

Goal-Plan hierarchy for test *testImpactvars2*

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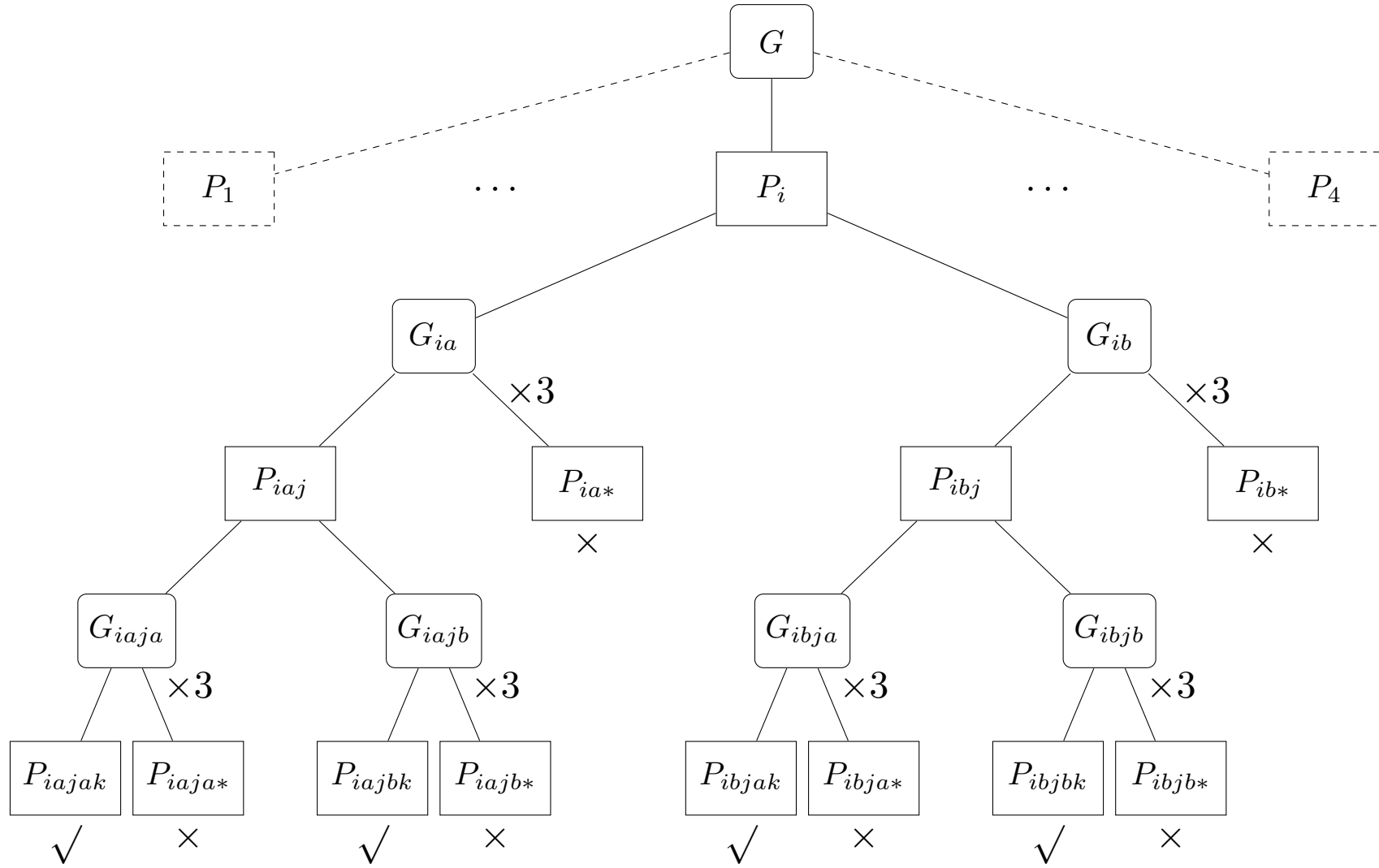


Figure 1: Goal-Plan hierarchy for test *testImpactvars2* (based on the structure T_3 discussed in the IJCAI submission). There are 2^4 worlds whose solutions are distributed evenly in each of the 4 top level plans. Successful execution trace is of length 4. Within each sub-tree P_i *Stable* is expected to perform better for a given world, but it suffers in the number of worlds. Overall, *Concurrent* and *Stable* perform equally well in this structure.