

# FAST AVERAGE CASE CONNECTIVITY ALGORITHMS ON RANDOM GRAPHS

---

Saurav Shekhar

Supervisor: Prof. Surender Baswana

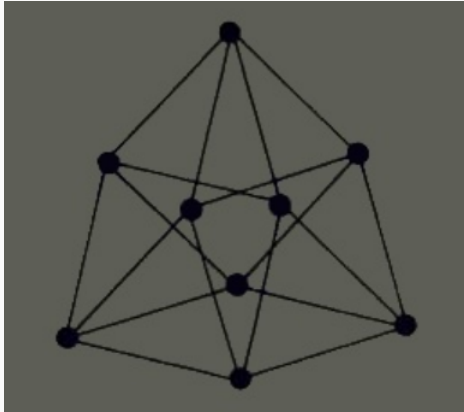
November 13, 2015

IIT Kanpur

## PRELIMINARIES

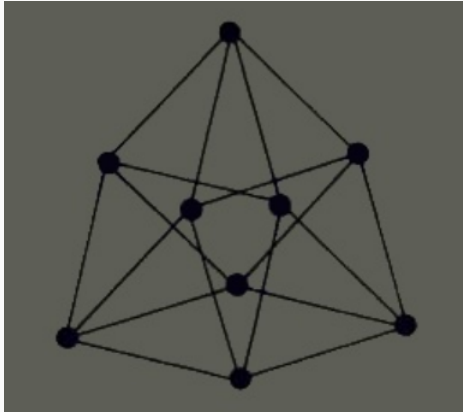
---

# WHAT ARE RANDOM GRAPHS



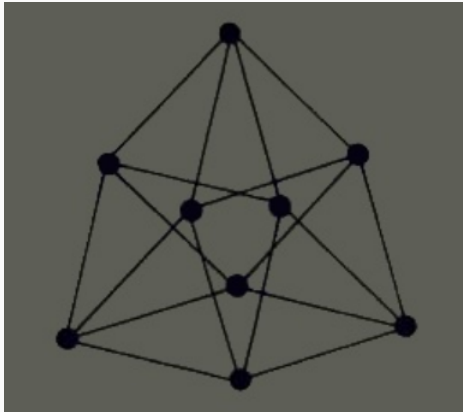
- Probability distribution over Graphs

# WHAT ARE RANDOM GRAPHS



- Probability distribution over Graphs
- Two major models,  $G(n, m)$  and  $G(n, p)$

# WHAT ARE RANDOM GRAPHS



- Probability distribution over Graphs
- Two major models,  $G(n, m)$  and  $G(n, p)$
- Entities(vertices and edges) independent of each other

Derived by Erdős and Rényi [2]. As edge probability  $p$  increases

- If  $p < \frac{1}{n}$ , all connected components of the graph will be of size  $O(\log n)$  **whp**

Derived by Erdős and Rényi [2]. As edge probability  $p$  increases

- If  $p < \frac{1}{n}$ , all connected components of the graph will be of size  $O(\log n)$  **whp**
- If  $p > \frac{1}{n}$ , the graph will have a giant component of size  $O(n)$  **whp**

Derived by Erdős and Rényi [2]. As edge probability  $p$  increases

- If  $p < \frac{1}{n}$ , all connected components of the graph will be of size  $O(\log n)$  **whp**
- If  $p > \frac{1}{n}$ , the graph will have a giant component of size  $O(n)$  **whp**
- If  $p < \frac{(1-\epsilon) \ln n}{n}$ , the graph will be disconnected **whp**



Derived by Erdős and Rényi [2]. As edge probability  $p$  increases

- If  $p < \frac{1}{n}$ , all connected components of the graph will be of size  $O(\log n)$  **whp**
- If  $p > \frac{1}{n}$ , the graph will have a giant component of size  $O(n)$  **whp**
- If  $p < \frac{(1-\epsilon) \ln n}{n}$ , the graph will be disconnected **whp**
- If  $p > \frac{(1+\epsilon) \ln n}{n}$ , the graph will be connected **whp**

- Proofs using counting / Branching models

- Proofs using counting / Branching models
- Krivelevich and Sudakov [3] gave a very simple proof of first two results using DFS.

- Proofs using counting / Branching models
- Krivelevich and Sudakov [3] gave a very simple proof of first two results using DFS.

DFS: 3 sets of vertices, set  $S$  (visited vertices),  $T$  (unvisited vertices)  $U = V \setminus (S \cup T)$  has 'visiting' vertices. Vertices in  $U$  form a stack.

- Proofs using counting / Branching models
- Krivelevich and Sudakov [3] gave a very simple proof of first two results using DFS.

DFS: 3 sets of vertices, set  $S$  (visited vertices),  $T$  (unvisited vertices)  $U = V \setminus (S \cup T)$  has 'visiting' vertices. Vertices in  $U$  form a stack. In each round

- If  $U$  is empty, choose the first vertex from  $T$  and push it into  $U$

- Proofs using counting / Branching models
- Krivelevich and Sudakov [3] gave a very simple proof of first two results using DFS.

