

A Spectral Analysis of the Domain Decomposed Monte Carlo Method for Linear Systems

Stuart R. Slattery and Paul P.H. Wilson, University of Wisconsin - Madison

Thomas M. Evans, Oak Ridge National Laboratory

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- First proposed by J. Von Neumann and S.M. Ulam in the 1940's
- General lack of published work
- Recent work by Evans and others has yielded new potential applications
- Implications for resilient exascale solver strategies
- Domain decomposed parallelism has yet to be exploited - would like a preliminary analytic framework

- Split the linear operator

$$\mathbf{H} = \mathbf{I} - \mathbf{A}$$

$$\mathbf{Ax} = \mathbf{b} \quad \rightarrow \quad \mathbf{x} = \mathbf{Hx} + \mathbf{b}$$

- Generate the *Neumann series*

$$\mathbf{A}^{-1} = (\mathbf{I} - \mathbf{H})^{-1} = \sum_{k=0}^{\infty} \mathbf{H}^k$$

- Require $\rho(\mathbf{H}) < 1$ for convergence

$$\mathbf{A}^{-1}\mathbf{b} = \sum_{k=0}^{\infty} \mathbf{H}^k \mathbf{b} = \mathbf{x}$$

- Expand the Neumann series

$$x_i = \sum_{k=0}^{\infty} \sum_{i_1}^N \sum_{i_2}^N \cdots \sum_{i_k}^N h_{i,i_1} h_{i_1,i_2} \cdots h_{i_{k-1},i_k} b_{i_k}$$

- Define a sequence of state transitions

$$\nu = i \rightarrow i_1 \rightarrow \cdots \rightarrow i_{k-1} \rightarrow i_k$$

- Use the adjoint Neumann-Ulam decomposition¹

$$\mathbf{H}^T = \mathbf{P} \circ \mathbf{W}$$

$$p_{ij} = \frac{|h_{ji}|}{\sum_j |h_{ji}|}, \quad w_{ij} = \frac{h_{ji}}{p_{ij}}$$

¹The Hadamard product $\mathbf{A} = \mathbf{B} \circ \mathbf{C}$ is defined element-wise as $a_{ij} = b_{ij}c_{ij}$.

- Build the estimator and expectation value

$$X_j(\nu) = \sum_{m=0}^k W_m \delta_{i_m, j}$$

$$\begin{aligned} E\{X_j\} &= \sum_{\nu} P_{\nu} X_{\nu} = \sum_{k=0}^{\infty} \sum_{i_1}^N \sum_{i_2}^N \cdots \sum_{i_k}^N b_{i_0} h_{i_0, i_1} h_{i_1, i_2} \cdots h_{i_{k-1}, i_k} \delta_{i_k, j} \\ &= x_j \end{aligned}$$

- Terminate a random walk below a weight cutoff, $W_m < W_c$

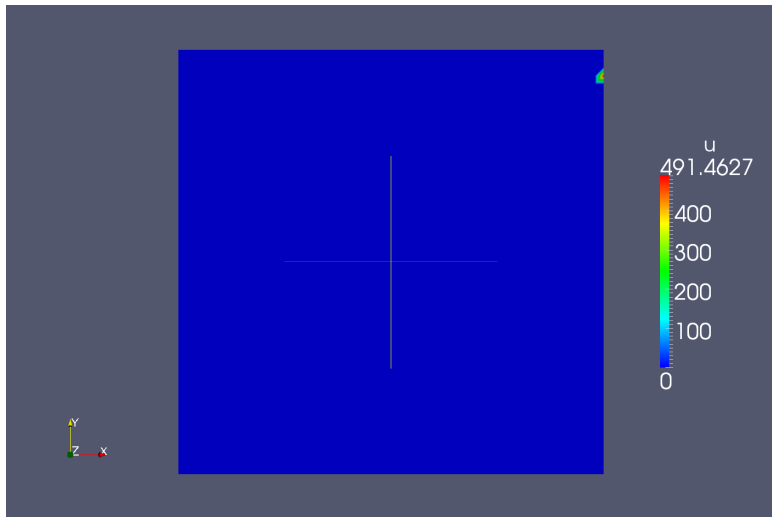


Figure: Adjoint solution to Poisson Equation. 1×10^0 total histories, 0.286 seconds CPU time.

