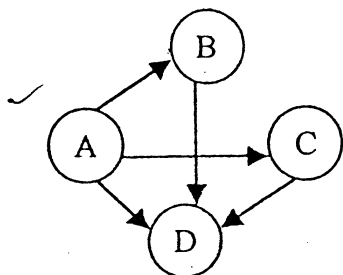


GRAPHS

(A graph G consists of a finite non-empty set V of vertices & a set E of edges.)
 $G = (V, E)$



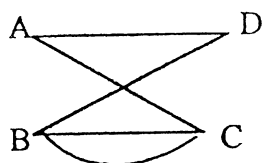
$V = \{A, B, C, D\}$
 $E = \{(A, B)(A, C)(A, D)(B, D)(C, D)\}$

* Directed graph (digraph)

(A graph is said to be directed graph in which every edge is directed.)
 $E = \{<A, B><A, C><A, D><B, D><C, D>\}$

* Multi graph

(A graph is said to be multi graph if there exist a loop or multiple edges in a given graph.)



Multiple edges: - Distinct edges e & e' are called multiple edges if they connect the same end points, that is if $e = [u, v]$ & $e' = [u, v]$

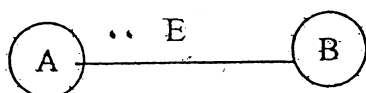
Loops: - An edge e is called a loop if it has Identical endpoints, that is if $e = [u, v]$

* Simple graph

(A graph without loops & parallel edges.)

* Incidence

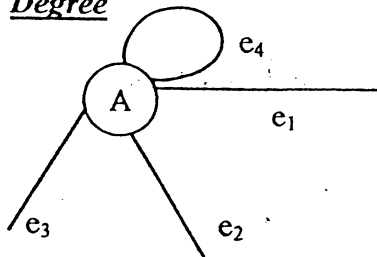
(Incidence means when a vertex V is an end vertex of some edge E , V & E are said to be incident with each other.)



B is incident on E.

2

* Degree



(The no of edges incident on a vertex V is called the degree $d(V)$ of vertex V . (For loops the edge is to be counted twice) So, the degree of A is 5.

* In degree

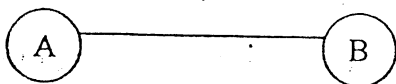
(In degree of a vertex V_i is the no of edges with V_i as their end vertex.)

* Out degree

(Out degree of a vertex V_i is the no of edges whose start vertex is V_i .)

* Adjacent

(Two vertices are said to be adjacent if they are end vertices of the same edge.)



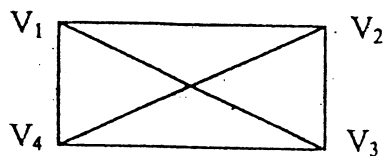
A is adjacent to B.

B is adjacent to A.

* Theorem

(The maximum number of edges in any simple undirected graph with n vertices is ${}^nC_2 = \frac{n(n-1)}{2}$)

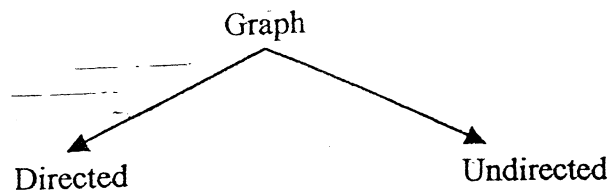
* Complete graph



(A graph will be complete if there is an edge between any two nodes) The no of edges in a complete graph having n nodes are

$$= (n-1) + (n-2) + \dots + 2 + 1$$

$$= \frac{n(n-1)}{2}$$



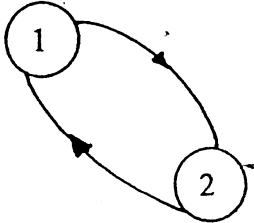
Directed

(A directed graph is a graph in which all the edges have specific direction.)

* Connected Graph

Strongly connected

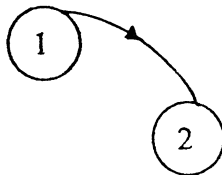
(A directed graph is strongly connected if for every pair of vertices V_i & V_j , there is a directed path from V_i to V_j & from V_j to V_i .)