DFS: 3 sets of vertices, set  $S$  (visited vertices),  $T$  (unvisited vertices)  $U = V \setminus (S \cup T)$  has 'visiting' vertices. Vertices in  $U$  form a stack. In each round

- If  $U$  is empty, choose the first vertex from  $T$  and push it into  $U$
- Else, the algorithm picks the top vertex  $u$  from the stack and scans  $T$ . On finding the first neighbor  $v$  of  $u$  in  $T$ , algorithm removes  $u$  from  $T$  and pushes it on top of  $U$

- Proofs using counting / Branching models
- Krivelevich and Sudakov [3] gave a very simple proof of first two results using DFS.

DFS: 3 sets of vertices, set  $S$  (visited vertices),  $T$  (unvisited vertices)  $U = V \setminus (S \cup T)$  has 'visiting' vertices. Vertices in  $U$  form a stack. In each round

- If  $U$  is empty, choose the first vertex from  $T$  and push it into  $U$
- Else, the algorithm picks the top vertex  $u$  from the stack and scans  $T$ . On finding the first neighbor  $v$  of  $u$  in  $T$ , algorithm removes  $u$  from  $T$  and pushes it on top of  $U$
- If  $u$  does not have a neighbor in  $T$ , pop  $u$  from  $U$  and insert it into  $S$
- Query all remaining edges after  $U \cup T = \emptyset$

- As long as  $U$  does not go empty, all vertices pushed into  $U$  belong to same connected component



- As long as  $U$  does not go empty, all vertices pushed into  $U$  belong to same connected component
- At each round either a vertex moves either from  $T$  to  $U$ , or from  $U$  to  $S$

- As long as  $U$  does not go empty, all vertices pushed into  $U$  belong to same connected component
- At each round either a vertex moves either from  $T$  to  $U$ , or from  $U$  to  $S$
- At any stage of the algorithm, there are no edges between current  $S$  and current  $T$

- As long as  $U$  does not go empty, all vertices pushed into  $U$  belong to same connected component
- At each round either a vertex moves either from  $T$  to  $U$ , or from  $U$  to  $S$
- At any stage of the algorithm, there are no edges between current  $S$  and current  $T$

We can map each query to a Bernoulli random variable with parameter  $p$ .

- As long as  $U$  does not go empty, all vertices pushed into  $U$  belong to same connected component
- At each round either a vertex moves either from  $T$  to  $U$ , or from  $U$  to  $S$
- At any stage of the algorithm, there are no edges between current  $S$  and current  $T$

We can map each query to a Bernoulli random variable with parameter  $p$ . Then the graph obtained is in  $G(n, p)$ .

- As long as  $U$  does not go empty, all vertices pushed into  $U$  belong to same connected component
- At each round either a vertex moves either from  $T$  to  $U$ , or from  $U$  to  $S$
- At any stage of the algorithm, there are no edges between current  $S$  and current  $T$

We can map each query to a Bernoulli random variable with parameter  $p$ . Then the graph obtained is in  $G(n, p)$ .

We can study the component structure using the properties of

$$\bar{X} = (X_i)_{i=1}^N$$

## Important Insights

- For small  $p$ , we will not get enough positive query results ( $> k$  where  $k = O(\log n)$ ) in a small interval  $kn$  so all components will be small in size ( $O(\log n)$ )

## Important Insights

- For small  $p$ , we will not get enough positive query results ( $> k$  where  $k = O(\log n)$ ) in a small interval  $kn$  so all components will be small in size ( $O(\log n)$ )
- For  $p$  above threshold, after some  $N_0$  time there will exist an interval of atleast a given length such that set  $U$  will not become empty during that interval

## Important Insights

- For small  $p$ , we will not get enough positive query results ( $> k$  where  $k = O(\log n)$ ) in a small interval  $kn$  so all components will be small in size ( $O(\log n)$ )
- For  $p$  above threshold, after some  $N_0$  time there will exist an interval of atleast a given length such that set  $U$  will not become empty during that interval  
Why not empty ?



## Important Insights

- For small  $p$ , we will not get enough positive query results ( $> k$  where  $k = O(\log n)$ ) in a small interval  $kn$  so all components will be small in size ( $O(\log n)$ )
- For  $p$  above threshold, after some  $N_0$  time there will exist an interval of atleast a given length such that set  $U$  will not become empty during that interval  
Why not empty ?
- $|S||T|$  will become much higher than expected no. of non-edges

## Important Insights

- For small  $p$ , we will not get enough positive query results ( $> k$  where  $k = O(\log n)$ ) in a small interval  $kn$  so all components will be small in size ( $O(\log n)$ )
- For  $p$  above threshold, after some  $N_0$  time there will exist an interval of atleast a given length such that set  $U$  will not become empty during that interval  
Why not empty ?
- $|S||T|$  will become much higher than expected no. of non-edges  
Giant component is formed in this continuous interval.

