

# **Affine Algebraic Decision Diagrams (AADDs) and their Application to Structured Probabilistic Inference**

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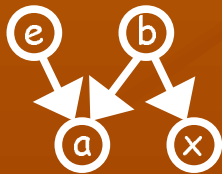
# Talk Outline

- Data structures for representing  $B^n \rightarrow R$ 
  - Why is efficiency for these functions important?
  - Compact forms for logical, additive, & mult. structure
  - Efficient operations:  $+$ ,  $\cdot$ ,  $\max(F)$ ,  $\oplus$ ,  $\otimes$ ,  $\max(F_1, F_2)$
  - Practical considerations (numerical precision issues)
- Applications to probabilistic inference
  - Variable elimination in Bayes nets
  - Value iteration in MDPs
- Conclusions and future work

# Motivations I

- Why do we need functions from  $B^n \rightarrow R$ ?
- They are ubiquitous in uncertain reasoning, e.g.

- Inference in Bayesian networks:

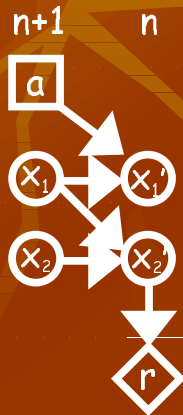


- Conditional prob. tables:  $P(\text{Alarm} \mid \text{Earthquake}, \text{Burglar})$

- Variable elimination:

$$\sum_{x_1 \dots x_i} \prod_{F_1 \dots F_j} F_1(x_1 \dots x_i) \dots F_j(x_1 \dots x_i)$$

- Solving Markov decision processes (MDPs):



- Value and reward functions:  $V(\text{Box-1-delivered}, \dots, \text{Box-n-delivered})$

- Value iteration:

$$V^{n+1}(x_1 \dots x_i) = R(x_1 \dots x_i) +$$

$$\gamma \max_a \sum_{x_1' \dots x_i'} \prod_{F_1 \dots F_i} P_1(x_1' \mid \dots a) \dots P_i(x_i' \mid \dots a) V^n(x_1' \dots x_i')$$

# Motivations II

- For  $\mathcal{B}^n \rightarrow \mathcal{R}$ , why do we need:
  - Compact representations?
  - Efficient operations:  $+$ ,  $\cdot$ ,  $\max(F)$ ,  $\oplus$ ,  $\otimes$ ,  $\max(F_1, F_2)$ ?
- Reason 1: Space considerations
  - $V(\text{Box-1-delivered}, \dots, \text{Box-40-delivered})$  would require ~1 terabyte if all states were enumerated
- Reason 2: Time considerations
  - With 1 gigaflop/s. computing power, one binary operation on the above function would require ~1000 seconds
  - Even simple MDP/BN inference problems can require 100+ binary operator applications!

# Function Representation (Tables)

- How do we represent a function from  $\mathcal{B}^n \rightarrow \mathcal{R}$ ?
- How about a fully enumerated table...
- ...OK, but can we be more compact?

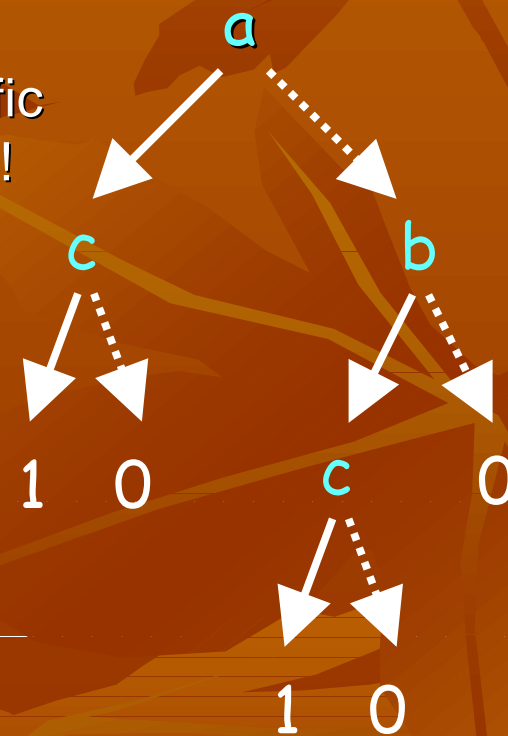
a	b	c	F(a,b,c)
0	0	0	0.00
0	0	1	0.00
0	1	0	0.00
0	1	1	1.00
1	0	0	0.00
1	0	1	1.00
1	1	0	0.00
1	1	1	1.00