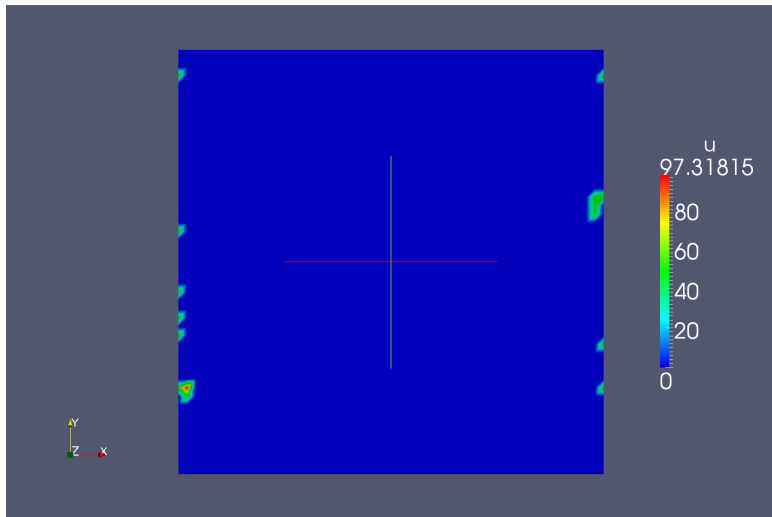


Figure: Adjoint solution to Poisson Equation. 1×10^1 total histories, 0.278 seconds CPU time.

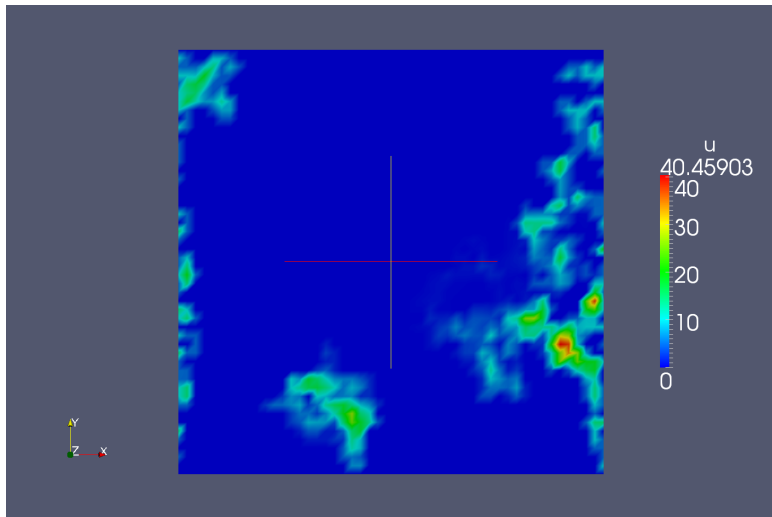


Figure: Adjoint solution to Poisson Equation. 1×10^2 total histories, 0.275 seconds CPU time.

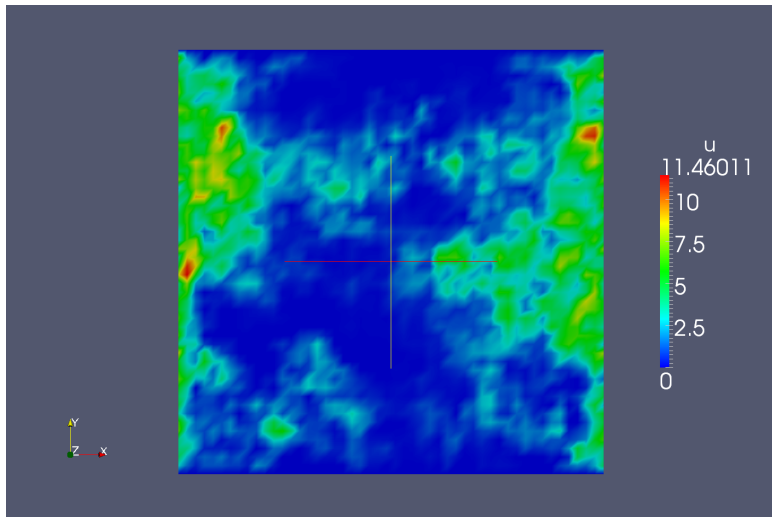


Figure: Adjoint solution to Poisson Equation. 1×10^3 total histories, 0.291 seconds CPU time.