## ALGORITHM OUTLINE

---

- Input graph with  $n$  vertices and  $m$  edges, in  $G(n, m)$ . Randomly permuted adjacency lists

- Input graph with  $n$  vertices and  $m$  edges, in  $G(n, m)$ . Randomly permuted adjacency lists
- For finding the connected component structure, it suffices to exhaust all edges in all except one component and explore enough edges in the remaining component so that we know it is connected

- Input graph with  $n$  vertices and  $m$  edges, in  $G(n, m)$ . Randomly permuted adjacency lists
- For finding the connected component structure, it suffices to exhaust all edges in all except one component and explore enough edges in the remaining component so that we know it is connected
- Remaining component large enough, will have to look at fewer edges

- Input graph with  $n$  vertices and  $m$  edges, in  $G(n, m)$ . Randomly permuted adjacency lists
- For finding the connected component structure, it suffices to exhaust all edges in all except one component and explore enough edges in the remaining component so that we know it is connected
- Remaining component large enough, will have to look at fewer edges

Giant Component ?

- Two Stages, first sampling (find giant component)



- Two Stages, first sampling (find giant component)
- Second, elements not in the giant component grouped into components

---

## Algorithm 1 Connected Components

---

**procedure** STAGE I( $G$ )

Let  $E_0 = \phi$

**while**  $E_0 \neq E$  **do**

Let  $D = \phi$

**if**  $|E - E_0| < n$  **then**

$D = E - E_0$

**else**

$D \leftarrow n$  distinct randomly selected edges from  $E - E_0$

**end if**

Use DFS to find connected components of  $G_0 = (V, E_0)$

**if** There exists a connected component in  $G_0$  of size  $> \theta n$

**then**

STAGE II

**return**

**end if**

**end while**

**return**

**end procedure**

---

## Algorithm 2 Connected Components

---

**procedure** STAGE II( $G$ )

Mark vertices of 'Giant component' as 'giant' and remaining as unmarked

**for**  $v \in \sigma$  **do**

**if**  $v$  is unmarked **then**

        Start DFS from vertex  $v$

**if** An edge leading to a giant vertex is found **then**

            Abort dfs and mark all vertices explored as 'giant'

**else**

            Mark all vertices visited as a new component

**end if**

**end if**

**end for**

**end procedure**

---

## AVERAGE CASE RUNTIME ANALYSIS

---

Theorem 9b in [2]

Let  $\varrho_{n,N}$  denote the size of the greatest component of  $\Gamma_{n,N}$ . If  $N(n) \sim cn$  where  $c > \frac{1}{2}$  we have for any  $\eta > 0$

$$\lim_{n \rightarrow +\infty} \mathcal{P} \left( \left| \frac{\varrho_{n,N(n)}}{n} - G(c) \right| < \eta \right) = 1$$

where  $G(c) = 1 - \frac{x(c)}{2c}$  and  $x(c) = \sum_{k=1}^{\infty} \frac{k^{k-1}}{k!} (2ce^{-2c})^k$  is the solution satisfying satisfying  $0 < x(c) < 1$  of the equation  $x(c)e^{-x(c)} = 2ce^{-2c}$ .

Theorem 9b in [2]

Let  $\varrho_{n,N}$  denote the size of the greatest component of  $\Gamma_{n,N}$ . If  $N(n) \sim cn$  where  $c > \frac{1}{2}$  we have for any  $\eta > 0$

$$\lim_{n \rightarrow +\infty} \mathcal{P} \left( \left| \frac{\varrho_{n,N(n)}}{n} - G(c) \right| < \eta \right) = 1$$

where  $G(c) = 1 - \frac{x(c)}{2c}$  and  $x(c) = \sum_{k=1}^{\infty} \frac{k^{k-1}}{k!} (2ce^{-2c})^k$  is the solution satisfying  $0 < x(c) < 1$  of the equation  $x(c)e^{-x(c)} = 2ce^{-2c}$ .

For a random graph  $G$  with  $n$  vertices and  $n$  edges, there is a constant  $\theta > 1/2$  such that **whp** there is a component in  $G$  with at least  $\theta n$  vertices

- $p_{in}$  be the probability that giant component exists in a random graph with  $n$  vertices and  $in$  edges.  $p_{in} > p_{(i-1)n}$

- $p_{in}$  be the probability that giant component exists in a random graph with  $n$  vertices and  $in$  edges.  $p_{in} > p_{(i-1)n}$
- Probability that STAGE I takes  $i$  rounds is



- $p_{in}$  be the probability that giant component exists in a random graph with  $n$  vertices and  $in$  edges.  $p_{in} > p_{(i-1)n}$
- Probability that STAGE I takes  $i$  rounds is

$$\begin{aligned}\mathcal{P}(i) &= (1 - p_n)(1 - p_{2n})(1 - p_{3n}) \dots (1 - p_{(i-1)n})p_{in} \\ &< (1 - p_n)(1 - p_n)(1 - p_n) \dots (1 - p_n)1 \\ &= (1 - p_n)^{i-1}\end{aligned}$$

- $p_{in}$  be the probability that giant component exists in a random graph with  $n$  vertices and  $in$  edges.  $p_{in} > p_{(i-1)n}$
- Probability that STAGE I takes  $i$  rounds is

$$\begin{aligned}\mathcal{P}(i) &= (1 - p_n)(1 - p_{2n})(1 - p_{3n}) \dots (1 - p_{(i-1)n})p_{in} \\ &< (1 - p_n)(1 - p_n)(1 - p_n) \dots (1 - p_n)1 \\ &= (1 - p_n)^{i-1}\end{aligned}$$