# Function Representation (Trees)

- How about a tree? Sure, now can simplify.

a	b	c	$F(a,b,c)$
0	0	0	0.00
0	0	1	0.00
0	1	0	0.00
0	1	1	1.00
1	0	0	0.00
1	0	1	1.00
1	1	0	0.00
1	1	1	1.00

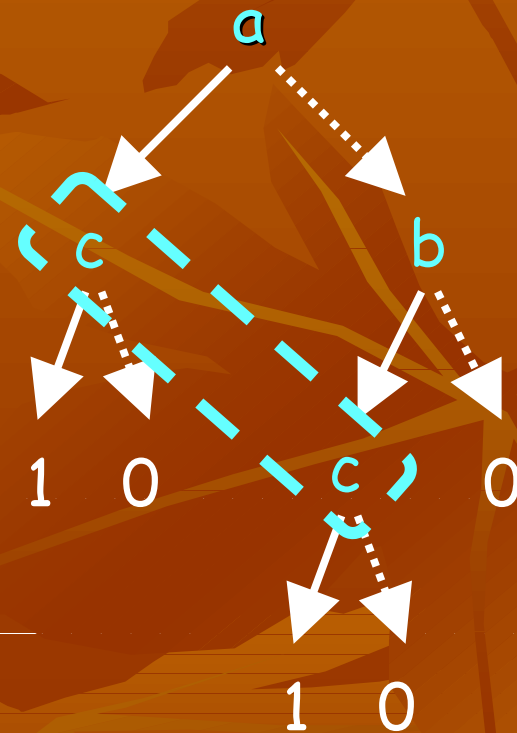
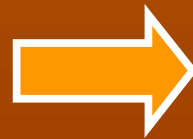
Context-specific  
independence!



# Function Representation (ADDs)

- Why not a directed acyclic graph (DAG)?

a	b	c	$F(a,b,c)$
0	0	0	0.00
0	0	1	0.00
0	1	0	0.00
0	1	1	1.00
1	0	0	0.00
1	0	1	1.00
1	1	0	0.00
1	1	1	1.00





# Function Representation (ADDs)

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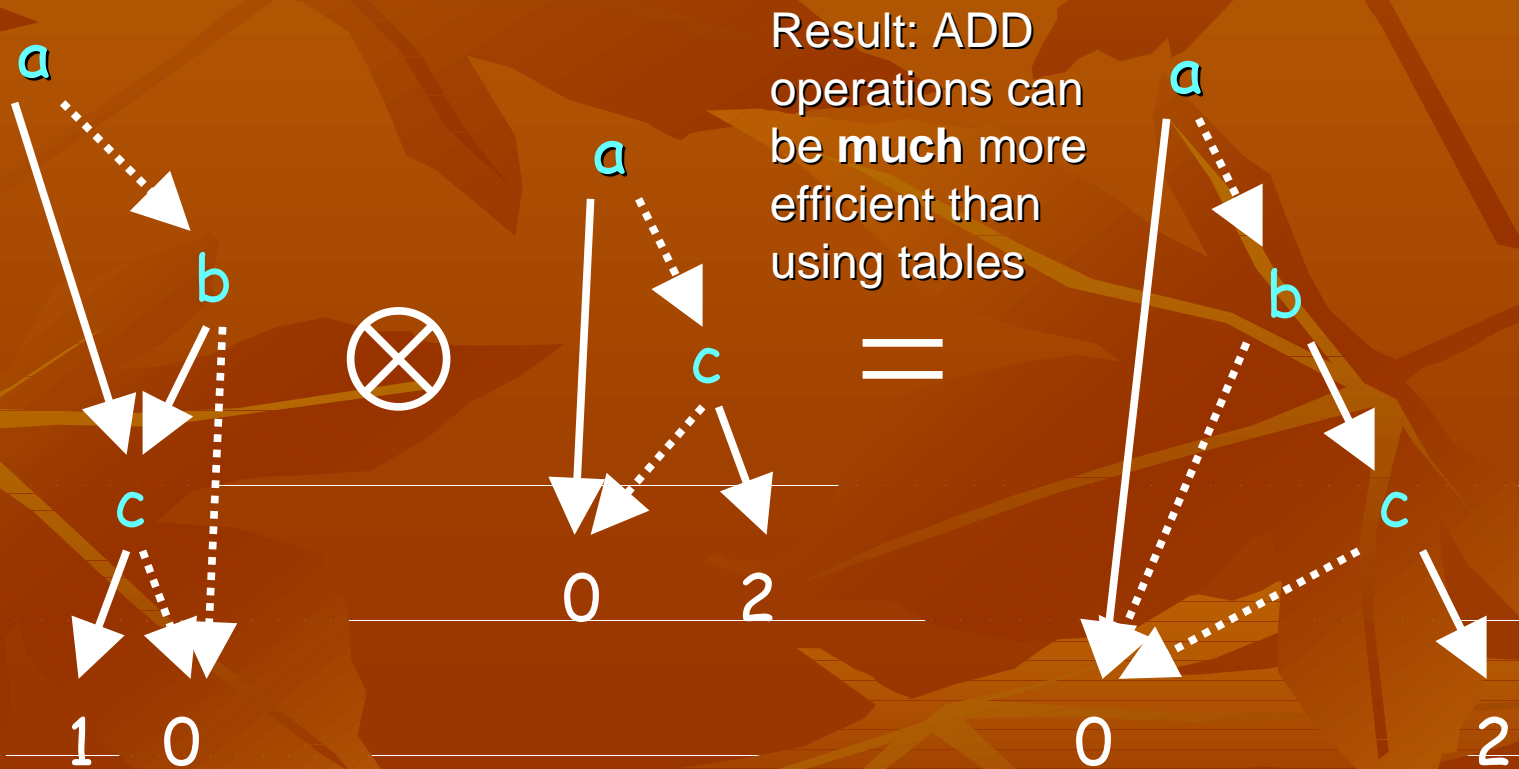
Algebraic  
Decision  
Diagram  
(ADD)





