y^{(2)} \dots a^{(m)} - y^{(m)}]$

(IV) $db = \frac{1}{m} (np.sum(dZ))$; $dw = \frac{1}{m} X dZ^T$

(V) $w := w - \alpha dw$
 $b := b - \alpha db$

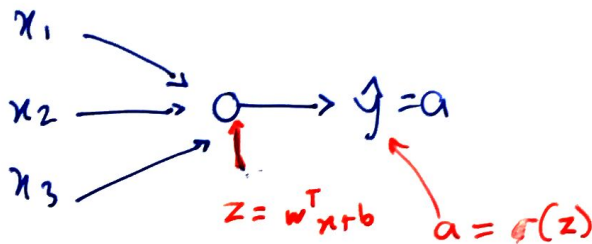
needs to be looped

$\frac{1}{m} \begin{bmatrix} x^{(1)} & x^{(2)} & \dots & x^{(m)} \end{bmatrix} \begin{bmatrix} dz^{(1)} \\ dz^{(2)} \\ \dots \\ dz^{(m)} \end{bmatrix}$

Neural Networks:

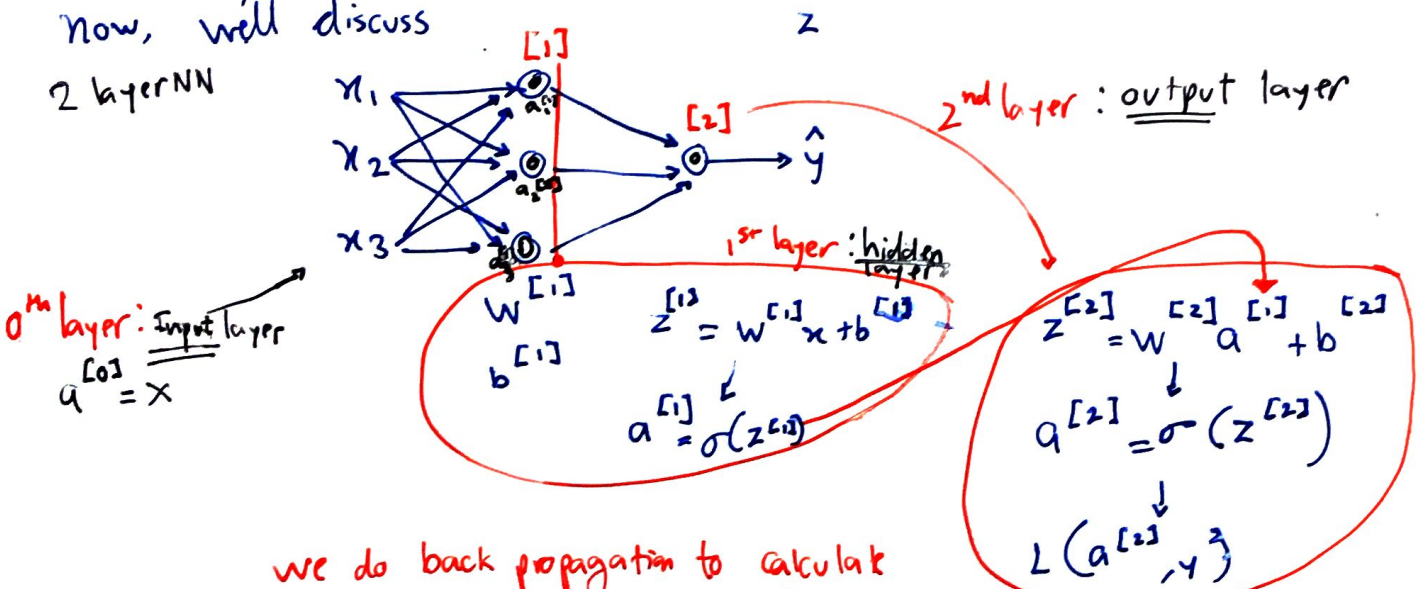
- Neural Networks are a set of algorithms, modeled loosely after a human brain, that are designed to recognize patterns.
- helps us cluster & classify.

previously, we saw:



now, we'll discuss

2 layer NN



we do back propagation to calculate

$$d a^{[2]} \rightarrow d z^{[2]} \rightarrow d w^{[1]} - d b^{[2]} \text{ \& so on}$$