- In the  $j^{\text{th}}$  step, number of edges are  $nj$ . If we do a naive brute force each time, the total time taken is  $O(\sum_{j=1}^i nj) = O(ni^2)$

- $p_{in}$  be the probability that giant component exists in a random graph with  $n$  vertices and  $in$  edges.  $p_{in} > p_{(i-1)n}$
- Probability that STAGE I takes  $i$  rounds is

$$\begin{aligned}\mathcal{P}(i) &= (1 - p_n)(1 - p_{2n})(1 - p_{3n}) \dots (1 - p_{(i-1)n})p_{in} \\ &< (1 - p_n)(1 - p_n)(1 - p_n) \dots (1 - p_n)1 \\ &= (1 - p_n)^{i-1}\end{aligned}$$

- In the  $j^{\text{th}}$  step, number of edges are  $nj$ . If we do a naive brute force each time, the total time taken is  $O(\sum_{j=1}^i nj) = O(ni^2)$
- Improve it by ‘remembering’ the connected component data found in previous round

Anyway, expected runtime is

Anyway, expected runtime is

$$O\left(\sum_{i=1}^{\infty} ni^2(1-p_n)^{i-1}\right) = O\left(\frac{n}{p_n^3}\right) = O(n) \text{ as } n \rightarrow \infty$$

### Stage II

- Typical step consists of examining some entry  $w$  in **adj**( $v$ )

### Stage II

- Typical step consists of examining some entry  $w$  in **adj**( $v$ )
- Edges not incident on giant component being explored one by one

### Stage II

- Typical step consists of examining some entry  $w$  in **adj**( $v$ )
- Edges not incident on giant component being explored one by one
- Probability of finding a giant component vertex increases



### Stage II

- Typical step consists of examining some entry  $w$  in **adj**( $v$ )
- Edges not incident on giant component being explored one by one
- Probability of finding a giant component vertex increases
- If all vertices equally likely,  $p(\text{encountering giant comp vertex}) = \theta n / (n - 1) \geq \theta$

### Stage II

- Typical step consists of examining some entry  $w$  in **adj**( $v$ )
- Edges not incident on giant component being explored one by one
- Probability of finding a giant component vertex increases
- If all vertices equally likely,  $p(\text{encountering giant comp vertex}) = \theta n / (n - 1) \geq \theta$
- All vertices not equally likely

## Lemma

*Let  $C_0$  be the giant component vertex set in  $G_0$  found during Stage I of the algorithm. Whenever an entry  $w \in \text{adj}(v)$  is examined, the probability that  $w \in C_0$ , given that  $\{v, w\} \notin E_0$  is  $\geq \theta$ .*

- For any vertex  $v$ , the number entries  $w \in \mathbf{adj}(v)$  examined such that  $w \in C_0$  is  $\leq 1$

## Lemma

*Let  $C_0$  be the giant component vertex set in  $G_0$  found during Stage I of the algorithm. Whenever an entry  $w \in \text{adj}(v)$  is examined, the probability that  $w \in C_0$ , given that  $\{v, w\} \notin E_0$  is  $\geq \theta$ .*

- For any vertex  $v$ , the number entries  $w \in \mathbf{adj}(v)$  examined such that  $w \in C_0$  is  $\leq 1$
- For  $\{v, w\} \notin E_0$ , probability that  $w$  is in  $C_0$  is  $\geq \theta$

## Lemma

*Let  $C_0$  be the giant component vertex set in  $G_0$  found during Stage I of the algorithm. Whenever an entry  $w \in \text{adj}(v)$  is examined, the probability that  $w \in C_0$ , given that  $\{v, w\} \notin E_0$  is  $\geq \theta$ .*

- For any vertex  $v$ , the number entries  $w \in \text{adj}(v)$  examined such that  $w \in C_0$  is  $\leq 1$
- For  $\{v, w\} \notin E_0$ , probability that  $w$  is in  $C_0$  is  $\geq \theta$
- Expected number of  $w$  examined where  $\{v, w\} \notin E_0$  is  $\leq 1/\theta$

### Lemma

*Let  $C_0$  be the giant component vertex set in  $G_0$  found during Stage I of the algorithm. Whenever an entry  $w \in \text{adj}(v)$  is examined, the probability that  $w \in C_0$ , given that  $\{v, w\} \notin E_0$  is  $\geq \theta$ .*

- For any vertex  $v$ , the number entries  $w \in \text{adj}(v)$  examined such that  $w \in C_0$  is  $\leq 1$
- For  $\{v, w\} \notin E_0$ , probability that  $w$  is in  $C_0$  is  $\geq \theta$
- Expected number of  $w$  examined where  $\{v, w\} \notin E_0$  is  $\leq 1/\theta$
- Summing over all  $v \in V$ , expected number of edges examined in Stage II is  $O(n/\theta) = O(n)$