# Binary Operations (ADDs)

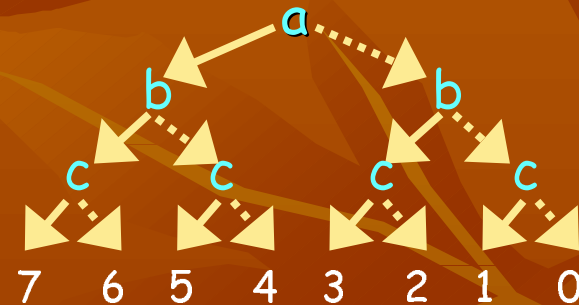
- Why do we order the variables?
- This enables us to do efficient binary operations...



# ADD Inefficiency

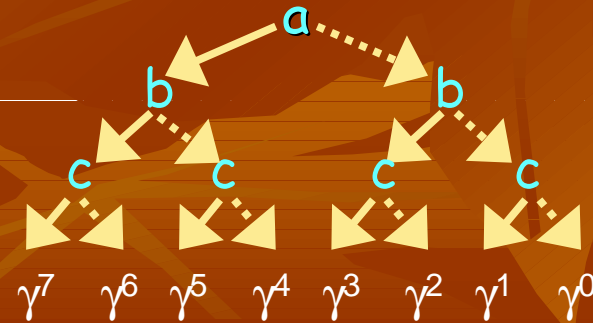
- Is context-specific independence enough?
- Or do we need more compactness?
- Example 1: Additive reward/utility functions

- $R(a,b,c) = R(a) + R(b) + R(c)$   
 $= 4a + 2b + c$



- Example 2: Multiplicative value functions

- $V(a,b,c) = V(a) \cdot V(b) \cdot V(c)$   
 $= \gamma^{(4a + 2b + c)}$



# Affine ADD (AADD)

- Let's define a new decision diagram – affine ADD
- Edges labeled by an offset ( $c$ ) and multiplier ( $b$ ):



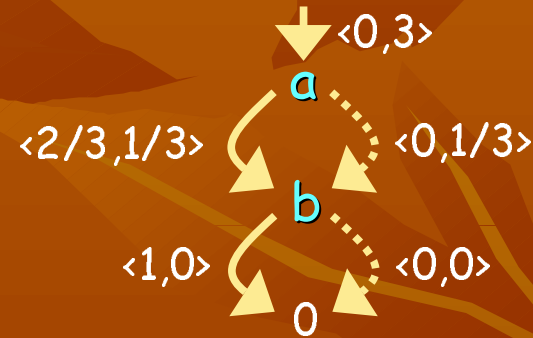
- General semantics:  $\text{if } (a) \text{ then } (c_1 + b_1 F_1) \text{ else } (c_2 + b_2 F_2)$
- To maximize sharing, normalize all nodes  $[0,1]$
- Example:  $\text{if } (a) \text{ then } (4) \text{ else } (2)$



