

Mathematically Structured Computer Programs

Sreekar M. Shastry

28 February 2011

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{
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- ★ In a computer program, a function f is called *referentially transparent* if it always produces the same output Y from the same input X , i.e. if

$$Y = f(X)$$

is a function in the sense of mathematics.

- ★ This is a fundamental design principle of functional programming languages: Lisp, ML, and most importantly for us
- ★ *Haskell*
The paradigm is also called “declarative programming.”

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 - ★ Also known as "imperative programming."
 - ★ Examples: C, C++, Java, Python, C#, Perl, etc.
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Who cares?

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The Factorial Function

Consider the factorial function which we define in an imperative but nevertheless referentially transparent manner

```
int factorial( int n ) {  
    if n < 0 then return error  
    if n = 0 then return 1  
  
    int x = 1  
    for i = 1,2,...,n  
        x = x*i  
  
    return x  
}
```

The Factorial Function

The standard mathematical definition gives us the referentially transparent definition in a declarative programming language

$$\text{factorial}(n) := \begin{cases} 1 & \text{if } n = 0 \\ n * \text{factorial}(n - 1) & \text{if } n > 0 \end{cases}$$

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From mathematics to algorithms and back again...

- ★ If we start with a function from mathematics then we can implement it in a referentially transparent manner in a programming language.
 - ★ How about going in the other direction?
 - ★ Can we take a standard algorithm from computer science and turn it into a mathematical function?
- Even further: can we model the interaction of the algorithm with the real world in pure mathematics?

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int f(int n, StateOfTheWorld)
{
    return n + CurrentSecond(StateOfTheWorld)
}
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- ★ ...and likewise for a function which interacts with the user.

- ★ This is what we will do.

- ★ We will see a highly elegant and concise solution to our problem which saves us from *explicitly* passing around cumbersome and potentially very fragile “state of the world” variables.
- ★ The solution to our problem will take us somewhat deeply into the branch of mathematics known as *category theory*.

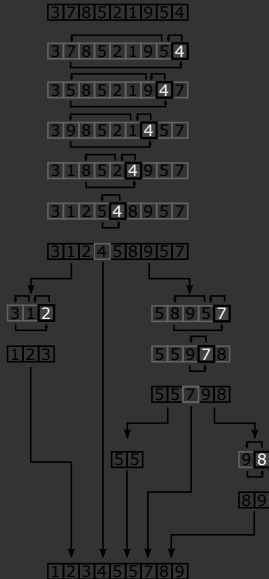
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A simple program...

```
Main ( Arguments )  
  print Quicksort( Arguments )  
  
function Quicksort( Array )  
  if length( Array ) <= 1 then return Array  
  Pivot := Array[1]  
  for each x in Array  
    if x <= Pivot then  
      append x to LessThanPivotArray  
    else  
      append x to GreaterThanPivotArray  
  
  return Concatenate( Quicksort( LessThanPivotArray ),  
                      Pivot,  
                      Quicksort( GreaterThanPivotArray ) )  
  
> ./a.out f g e d c a b  
a b c d e f g
```

Visualizing Quicksort




```
liftM          :: (Monad m) => (a -> b) -> m a -> m b
liftM f t      = (\y -> return (f y)) >>> t

q              :: (Ord a) => [a]->[a]
q []           = []
q (x:xs)       = q [y|y<-xs,y<x] ++ [x] ++ q [y|y<-xs,y>=x]

main = print >>> (liftM q) getArgs
```

```
> runghc quicksort.hs f g e d c a b
["a","b","c","d","e","f","g"]
```

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- ★ For the rest of this talk, we will try to understand it, from a mathematical point of view.
- ★ We must review some category theory first. . .

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Some Category Theory

A *category* \mathcal{C} consists of

- a class $\text{obj}(\mathcal{C})$ of objects
- for all objects $A, B, C, \dots \in \mathcal{C}$
 - a set $\text{Hom}_{\mathcal{C}}(A, B)$ of morphisms
 - an identity morphism $\text{id}_A \in \text{Hom}_{\mathcal{C}}(A, A)$
 - a composition function

$$\text{Hom}_{\mathcal{C}}(A, B) \times \text{Hom}_{\mathcal{C}}(B, C) \rightarrow \text{Hom}_{\mathcal{C}}(A, C)$$

denoted by $g \circ f$ or $f; g$ for

$$A \xrightarrow{f} B \xrightarrow{g} C$$

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- ★ The fundamental example is the category of sets, denoted **Sets**
 - ▶ objects are sets
 - ▶ morphisms are set theoretic functions
 - ▶ composition is composition of set functions, etc
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- ★ We will model \mathcal{H} by **Sets**, i.e. for this talk we define

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The Category of Data Types

- ★ Let us consider \mathcal{H}

- ★ An object is to be a data type
- ★ A morphism between data types has as input a data type and produces as output a data type...

