## Lecture 7: Minimax Lower Bounds Part II

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In this lecture, we will study a generalization of the two-point method in which the second point is replaced with a mixture. This minor change makes this method significantly more potent in testing problems involving a "k-subset" structure and for functional estimation tasks.

## 1 Generalized Two-Point Method

As before, we are working in a decision-theoretic setting with model  $\{P_{\theta} : \theta \in \Theta\}$ , decision space  $\mathcal{W}$ , and a loss function  $L : \Theta \times \mathcal{W} \to \mathbb{R}$ .

**Theorem 1.1.** Suppose there exist  $\theta_0 \in \Theta$ , and  $\Theta_1 \subset \Theta$ , satisfying the following uniform separation condition with some  $\omega > 0$ :

$$\inf_{w \in \mathcal{W}} \inf_{\theta_1 \in \Theta_1} \frac{L(\theta_0, w) + L(\theta_1, w)}{2} \ge \omega.$$

Let  $\mu$  denote any probability measure supported on  $\Theta_1$ , and let  $P_{\mu}$  denote the mixture distribution satisfying

$$P_{\mu}(E) = \int_{\Theta_1} P_{\theta}(E) d\mu(\theta), \quad \textit{for all} \quad E \in \mathcal{F}_{\mathcal{X}}.$$

Then, we have the following lower bound:

$$R^*(\Theta, \mathcal{W}) = \inf_{P_{W|X}} \sup_{\theta \in \Theta} \mathbb{E}_{\theta} \left[ L(\theta, W) \right] \geq \omega \left( 1 - TV(P_{\theta_0}, P_{\mu}) \right).$$

Remark 1.2. Observe that the only difference from the two-point lower bound we saw in the previous lecture is that  $TV(P_{\theta_0}, P_{\theta_1})$  is replaced with  $TV(P_{\theta_0}, P_{\mu})$ . Since  $P_{\mu} = \mathbb{E}_{\theta \sim \mu}[P_{\theta}]$ , the convexity property of total variation implies that  $TV(P_{\theta_0}, P_{\mu}) \leq \mathbb{E}_{\theta_1 \sim \mu}[TV(P_{\theta_0}, P_{\theta_1})]$ . This fact hints at the use cases of Theorem 1.1 to be problems where the total variation (and other divergences) between the mixture  $P_{\mu}$  and  $P_{\theta_0}$  can be much smaller than the total variation between  $P_{\theta_0}$  and any individual  $P_{\theta}$  for  $\theta \in \Theta_1$ .

*Proof of Theorem 1.1.* Let  $\pi = \frac{1}{2} (\delta_{\theta_0} + \mu)$  denote a prior distribution over the parameter space. Then, we know that the minimax risk is always lower bounded by any Bayes risk, which implies

$$\sup_{\theta \in \Theta} R(\theta, P_{W|\mathbf{X}}) \ge R(\pi, P_{W|\mathbf{X}}) = \frac{1}{2} \left( \mathbb{E}_{\theta_0} [L(\theta_0, W)] + \mathbb{E}_{\underline{\theta} \sim \mu} [L(\underline{\theta}, W)] \right)$$

Now, we can expand the two terms in the RHS as follows (assuming densities  $p_{\theta}$ ,  $p_{\mu}$ ):

$$\mathbb{E}_{\theta_0}[L(\theta_0, W)] = \int_{\mathcal{X}} \left( \int_{\mathcal{W}} L(\theta_0, w) p_{W|\mathbf{X}}(w|x) dw \right) p_{\theta_0}(x) =: \int f_0(x) p_{\theta_0}(x) dx, \quad \text{and} \quad \mathbb{E}_{\underline{\theta} \sim \mu}[L(\underline{\theta}, W)] = \int_{\mathcal{X}} p_{\mu}(x) \left( \int_{\Theta_1} \frac{p_{\theta}(x)}{p_{\mu}(x)} \mu(\theta) \left( \int_{\mathcal{W}} L(\theta, w) p_{W|\mathbf{X}}(w|x) dw \right) d\theta \right) dx$$

$$= \int_{\mathcal{X}} p_{\mu}(x) \left( \int_{\mathcal{W}} p_{W|\mathbf{X}}(w) \left( \int_{\Theta_1} L(\theta, w) \frac{p_{\theta}(x)}{p_{\mu}(x)} \mu(\theta) d\theta \right) dw \right) dx$$