# AADD Examples

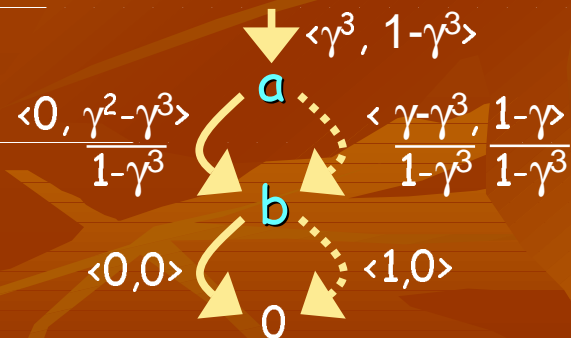
- Back to our previous examples...
- Example 1: Additive reward/utility functions

- $R(a,b) = R(a) + R(b)$   
 $= 2a + b$



- Example 2: Multiplicative value functions

- $V(a,b) = V(a) \cdot V(b)$   
 $= \gamma^{(2a + b)}; \gamma < 1$



# AADD Operations

- How do we perform operations on AADDs?
- Let's look at a simple addition example:



- Two recursive cases:
  - If  $a$  is true:  $(0+1F_1) \oplus (0+2F_2) = (c_{1R} + b_{1R}F_{1R})$
  - If  $a$  is false:  $(3+2F_1) \oplus (7+4F_2) = (c_{2R} + b_{2R}F_{2R})$
- But, can we avoid the second recursion?
  - By simple algebraic manipulation, we know:  

$$(3+2F_1) \oplus (7+4F_2) = 10+2(F_1+2F_2) = 10+2(c_{1R}+b_{1R}F_{1R})$$
- Suggests canonical caching scheme...

# AADD Algorithms and Caching

- To maximize cache hits for binary operators, must use following canonical caching scheme:

Operator	Compute & Store	Return
$c_1+b_1F_1 \oplus c_2+b_2F_2$	$F_1 \oplus (b_2/b_1)F_2$	$c_1+c_2+b_1 \cdot \text{Result}$
$c_1+b_1F \oplus c_2+b_2F$	nothing	$c_1+c_2+(b_1+b_2)F$
$c_1+b_1F_1 \otimes c_2+b_2F_2$	$(c_1/b_1)+F_1 \otimes (c_2/b_2)+F_2$	$b_1b_2 \cdot \text{Result}$
$\max(c_1+b_1F_1, c_2+b_2F_2)$	$\max(F_1, ((c_2-c_1)/b_1) + (b_2/b_2)F_2)$	$c_1+b_1 \cdot \text{Result}$
$\max(c_1+b_1F, c_2+b_2F)$ (see return conditions)	nothing	$c_1 \geq c_2 \wedge b_1 \geq b_2: c_1+b_1F$ $c_2 \geq c_1 \wedge b_2 \geq b_1: c_2+b_2F$

- Otherwise, operations similar to those for ADDs:
  - Just propagate affine transform on recursion
  - And normalize and cache results on return



# AADD Theorems

- How important is canonical caching?
  - Without it, AADD operations provably same as ADD!
  - With it, AADD can yield an exponential time/space improvement over ADD – and never performs worse!
- Stated more formally:
  - **Theorem 1:**
    - The time and space performance of the Reduce and Apply operations for AADDs is within a multiplicative constant of that of ADDs in the worst case.
  - **Theorem 2:**
    - There exist functions  $F_1$  and  $F_2$  and an operator 'op' such that the running time and space performance of  $\langle F_1 \text{ op } F_2 \rangle$  can be linear in the number of variables (in  $F_1$  and  $F_2$ ) for the AADD when the corresponding ADD operation must be exponential in the number of variables.
    - E.g.  $\langle \sum_{i=1}^n 2^i \cdot x_i \oplus \sum_{i=1}^n 2^i \cdot x_i \rangle, \langle \prod_{i=1}^n \gamma^{2^i \cdot x_i} \otimes \prod_{i=1}^n \gamma^{2^i \cdot x_i} \rangle$



