(1) Carried

Set up the equation of Bezier curve and roughly trace it for three control points (1, 1), (2, 2) and (3, 1).

b) Write short notes on any two:

Z-buffer algorithm

ii) RGB and CMY color modelsiii) Phong's shading model

(iv) Virtual reality.

Total Pages -4

UL(7)-Comp. Graph.

B. Tech 7th Semester Examination 2015

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COMP. GRAPH.

Full Marks: 70

Time: 3 hours

Answer any five questions

The figures in the right-hand margin indicate marks

Candidates are required to give their answers in their own words as far as practicable

- ., (a) What are the criteria that should be satisfied by a good line drawing algorithm? Explain. 7
- (b) Write mid-point circle algorithm and predict the pixels in any octant of circle for radius = 10 pixels with its center at origin.
- (a) Write advantages of raster scan display over random scan display.

Turn Over

- (b) Consider three different raster systems, with resolutions of 640 × 400, 1280 × 1024 and 2560 × 2048. What size frame buffer (in byte) is needed for each of these systems to store 12 bits per pixel? How much storage is required for each system if 24 bits per pixel are to be stored?
- 3. (a) Write an algorithm for filling polygons and explain it with a suitable example.
- (b) Compare Scan line fill and Boundary fill algorithms.
- general pivot-point rotation? Derive general pivot-point rotation and general fixed-point scaling matrices. Compute the computational efficiency of each.
- (b) What are homogeneous coordinates? If a line whose end points are (x1, y1) and (x2, y2) exists in 2D space, then write the concatenation of matrices that will rotate the mirror image of the line about mid-point

of the line by an angle 60° counter-clockwise. Each of the transformations has to be in homogenous coordinate system.

- (a) Write any one line clipping algorithm.
- (b) Reflect the polygon (-1, 0), (0, -2), (1, 0) and (0, 2) about the line Y = 2 by using transformation matrices.
- (a) Explain the issues related to three dimensional display methods. Compare parallel projection and perspective projection methods for 3-D objects.
- b) Derive a general form of 3D rotation about:
- (i) X-axis

(ii) Z-axis

- (a) Write the properties of B-Spline curves. Also write advantages of B-Spline curves over Bezier curves.
- (b) What do you understand by the term "Back
 -Face Removal"? Explain a Back-Face
 removal algorithm.

(Continued)

Comp. Graph.

(Turn Over)

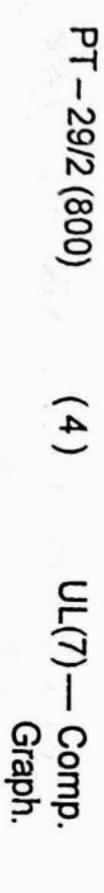
points: equidistant parameter values having central

$$(x_0, y_0) = (50, 180), (x_1, y_1) = (250, 100), (x_2, y_2) = (600, 300) (x_3, y_3) = 500, 50$$

 $(x_2, y_2) = (600, 300) (x_3, y_3) = 500, 50$

- a) Explain Z-Buffer algorithm:
- projections. Describe briefly parallel and perspective





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Time: 3 hours

Full Marks: 70

Candidates are required to give their answers in their own words as far as practicable.

The figures in the margin indicate full marks. Answer any five questions.

- What do you mean by Interactive Computer Graphics? Define persistence in terms of CRT phosphorus
- Discuss the applications of computer Differentiate raster and random scan View Storage Tube (DVST) over CRT? displays. What are the advantages of Direct graphics.
- (b) Explain Beam penetration method.

Also list some disadvantages of DVST.

Tum over)

PT-29/2

- 2560 × 2048 : Consider three different raster system with resolutions of 640 × 480, 1280×1024 and
- What size is frame buffer (in bytes) for each of these systems to store 12 bits per pixel?
- (ii) How much storage (in bytes) is required be stored ? for each system if 24 bits per pixel are to
- tions of 640 × 480 and 1280 × 1024 : Consider two raster systems with the resolu-
- \ni How many pixels could be accessed per display controller that refreshes the screen at a rate of 60 frames per second in each of these systems by a second?
- \equiv What is the access time per pixel in each system? 7+7=14
- Explain, in detail, about the DDA scan conversion algorithm.