$$:= \int_{\mathcal{X}} g(x) p_{\mu}(x) dx$$

Now, observe that  $(p_{\theta}(x)\mu(\theta)/p_{\mu}(x)) = \mu(\theta|x)$  is the posterior distribution of  $\underline{\theta}$ , which implies

$$f(x) + g(x) = \int_{\mathcal{W}} p_{W|\mathbf{X}}(w|x) \left( \int_{\Theta_1} \left( L(\theta, w) + L(\theta_0, w) \right) \mu(\theta|x) d\theta \right) dw$$
$$\geq 2\omega \int_{\mathcal{W}} p_{W|\mathbf{X}}(w|x) \left( \int_{\Theta_1} \mu(\theta|x) d\theta \right) dw = 2\omega.$$

The inequality above relies on the separation assumption. Finally, this implies that

$$\sup_{\theta \in \Theta} R(\theta, P_{W|X}) \geq \frac{1}{2} \left( \int f(x) p_{\theta_0}(x) dx + \int g(x) p_{\mu}(x) dx \right) \\
\geq \frac{1}{2} \int (f(x) + g(x)) \min\{ p_{\theta_0}(x), p_{\mu}(x) \} dx \\
\geq \omega \int \min\{ p_{\theta_0}(x), p_{\mu}(x) \} dx = \omega (1 - TV(P_{\theta_0}, P_{\mu})),$$

where the last equality uses the fact that  $TV(P,Q) = 1 - \int \min\{p,q\}$ .

*Remark* 1.3. A close look at the proof suggests that the same argument would have also worked for the case of two mixtures (instead of point-vs-mixture).

## 1.1 Divergence Bound

To apply Theorem 1.1 in practice, we first need to fix  $(\theta_0, \Theta_1)$ , then select an appropriate mixture distribution  $\mu$ , and finally get an upper bound on  $TV(P_{\theta_0}, P_{\mu})$ . In most cases, it suffices to choose  $(\theta_0, \Theta_1)$  to maximize  $\omega$  (the separation) while controlling  $TV(P_{\theta_0}, P_{\mu})$  to a value less than 1/2. It turns out that for mixtures, working with chi-squared distance is most convenient, as we explain next.

For simplicity, throughout we will assume that  $P_{\theta}$  has a density  $p_{\theta}$  with respect to some common dominating measure (which we simply denote by dx). Recall that the chi-squared divergence between any pair (P,Q) with densities (p,q) is defined as

$$\chi^{2}(P \parallel Q) = \int \left(\frac{p(x)}{q(x)} - 1\right)^{2} q(x)dx = \int \frac{\left(p(x) - q(x)\right)^{2}}{q(x)}dx = \int \frac{p(x)^{2}}{q(x)}dx - 1.$$

Our next result shows why this formulation of chi-squared is useful in handling mixtures.

**Lemma 1.4.** Assume throughout that  $\int p_{\theta}(x)^2/p_{\theta_0}(x)dx < \infty$  for all  $\theta \in \Theta_1$ . Then, we have the following:

$$1 + \chi^{2}(P_{\mu}, P_{\theta_{0}}) = \mathbb{E}_{\theta, \theta' \sim \mu} \left[ \int \frac{p_{\theta}(x)p_{\theta'}(x)}{p_{\theta_{0}}(x)} dx \right] = \mathbb{E}_{\theta, \theta' \sim \mu} \left[ \int \ell_{\theta, \theta_{0}}(x)\ell_{\theta', \theta_{0}}(x)p_{\theta_{0}}(x)dx \right]$$
$$= \mathbb{E}_{\theta, \theta' \sim \mu} \left[ \langle \ell_{\theta, \theta_{0}}, \ell_{\theta', \theta_{0}} \rangle_{L^{2}(P_{\theta_{0}})} \right],$$

where  $\ell_{\theta,\theta_0}(x) = p_{\theta}(x)/p_{\theta_0}(x)$ , and we use  $\langle \cdot, \cdot \rangle_{L^2(P_{\theta_0})}$  to denote the inner product in the space of square integrable functions (w.r.t.  $P_{\theta_0}$ ).

*Proof of Lemma 1.4.* We know from the definition of chi-squared divergence that

$$1 + \chi^{2}(P_{\mu} \parallel P_{\theta_{0}}) = \int \frac{p_{\mu}(x)^{2}}{p_{\theta_{0}}(x)} dx = \int \frac{\left(\int p_{\theta}(x)d\mu(\theta)\right) \left(\int p_{\theta'}(x)d\mu(\theta')\right)}{p_{\theta_{0}(x)}} dx$$
$$= \int d\mu(\theta) \int d\mu(\theta') \int \frac{p_{\theta}(x)p_{\theta'}(x)}{p_{\theta_{0}}(x)} dx.$$

This completes the proof.