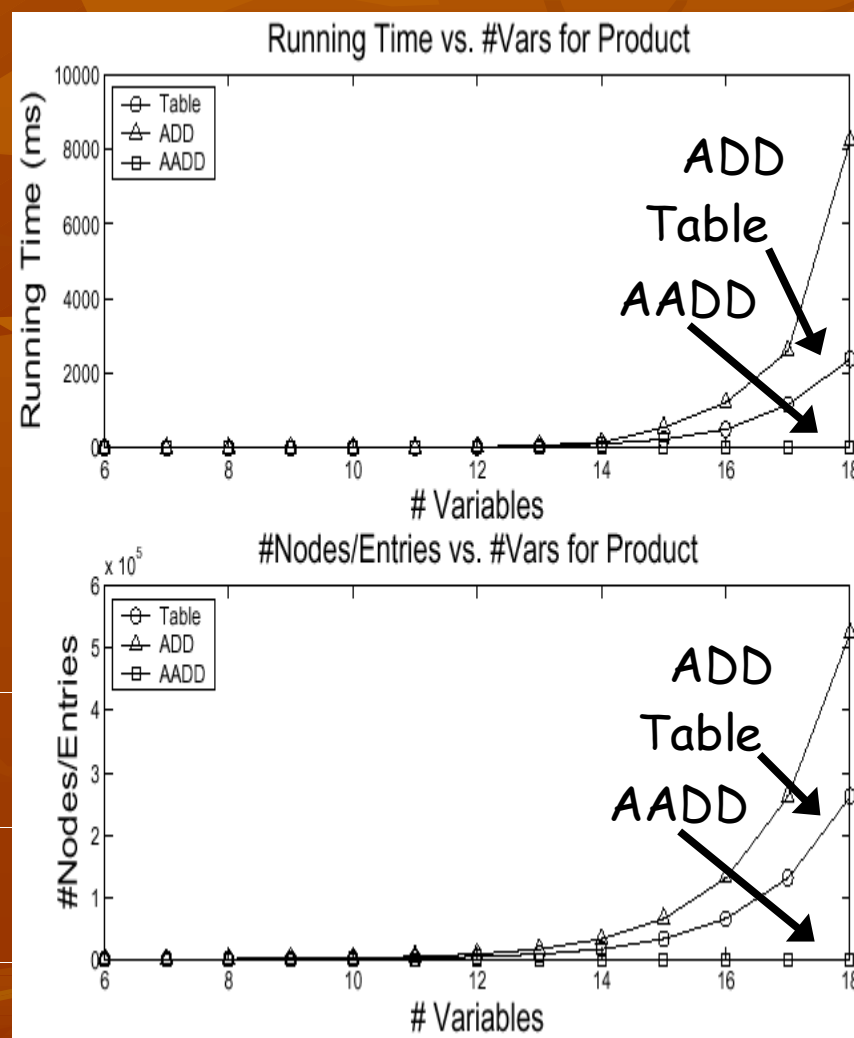
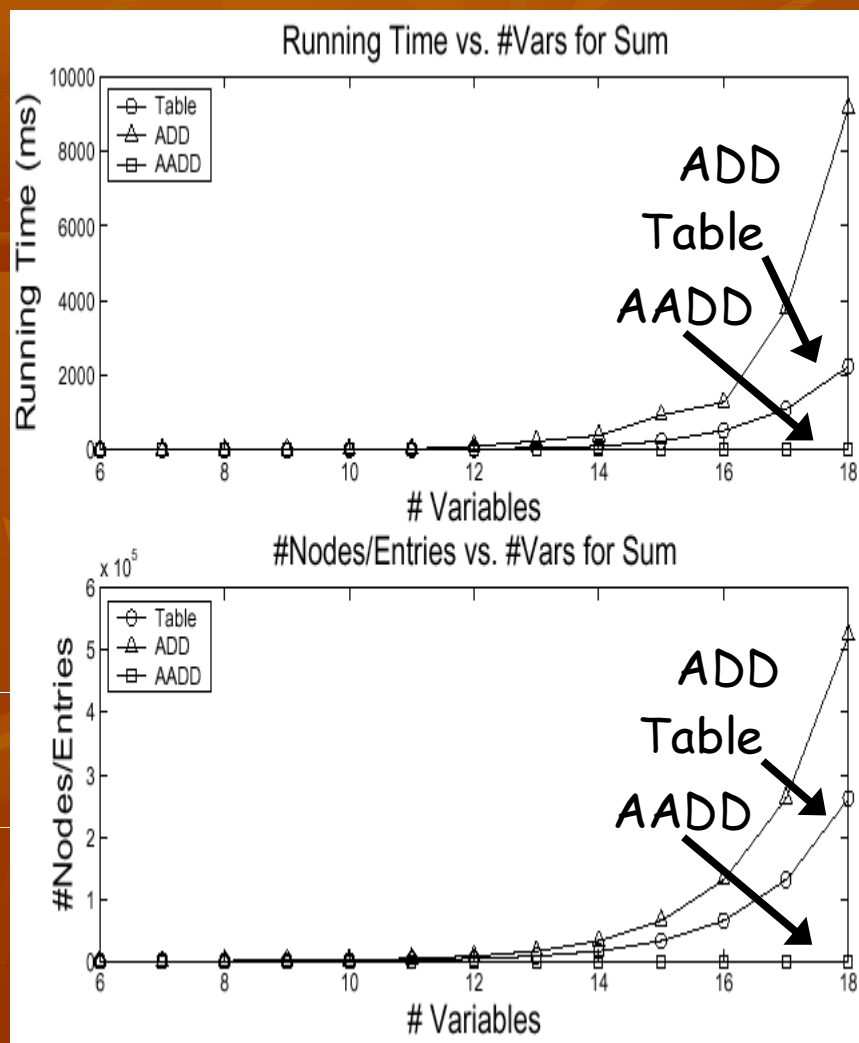
# Numerical Precision Issues