- Consider  $k^{th}$  examination in Stage II

- Consider  $k^{th}$  examination in Stage II
- Edges examined :  $E_0$  and  $\alpha = (v_1, w_1), \dots (v_{k-1}, w_{k-1})$



- Consider  $k^{th}$  examination in Stage II
- Edges examined :  $E_0$  and  $\alpha = (v_1, w_1), \dots (v_{k-1}, w_{k-1})$
- $i^{th}$  edge examination selects  $w_i$  from  $adj(v_i)$

- Consider  $k^{th}$  examination in Stage II
- Edges examined :  $E_0$  and  $\alpha = (v_1, w_1), \dots (v_{k-1}, w_{k-1})$
- $i^{th}$  edge examination selects  $w_i$  from  $adj(v_i)$

Let  $\hat{G} = (V, \hat{E})$  where  $\hat{E} = E - E_0$  be the 'residual graph' at end of Stage I

- Consider  $k^{th}$  examination in Stage II
- Edges examined :  $E_0$  and  $\alpha = (v_1, w_1), \dots (v_{k-1}, w_{k-1})$
- $i^{th}$  edge examination selects  $w_i$  from  $adj(v_i)$

Let  $\hat{G} = (V, \hat{E})$  where  $\hat{E} = E - E_0$  be the 'residual graph' at end of Stage I

1.  $|\hat{E}| = m - |E_0|$

- Consider  $k^{th}$  examination in Stage II
- Edges examined :  $E_0$  and  $\alpha = (v_1, w_1), \dots (v_{k-1}, w_{k-1})$
- $i^{th}$  edge examination selects  $w_i$  from  $adj(v_i)$

Let  $\hat{G} = (V, \hat{E})$  where  $\hat{E} = E - E_0$  be the 'residual graph' at end of Stage I

1.  $|\hat{E}| = m - |E_0|$
2.  $\hat{E} \cap E_0 = \phi$

- Consider  $k^{th}$  examination in Stage II
- Edges examined :  $E_0$  and  $\alpha = (v_1, w_1), \dots (v_{k-1}, w_{k-1})$
- $i^{th}$  edge examination selects  $w_i$  from  $adj(v_i)$

Let  $\hat{G} = (V, \hat{E})$  where  $\hat{E} = E - E_0$  be the 'residual graph' at end of Stage I

1.  $|\hat{E}| = m - |E_0|$
2.  $\hat{E} \cap E_0 = \phi$

Given  $\hat{G}, E_0$  the probability that algorithm produces trace  $\alpha$  is denoted by  $p(\alpha|\hat{G}, E_0)$ .  $\alpha$  satisfies the following condition:

- Consider  $k^{th}$  examination in Stage II
- Edges examined :  $E_0$  and  $\alpha = (v_1, w_1), \dots (v_{k-1}, w_{k-1})$
- $i^{th}$  edge examination selects  $w_i$  from  $adj(v_i)$

Let  $\hat{G} = (V, \hat{E})$  where  $\hat{E} = E - E_0$  be the 'residual graph' at end of Stage I

1.  $|\hat{E}| = m - |E_0|$
2.  $\hat{E} \cap E_0 = \phi$

Given  $\hat{G}, E_0$  the probability that algorithm produces trace  $\alpha$  is denoted by  $p(\alpha|\hat{G}, E_0)$ .  $\alpha$  satisfies the following condition:

3. If  $(v_i, w_i)$  occurs in  $\alpha$ , then  $\{v_i, w_i\} \in E_0 \cup \hat{E}$

- Consider  $k^{th}$  examination in Stage II
- Edges examined :  $E_0$  and  $\alpha = (v_1, w_1), \dots (v_{k-1}, w_{k-1})$
- $i^{th}$  edge examination selects  $w_i$  from  $adj(v_i)$

Let  $\hat{G} = (V, \hat{E})$  where  $\hat{E} = E - E_0$  be the 'residual graph' at end of Stage I

1.  $|\hat{E}| = m - |E_0|$
2.  $\hat{E} \cap E_0 = \phi$

Given  $\hat{G}, E_0$  the probability that algorithm produces trace  $\alpha$  is denoted by  $p(\alpha | \hat{G}, E_0)$ .  $\alpha$  satisfies the following condition:

3. If  $(v_i, w_i)$  occurs in  $\alpha$ , then  $\{v_i, w_i\} \in E_0 \cup \hat{E}$

Let  $S$  denote set of all graphs which satisfy (1) - (3)

Consider the  $i^{\text{th}}$  examination.



Consider the  $i^{th}$  examination.

- $v_i$  will be uniquely determined by  $E_0$  and  $(v_1, w_1), (v_2, w_2), \dots (v_{i-1}, w_{i-1})$

Consider the  $i^{\text{th}}$  examination.

- $v_i$  will be uniquely determined by  $E_0$  and  $(v_1, w_1), (v_2, w_2), \dots, (v_{i-1}, w_{i-1})$
- Let  $b_i$  edges incident on  $v_i$  be selected in  $E_0$

Consider the  $i^{th}$  examination.

