



Ant System: Application to TSP

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Motivation:

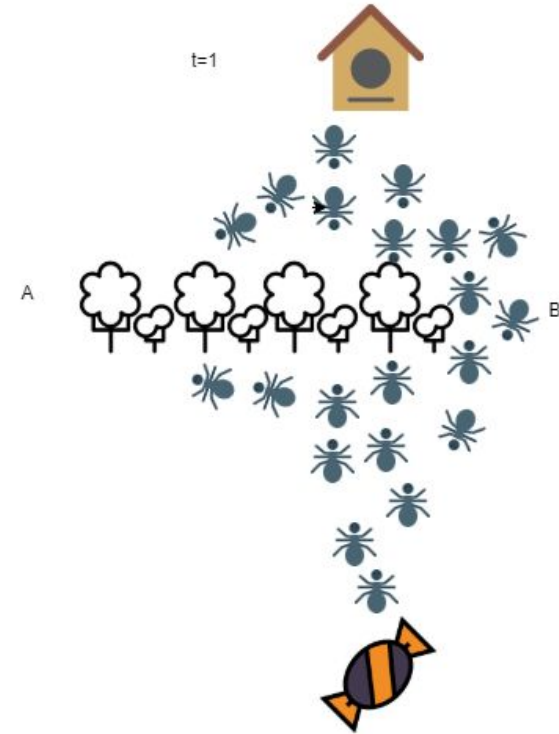
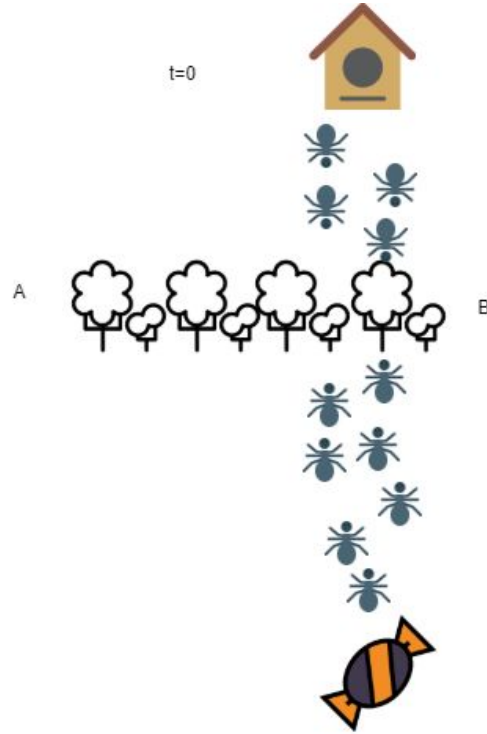
- Failed ant keeper
 - Virtual ants > Real Ants
- Inspired by real life biological ants
 - Ants = Mostly Blind
 - No method of visual communication
 - Pheromones!
 - Ants have been around since dinosaurs
 - Span every continent besides “Ant”arctica!
- Unique, and interesting approach

Origin:

- First presented by:
 - Marco Dorigo, Victor Maniezzo, Alberto Colorni
 - 1996
 - The Ant System: Optimization by a colony of cooperating agents
 - Implementation based on this.

Method Overview (Example):

- $T=0$
 - No pheromones.
 - Randomly traveling.
 - Both sides.
- $T=1$
 - 2x pheromone levels at B.
 - Influence movements towards B.
- How to represent?



Implementation/Representation

- N cities/locations
- $N*N$ edges
- Graph data structure obvious choice
- K “ant” agents
- Each edge contains:
 - Pheromone at time t
 - Distance from node i to j

Implementation/Representation:

- Probabilistic Edge Choice:

- τ : pheromone on edge i,j
- α : parameter defining contribution of pheromone
- β : parameter defining contribution of inverse distance.
- η : $1/d$ inverse of distance of edge i,j
- Only search edges we haven't used yet. (TSP)
- Series of probabilities that sum to 1.
- Use probability distribution to choose next edge.

$$p_{ij}^k(t) = \begin{cases} \frac{[\tau_{ij}(t)]^\alpha \cdot [\eta_{ij}]^\beta}{\sum_{k \in \text{allowed}_k} [\tau_{ik}(t)]^\alpha \cdot [\eta_{ik}]^\beta} & \text{if } j \in \text{allowed}_k \\ 0 & \text{otherwise} \end{cases}$$

Implementation/Representation:

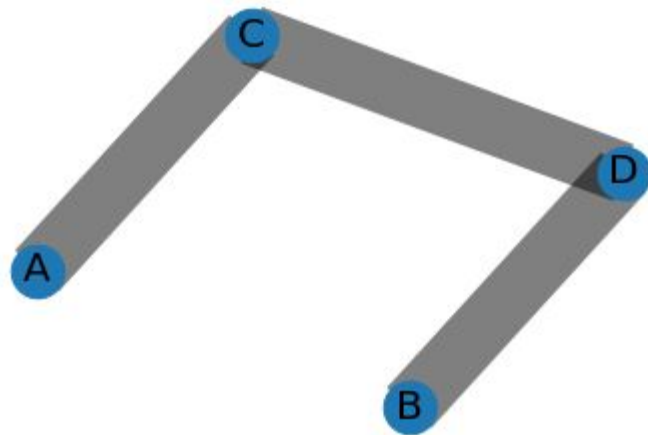
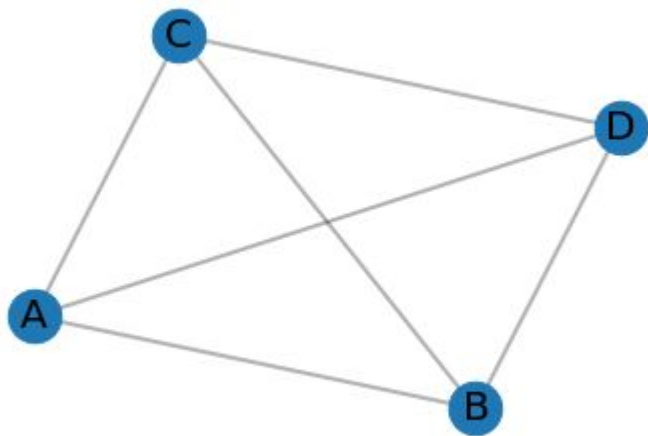
- Pheromone Update

- Only update per cycle. (t+n)
- p : parameter representing evaporation rate. (0-1)
- Q : parameter controlling amount of pheromone deposited
- L : represents the length of the tour that “ant” agent k took between time t to $t+n$.

$$\tau_{ij}(t+n) = \rho \cdot \tau_{ij}(t) + \Delta\tau_{ij}$$

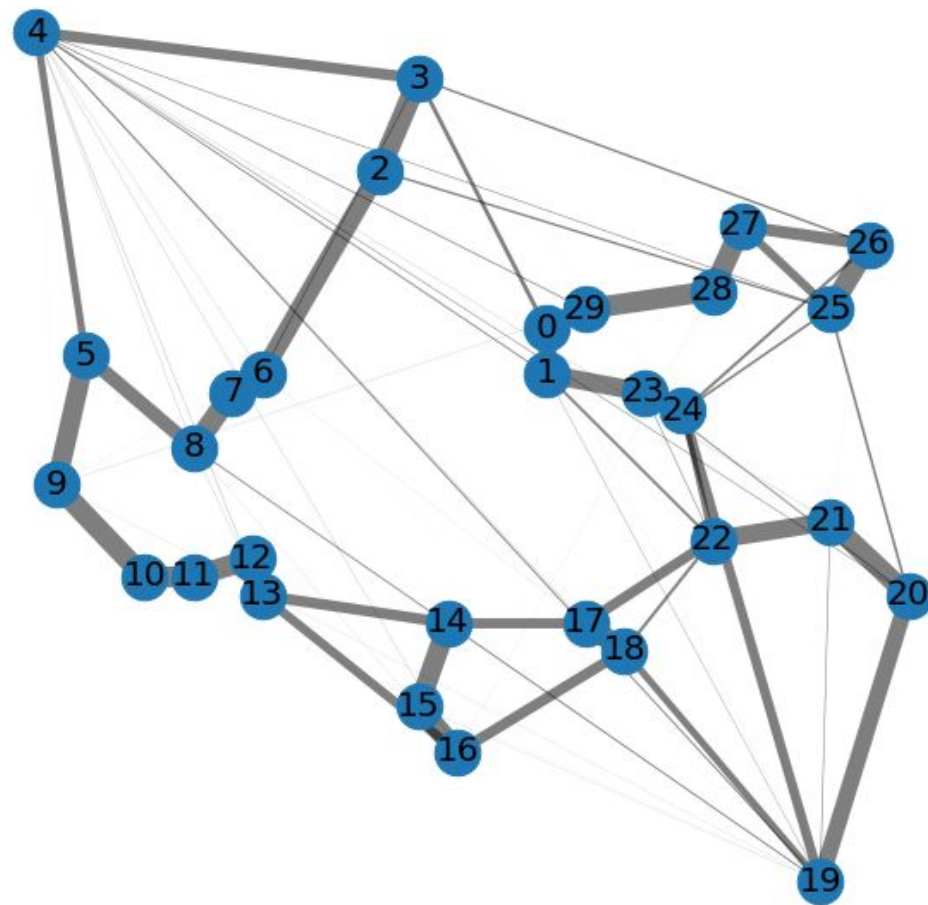
$$\Delta\tau_{ij} = \sum_{k=1}^m \Delta\tau_{ij}^k$$

$$\Delta\tau_{ij}^k = \begin{cases} \frac{Q}{L_k} & \text{if } k\text{-th ant uses edge } (i, j) \text{ in its tour (between time } t \text{ and } t+n) \\ 0 & \text{otherwise} \end{cases}$$



- Costly edges disappear

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Conclusion

- Very unique, and interesting algorithm
- Biological inspiration
- Shed light on different types of optimization algorithm
- Converges quickly
- Versatile
- A Lot of parameters to mess with!

Questions?