- AADDs introduce numerical precision issues:
  - AADDs perform many subtractions and divisions
  - Operations cache has to store keys  $\langle b_1, c_1, F_1, b_2, c_2, F_2, op \rangle$  where  $b_1, c_1, b_2$ , and  $c_2$  are floating point values
  - If cache keys stored exactly  $\Rightarrow$  explosion of distinct nodes equivalent within numerical precision!
- Solution: Implement “nearest neighbor” cache lookup
  - Hash on node distance from origin
  - Truncate distance at desired precision
  - $\Rightarrow$  Nodes equivalent within precision will hash to same bucket (with high probability), test equality within precision
- Works efficiently and effectively in practice

# Empirical Comparison: Table/ADD/AADD

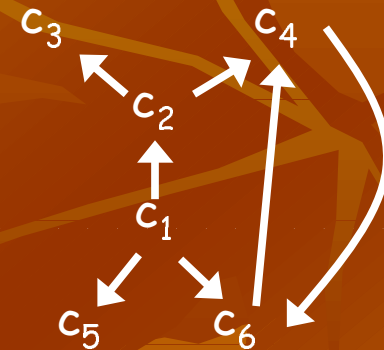
■ Sum:  $\sum_{i=1}^n 2^i \cdot x_i \oplus \sum_{i=1}^n 2^i \cdot x_i$

■ Prod:  $\prod_{i=1}^n \gamma^{(2^i \cdot x_i)} \otimes \prod_{i=1}^n \gamma^{(2^i \cdot x_i)}$



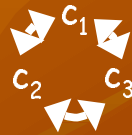
# Application: MDP Solving

- Extend SPUDD (Hoey, St-Aubin, Hu, Boutilier; 1999)
  - Replace ADD with AADD, same value iteration algorithm
  - $V^{n+1}(x_1 \dots x_i) = R(x_1 \dots x_i) + \gamma \cdot \max_a \sum_{x_1' \dots x_i'} \prod_{F_1 \dots F_i} P_1(x_1' | \dots x_i) \dots P_i(x_i' | \dots x_i) V^n(x_1' \dots x_i')$
- SysAdmin MDP (Guestrin, Koller, Parr; 2001)
  - Have a network of computers
  - Various network configurations
  - Every computer is running or crashed
  - At each time step, status is affected by
    - Previous status
    - Status of incoming connections
  - Reward: +1 for every computer running (additive)