This result indicates that the chi-squared divergence between a point and a mixture distribution depends on the average "similarity" (as measured by the inner product) between two randomly drawn independent distributions according to  $\mu$ .

In many applications, we work with i.i.d. observations, and our next result shows the crucial property of tensorization which makes chi-squared divergence the appropriate choice when working with mixtures.

**Lemma 1.5.** For any  $\theta \in \Theta$ , let  $P_{\theta}^n$  denote the n-fold product measure, and for some probability measure  $\mu$  supported on  $\Theta_1$ , let  $P_{\mu}^n$  denote  $\mathbb{E}_{\underline{\theta} \sim \mu}[P_{\underline{\theta}}^n]$ . Then, with  $\kappa(\theta, \theta') := \langle \ell_{\theta,\theta_0}, \ell_{\theta',\theta_0} \rangle_{L^2(P_{\theta_0})}$ , we have the following:

$$1 + \chi^2 \left( P_{\mu}^n \parallel P_{\theta_0}^n \right) = \mathbb{E}_{\theta, \theta' \sim \mu} \left[ \kappa(\underline{\theta}, \underline{\theta'})^n \right].$$

*Proof of Lemma 1.5.* The proof is a simple consequence of the previous derivation. In particular, from Lemma 1.4, we know that

$$1 + \chi^2(P_\mu^n \parallel P_{\theta_0}^n) = \mathbb{E}_{\underline{\theta},\underline{\theta}' \sim \mu} \left[ \left\langle \frac{p_{\underline{\theta}}^n(x^n)}{p_{\theta_0}^n(x^n)}, \frac{p_{\underline{\theta}'}^n(x^n)}{p_{\theta_0}^n(x^n)} \right\rangle_{L^2(P_{\theta_0}^n)} \right].$$

Now, on expanding the inner product term, we get

$$\left\langle \frac{p_{\underline{\theta}}^{n}(x^{n})}{p_{\theta_{0}}^{n}(x^{n})}, \frac{p_{\underline{\theta}'}^{n}(x^{n})}{p_{\theta_{0}}^{n}(x^{n})} \right\rangle_{L^{2}(P_{\theta_{0}^{n}})} = \int \frac{p_{\underline{\theta}}^{n}(x^{n})p_{\underline{\theta}'}^{n}(x^{n})}{p_{\theta_{0}}^{n}(x^{n})} dx^{n}$$

$$= \int \frac{p_{\underline{\theta}}(x_{1})p_{\underline{\theta}'}(x_{1})}{p_{\theta_{0}}(x_{1})} dx_{1} \dots \int \frac{p_{\underline{\theta}}(x_{1})p_{\underline{\theta}'}(x_{1})}{p_{\theta_{0}}(x_{1})} dx_{n} = \kappa(\underline{\theta}, \underline{\theta}')^{n}.$$

This completes the proof.

Remark 1.6. The previous two lemmas tell us that the chi-squared divergence between  $P_{\mu}^{n} = \mathbb{E}_{\underline{\theta} \sim \mu}[P_{\theta}^{n}]$  and  $P_{\theta_{0}}$  is controlled by the average value of  $\kappa(\underline{\theta},\underline{\theta}')$ ; a measure of how similar two randomly drawn product distributions in  $\Theta_{1}$  are. This gives us an indication of the type of problems in which the point-vs-mixture approach is useful: if each  $\theta_{1}$  is such that  $P_{\theta_{0}}$  and  $P_{\theta_{1}}$  are quite distinct from each other, but any two  $P_{\theta_{1}}$  and  $P_{\theta'_{1}}$  are almost "orthogonal". In such cases, the two-point method would lead to a suboptimal lower bound (owing to the large distinctness between  $P_{\theta_{0}}$  and  $P_{\theta_{1}}$ ), but a mixture method may be more useful (owing to the almost orthogonality between two randomly drawn elements from  $\mu$ ).

## 2 Application: Uniformity Testing

Let us consider the hypothesis testing problem within the minimax framework. For some  $\{P_{\theta}: \theta \in \Theta\}$ , we are given n i.i.d. observations  $\boldsymbol{X} = X^n = (X_1, \dots, X_n)$  drawn from an unknown  $P_{\theta}$ . Our goal is to test between

$$H_0: \theta \in \Theta_0$$
, versus  $H_1: \theta \in \Theta_1$ , for disjoint  $\Theta_0, \Theta_1 \subset \Theta$ .