2 is adjacent to 1
1 is adjacent to 2

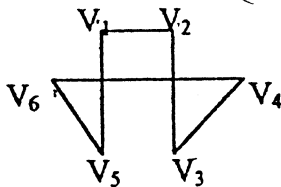
Weakly connected

(A directed graph is weakly connected if there is a directed path from V_i to V_j or from V_j to V_i .)



* Path

(A path is a collection of vertex V_1, V_2, \dots, V_n . Where $(V_1, V_2), (V_2, V_3), \dots, (V_{n-1}, V_n)$ are the edges of the graph.)



* Length of a path

(The length of the path is the number of edges in the path.)

Simple path

(A simple path is a path in which all nonterminal nodes cannot be repeated.)

(u)

* Cycle

(A cycle is a simple path so that the terminal node coincides with the starting node)

Subgraph & connected components

(A subgraph of G is G' such that $V(G') \subseteq V(G)$ & $E(G') \subseteq E(G)$)

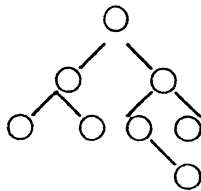
(A connected component of a graph is a maximal connected subgraph.)

Weighted graph

(A weighted graph is a graph in which edges are assigned some weight or value. (such graph often known as a network.))

Tree

(A tree is a connected graph, which is acyclic i.e. having no cycle.)



Theorem

(There is one and only one path between any two vertices in a tree T .)

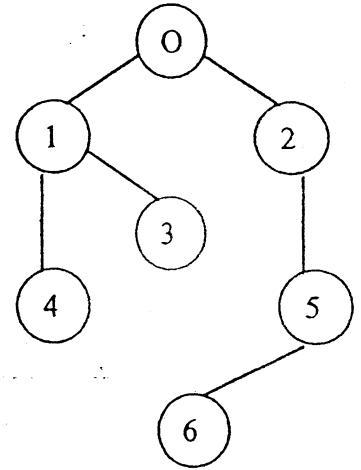
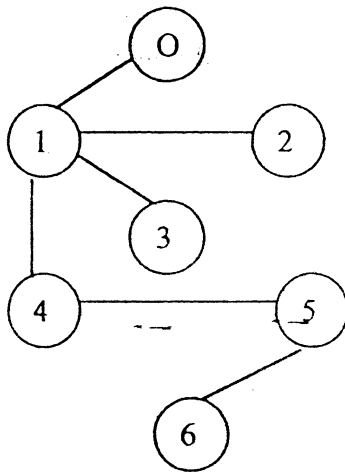
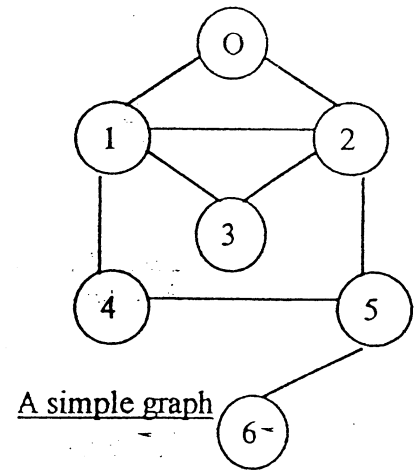
Proof (By contradiction)

Let a & b any two vertices, by combining this two we have cycle. But a tree cannot have a cycle. So, assuming two path is contradictory. So any two vertices of the tree there is only one path.

Spanning Tree

(A subgraph of a graph $G=(V,E)$ which is a tree containing all vertices of " V " is called a spanning tree of " G ".)

Note:- There will not be a unique spanning tree of a graph " G "



Minimal Spanning Tree

(A spanning tree T of G where the sum of weights of all edges in T is the minimum is called the minimal cost spanning tree or the minimal spanning tree of G . (It is not necessarily unique))

6

Graph representations

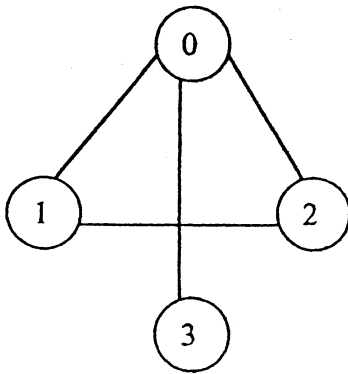
The most commonly used representation for graphs are

- I. Adjacency matrices
- II. Adjacency lists
- III. Adjacency multilist

*

Adjacency matrix

The adjacency matrix of G is a two-dimensional array of size $n \times n$ (where n is the number of vertices in the graph) with the property that a $[i][j]=1$ if the edge (V_i, V_j) is in the set of edges, & a $[i][j]=0$ if there is no such edge.