Thus an algorithm written in Haskell is *defined* to be a morphism $f : A \rightarrow B$ in \mathcal{H} ,

and $A \rightarrow B$ is its type signature

There are further requirements to be an algorithm which we will ignore for this talk...

Absent a more precise definition, *we know an algorithm when we see one.*

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- ★ Examples of data types:

- ★ \mathbb{Z} , the integers

- ★ $L(\mathbb{Z})$:= the set of lists of integers

- ★ $L(A)$:= the set of lists of type A for $A \in \mathcal{H}$

$$\begin{aligned} L(A) &:= \bigcup_{n \geq 0} A^n \\ &= \{(a_1, \dots, a_m) : m < \infty, a_i \in A, \forall i = 1, \dots, m\}. \end{aligned}$$

Strings := Lists of characters

Binary trees with leaves of type $A \in \mathcal{H}$

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- ★ We may say that “List” is a parametrized data type

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Some Category Theory

Definition

A functor $F : \mathcal{C} \rightarrow \mathcal{C}'$ from a category \mathcal{C} to a category \mathcal{C}' is a rule which

- given $A \in \mathcal{C}$ produces $F(A) \in \mathcal{C}'$ and
- given $f : A \rightarrow B$ in \mathcal{C} , produces $F(f) : F(A) \rightarrow F(B)$ in \mathcal{C}'
- and satisfies various axioms, for instance $F(f; g) = F(f); F(g)$

Some Category Theory

Definition

Given functors $F : \mathcal{C} \rightarrow \mathcal{C}'$ and $G : \mathcal{C}' \rightarrow \mathcal{C}''$ we may compose them to obtain

$$F; G : \mathcal{C} \rightarrow \mathcal{C}''.$$

Thus we have the notion of $\text{End}(\mathcal{C})$, which is the category of all endofunctors of \mathcal{C} :

- the objects are functors $F : \mathcal{C} \rightarrow \mathcal{C}$ (known as endofunctors)
- the morphisms are natural transformations of functors

Some Category Theory

Definition

A monad over \mathcal{C} is a monoid in $\text{End}(\mathcal{C})$. By this we mean a functor $T \in \text{End}(\mathcal{C})$ together with natural transformations $\mu : T \times T \rightarrow T$ and $\eta : \text{id}_{\mathcal{C}} \rightarrow T$ which satisfy the associativity and unit axioms of a monoid

$$\begin{array}{ccc}
 T \times T \times T & \xrightarrow{\mu \times \text{id}_T} & T \times T \\
 \text{id}_T \times \mu \downarrow & & \downarrow \mu \\
 T \times T & \xrightarrow{\mu} & T
 \end{array}$$

$$\begin{array}{ccccc}
 T \times \text{id}_{\mathcal{C}} & \xrightarrow{\text{id}_T \times \eta} & T \times T & \xleftarrow{\eta \times \text{id}_T} & \text{id}_{\mathcal{C}} \times T \\
 & \searrow & \downarrow \mu & \swarrow & \\
 & & T & &
 \end{array}$$

(here “ \times ” indicates the composition of functors, which is the product structure in $\text{End}(\mathcal{C})$.)

Some Category Theory

Definition

A Kleisli triple over \mathcal{C} is a triple

$$(T, \eta, (\cdot)^*)$$

where

(1) $T : |\mathcal{C}| \rightarrow |\mathcal{C}|$ is an assignment on objects

(2) $\eta_A : A \rightarrow TA$ is a morphism in \mathcal{C}

(3) $f^* : TA \rightarrow TB$ for given $f : A \rightarrow TB$

s.t. the following hold:

(a) $\eta_A^* = \text{id}_{TA}$

(b) $\eta_A; f^* = f$ for $f : A \rightarrow TB$

(c) $f^*; g^* = (f; g^*)^*$ for $f : A \rightarrow TB$ and $g : B \rightarrow TC$

Some Category Theory

Theorem

The notions of Kleisli triple and monad are equivalent.

Proof.

Given a Kleisli triple $(T, \eta, (\cdot)^*)$ the corresponding monad is (T, η, μ) where we make T into an endofunctor by defining for $f : A \rightarrow B$

$$Tf := (f; \eta_B)^* \text{ and } \mu_A := \text{id}_{TA}^*.$$

Conversely, given a monad (T, η, μ) we define a Kleisli triple by restricting the functor T to objects and for $f : A \rightarrow TB$ we put

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The List Monad

- ★ Let us see that the endofunctor $L \in \text{End}(\mathcal{H})$ is actually a monad.
- ★ $L(A) :=$ the set of lists of type A for $A \in \mathcal{H}$

$$\begin{aligned} L(A) &:= \bigcup_{n \geq 0} A^n \\ &= \{(a_1, \dots, a_m) : m < \infty, a_i \in A, \forall i = 1, \dots, m\}. \end{aligned}$$

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- ★ An example will tell us how to define the monadic “multiplication” and “identity”

$$\mu_A : (L \times L)(A) := L(L(A)) \rightarrow L(A) \text{ and } \eta_A : A \rightarrow L(A)$$

- ★ Take $A := \mathbb{Z}$. Then

$$((1, 2), (3), (4, 5)) \xrightarrow{\mu_{\mathbb{Z}}} (1, 2, 3, 4, 5)$$

removes a layer of parentheses and

$$n \xrightarrow{\eta_{\mathbb{Z}}} (n)$$

is the list consisting of a single element.

