## **CAN-2088C Quick Start**

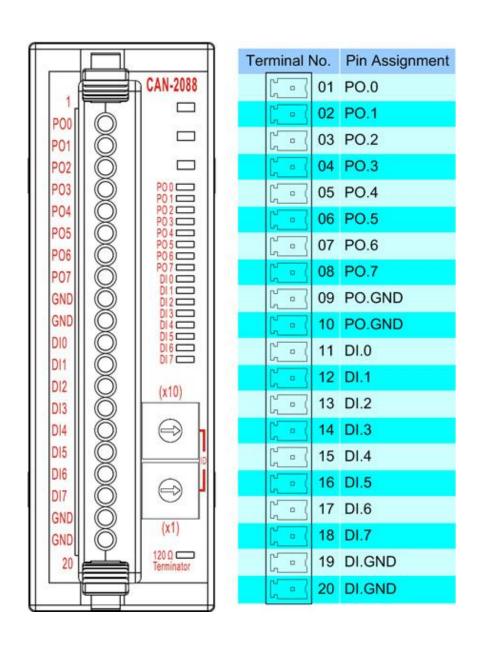
# **Hardware Specification**

CAN Interface			
CANopen Specification	CiA DS-301 v4.02, DS-401 v2.1		
No. of PDOs	10 Rx, 10 Tx (Support dynamic PDO)		
PDO Mode	Event triggered, Remotely requested, Cyclic and acyclic SYNC		
Node ID	1~99 selected by rotary switch		
Baud Rate (bps)	10k, 20k, 50, 125k, 250k, 500k, 800k and 1M		
Error Control	Node Guarding protocol and Heartbeat Producer protocol		
Terminator Resistor	Switch for 120 Ω terminator resistor		
Connector	5-pin screwed terminal block (CAN_GND, CAN_L, CAN_SHLD, CAN_H, CAN_V+)		
PWM			
Channels	8 (Source)		
Max. Load Current	1 mA		
Frequency	0.2 Hz ~500Hz		
PWM Mode	Burst mode, Continuous mode		
Burst mode counter	1 ~ 65535 counts		
Trigger Mode	Hardware (Start and Stop) or Software (Start and Stop)		
Digital Input			
Channels	8 (Sink/Source)		
Counter Frequency	500 kHz Max, 32-bits		
ESD Protection	+/-4 kV, Contact for each channel		
LED			
Status LED	PWR LED, RUN LED, ERR LED		
Terminal Resister LED	Terminal Resister Indicator		
PWM/DI LED  8 LEDs as PWM indicator 8 LEDs as Digital Input indicator			
Power			
Input range	Unregulated +10 ~ +30 V <sub>DC</sub>		
Power Consumption	2.0 W		
Environment			
Operating Temp.	-25 ~ 75 ℃		
Storage Temp.	-30 ~ 80 ℃		
Humidity	10 ~ 90% RH, non-condensing		
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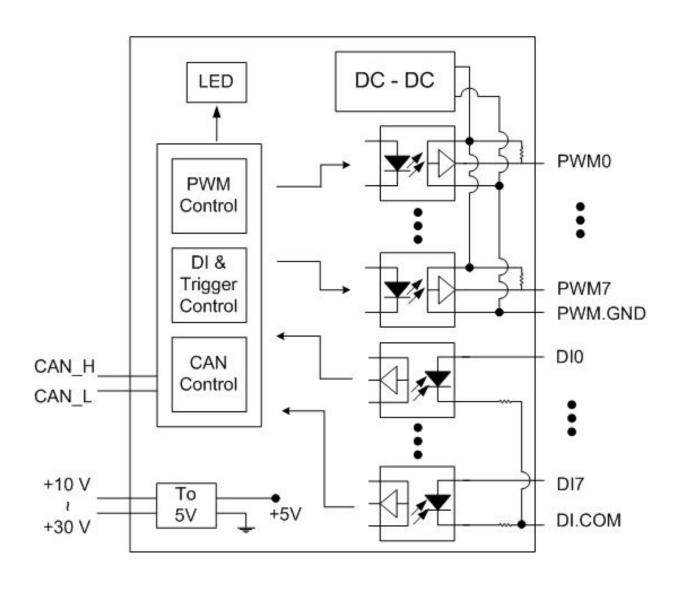
For more information about CAN-2088C, please visit the following website:

http://www.icpdas.com/products/Remote\_IO/can\_bus/can-2088c.htm

## **CAN-2088C Pin Assignments**



## **CAN-2088C Internal I/O Structure**



## **CAN-2088C Wiring Connection Type**

Output Type	ON State LED ON Readback as 1	OFF State LED OFF Readback as 0	
Drive Relay	Relay On	Relay Off	
	PO X PO.GND	PO.GND PO.GND	
Resistance Load	PO X PO.GND	PO X PO.GND	

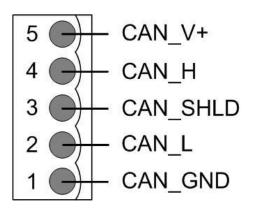
Input Type	ON State LED ON Readback as 1	OFF State LED OFF Readback as 0	
Relay Contact	Relay On	Relay Off	
	+ DI X Relay Close DI.GND	+ DI X Relay Open DI.GND	
TTL/CMOS Logic	Voltage > 10 V	Voltage < 4 V	
	Logic Power  Logic Level Low  DI X  DI COND	Logic Power  Cogic Level Low  DI X  DI COND	
NPN Output	Open Collector On	Open Collector Off	
	DI X DI.GND	OFF □ DI X □ DI.GND	
PNP Output	Open Collector On	Open Collector Off	
	DI X DI.GND	□ DIX □ DI.GND	

Output Type	ON State LED ON Readback as 1	OFF State LED OFF Readback as 0	
	Relay On	Relay Off	
Drive Relay	PO X PO.GND	PO X PO.GND	
Resistance Load	PO X PO.GND	PO X PO.GND	

Input Type	ON State LED ON Readback as 1	OFF State LED OFF Readback as 0	
Relay Contact	Relay On	Relay Off	
	+ ☐ ☐ DI X ☐ DI.GND	+ ☐ ☐ DI X ☐ DI.GND	
TTL/CMOS Logic	Voltage > 10 V	Voltage < 4 V	
	Logic Power  Logic Level Low  DI X  DI JI  D	Logic Power  Logic Level Low  DI X  DI SND	
NPN Output	Open Collector On	Open Collector Off	
	DI X DI.GND	OFF □ DI X □ DI.GND	
PNP Output	Open Collector On	Open Collector Off	
	DI X DI.GND	□⊕ DIX DI.GND	

**Note:** When connecting to a current source, an optional external 125-Ohm precision resistor is required.

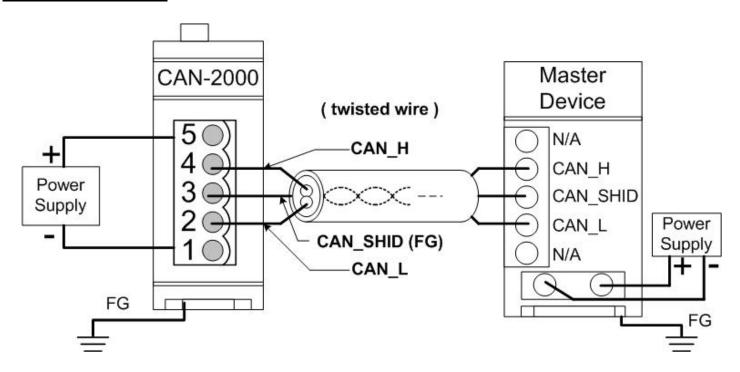
#### **CAN-2088C CAN Bus Wire Connection**