	0	1	2	3
0	0	1	1	1
1	1	0	1	0
2	1	1	0	0
3	1	0	0	0

C representation of a graph

```
#define Maxnode 100
int adj[Maxnode][Maxnode];
```

Write a routine to insert an edge in the graph.

```
Void insert (int adj[][100], int v1, int v2)
{
    adj[v1][v2]=1;
}
```

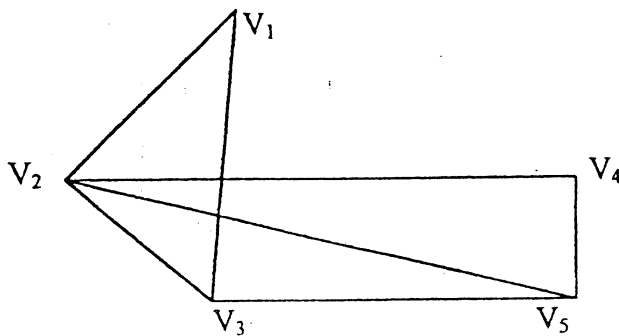
Write a routine to delete an edge from the graph.

```
Void remove (int adj[][100], int v1, int v2)
{
    adj[v1][v2]=0;
}
```

In this representation the n rows of the adjacency matrix are represented as n link lists. There is one list for each vertex in the graph. The nodes in list i represent the vertices that are adjacent from vertex i . Each list has a head node.

* Implementation

```
#define MAX 20
struct node
{
    int vno;
    struct node *next;
};
struct node *nodeptr;
nodeptr adj-list[MAX];
```



Vertex V_1

Vertex V_2

Vertex V_3

Vertex V_5

Vertex V_4

8

Traversal of a Graph

A graph can be traversed in two ways: -

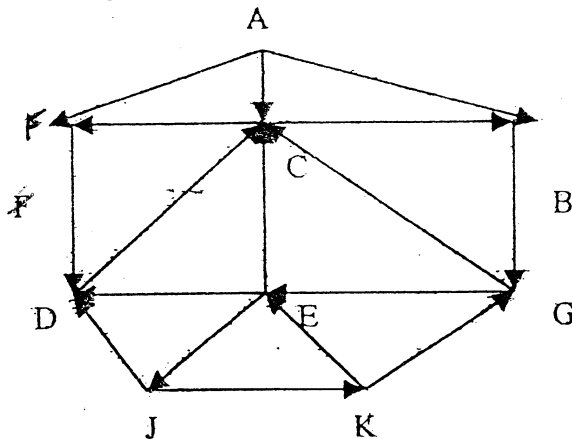
- I. BFS (Breadth First Search)
- II. DFS (Depth First Search)

Depth First Search (DFS)

Algorithm

1. Initialize all the node of the graph to status 1.
2. Push the starting node in the stack & make it status 2
3. Repeat steps 4 & 5 until the stack becomes empty.
4. Pop the top node & print it make it status 3.
5. Push all the neighbor node of the deleted node whose status is 1 & make the status 2
6. Exit.

Example

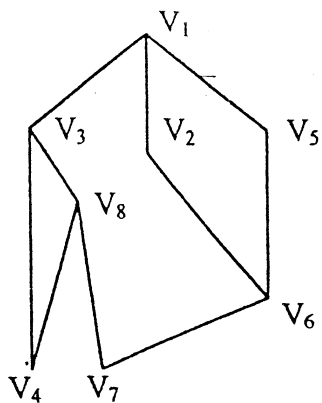


We want to find & print all the nodes
Reachable from the node J

- I. Push J onto the stack
- II. Print J
- III. Print K
- IV. Print G
- V. Print C
- VI. Print F
- VII. Print E
- VIII. Print D

Stack: J
Stack: D, K
Stack: D, E, G
Stack: D, E, C
Stack: D, E, F
Stack: D, E
Stack: D
Stack:

The stack is now empty, so the DFS of G starting at j is now complete. So the result is: - J K G C F E D