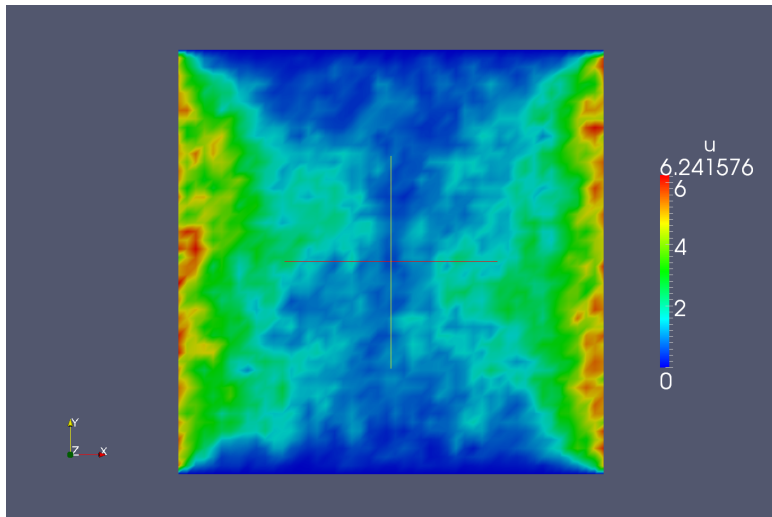


Figure: Adjoint solution to Poisson Equation. 1×10^4 total histories, 0.428 seconds CPU time.

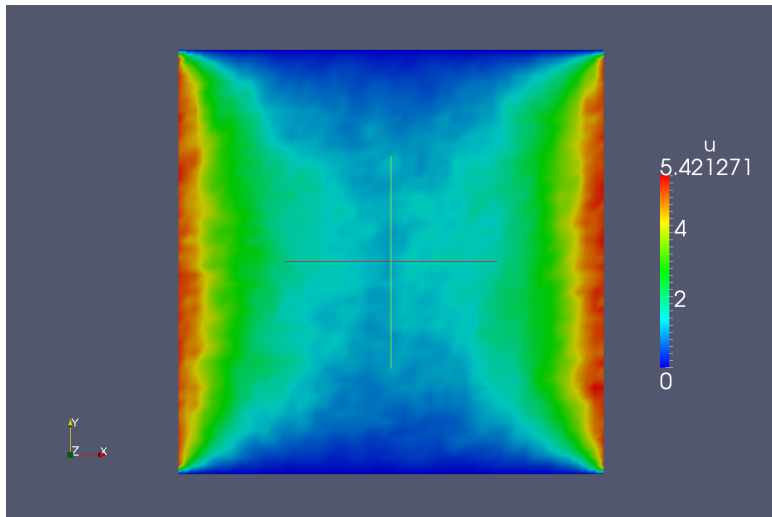


Figure: Adjoint solution to Poisson Equation. 1×10^5 total histories, 1.76 seconds CPU time.

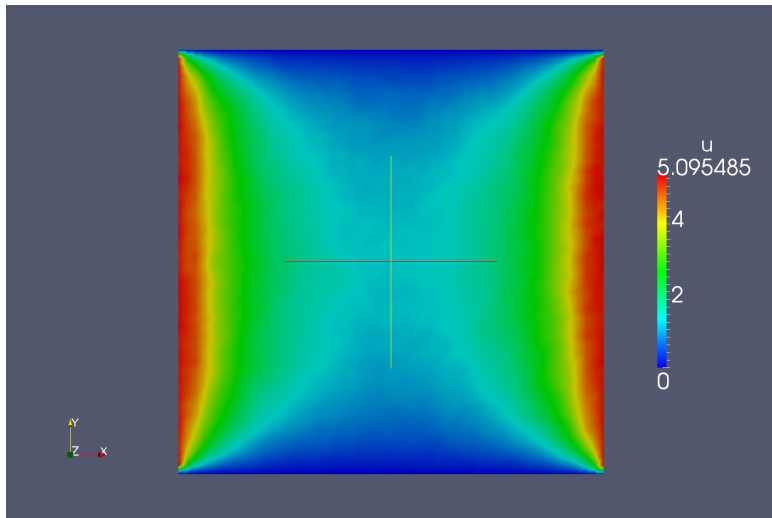


Figure: Adjoint solution to Poisson Equation. 1×10^6 total histories, 15.1 seconds CPU time.