A randomized hypothesis test can be represented by a mapping  $\Psi: \mathcal{X}_n := \mathcal{X}^n \to [0,1]$ , with  $\Psi(\boldsymbol{x})$  denoting the probability of deciding that  $H_1$  is true. In other words, the decision space is  $\mathcal{W} = \{0,1\}$ , and our decision is  $W \sim \mathrm{Bernoulli}(\Psi(X^n))$ . Then, the minimax risk with the 0-1 loss is defined as

$$R_n^*(\Theta_0,\Theta_1) = \inf_{\Psi} \sup_{\theta \in \Theta_0 \cup \Theta_1} \mathbb{E}_{\theta}[\mathbf{1}_{W \neq h_{\theta}}] = \inf_{\Psi} \sup_{\theta \in \Theta_0 \cup \Theta_1} \mathbb{P}_{\theta}(W \neq h_{\theta}), \quad \text{where} \quad h_{\theta} = \mathbf{1}_{\theta \in \Theta_1}.$$

A simple instance of this problem is for the identity testing for discrete distributions. Assume that  $X_1, \ldots, X_n \overset{i.i.d.}{\sim} P_X$  for some distribution supported on a finite alphabet  $\mathcal{X}$  with  $|\mathcal{X}| = k$ , and let  $U_k$  denote the uniform distribution over  $\mathcal{X}$ . Then, for some  $\epsilon > 0$ , consider the problem:

$$H_0: P_X = U_k$$
, versus  $H_1: ||P_X - U_k||_1 \ge \epsilon$ .

Here, the parameter space is  $\Theta = \Delta_k$ , with  $\Theta_0 = \{\theta_0\}$  and  $\Theta_1 = \{\theta : \|\theta_0 - \theta\|_1 \ge \epsilon\}$ , where  $\theta_0 = (1/k, \dots, 1/k)$ . This task is called uniformity testing in the theoretical computer science literature.

**Lower Bound via Theorem 1.1.** The first step is note that the "separation condition" is satisfied with  $\omega = 1/2$ : for any  $\theta \in \Theta_1$ , we have

$$L(\theta_0, w) + L(\theta, w) = \mathbf{1}_{w=1} + \mathbf{1}_{w=0} = 1.$$

Hence, Theorem 1.1 implies that the minimax risk in this case is lower bounded by

$$R_n^*(\theta_0, \epsilon) \ge \sup_{\mu} \frac{1}{2} (1 - TV(P_{\mu}, P_{\theta_0})),$$

where  $\mu$  is any probability measure of the alternative set. We will now describe Paninski's construction of this mixture.

Assume that k is even, and pair off the coordinates into  $\{(2j-1,2j): 1 \leq j \leq k/2\}$ . let  $v = (v_1, \ldots, v_{k/2}) \in \{-1,\}^{k/2}$  be drawn i.i.d. from a Rademacher distribution (i.e.,  $\pm 1$  w.p. 1/2 each), and define

$$q_{\boldsymbol{v}} \in \Delta_k$$
, with  $q_{\boldsymbol{v}}[2j-1] = \frac{1+\epsilon v_j}{k}$ , and  $q_{\boldsymbol{v}}[2j] = \frac{1-\epsilon v_j}{k}$ , for  $j \in [k/2]$ .

It is easy to verify that each  $q_v$  lies in  $\Theta_1$ , and the mixture distribution  $\mu$  is uniformly distributed over the subset  $\{q_v : v \in \{-1,1\}^{k/2}\} \subset \Theta_1$ . Interestingly, we have  $\mathbb{E}_v[q_v] = p_{\theta_0}$ . Based on this, we can compute the chi-squared divergence as follows:

$$\kappa(\boldsymbol{v}, \boldsymbol{v}') = \sum_{i=1}^{k} \frac{q_{\boldsymbol{v}}[i]q_{\boldsymbol{v}'}[i]}{1/k} = k \sum_{j=1}^{k/2} \left( \frac{1 + \epsilon v_j}{k} \frac{1 + \epsilon v_j'}{k} + \frac{1 - \epsilon v_j}{k} \frac{1 - \epsilon v_j'}{k} \right)$$

$$= \frac{1}{k} \sum_{j=1}^{k/2} \left( 1 + \epsilon(v_j + v_j') + \epsilon^2 v_j v_j' + 1 - \epsilon(v_j + v_j') + \epsilon^2 v_j v_j' \right) = 1 + \frac{2\epsilon^2}{k} \sum_{j=1}^{k/2} v_j v_j'.$$