V ₄
V₈
V₇
V₆
V₅
V ₂
V ₃
V₁
NULL

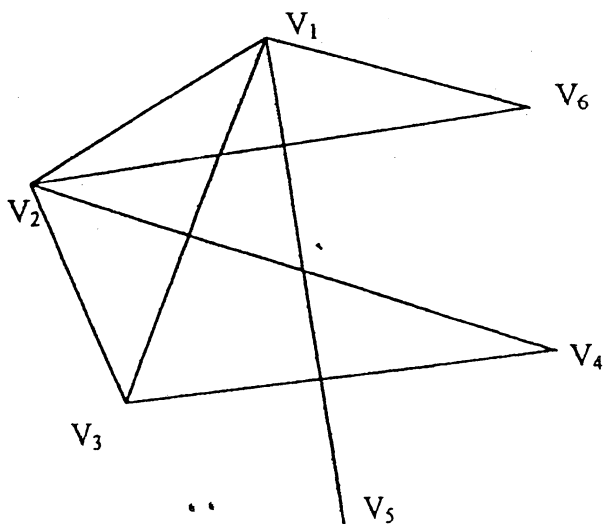
So the result is, V₁, V₅, V₆, V₇, V₈, V₄, V₂, V₃

Breadth First Search (BFS)

* Algorithm

1. Initialize all the nodes of the graph to status 1.
2. Insert the starting node in the queue & make it status 2
3. Repeat steps 4 & 5 until the queue becomes empty.
4. Delete the front node & make it status 3
5. Insert all the neighbors of the deleted node in the graph (whose status is 1) & make the status 2
6. Exit.

Example

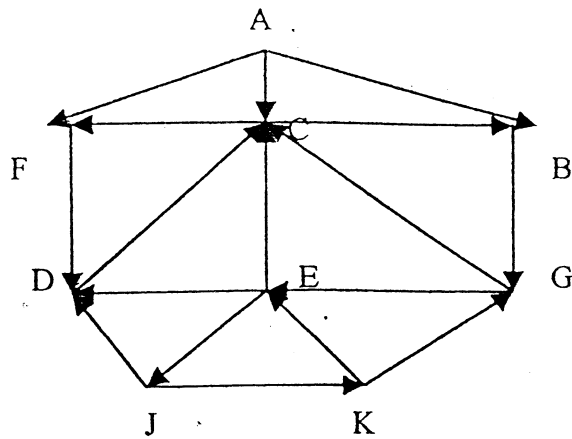


Rear	front
V ₅ V ₆ V ₃ V ₄	V₁ V₂

So, the result is,
V₂ V₁ V₄ V₃ V₆ V₅

Example

(10)



We want minimum path p from A to J

- | | |
|--|---|
| 1) FRONT=1
REAR=1 | Queue: A
Origin: Φ |
| 2) FRONT=2
REAR=4
Remove <u>A</u> | <div style="text-align: center;">x</div> Queue: A F C B
Origin: Φ A A A |
| 3) FRONT=3
REAR=5
Remove (<u>AF</u>) | <div style="text-align: center;">x x</div> Queue: A F C B D
Origin: Φ A A A F |
| 4) FRONT=4
REAR=5
Remove (<u>AFC</u>) | <div style="text-align: center;">x x x</div> Queue: A F C B D
Origin: Φ A A A F |
| 5) FRONT=5
REAR=6
Remove (<u>AFCB</u>) | <div style="text-align: center;">x x x x</div> Queue: A F C B D G
Origin: Φ A A A F B |

Contd.....

- 6) FRONT=6 x x x x x
 REAR=6 Queue: A F C B D G
 Remove (AFCBDD) Origin: Φ A A A F B
- 7) FRONT=7 x x x x x x
 REAR=7 Queue: A F C B D G E
 Remove (AFCBDGE) Origin: Φ A A A F B G
- 8) FRONT=8 x x x x x x x
 REAR=8 Queue: A F C B D G E J
 Remove (AFCBDGE) Origin: Φ A A A F B G E

We stop as soon as J is added to the queue, since J is our final destination. We now backtrack from J, using the array *origin* to find the path P. Thus

J \longleftarrow E \longleftarrow G \longleftarrow B \longleftarrow A is required path.

