

## Education

### Stony Brook University

*Ph.D., Mechanical (Concentration: Design and Robotics, Minor: Applied Mathematics), GPA 3.95*

Stony Brook, NY

*Aug. 2015 – Present*

- **Relevant Courses:** Robotics, Advanced Dynamics, Vibration and Control, Kinematic Analysis and Synthesis, Applied Stress Analysis, Product Design Optimization, Geometric Modeling, Analysis of Algorithms

### Udacity, School of Autonomous Systems

*Self Driving Car Engineer Nanodegree*

Mountain View, CA

*Mar. 2019 – Present*

- **Relevant Areas:** Computer Vision, Deep Learning, Sensor Fusion, Localization, Planning, Control, System Integration

## Experience

### Stony Brook University

*Research Assistant*

Stony Brook, NY

*May 2017 – Present*

- Developing a Computational Framework for Data-Driven Mechanism Design Innovation supported by \$450K [NSF grant](#).
- Creating [MotionGen](#) a web-based mechanism design framework. Uses MEAN (MongoDB, Express.js, Angular.js, Node.js) stack to create a RESTful web service based on MVC architecture. iOS and Android app created using Apache Cordova framework.
- Designing algorithms for simulation and synthesis of Planar, Spherical and Spatial single-degree-of-freedom Robotic systems resulting in publications in journals by American Society of Mechanical Engineers.
- In-charge of Computer-Aided Design and Innovation Lab and collaborating with a research group of 10+ graduate students.

*Teaching Assistant*

*Aug 2016 – Apr 2017*

- Developed [SnappyXO](#), a laser-cut design-driven robotics platform which enables designing mechanisms, structures, and robots.
- Advised 250+ undergraduate students in MEC101-Freshman Design Innovation and MEC 102-Engineering Computing.
- Mentored students for their Robot Design projects which gained recognition from the Office of President at university.

### Vivonics, Inc.

*Product Design Intern*

Stony Brook, NY

*Feb 2016 – Aug 2016*

- Coordinated with design team on developing PMT Monitor, a portable medical headset which detects head trauma.
- Generated concepts for an interpupillary distance adjusting mechanism focusing on manufacturability and robustness.

### Leviathan Energy

*Strategic Partnership for Industrial Resurgence (SPIR) Intern*

Stony Brook, NY

*Feb 2016 – May 2016*

- Designed and manufactured Hydro-kinetic turbines with improved airfoil design which produce 50% more power in collaboration with Leviathan Energy.
- Created engineering models using Solidworks and Autodesk Inventor and fabricated parts by FDM based 3D printing.

### Indian Institute of Information Technology

*Junior Research Fellow*

Jabalpur, India

*May 2014 – May 2015*

- Led a \$70k+ research project funded by the Science and Engineering Research Board titled “Development of Additive-Subtractive Integrated Rapid Prototyping System for Improved Part Quality”.
- Spearheaded design and manufacturing teams to create a new hybrid 3D printing process using Pellet based Screw Extruder with CNC machines
- Developed Toolpath Planning strategies to manufacture CAD models using Hybrid Manufacturing techniques.

## Relevant Projects

### Lane Detection for Autonomous Vehicles

*Python, Jupyter, OpenCV [github.com/ssharma1991/autonomous-car-basic-lane-detection](https://github.com/ssharma1991/autonomous-car-basic-lane-detection)*

Udacity

*May 2019 – Aug 2019*

- Created a robust image processing pipeline to detect a highway lane in an image, pre-recorded video, or live-feed from dashcam.
- Calculated the car's position within lane and lane's radius of curvature using perspective transform and polynomial fitting.

### Traffic Sign Classification

*Python, Jupyter, OpenCV, TensorFlow [github.com/ssharma1991/autonomous-car-traffic-sign-classification](https://github.com/ssharma1991/autonomous-car-traffic-sign-classification)*

Udacity

*May 2019 – Aug 2019*

- Developed a LeNet inspired convolution neural network using TensorFlow to classify the [GTSRB](#) traffic sign dataset.
- Achieved 94.8% accuracy on test dataset by data augmentation and image enhancement using OpenCV.

### Behavioral Cloning

*Python, Jupyter, Keras [github.com/ssharma1991/autonomous-car-behavioral-cloning](https://github.com/ssharma1991/autonomous-car-behavioral-cloning)*

Udacity

*May 2019 – Aug 2019*

- Designed an end-to-end convolution neural network using Keras that predicts steering angles from dash-cam images.
- Successfully used this model to autonomously steer a car around a virtual test track after neural network tuning and data augmentation.

### Sensor Fusion

*C++ [github.com/ssharma1991/autonomous-car-sensor-fusion](https://github.com/ssharma1991/autonomous-car-sensor-fusion)*

Udacity

*May 2019 – Aug 2019*

- Implemented car location estimation algorithm using extended Kalman filter based on LIDAR and RADAR sensors data.

## Two Armed Robotic Manipulator

Matlab

MEC529 Robotics  
March 2016 – May 2016

- Optimal motion planning in Dual Quaternion space to pick and place objects considering manipulator reachability.

## Interactive Manipulation of NURBS Surfaces

C++, OpenGL, Qt5

MEC572 Geomtric Modelling  
March 2016 – May 2016

- OpenGL based implementation in C++ for interactive manipulation of Non Uniform Rational B-Spline Surfaces.

## Fracture test analysis for compact tension specimen

Feb 2017 – May 2017

- Finite element analysis of a fracture specimen to predict and validate deformations at the crack tip using Abacus.

## Conceptual Design

Aug 2015 – May 2016

- Conceptual design of an Ergonomic Nutcracker and Stone Crusher.
- Formulation of product design specification and criteria and generation of the best possible product concept.

## Quality Improvement of Aircraft Wing Assembly

Aug 2015 – Nov 2015

- Identifying and correcting the root cause for high rejection rate of final assembly using Pareto Charts, Cause and Effect Diagrams, Control Charts and Histograms.

## Mold Design and Manufacturing

May 2012 – Nov 2012

- Designed and manufactured molds for irrigation industry products for Injection Molding Process.
- Flow Analysis results were used to optimize design and a Pricing Strategy was developed for industry.

## Technical Proficiency

---

- **Languages** : Python, Javascript, C++, MATLAB, Mathematica
- **CAD softwares** : Solidworks, Autodesk Inventor, PTC Creo, CATIA, Ansys (CFD and Mechanical), Autodesk AutoCAD, Autodesk Moldflow, FeatureCAM , MSC-Adams, ZWCAD, Altair HyperMesh, Altair OptiStruct, Materialize Magics, Materialize Mimics, CNC G-M Code, Minitab
- **Tools & Technologies** : Keras, Tensorflow, OpenCV, HTML, CSS, Canvas, Node.js, Express.js, Redis, Apache Cordova, OpenGL, Jupyter, Anaconda, Git, npm, MongoDB

## Selected Publications

---

- Sharma S., Purwar A., Ge Q.J.; **A Motion Synthesis Approach to Solving Alt-Burmester Problem by Exploiting Fourier Descriptor Relationship Between Path and Orientation.**, ASME J. Mechanisms Robotics; doi:10.1115/1.4042054
- Sharma S., Purwar A., Ge Q.J.; **An Optimal Parametrization Scheme for Path Generation Using Fourier Descriptors for Four-Bar Mechanism Synthesis.**, ASME J. Computing and Information Science in Engineering; doi:10.1115/1.4041566