Table 44
Three-phase ac motors
(See Rules 28-010 and 28-704.)

Motor roting	Inductio	n type, squ	Induction type, squfrrel-cage	and wound rotor, A	1 rotor, A		7.	Synchron   [see Note	Synchronous type, unity power factor [see Note 3]], A	unity pow	er factor	
hp	115 V	Z00 V	208 V	230 V	460 V	575 V	2300 V	Z00 V	230 V	460 V	575 V	2300 V
1/2	4.4	2.5	2.4	2.2	Н	6.0	I	ī	ī	1	I	i
3/4	6.4	3.7	3.5	3.2	1.4	1.3	1		1		Ī	1_
Ţ	8.4	4.8	4.6	4.2	1.8	1.7				1	1	
L/ F	12.0	0	u u	C	3 6	2.4	ļ		1	1	I	1
7/1-7	12 5	2 0	) L	) o	2:5			I		1	II	J
<b>V</b>	0.61	0','	C: /	5	t (	/						
m	19.2	11.0	10.6	9.6	8.8	ر ر ر	1	l		ļ		
	(			i i	í	į		U		ij		
5	30.4	17.5	16.7	15.2	7.6	6.1						
7-1/2	44	25.3	24.2	22	11	6	1	1	83		Ī	T
10	95	32.2	30.8	28	14	11	1	I	1	1		Ī
		•										
15	84	48.3	46.2	42	21	17	I	[	1	1	1	1
20	108	62,1	59.4	54	27	22	1	-	Ī	I	I	I
25	136	78.2	74.8	89	34	27	L	62	54	27	22	
00	160	03	OX OX	C	Ç	37	1	75	65	33	26	1
40	208	120	114	104	52	41	Ţ	66	98	43	35	1
50	260	150	143	130	65	52	1	124	108	54	44	F

## Table 44 (Concluded)

Three-phase	AC moto	AC motor full load current, A		[see Notes 1), 2), and 4)]	1), 2), and	4)]						
Motor rating	Inductio	n type, squ	Induction type, squirrel-cage	and wound rotor, A	l rotor, A			Synchronous ty [see Note 3]], A	Synchronous type, unity power factor [see Note 3)], A	unity pow	er factor	
hp	115 V	200 V	208 V	230 V	460 V	575 V	2300 V	200 V	230 V	460 V	575 V	2300 V
09	ī	177	169	154	77	62	16	147	128	1 64	51	12
75	1	221	211	192	96	77	20	185	161	81	65	15
100	1	285	273	248	124	66	26	243	211	106	85	20
125		359	343	312	156	125	31	304	264	132	106	25
150	1	414	396	360	180	144	37	ĺ	1	158	127	30
200	I	552	528	480	240	192	49	Ļ	Ī	210	168	40
250	1	1	ı	604	302	242	I	1	Ţ	1	Ī	ſ
300	<u>l</u>	1	Į	722	361	289	ı		I		1	
350	ĮĮ.	Ī	L	828	414	336		IL.	ı	1		
400	1	I	1	954	477	382	1	1	l			T
450	1	10	1	1030	515	412	1	1	1			I
200	L		Ī	1180	290	472	Ī		I	Ī	I	Ī

Notes:

These values of motor full load current are to be used as guides only. Where exact values are required (e.g., for motor protection), always use the values on the motor nameplate. 1

These values of motor full load current are for motors running at speeds typical for belted motors and motors with normal torque characteristics. Motors built for especially low speeds or high torques may require more running current, and multi-speed motors have full load current varying with speed, in which case the nameplate current ratings shall be used. 2

The voltages listed are rated motor voltages. Corresponding nominal system voltages are 120, 208, 240, 480, and 600 V. Refer to CSA CAN3-C235. For 90 and 80% power factor, multiply the values in this Table by 1.1 and 1.25, respectively.

3)

## Table 45 Single-phase ac motors (See Rules 28-010 and 28-704.)

Single-phase ac motors full load current, A [see Notes 1] to 4)]

hp rating	115 V	230V
1/6	4.4	2.2
1/4	5.8	2.9
1/3	7.2	3,6
1/2	9.8	4.9
3/4	13.8	6.9
1	16	8
1-1/2	20	10
2	24	12
3	34	17
5	56	28
7-1/2	80	40
10	100	50

## Notes:

- 1) For full load currents of 208 and 200 V motors, increase the corresponding 230 V motor full load current by 10 and 15%, respectively.
- 2) These values of motor full load current are to be used as guides only. Where exact values are required (e.g., for motor protection), always use the values on the motor nameplate.
- These values of full load current are for motors running at their usual speeds and motors with normal torque characteristics. Motors built for especially low speeds or high torques may have higher full load currents, and multi-speed motors have full load current varying with speed, in which case the nameplate current ratings shall be used.
- 4) The voltages listed are rated motor voltages. Corresponding nominal system voltages are 120 and 240 V. Refer to CSA CAN3-C235.