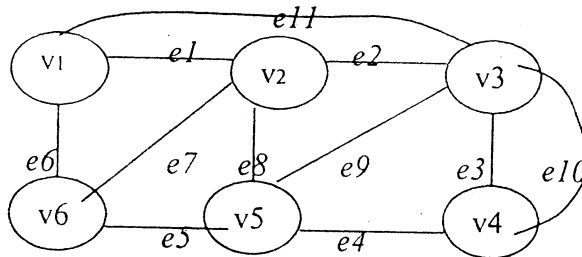
Graphs

1. Define the following terms. Associate appropriate figures to illustrate the terms

- | | |
|-------------------------|-----------------------|
| ➤ Walk | ➤ Indegree |
| ➤ Open & closed walk | ➤ Sink |
| ➤ Path | ➤ Cycle |
| ➤ Length of the path | ➤ Network. |
| ➤ Circuit | |
| ➤ Connected graph | |
| ➤ Degree of a vertex | |
| ➤ Clique/Complete Graph | |

Ans:- Walk:- A walk in a graph $G=(V,E)$ is a finite alternating sequence of vertices & edges $(v_1, e_1, v_2, e_2, v_3, \dots)$ beginning & ending with vertices, in such a way that each edge is incident with vertices preceding & following it.

Open & closed walk:- a walk is open if its end vertices or terminal vertices are distinct, otherwise it is considered as a closed walk.



Open walk:- $v_1, e_1, v_2, e_2, v_3, e_3, v_4, e_4, v_5, e_9, v_3, e_{10}, v_4$

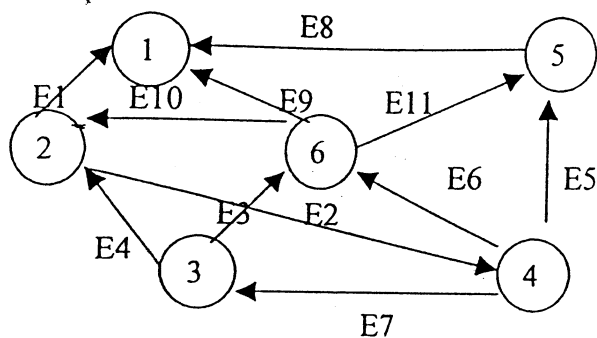
Closed walk:- $v_1, e_1, v_2, e_2, v_3, e_3, v_4, e_4, v_5, e_9, v_3, e_{11}, v_1$

Circuit:- in a closed walk if no vertex appears more than once, except the terminal vertices, then the closed walk is called the circuit.
 $v_1, e_1, v_2, e_2, v_3, e_3, v_4, e_4, v_5, e_5, v_6, e_6, v_1$.

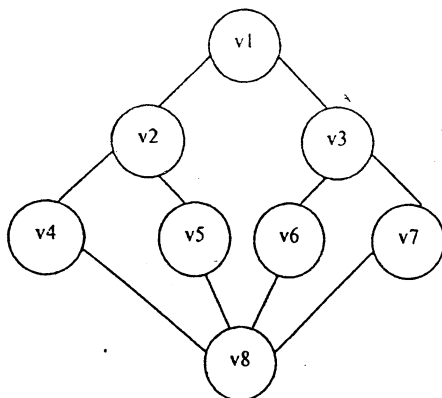
2. What are the various ways of representation of graph in memory? Explain each of them.

3)

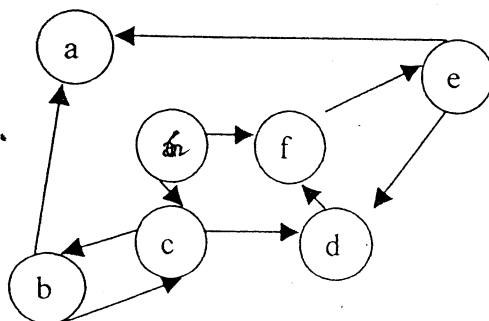
3. For the following graph obtain:
- a) The indegree & out degree of each vertex.
 - b) Its adjacency matrix.
 - c) Its adjacency list representation.



4. Explain the BFS & DFS traversals of the following undirected graph. Write down the required algorithm of the above two traversals.



5. For the following directed graph (digraph) find the DFS & BFS



6. The adjacency matrix of an undirected graph is
- a) unit matrix
 - b) an asymmetric matrix
 - c) symmetric matrix
 - d) None of the above.