- $v_i$  will be uniquely determined by  $E_0$  and  $(v_1, w_1), (v_2, w_2), \dots (v_{i-1}, w_{i-1})$
- Let  $b_i$  edges incident on  $v_i$  be selected in  $E_0$
- If  $a_i$  vertices have already been selected from  $\mathbf{adj}(v_i)$  and  $d(v_i, G)$  denotes the degree of  $v_i$  in graph  $G$ ,

## PROOF OF LEMMA

Consider the  $i^{th}$  examination.

- $v_i$  will be uniquely determined by  $E_0$  and  $(v_1, w_1), (v_2, w_2), \dots (v_{i-1}, w_{i-1})$
- Let  $b_i$  edges incident on  $v_i$  be selected in  $E_0$
- If  $a_i$  vertices have already been selected from  $\mathbf{adj}(v_i)$  and  $d(v_i, G)$  denotes the degree of  $v_i$  in graph  $G$ ,

$$\begin{aligned}\mathcal{P}(w_i | E_0, \dots (v_{i-1}, w_{i-1})) &= \frac{1}{d(v_i, G) - a_i} \\ \Rightarrow \mathcal{P}((v_i, w_i) | \hat{G}, E_0, \dots (v_{i-1}, w_{i-1})) &= \frac{1}{d(v_i, G) - a_i} = \frac{1}{d(v_i, \hat{G}) - a_i + b_i} \\ \Rightarrow p(\alpha | \hat{G}, E_0) &= \prod_{i=1}^{k-1} \frac{1}{d(v_i, \hat{G}) - a_i + b_i} \quad (1)\end{aligned}$$

Consider the  $i^{th}$  examination.

- $v_i$  will be uniquely determined by  $E_0$  and  $(v_1, w_1), (v_2, w_2), \dots (v_{i-1}, w_{i-1})$
- Let  $b_i$  edges incident on  $v_i$  be selected in  $E_0$
- If  $a_i$  vertices have already been selected from  $\mathbf{adj}(v_i)$  and  $d(v_i, G)$  denotes the degree of  $v_i$  in graph  $G$ ,

$$\begin{aligned}
 \mathcal{P}(w_i | E_0, \dots (v_{i-1}, w_{i-1})) &= \frac{1}{d(v_i, G) - a_i} \\
 \Rightarrow \mathcal{P}((v_i, w_i) | \hat{G}, E_0, \dots (v_{i-1}, w_{i-1})) &= \frac{1}{d(v_i, G) - a_i} = \frac{1}{d(v_i, \hat{G}) - a_i + b_i} \\
 \Rightarrow p(\alpha | \hat{G}, E_0) &= \prod_{i=1}^{k-1} \frac{1}{d(v_i, \hat{G}) - a_i + b_i} \quad (1)
 \end{aligned}$$

Note that the function is decreasing with  $d(v_i, \hat{G})$ . Define function  $f_{u,\alpha}$  by

Note that the function is decreasing with  $d(v_i, \hat{G})$ . Define function  $f_{u,\alpha}$  by

$$f_{u,\alpha}(d(u, \hat{G})) = \prod_{i, v_i=u} \frac{1}{d(v_i, \hat{G}) - a_i + b_i}$$

Note that the function is decreasing with  $d(v_i, \hat{G})$ . Define function  $f_{u,\alpha}$  by

$$f_{u,\alpha}(d(u, \hat{G})) = \prod_{i, v_i=u} \frac{1}{d(v_i, \hat{G}) - a_i + b_i}$$

We can now write

$$p(\alpha|\hat{G}, E_0) = \prod_{u \in V - C_0} f_{u,\alpha}(d(u, \hat{G})) \quad (2)$$



We've

$p(\hat{G}|E_0)$  is constant ( $= \frac{1}{\binom{N-|E_0|}{m-|E_0|}}$ ). Using Baye's theorem,

We've

$p(\hat{G}|E_0)$  is constant ( $= \frac{1}{\binom{N-|E_0|}{m-|E_0|}}$ ). Using Baye's theorem,

$$\begin{aligned}
 p(\hat{G}|\alpha, E_0) &= \frac{p(\alpha|\hat{G}, E_0)p(\hat{G}|E_0)}{p(\alpha|E_0)} \\
 \Rightarrow p(\hat{G}|\alpha, E_0) &= c \prod_{u \in V - C_0} f_{u,\alpha}(d(u, \hat{G}))
 \end{aligned} \tag{3}$$

After  $\alpha$  has occurred, we are choosing  $w_k \in \mathbf{adj}(v_k)$

After  $\alpha$  has occurred, we are choosing  $w_k \in \mathbf{adj}(v_k)$

- Call  $w_k$  eligible if  $w_k \neq v_k$ ,  $\mathbf{adj}(w_k)$  is not exhausted and  $\{v_k, w_k\} \notin E_0$

After  $\alpha$  has occurred, we are choosing  $w_k \in \mathbf{adj}(v_k)$

- Call  $w_k$  eligible if  $w_k \neq v_k$ ,  $\mathbf{adj}(w_k)$  is not exhausted and  $\{v_k, w_k\} \notin E_0$
- Let  $x \in C_0$ , we'll show  $\mathcal{P}(w_k = x | w_k \text{ is eligible}) \geq 1/(n-1)$