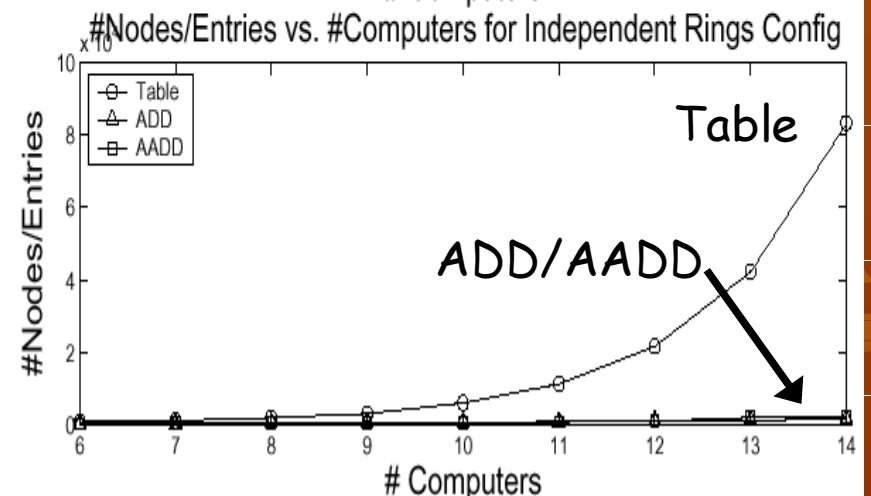
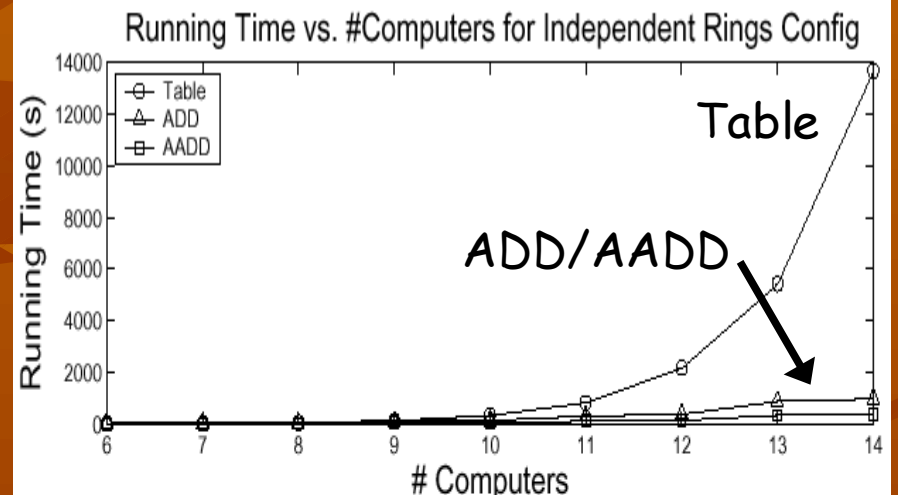
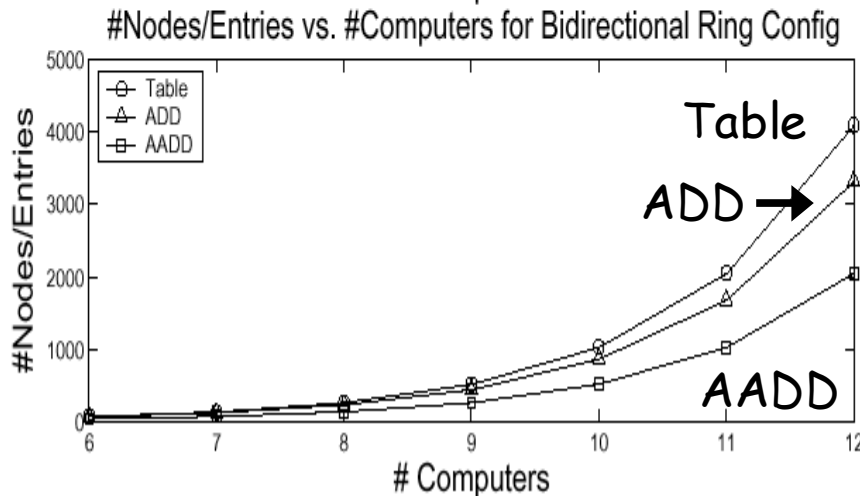
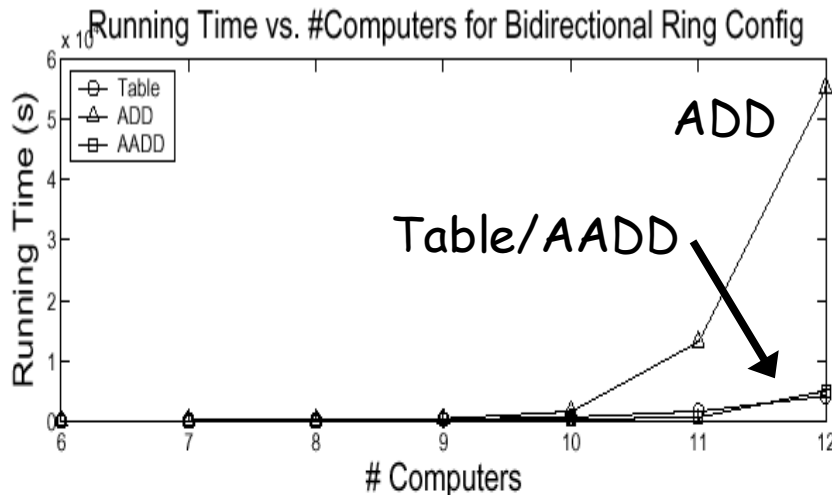


