

## Education

### Stony Brook University

*Ph.D., Mechanical (Concentration: Design and Robotics, Minor: Applied Mathematics), GPA 3.95*

Stony Brook, NY

*Aug 2015 – Present*

- **Relevant Courses:** Robotics, Advanced Dynamics, Vibration and Control, Kinematic Analysis and Synthesis, Applied Stress Analysis, Product Design Optimization, Geometric Modeling, Analysis of Algorithms

### Udacity, School of Autonomous Systems

*Self Driving Car Engineer Nanodegree*

Mountain View, CA

*Mar 2019 – Mar 2020*

- **Relevant Areas:** Computer Vision, Deep Learning, Sensor Fusion, Localization, Planning, Control, System Integration

## Experience

### Stony Brook University

*Research Assistant*

Stony Brook, NY

*May 2017 – Present*

- Developing a Computational Framework for Data-Driven Mechanism Design Innovation supported by a \$450K [NSF grant](#).
- Creating [MotionGen](#) a web-based mechanism design framework. Uses MEAN (MongoDB, Express.js, Angular.js, Node.js) stack to create a RESTful web service based on MVC architecture. iOS and Android apps created using Apache Cordova framework.
- Designing algorithms for simulation and synthesis of Planar, Spherical and Spatial single-degree-of-freedom Robotic systems resulting in publications in journals by the American Society of Mechanical Engineers.
- In-charge of Computer-Aided Design and Innovation Lab and collaborating with a research group of 10+ graduate students.

*Teaching Assistant*

*Aug 2016 – Apr 2017*

- Developed [SnappyXO](#), a laser-cut design-driven robotics platform that enables designing mechanisms, structures, and robots. It has successfully raised \$16K+ on [Indiegogo](#) for a crowdfunding campaign.
- Advised 250+ students in MEC101-Freshman Design Innovation, MEC 102-Engineering Computing, and Vertically Integrated Projects(VIP) Program. The Robot Design projects gained recognition from the Office of President at university.

### Vivonics, Inc.

*Product Design Intern*

Stony Brook, NY

*Feb 2016 – Aug 2016*

- Coordinated with the design team on developing PMT Monitor, a portable medical headset that detects head trauma.
- Generated concepts for an interpupillary distance adjusting mechanism focusing on manufacturability and robustness.

### Leviathan Energy

*Strategic Partnership for Industrial Resurgence (SPIR) Intern*

Stony Brook, NY

*Feb 2016 – May 2016*

- Designed and manufactured Hydro-kinetic turbines with improved airfoil design which produce 50% more power in collaboration with Leviathan Energy.
- Created engineering models using Solidworks and Autodesk Inventor and fabricated parts by FDM based 3D printing.

### Indian Institute of Information Technology

*Junior Research Fellow*

Jabalpur, India

*May 2014 – May 2015*

- Led a \$70k+ research project funded by the Science and Engineering Research Board titled “Development of Additive-Subtractive Integrated Rapid Prototyping System for Improved Part Quality”.
- Spearheaded design and manufacturing teams to create a new hybrid 3D printing process using Pellet based Screw Extruder with CNC machines. Created Toolpath Planning strategies to manufacture CAD models using Hybrid Manufacturing techniques.

## Relevant Projects

### Fracture test analysis for compact tension specimen

Feb 2017 – May 2017

- Finite element analysis of a fracture specimen to predict and validate deformations at the crack tip using Abacus.

### Conceptual Design

Aug 2015 – May 2016

- Formulation of design specification/criteria and conceptual design generation of an Ergonomic Nutcracker and Stone Crusher.

### Quality Improvement of Aircraft Wing Assembly

Aug 2015 – Nov 2015

- Identifying and correcting the root cause for high rejection rate of final assembly using Pareto Charts, Cause and Effect Diagrams, Control Charts and Histograms.

### Mold Design and Manufacturing

May 2012 – Nov 2012

- Designed and manufactured molds for irrigation industry products for Injection Molding Process.
- Flow Analysis results were used to optimize design and a Pricing Strategy was developed for industry.

## Technical Proficiency

- **Languages :** Python, Javascript, C++, MATLAB, Mathematica
- **CAD softwares :** Solidworks, Autodesk Inventor, PTC Creo, CATIA, Ansys (CFD and Mechanical), Autodesk AutoCAD, Autodesk Moldflow, FeatureCAM, MSC-Adams, ZWCAD, Altair HyperMesh, Altair OptiStruct, Materialize Magics, Materialize Mimics, CNC G-M Code
- **Tools & Technologies :** Keras, Tensorflow, OpenCV, HTML, CSS, Canvas, Node.js, Express.js, Redis, Apache Cordova, OpenGL, Jupyter, Anaconda, Git, npm, MongoDB, Docker, ROS

## Selected Publications

- Sharma S., Purwar A., Ge Q.J.; **A Motion Synthesis Approach to Solving Alt-Burmester Problem by Exploiting Fourier Descriptor Relationship Between Path and Orientation.**, ASME J. Mechanisms Robotics; doi:10.1115/1.4042054
- Sharma S., Purwar A., Ge Q.J.; **An Optimal Parametrization Scheme for Path Generation Using Fourier Descriptors for Four-Bar Mechanism Synthesis.**, ASME J. Computing and Information Science in Engineering; doi:10.1115/1.4041566