# **Clipping Lines and Polygons**

# Must easily calculate where a segment crosses a plane:

Given a plane EQ  $Q(P) = N \cdot P + d$ 

- Q(P) is 0 if P is on Q
- Q(P) is positive P if same side as N
- Q(P) is negative if P is on opposite side
- Q(P) is a "scaled", "signed" distance of P from plane.

#### Given two points, PO, P1, and plane eq Q:

Calculate distance of points from plane equation

$$d0 = Q(P0)$$

$$d1 = Q(P1)$$

Then the fraction of distance along segment where it crosses the plane:

$$t = \frac{0 - d0}{d1 - d0} = \frac{d0}{d0 - d1}$$

and the point of intersection is

$$I = P0 + t(P1-P0)$$

# Clipping plane equations:

Boundaries of the clipping coordinates (after homogeneous division)

$$-1 \le x/w \le 1$$

$$-1 \le y/w \le 1$$

$$0 \le z/w \le 1$$

Converting these to pre-homogeneous-division plane equations yields

$$-1 \le x/w \rightarrow w+x \ge 0 \rightarrow \begin{bmatrix} 1 & 0 & 0 & 1 \end{bmatrix}$$

$$x/w \le 1 \rightarrow w-x \ge 0 \rightarrow \begin{bmatrix} -1 & 0 & 0 & 1 \\ -1 \le y/w \rightarrow w+y \ge 0 \rightarrow \begin{bmatrix} 0 & 1 & 0 & 1 \end{bmatrix}$$

$$y/w \le 1 \rightarrow w-y \ge 0 \rightarrow \begin{bmatrix} 0 & 1 & 0 & 1 \\ 0 & -1 & 0 & 1 \end{bmatrix}$$

$$0 \le z/w \rightarrow z \ge 0 \rightarrow \begin{bmatrix} 0 & -1 & 0 & 1 \\ 0 & 0 & 1 & 0 \end{bmatrix}$$

$$z/w \le 1 \rightarrow w-z \ge 0 \rightarrow \begin{bmatrix} 0 & 0 & -1 & 1 \end{bmatrix}$$

For testing purposes when writing a clipper,

provide better visual clues of the clipping boundaries by modifying these to clip at 90% of the way to the boundary:

$$-0.9 \le x/w \rightarrow 0.9w + x \ge 0 \rightarrow \begin{bmatrix} 1 & 0 & 0.9 \end{bmatrix}$$

$$x/w \le 0.9 \rightarrow 0.9 \text{w} - x \ge 0 \rightarrow [-1 \quad 0 \quad 0 \quad 0.9]$$

$$-0.9 \le y/w \rightarrow 0.9w + y \ge 0 \rightarrow [0 \quad 1 \quad 0 \quad 0.9]$$

$$y/w \le 0.9 \rightarrow 0.9 \text{w} - y \ge 0 \rightarrow \begin{bmatrix} 0 & -1 & 0 & 0.9 \end{bmatrix}$$

# **Line clipping**

# Representation of a line segment

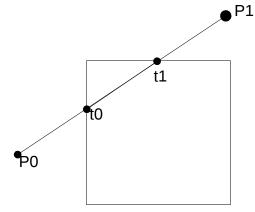
Points on a line segment are represented with a parameter t representing fraction of distance along the segment

The two endpoints of the visible (non-clipped) portion of a segment are represented with t0 and t1.

Initial values (used to represent the full segment) are:

t0 = 0 and t1 = 1

As we clip, t0 will increase, and t1 will decrease.



# First we work out how to clip to a single boundary:

```
Input: d0, d1
In-Out: t0, t1
Return: boolean indicating if any portion of line is visible
ClipB(d0, d1, t0, t1):
    if d0 <0 and d1 < 0: // Both endpoints outside boundary
        return False
    else if d0 >= 0 and d1 >= 0: // Both endpoints inside or on boundary
        return True
    else: // Endpoints on both sides of boundary – must clip
        t = d0/(d0-d1) // Cannot be a zero divide
        if d0 < 0:
            t0 = max(t0,t)
        else:
            t1 = min(t1,t)
        return True</pre>
```

# Full algorithm calls single boundary alg 6 times:

```
In: vertices P0, P1
Out: vertices R0, R1
Returns: Boolean indicating if an portion is visible
Clip(P0,P1, R0,R1): \\ t0 = 0 \\ t1 = 1 \\ for \ Q \ in \ list \ of \ six \ plane \ equations: \\ r = ClipB(Q(P0), Q(P1), t0, t1) \\ if \ not \ r: \\ return \ false \ // \ P0:P1 \ is \ outside \ this \ boundary \ so \ outside \ full \ window \ if \ t0 > t1: \\ return \ false \ // \ corner \ case
R0 = P0 + t0(P1 - P0) \\ R1 = P0 + t1(P1 - P0) \\ return \ true
```

# Clipping Polygons Sutherland-Hodgeman Algorithm

#### **Algorithm**

Pass a polygon through the following **PolyClip** procedure once for each clip boundary

# PolyClip (single clipping plane pass):

```
Input: P -- array of vertex, Q a Plane EQ
Output: array of vertex
PolyClip(P):
       R = empty list
       S = P[size(P)-1]
       for i = 0 to size(P)-1:
               T = P[i]
               if both S,T are on + side of Q:
                      append T to R
               else if S is on + side of Q:
                      I = intersection of segment S,T and plane Q
                      append I to R // See note below
               else if T is on + side of Q:
                      I = intersection of segment S,T and plane Q
                      append I to R // See note below
                      append T to R
               S = T
       return R
```

### Intersection of S,T with plane Q:

$$t = \frac{0 - Q(S)}{Q(T) - Q(S)} = \frac{Q(S)}{Q(S) - Q(T)}$$

$$I = S + t(T - S)$$

#### Must handle some zero and round-off casses:

```
To test for P being "on + side" of plane Q: include 0 as "on + side" include even within \epsilon as "on + side" So the test for "on + side" becomes if Q(P) > -\epsilon
```

# Consider what it takes to do this in a streaming fashion:

```
Sequence of clippers and one last writer

input-list ==> clipper1 ==> cliper2 ==> ... ==> clipper6 ==> output-list

Each clipper

knows its plane EQ

has a NextVertex method for input
has a nextClipper reference
calls nextClipper.NextVertex(...) instead of "append to R"
has copies of first point and last point seen
has a Done method which considers edge from last to first point.

Startup
calls clipper1.NextVertex(P[i]) in a loop.
```