# MDP Results: SysAdmin

## ■ Bidirectional Ring



## ■ Independent Rings



# Application: Bayes Net Inference

- Use variable elimination (Zhang & Poole; 1994)

- Just replace CPTs with AADDs, same algorithm

- Could do same for clique/junction-tree algorithms

- $P(\text{query}|\text{evidence}) = \sum_{x_1 \dots x_i} \prod_{F_1 \dots F_j} F_1(x_1 \dots x_i) \dots F_j(x_1 \dots x_i)$

- Handles CPT structure without specialized inference/transformation

- Context-specific independence

- Probability has logical structure:

$$P(a|b,c) = \text{if } b \text{ ? } 1 : \text{if } c \text{ ? } .7 : .3$$

- Additive CPTs

- Probability is discretized linear function:

$$P(a|b_1 \dots b_n) = c + b \cdot \sum_i (1/2^i) b_i$$

- Multiplicative CPTs

- Noisy-or represented by multiplicative AADD:

$$P(e|c_1 \dots c_n) = 1 - \prod_i (1 - p_i)$$

- When CPT or intermediate factor has such a compact form, AADD will find it...

# Bayes Net Results: Various Networks

Bayes Net	Table		ADD		AADD	
	# Entries	Time	# Nodes	Time	# Nodes	Time
Alarm	1,192	2.97s	689	2.42s	405	1.26s
Barley	470,294	EML*	139,856	EML*	60,809	207m
Carpo	636	0.58s	955	0.57s	360	0.49s
Hailfinder	9,045	26.4s	4,511	9.6s	2,538	2.7s
Insurance	2,104	278s	1,596	116s	775	37s
Noisy-Or-15	65,566	27.5s	125,356	50.2s	1,066	0.7s
Noisy-Max-15	131,102	33.4s	202,148	42.5s	40,994	5.8s

\*EML: Exceeded Memory Limit (1GB)



# Related Work

- A lot of related work in formal verification literature:
  - Work in MTBDDs that looks at additive & multiplicative structure (algorithms/caching similar to AADD):
    - \*BMDs, K\*BMDs, EVBDDs, FEVBDDs, HDDs
  - MTBDDs use finite integer terminals (not floating point)
    - Can still approximate reals via rationals or fixed point values
  - **Problem:** Uncontrollable error when rationals/fixed point representations used for probabilistic inference
    - Probabilities often below representable min, errors accumulate
- \*PHDD is an MTBDD that should work in *theory*:
  - Terminal value represents IEEE floating point representation
  - **Problem:** Would amount to doing floating point arithmetic in software (AADD uses doubles and native arithmetic)



# Conclusions and Future Work

- Conclusions:
  - AADDs are a general replacement for Tables/ADDs
  - Compactly represent logical (CSI), additive, and multiplicative structure
  - In theory: never more than a constant times worse than ADDs, potentially exponentially less space/time
  - Empirically on MDP/BN examples: never worse than ADD/Table, sometimes exponentially better
- Future Work:
  - Approximate inference similar to APRICODD (St. Aubin, Hoey, Boutilier, 2000)
  - Other approximation techniques