



Script

Import libraries

Load fixed configuration parameters

Set the hyperparameters

Load the pretrained models (if necessary)

Periodically do:

`benchmark_agents.dyad_eval`

`train_agents.py`

save the results

For the duration of an episode

- observe the environment: `env.step()`, `agent.observe()`
- Take action (a) using the current policy: `agent.get_force()`
- observe the new state (s'), collect the reward (r)
- Add the experience tuple (s,a,s',r): `agent.add_experience(buffer, experience)`
- run `agent.train_step()` if it's time every few seconds