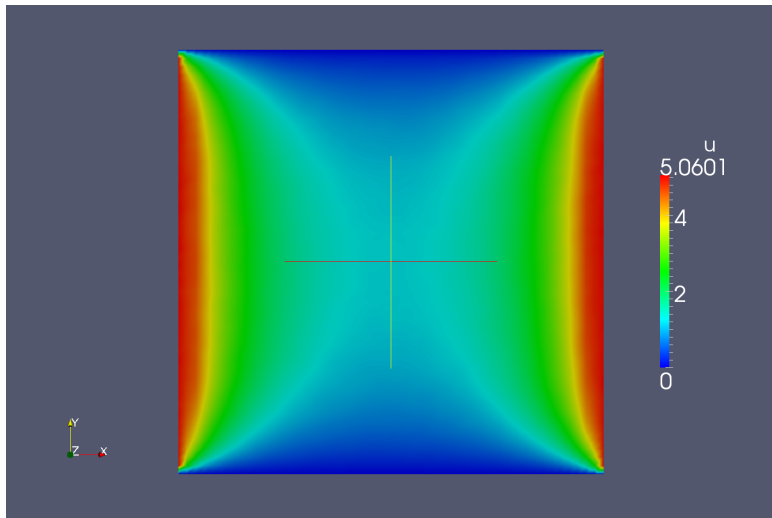


Figure: Adjoint solution to Poisson Equation. 1×10^7 total histories, 149 seconds CPU time.

- Each parallel process owns a piece of the domain (linear system)
- Random walks must be transported between adjacent domains through parallel communication
- Domain decomposition determined by the input system

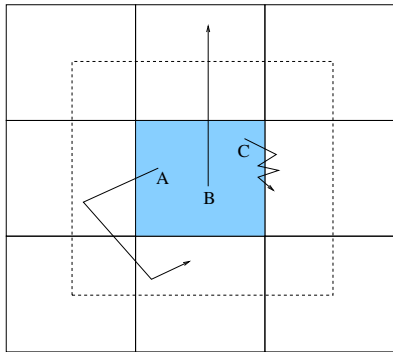
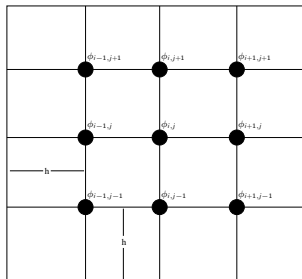


Figure: Domain decomposition example illustrating how domain-to-domain transport creates communication costs.



$$-D\nabla^2\phi + \Sigma_a\phi = S$$

$$\mathbf{D}\phi = \mathbf{s}$$

Figure: Nine-point Laplacian stencil.

$$-\frac{1}{6h^2}[4\phi_{i-1,j} + 4\phi_{i+1,j} + 4\phi_{i,j-1} + 4\phi_{i,j+1} + \phi_{i-1,j-1} + \phi_{i-1,j+1} + \phi_{i+1,j-1} + \phi_{i+1,j+1} - 20\phi_{i,j}] + \Sigma_a\phi_{i,j} = s_{i,j} \quad (1)$$

$$\Phi_{p,q}(x,y) = e^{2\pi i p x} e^{2\pi i q y}$$

$$\begin{aligned} \mathbf{D}\Phi_{p,q}(x,y) = \lambda_{p,q}(\mathbf{D}) = \\ -\frac{D}{6h^2} \left[4e^{-2\pi i p h} + 4e^{2\pi i p h} + 4e^{-2\pi i q h} + 4e^{2\pi i q h} + e^{-2\pi i p h} e^{-2\pi i q h} \right. \\ \left. + e^{-2\pi i p h} e^{2\pi i q h} + e^{2\pi i p h} e^{-2\pi i q h} + e^{2\pi i p h} e^{2\pi i q h} - 20 \right] + \Sigma_a \quad (2) \end{aligned}$$