For a positive integer  $d$

For a positive integer  $d$

- let  $G_d = \{\hat{G} \in S \mid d(v_k, \hat{G}) = d\}$

For a positive integer  $d$

- let  $G_d = \{\hat{G} \in S \mid d(v_k, \hat{G}) = d\}$
- Define  $G_{d+} = G_d \cap \{\hat{G} = (V, \hat{E} \mid \{v_k, x\} \in \hat{E})\}$



For a positive integer  $d$

- let  $G_d = \{\hat{G} \in S \mid d(v_k, \hat{G}) = d\}$
- Define  $G_{d+} = G_d \cap \{\hat{G} = (V, \hat{E} \mid \{v_k, x\} \in \hat{E})\}$
- And  $G_{d-} = G_d \setminus G_{d+}$

For a positive integer  $d$

- let  $G_d = \{\hat{G} \in S \mid d(v_k, \hat{G}) = d\}$
- Define  $G_{d+} = G_d \cap \{\hat{G} = (V, \hat{E} \mid \{v_k, x\} \in \hat{E})\}$
- And  $G_{d-} = G_d \setminus G_{d+}$
- Define relation  $R$  on  $G_{d+} \times G_{d-}$  by  $(H_1, H_2) \in R$  iff  $H_1 \in G_{d+}$ ,  $H_2 \in G_{d-}$  and  $H_2$  is obtained from  $H_1$  by deleting edge  $\{v_k, x\}$  and adding some other edge  $\{v_k, x'\}$  incident to  $v_k$  such that  $x'$  is eligible.

- If  $(H_1, H_2) \in R$  then in going from  $H_1$  to  $H_2$ , we remove  $\{v_k, x\}$  and add  $\{v_k, x'\}$ . If  $x' \in C_0$  then  $p(\hat{G}|\alpha, E_0)$  remains the same. If  $x' \notin C_0$  then  $d(x', \hat{G})$  increases, decreasing  $p(\hat{G}|\alpha, E_0)$ . This implies,  
$$p(H_1|\alpha, E_0) \geq p(H_2|\alpha, E_0)$$

- If  $(H_1, H_2) \in R$  then in going from  $H_1$  to  $H_2$ , we remove  $\{v_k, x\}$  and add  $\{v_k, x'\}$ . If  $x' \in C_0$  then  $p(\hat{G}|\alpha, E_0)$  remains the same. If  $x' \notin C_0$  then  $d(x', \hat{G})$  increases, decreasing  $p(\hat{G}|\alpha, E_0)$ . This implies,  

$$p(H_1|\alpha, E_0) \geq p(H_2|\alpha, E_0)$$
- Fixing  $H_1$ , we have  $\leq (n - 1 - d)$  options for  $x'$  ( $x'$  must be eligible). Thus for fixed  $H_1$  we have the atmost  $(n - 1 - d)H_2$ .

- If  $(H_1, H_2) \in R$  then in going from  $H_1$  to  $H_2$ , we remove  $\{v_k, x\}$  and add  $\{v_k, x'\}$ . If  $x' \in C_0$  then  $p(\hat{G}|\alpha, E_0)$  remains the same. If  $x' \notin C_0$  then  $d(x', \hat{G})$  increases, decreasing  $p(\hat{G}|\alpha, E_0)$ . This implies,  

$$p(H_1|\alpha, E_0) \geq p(H_2|\alpha, E_0)$$
- Fixing  $H_1$ , we have  $\leq (n - 1 - d)$  options for  $x'$  ( $x'$  must be eligible). Thus for fixed  $H_1$  we have the atmost  $(n - 1 - d)H_2$ .
- For fixed  $H_2$ , we can replace  $d$  of them with  $x$ . Thus, there are  $d$  graphs  $H_1$  with  $(H_1, H_2) \in R$

- If  $(H_1, H_2) \in R$  then in going from  $H_1$  to  $H_2$ , we remove  $\{v_k, x\}$  and add  $\{v_k, x'\}$ . If  $x' \in C_0$  then  $p(\hat{G}|\alpha, E_0)$  remains the same. If  $x' \notin C_0$  then  $d(x', \hat{G})$  increases, decreasing  $p(\hat{G}|\alpha, E_0)$ . This implies,  

$$p(H_1|\alpha, E_0) \geq p(H_2|\alpha, E_0)$$
- Fixing  $H_1$ , we have  $\leq (n - 1 - d)$  options for  $x'$  ( $x'$  must be eligible). Thus for fixed  $H_1$  we have the atmost  $(n - 1 - d)H_2$ .
- For fixed  $H_2$ , we can replace  $d$  of them with  $x$ . Thus, there are  $d$  graphs  $H_1$  with  $(H_1, H_2) \in R$

Sum over  $p(H_1|\alpha, E_0) \geq p(H_2|\alpha, E_0)$  over all pairs  $(H_1, H_2) \in R$