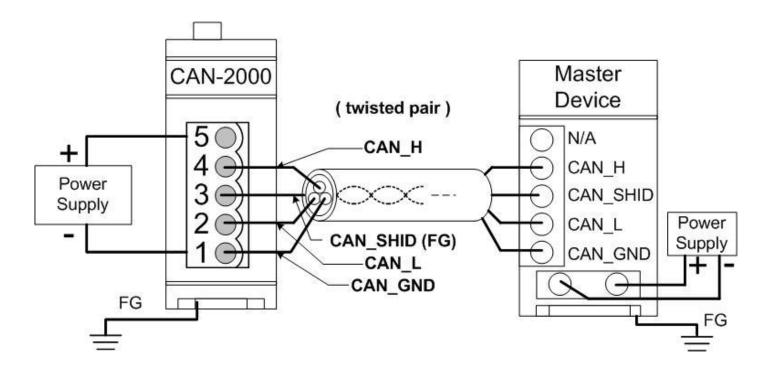
Pin	Signal	Description
5	CAN_V+	Power positive
4	CAN_H	Signal high of CAN Bus line
3	CAN_SHLD	Cable Shield (FG)
2	CAN_L	Signal low of CAN Bus line
1	CAN_GND	CAN ground

<sup>\*</sup> CAN\_SHID (FG) is Optional.

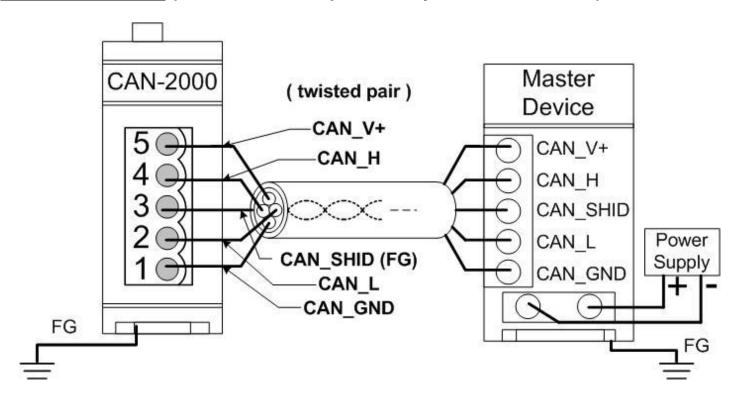
#### **2-Wire Connection**



## **3-Wire Connection**

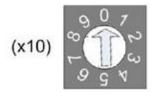


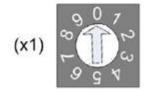
### 4-Wire Connection (The CAN-2000 is powered by the master device)



## **CAN-2088C Firmware Update**

Step 1 – Set Module to "Bootloader" mode (set Node ID to 00). Then power on the module.





Node ID rotary switch

Step 2 – Run FW\_Update\_CAN Utility



(FW\_Update\_CAN Utility)

#### [1] CAN Device:

The below ICP DAS CAN products are supported by FW\_Update\_CAN utility for firmware update.

(1) RS232 to CAN: <u>I-7530</u>

(2) Ethernet to CAN: I-7540D

(3) USB to CAN: <u>I-7565</u>, <u>I-7565-H1</u>, <u>I-7565-H2</u>

(4) CAN Card: PISO-CM100(U),

PISO-/PCM-/PEX-CAN200 / CAN400

Before firmware update, users need to set the below parameters.

- (1) Select CAN hardware interface
- (2) set Dev\_Port or Board\_ID
- (3) set CAN\_Port" number

#### [2] Download Firmware:

- (1) Click "Browser..." button to choose firmware file, can\_2088c\_xx.fw.
- (2) Click "**Start Firmware Update**" button to start firmware update and it will show the total percentage of firmware update in progress bar. After the firmware update finished, it will show the "Firmware Update Success!!" message.



#### CAN-2088C firmware Download:

ftp://ftp.icpdas.com/pub/cd/fieldbus\_cd/canopen/slave/can-2000c/can-2088c/

FW\_Update\_CAN Utility Download:

ftp://ftp.icpdas.com/pub/cd/fieldbus\_cd/canopen/slave/can-2000c/tools/