$$\lambda_{p,q}(\mathbf{D}) = -\frac{D}{6h^2} [8 \cos(\pi p h) + 8 \cos(\pi q h) + 4 \cos(\pi p h) \cos(\pi q h) - 20] + \Sigma_a$$

$$\mathbf{M}^{-1}\mathbf{D}\phi = \mathbf{M}^{-1}\mathbf{s}$$

$$\lambda_{p,q}(\mathbf{M}^{-1}\mathbf{D}) = \alpha\lambda_{p,q}(\mathbf{D})$$

$$\alpha = \left[\frac{10D}{3h^2} + \Sigma_a \right]^{-1}$$

$$\mathbf{H} = \mathbf{I} - \mathbf{M}^{-1}\mathbf{D}$$

$$\rho(\mathbf{H}) = \frac{10\alpha D}{3h^2}$$

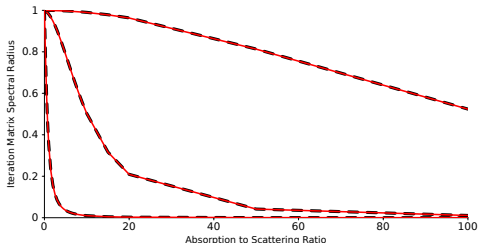


Figure: Measured and analytic preconditioned diffusion operator spectral radius as a function of the absorption cross section to scattering cross section ratio.

$$\mathbf{e}^k = \mathbf{H}^k \mathbf{e}^0 \rightarrow \|\mathbf{e}^k\|_2 \leq \rho(\mathbf{H})^k \|\mathbf{e}^0\|_2 \rightarrow k \approx \frac{\log(W_c)}{\log(\rho(\mathbf{H}))}$$

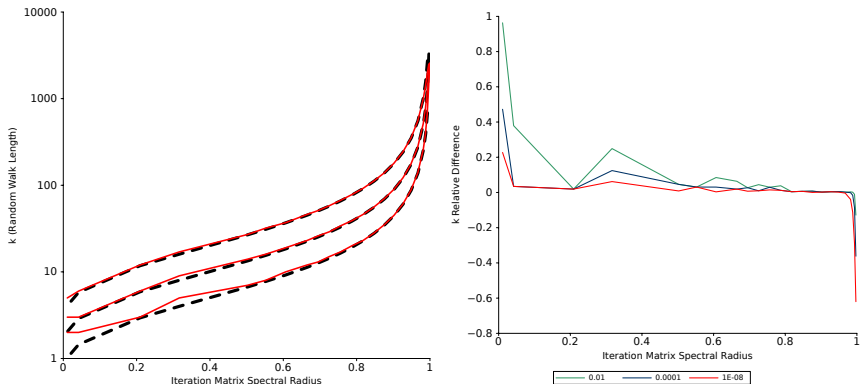


Figure: Measured and analytic random walk length as a function of the iteration matrix spectral radius.

$$\langle \bar{r}_1^2 \rangle = (n_s h)^2 \quad \rightarrow \quad \langle \bar{r}_k^2 \rangle = k(n_s h)^2$$

- l = chord length
- n_i = # of discrete states along the chord
- n_s = # of discrete states per transition along the chord
- d = dimensionality of problem

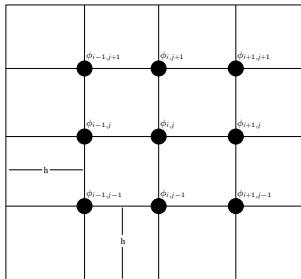
$$\langle \bar{r}_k^2 \rangle = k \left(\frac{n_s l}{n_i} \right)^2$$

$$\tau = \frac{l}{2d \sqrt{\langle \bar{r}_k^2 \rangle}}$$

$$\tau = \frac{n_i}{2dn_s \sqrt{k}}$$

$$\tau = \frac{n_i}{2dn_s} \sqrt{\frac{\log(\rho(\mathbf{H}))}{\log(W_c)}}$$

Choosing d , n_i , and n_s



$$d = 2 \quad (i, j)$$

$$n_i = 5$$

$$n_s = \frac{3}{5}$$

Figure: Nine-point Laplacian stencil.