Sum over  $p(H_1|\alpha, E_0) \geq p(H_2|\alpha, E_0)$  over all pairs  $(H_1, H_2) \in R$

$$\begin{aligned}
 (n-1-d) \sum_{H_1 \in G_{d+}} p(H_1|\alpha, E_0) &\geq d \sum_{H_2 \in G_{d-}} p(H_2|\alpha, E_0) \\
 \Rightarrow \sum_{H \in G_d} p(H|\alpha, E_0) &\geq \frac{d}{n-1} \sum_{\hat{G} \in G_d} p(\hat{G}|\alpha, E_0)
 \end{aligned}$$



Sum over  $p(H_1|\alpha, E_0) \geq p(H_2|\alpha, E_0)$  over all pairs  $(H_1, H_2) \in R$

$$\begin{aligned} (n-1-d) \sum_{H_1 \in \hat{G}_{d+}} p(H_1|\alpha, E_0) &\geq d \sum_{H_2 \in \hat{G}_{d-}} p(H_2|\alpha, E_0) \\ \Rightarrow \sum_{H \in \hat{G}_d} p(H|\alpha, E_0) &\geq \frac{d}{n-1} \sum_{\hat{G} \in \hat{G}_d} p(\hat{G}|\alpha, E_0) \end{aligned}$$

Thus, conditional probability that  $\hat{G}$  contains  $\{v_k, x\}$  is  $\geq d/(n-1)$ .

Sum over  $p(H_1|\alpha, E_0) \geq p(H_2|\alpha, E_0)$  over all pairs  $(H_1, H_2) \in R$

$$\begin{aligned} (n-1-d) \sum_{H_1 \in \hat{G}_{d+}} p(H_1|\alpha, E_0) &\geq d \sum_{H_2 \in \hat{G}_{d-}} p(H_2|\alpha, E_0) \\ \Rightarrow \sum_{H \in \hat{G}_d} p(H|\alpha, E_0) &\geq \frac{d}{n-1} \sum_{\hat{G} \in \hat{G}_d} p(\hat{G}|\alpha, E_0) \end{aligned}$$

Thus, conditional probability that  $\hat{G}$  contains  $\{v_k, x\}$  is  $\geq d/(n-1)$ .

The probability that  $w_k = x$  is  $\geq \left(\frac{1}{d}\right) \frac{d}{n-1} = \frac{1}{n-1}$

Sum over  $p(H_1|\alpha, E_0) \geq p(H_2|\alpha, E_0)$  over all pairs  $(H_1, H_2) \in R$

$$\begin{aligned} (n-1-d) \sum_{H_1 \in \hat{G}_{d+}} p(H_1|\alpha, E_0) &\geq d \sum_{H_2 \in \hat{G}_{d-}} p(H_2|\alpha, E_0) \\ \Rightarrow \sum_{H \in \hat{G}_d} p(H|\alpha, E_0) &\geq \frac{d}{n-1} \sum_{\hat{G} \in \hat{G}_d} p(\hat{G}|\alpha, E_0) \end{aligned}$$

Thus, conditional probability that  $\hat{G}$  contains  $\{v_k, x\}$  is  $\geq d/(n-1)$ .

The probability that  $w_k = x$  is  $\geq \left(\frac{1}{d}\right) \frac{d}{n-1} = \frac{1}{n-1}$

Summing over all  $x$  in  $C_0$  gives  $\mathcal{P}(w_k \in C_0) \geq \theta n / (n-1) \geq \theta$

Thus the algorithm finds all connected components of a graph with  $n$  nodes in average case  $O(n)$  time.

Future work

Thus the algorithm finds all connected components of a graph with  $n$  nodes in average case  $O(n)$  time.

Future work

We could use these techniques to analyse more algorithms.

Thus the algorithm finds all connected components of a graph with  $n$  nodes in average case  $O(n)$  time.

Future work

We could use these techniques to analyse more algorithms.

Recently Baswana et al [1] published two algorithms for maintaining the DFS tree in an incremental graph, one with complexity  $O(n^{3/2}\sqrt{m})$  and other with complexity  $O(n^2)$ .

Thus the algorithm finds all connected components of a graph with  $n$  nodes in average case  $O(n)$  time.

Future work

We could use these techniques to analyse more algorithms.

Recently Baswana et al [1] published two algorithms for maintaining the DFS tree in an incremental graph, one with complexity  $O(n^{3/2}\sqrt{m})$  and other with complexity  $O(n^2)$ .

It has been shown that on random graphs the first algorithm takes time closer to  $O(n^2\sqrt{\log n})$ . We believe that further work is possible on this and it can be reduced to  $O(n^2)$ .

I would like to thank Prof. Surender Baswana for his motivation and guidance.





Surender Baswana and Shahbaz Khan.

Incremental algorithm for maintaining dfs tree for undirected graphs.

In *Automata, Languages, and Programming*, pages 138–149. Springer Berlin Heidelberg, 2014.



Paul Erdos and Alfréd Rényi.

On the evolution of random graphs.

*Bull. Inst. Internat. Statist*, 38(4):343–347, 1961.



Benny Sudakov Michael Krivelevich.

The phase transition in random graphs - a simple proof.

THANK YOU !