Now, observe that each  $s_j := v_j v_j'$  is also a Rademacher random variable. Hence, we have

$$1 + \chi^{2}(P_{\mu}^{n} \parallel P_{\theta_{0}}) = \mathbb{E}_{v,v'} \left[ \left( 1 + \frac{2\epsilon^{2}}{k} \sum_{j=1}^{k/2} s_{j} \right)^{n} \right]$$

$$\leq \mathbb{E}_{v,v'} \left[ \exp\left( \frac{2n\epsilon^{2}}{k} \sum_{j=1}^{k/2} s_{j} \right) \right] \qquad (\text{since } 1 + x \leq e^{x})$$

$$= \prod_{j=1}^{k/2} \mathbb{E} \left[ \exp\left( \frac{2n\epsilon^{2}}{k} s_{j} \right) \right] = \prod_{j=1}^{k/2} \frac{1}{2} \left( e^{2n\epsilon^{2}/k} + e^{-2n\epsilon^{2}/k} \right)$$

$$\leq \prod_{j=1}^{k/2} e^{2n^{2}\epsilon^{4}/k^{2}} \qquad (\text{since } e^{x} + e^{-x} \leq 2e^{x^{2}/2})$$

$$= e^{n^{2}\epsilon^{4}/k}$$

Thus, using the fact that  $TV(P,Q) \leq \sqrt{\chi^2(P \parallel Q)/2}$ , we get

$$R_n^*(\theta_0, \epsilon) \ge \frac{1}{2} \left( 1 - \sqrt{\frac{e^{n^2 \epsilon^4/k} - 1}{2}} \right). \tag{1}$$

**Interpreting the lower bound.** This lower bound can be used to characterize fundamental limits on either the detection boundary, or the sample complexity. In particular, suppose we wish to answer the question: For a fixed n, k, suppose we have a procedure that can achieve a minimax

risk of  $r \in (0,1)$ . Then, what is the smallest possible value of  $\epsilon \equiv \epsilon_{n,k,r}$ ? To answer this, note that (1) implies

$$\log(1+2(1+2r)^2) \le n^2 \epsilon^4/k \implies \epsilon_{n,k,r} \ge \frac{c_r k^{1/4}}{\sqrt{n}} \quad \text{for} \quad c_r = \left(\log(1+2(1+2r)^2)\right)^{1/4}.$$

This characterizes the *detection boundary*, or a lower limit on the closest alternative that can be distinguished well enough by any test. Conversely, we can also characterize the sample complexity, which is the smallest n for which there exists a procedure with a minimax risk of r (with  $\epsilon, k$  fixed). The above equation tells us that

$$n_{\epsilon,k,r} \ge \frac{c_r^2 \sqrt{k}}{\epsilon^2}.$$

The key benefit of the two point method is that it can capture the k-dependence of the detection boundary / sample complexity.

**Failure of the two-point method.** If we were to use the two-point method, then we have for any Q in the alternative class

$$\chi^2(Q^n \parallel P_{\theta_0}^n) = (1 + \chi^2(Q \parallel P_{\theta_0})^n) - 1.$$

Now, we can show that

$$\inf_{q:\|q-p_{\theta_0}\|_1 \ge \epsilon} \chi^2(q \parallel p_{\theta_0}) = \epsilon^2,$$

achieved at the pmf with equal  $\pm \epsilon$  perturbation from the uniform pmf. This gives us

$$\chi^2(Q^n \parallel P_{\theta_0}^n) \le (1 + \epsilon^2)^n - 1 \le e^{n\epsilon^2} - 1.$$

This will result in

$$\epsilon_{n,k,r} \gtrsim \frac{1}{\sqrt{n}}, \quad \text{and} \quad n_{\epsilon,k,r} \gtrsim \frac{1}{\epsilon^2},$$

thus not capturing the k dependence.

**Achievability.** One constructive approach for addressing this task is based on the so-called "collision statistic"

$$C_n = \frac{1}{\binom{n}{2}} \sum_{i \neq j} \mathbf{1}_{X_i = X_j}.$$

The idea is that in expectation the number of collisions will be the smallest under the uniform distribution, and hence we can reject the null if  $C_n$  is above an appropriately chosen threshold. We will work out the details in Homework 2.