$$\begin{aligned} -\frac{1}{6h^2} [4\phi_{i-1,j} + 4\phi_{i+1,j} + 4\phi_{i,j-1} + 4\phi_{i,j+1} + \phi_{i-1,j-1} \\ + \phi_{i-1,j+1} + \phi_{i+1,j-1} + \phi_{i+1,j+1} - 20\phi_{i,j}] + \Sigma_a \phi_{i,j} = s_{i,j} \quad (3) \end{aligned}$$

$$\Lambda = \frac{\text{average \# of histories leaving local domain}}{\text{total of \# of histories starting in local domain}}$$

Wigner Rational Approximation

$$\Lambda = \frac{1}{1 + \tau}$$

Mean Chord Approximation

$$\Lambda = \frac{1 - e^{-\tau}}{\tau}$$

Domain Leakage Results

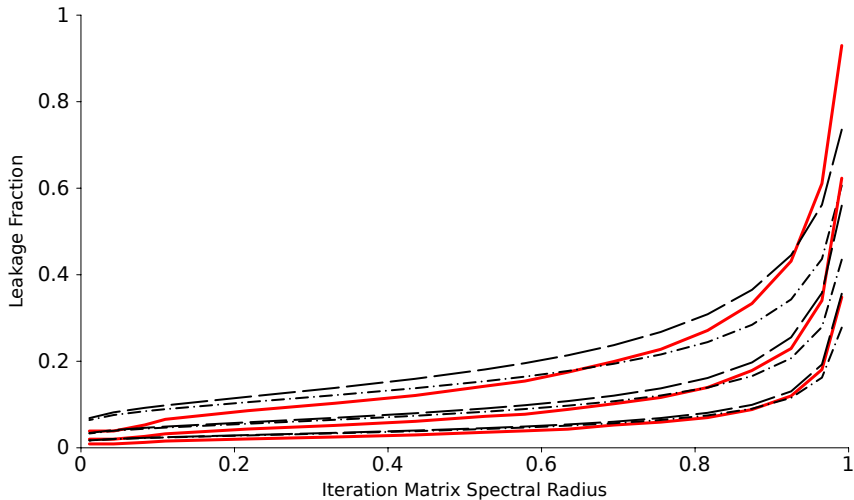


Figure: Measured and analytic domain leakage as a function of the iteration matrix spectral radius.

Domain Leakage Results

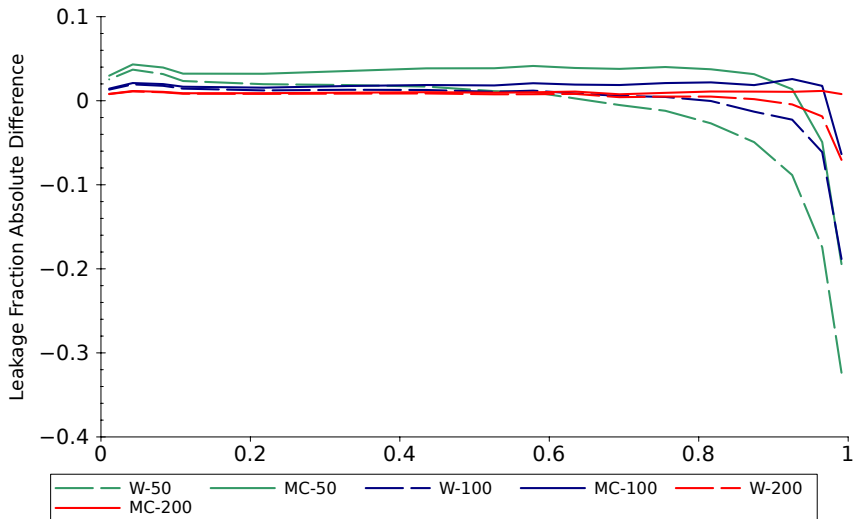


Figure: Measured and analytic domain leakage absolute error as a function of the iteration matrix spectral radius.



- Good agreement between theory and numerical experiments
- Extension to asymmetric systems and communication cost analysis
- Coordinate measurements with massively parallel computations
- Explore in the context of synthetic acceleration methods



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