

Perspective

Perspective requires a division

The perspective projection of a point (x,y,z) onto a viewplane $z=1$

By similar triangles: $(x',y')=(x/z,y/z)$

But we don't want z/z to lose all depth information

Homogeneous coordinates

Use 4D points (x,y,z,w) to represent 3D points like this

$$(x,y,z,w) \sim (x/w,y/w,z/w) \quad \text{if } w \neq 0$$

For non-zero scalars:

$$(sx,sy,sz,sw) \sim (sx/sw,sy/sw,sz/sw) \sim (x/w,y/w,z/w)$$

We can interpret $w=0$ as:

points at infinity., or
vectors (directions)

We can rig w to contain a useful quantity for perspective

Perspective projection transformation

View frustum is specified by

r_x : half width to viewing distance ratio

r_y : half height to viewing distance ratio

f : distance to view plane

b : distance to far plane

Projection matrix:

$$\begin{bmatrix} \frac{1}{r_x} & 0 & 0 & 0 \\ 0 & \frac{1}{r_y} & 0 & 0 \\ 0 & 0 & \frac{b}{b-f} & -\frac{fb}{b-f} \\ 0 & 0 & 1 & 0 \end{bmatrix}$$

Some View Frustum calculations:

Corners and edges

Front corners are $(\pm w, \pm h, d, 1)$,

Corners at z depth are $E = (\pm wz/d, \pm hz/d, z, 1)$

Transform to $PE = (\pm z, \pm z, ?, z) \Rightarrow (\pm 1, \pm 1, ?)$

Points on z axis, different depths:

$$P(0,0,0,1)^T = (0,0,-?,0)^T \Rightarrow \infty(-Z) \text{ (Eye goes to -infinity on } z \text{ axis)}$$

$$P(0,0,f,1)^T = (0,0,0,0)^T \Rightarrow (0,0,0) \text{ (Front CP goes to 0)}$$

$$P(0,0,b,1)^T = (0,0,b,b)^T \Rightarrow (0,0,1) \text{ (Back CP goes to 1)}$$

$$P(0,0,1,0)^T = (0,0,b/(b-f),1)^T \Rightarrow (0,0,b/(b-f)) \text{ (Infinity to vanishing point)}$$

Perspective Transformation's effect on depth values

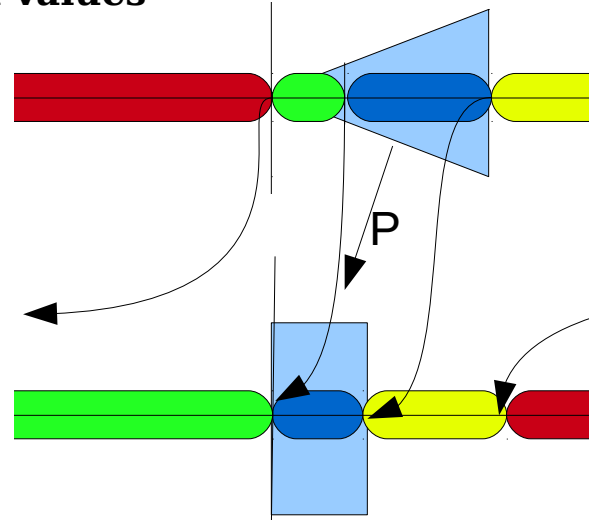
Eye \rightarrow -infinity on z axis

Eye:front \rightarrow -infinity:0

front:back \rightarrow 0:1

back:infinity \rightarrow 1:some z

-infinity:eye \rightarrow some z : infinity



Perspective transformation's effect on ranges of z values.

Homogeneous coordinate facts

(x, y, z, w) when $w \neq 1$ is a "finite" point

Homogeneous division gives the associated 3D point: $(x, y, z, w) \rightarrow (x/w, y/w, z/w)$

$(x, y, z, 0)$ has multiple related interpretations:

vector (x, y, z)

point at ∞ in direction (x, y, z)

intersection of parallel lines in direction (x, y, z)

vanishing point in direction (x, y, z)

These facts can be seen by trying:

Translate (x, y, z, w) for both $w=0$ and $w \neq 0$

Consider $\lim_{w \rightarrow 0} (x, y, z, w)$

Some notes about Projection coordinate systems

In truth, this C.S. is most useful **before** the homogeneous division.

That is given a point (x, y, z, w) we have stated the bounds of Projection space as

$$-1 \leq \frac{x}{w} \leq +1$$

$$-1 \leq \frac{y}{w} \leq +1$$

$$0 \leq \frac{z}{w} \leq +1$$

but consider that $(-x, -y, -z, -w)$ also satisfies these bounds.

The division by w loses (sign) info! We can't allow that!

This works:

$$-w \leq x \leq +w$$

$$-w \leq y \leq +w$$

$$0 \leq z \leq +w$$

Eye position and plane

P is perspective matrix, M is any viewing matrix

M : maps world \rightarrow eye coordinate systems

P : maps eye \rightarrow projection coordinate systems

so the inverses map as follows

M^{-1} : maps eye \rightarrow world coordinate systems

P^{-1} : maps projection \rightarrow eye coordinate systems

Eye Position:

Eye position in eye C.S. is the origin $(0,0,0,1)^T$

so $M^{-1}(0,0,0,1)^T$ is the eye position in world C.S.,

and the eye position in projection C.S. is $P(0,0,0,1)^T = (0,0,-1,0)^T$,

which is infinity along the -z axis.

Eye Plane:

Eye plane in eye CS is $z=0$. In plane equation form this is

$$\begin{bmatrix} 0 & 0 & 1 & 0 \end{bmatrix} \begin{bmatrix} x & y & z & 1 \end{bmatrix}^T = 0$$

A slight manipulation with the identity matrix (in the form $M M^{-1}$) gives

$$\begin{bmatrix} 0 & 0 & 1 & 0 \end{bmatrix} M M^{-1} \begin{bmatrix} x & y & z & 1 \end{bmatrix}^T = 0$$

which can be interpreted as a plane equation where

$$M^{-1} \begin{bmatrix} x & y & z & 1 \end{bmatrix}^T$$

is a point in world coordinates, and so

$$\begin{bmatrix} 0 & 0 & 1 & 0 \end{bmatrix} M$$

must be a plane **IN WORLD COORDS**

Stereo projections

Require a shear before projection:

x_e is the eye's offset in the x direction

x_s is the screen center's offset in the x direction

$$\begin{bmatrix} 1 & 0 & \frac{x_e - x_s}{d} & -x_e \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

Ways to present stereo images:

Side-by-side

- cross-eyed
- wall-eyed aka parallel-eyed
- end-on-mirror
- double mirror system
- head mounted display
- stereo viewer aka transparency viewer

3D glasses

- prismatic & self-masking crossview glasses
- red-blue glasses (actually red-cyan) aka anaglyph
- linearly polarized glasses and a silvered screen
- circularly polarized glasses
- flicker with synchronized glasses aka alternate frame sequencing
- interference filter (infitec) glasses
- ColorCode 3D

other

- lenticular sheet
- parallax barrier
- varifocal lens