Goal-Plan hierarchy for test *testImpactvars3*

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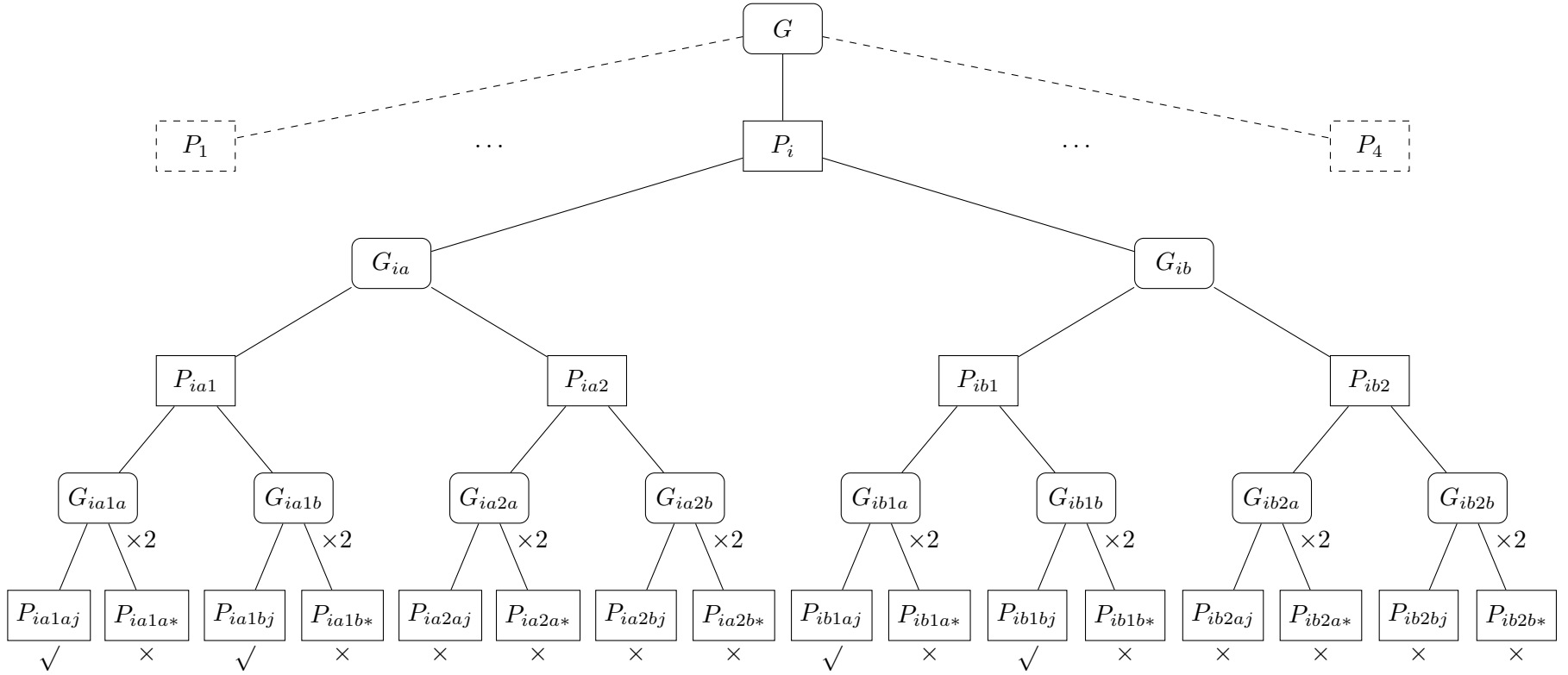
Figure 1: Goal-Plan hierarchy for test *testImpactvars3*. There are 2^3 worlds whose solutions are distributed evenly in each of the 4 top level plans. Successful execution trace is of length 4. Within each sub-tree P_i there is sufficient complexity but is not biased towards any approach. Overall both *Stable* and *Concurrent* perform comparably.