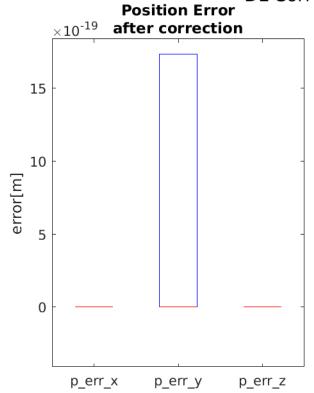
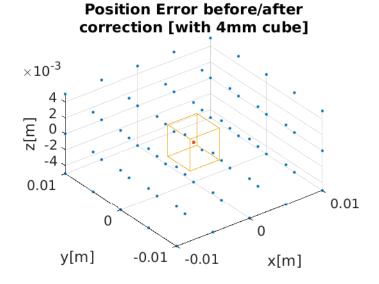
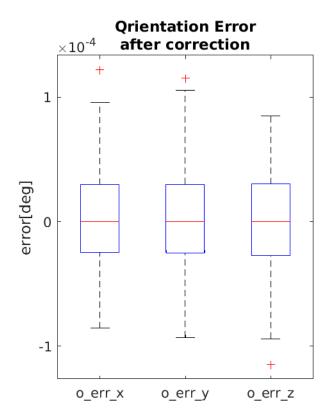
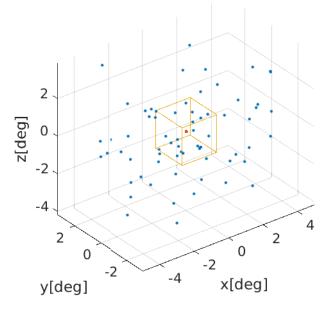
stat_matrix_12_03_2020_perfect.txt DL Correction Error



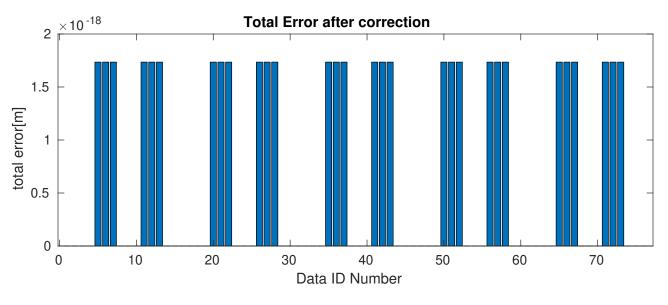


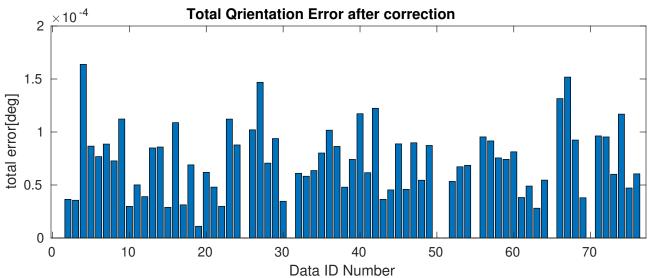


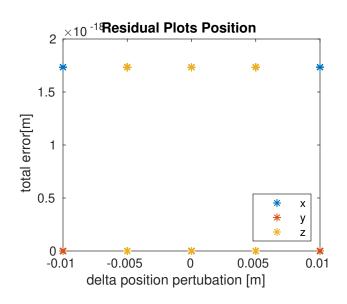


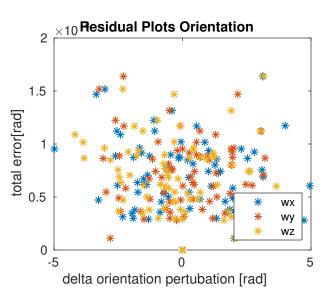


stat_matrix_12_03_2020_perfect.txt DL Total Errors

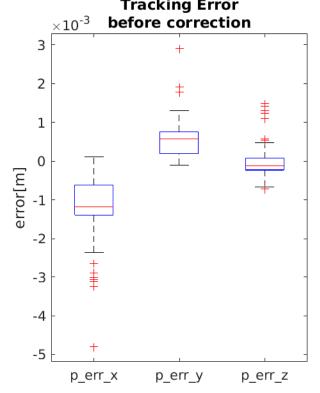


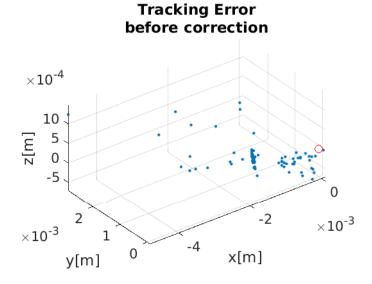






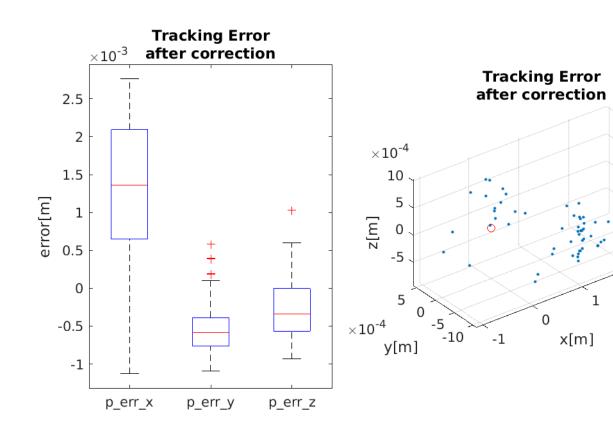
stat_matrix_12_03_2020_perfect.txt Tracking Position Error Before Insertion Tracking Error



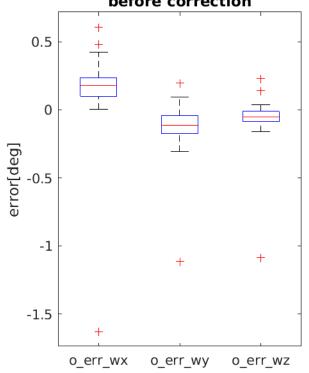


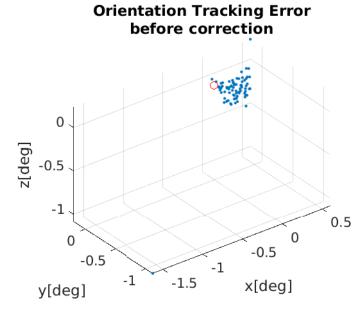
2

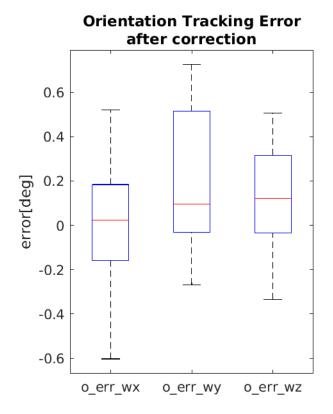
 $\times 10^{-3}$

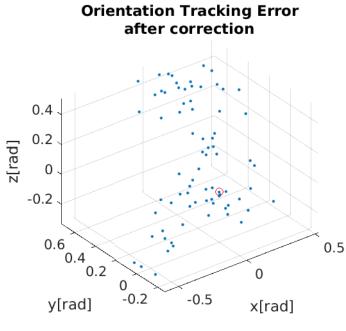


stat_matrix_12_03_2020_perfect.txt Orientation Error Before Insertion before correction









stat_matrix_12_03_2020_perfect.txt Position/Orientation Error Relative to Optimal Pose