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```
instance Monad List where
  return x = [x]
  f >>> xs = (concat . fmap f) xs
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- * `return x` is $\eta_A(x)$
- * `xs` is a list, so how to define `f >>> xs`?
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The State Monad

- ★ We model the current state of the world as a pair of strings $(is, os) \in \mathcal{S} \times \mathcal{S}$ where
 - ★ \mathcal{S} is the set of all strings
 - ★ is = characters waiting to be read in the input stream
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- ★ We define the state monad as an endofunctor of \mathcal{H} , $T : \mathcal{H} \rightarrow \mathcal{H}$ to be

$$T(A) := \text{Hom}(\mathcal{S} \times \mathcal{S}, \mathcal{S} \times \mathcal{S} \times A)$$

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- ★ Thus a $f \in T(A)$ assigns to every possible initial state of the world (i, o) a final state (i', o', α)
- ★ We view f as the action of a single step of an algorithm
- ★ In case we are reading input, we think of α as the value read off of the initial input stream, resulting in the final input stream and output stream

In case of printing output, α would be an empty value

Example of reading input

$i = \text{"def"}, o = \text{"cba"}$

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As described earlier, it is in this way that we pass around the state of the world as a variable, in a referentially transparent manner.

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Given $f : A \rightarrow T(B)$ and $t \in T(A)$ we define $f \gg t \in T(B)$ to be

$$x \mapsto f(\text{return-value}(t(x)))(\text{new-state}(t(x)))$$

where we think of

$$\begin{aligned} T(B) &= \text{Hom}(S, S \times B) \\ &= \text{Hom}(\text{initial-state}, \text{new-state} \times \text{return-value}) \end{aligned}$$

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Back to our three line program

Let us now consider the function liftM

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liftM      :: (Monad m) => (a -> b) -> m a -> m b
liftM f xs = (\y -> return (f y)) >>> xs
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... liftM q ...

- ★ Recall from before that we have $f \ggg xs := \mu_A(L(f)(xs)) = \mu_A((f(y) : y \in xs)) = \text{concat}(f(y) : y \in xs)$
- ★ Now, $q : L(A) \rightarrow L(A)$ so that liftM q is the function $g(xs) = (\backslash y \rightarrow \text{return } (q\ y)) \ggg xs$ where xs is a list
- ★ *In other words, it is the function which takes a list of lists and sorts each of the sublists therein, returning the result in list which is the result of concatenating all of those sorted sublists!*

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getArgs      :: State [String]  
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main = print >>> (liftM q) getArgs
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- ★ We know that `getArgs` is of type `State [String]`
- ★ thus it is an assignment which takes the initial input/output state and gives us the final input/output state as well as a list of strings read off of the input
- ★ After what we have seen on `liftM q`, we know that it simply sorts the list of strings (and strips off a layer of parentheses)

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Back to our three line program

```
getArgs      :: State [String]  
print        :: a -> State ()
```

```
main = print >>> (liftM q) getArgs
```

- ★ We know that `getArgs` is of type `State [String]`
- ★ thus it is an assignment which takes the initial input/output state and gives us the final input/output state as well as a list of strings read off of the input
- ★ After what we have seen on `liftM q`, we know that it simply sorts the list of strings (and strips off a layer of parentheses)
- ★ Finally, given the initial input/output state, `print` appends the resulting sorted list to the output and returns an empty value

This is our program, in its entirety.

```
import System.Environment
```

```
(>>>)      :: (Monad m) => (a -> m b) -> m a -> m b  
f >>> x     = x >>= f
```

```
liftM      :: (Monad m) => (a -> b) -> m a -> m b  
liftM f t  = (\y -> return (f y)) >>> t
```

```
q          :: (Ord a) => [a]->[a]  
q []       = []  
q (x:xs)   = q [y|y<-xs,y<x] ++ [x] ++ q [y|y<-xs,y>=x]
```

```
main = print >>> (liftM q) getArgs
```

```
> runghc quicksort.hs f g e d c a b  
["a","b","c","d","e","f","g"]
```



```
-- the true type signatures
getArgs      :: IO [String]
print        :: (Show a) => a -> IO ()
```