R \rightarrow L Back calculation

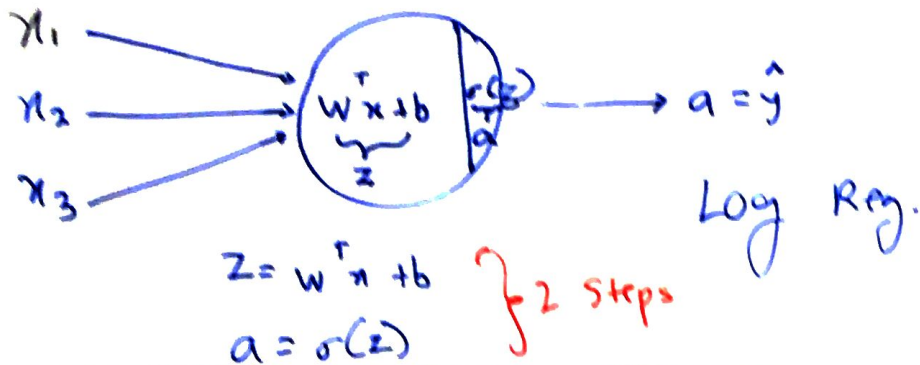
- NN \rightarrow basically take a logistic regression & repeat it twice.

Notation

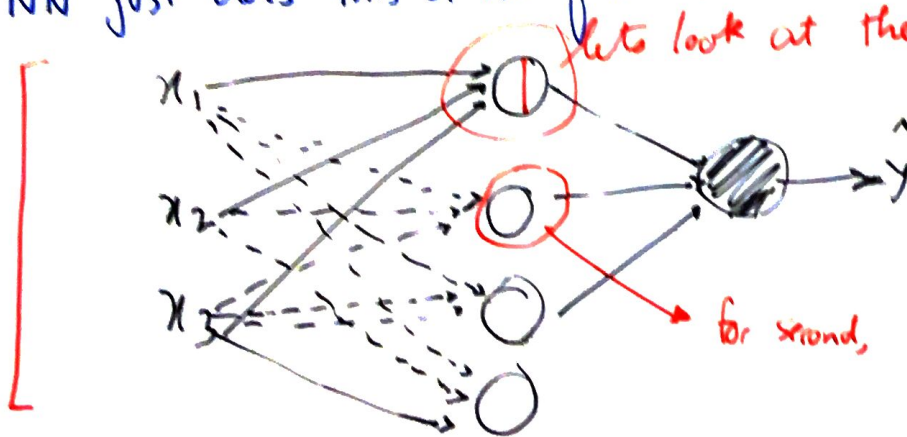
$a_1^{[1]} \rightarrow$ 1st layer, 1st weight

$a_2^{[1]} \rightarrow$ 1st layer, 2nd weight

Computing a NN's output:



* NN just does this a no. of times



Let's look at the 1st Node:

$$z_1^{[1]} = w_1^{[0]T} x + b_1^{[1]}$$

$$a_1^{[1]} = \sigma(z_1^{[1]})$$

$[1] \leftarrow \text{layer}$
 $a_i \leftarrow \text{node in layer}$

$$z_2^{[1]} = w_2^{[0]T} x + b_2^{[1]}$$

$$a_2^{[1]} = \sigma(z_2^{[1]})$$

$$\begin{bmatrix} w_1^{[1]T} \\ w_2^{[1]T} \\ w_3^{[1]T} \\ w_4^{[1]T} \end{bmatrix} \times \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} + \begin{bmatrix} b_1^{[1]} \\ b_2^{[1]} \\ b_3^{[1]} \\ b_4^{[1]} \end{bmatrix} \Rightarrow \begin{bmatrix} z_1^{[1]} \\ z_2^{[1]} \\ z_3^{[1]} \\ z_4^{[1]} \end{bmatrix} = \begin{bmatrix} z^{[1]} \end{bmatrix}$$

transposed: row

think as follows:

- logistic regression units
- each unit has corresponding parameter w
- by sticking together we get this

$$W^{[1]} \quad b^{[1]}$$

$$z^{[1]}_{(4 \times 1)} = W^{[1]}_{(4,3)} x_{(3,1)} + b^{[1]}_{(4,1)}$$

$$a^{[1]}_{(4,1)} = \sigma(z^{[1]}_{(4,1)})$$

$$a^{[2]}_{(4,1)} = \sigma(z^{[2]}_{(4,1)})$$

$$z^{[2]}_{(1,1)} = W^{[2]}_{(1,4)} a^{[1]}_{(4,1)} + b^{[2]}_{(1,1)}$$

$$= \begin{bmatrix} a^{[1]}_1 \\ \vdots \\ a^{[1]}_4 \end{bmatrix} = \begin{bmatrix} a \end{bmatrix}$$