Contd.

- ਭ radius = 4 and centre is at (0, 0). 8+6 = 14 Plot a circle using mid pain algorithm whose
- a) matrix representation in 2 – D plane : Explain the following transformations with
- \odot Reflection
- \equiv Shearing
- 豆 Perform a 45° rotation of triangle A(0,0), B(1, 1), C(5, 2):
- About the origin

 \ni

About P(-1, -1)

 \equiv

- 7+7 = 14
- Based on Cohen Sutherland line clipping Algorithm:

the bitwise logical AND of the region codes not 0000' (representing the end-points of the line) is Prove or disprove that 'A line is not visible if

- ত্র Derive the matrix representation for 3 - D rotation about x - axis.
- (a) Explain the advantages and disadvantages of B-spline surface over Bezier Surface

PT-29/2

छ

Determine I points on a Bezier curve with

(Tum over)

With the help of a neat and clear diagram relationship between the RGB and the CMY explain the RGB color model. Show the color models

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Time: 3 hours

Full Marks: 70

their own words as far as practicable. Candidates are required to give their answers in

11分別を表記を設定して A CHILD

The figures in the margin indicate full marks.

Answer any five questions.

- (a) With the help of a neat and clear diagram explain the functioning of a CRT.
- Distinguish between Random scan and seven important differences. Raster scan display devices. Give at least
- Explain the Bresenham's line drawing is more efficient and why? algorithm. According to you, among DDA and Bresenham's line drawing algorithm, which

28/2 (900)

1.12

	crossing lines. 7	window boundary intersections with the	Point subdivision method for finding the	Cohen and Sutherland. Also discuss the Mid-	(b) Explain the line clipping algorithm given by	suitable diagram.	4. (a) Explain the Boundary-fill algorithm with a	display. 7	200 ns per pixel on a simple RGB color	frame buffer with an average access rate of	(b) What is the refresh rate of a 1024 × 1024	resized image?	Aspect-Ratio, what would be the height of the	to that is 640 pixels wide retaining the original	3. (a) If we wish to rasterize a 1024 × 768 image,	the coordinate origin. 7	having a radius of 10 units and centered at	the points required to rasterize or circle	(b) Using Mid Point circle drawing algorithm find
?			(b)		7. (a)			(b)		•	6. (a)				(b)				5. (a)
	designi	do we	Explain	Approxi	Give th	IOI Pels	the tran	Define t	you drav	transfor	Obtain t	Serilation	and the	coordin	Derive	while ke	A(0, 0),	coordin	Whata

- Derive all the 3D rotation (w. r. t. different coordinate axes) transformation equations and their corresponding matrix representations.
- (a) Obtain the rectangular window-to-viewport transformation equations. What inference do you draw from the derived equations? 7
- b) Define the term Parallel Projection. Derive the transformation equations and the matrix for Perspective Projection.
- (a) Give the properties of Bezier-Bernstein Approximation.
-) Explain what are Blending functions. Why do we prefer cubic splnies for curve designing? Explain.

Full Marks: 70

Answer any five questions.

The figures in the right-hand margin indicate marks.

Candidates are required to give their answers in their own words as far as practicable.

- (a) Distinguish between raster Graphics and random Graphics System.
- (b) Discuss the shadow-mask method for color CRT monitors.
- (a) Discuss Bresenham line and compare it with DDA line drawing algodrawing algorithm
- (b) Calculate the pixels on a Straight Line with End line drawing algorithm. points (24, 12) and (32, 18) using Bresenham
- (a) Discuss mid-point circle with suitable diagram and necessary derivations. drawing

2019 (A)

Full Marks: 70

Time: 3 hours

Answer any five questions.

The figures in the right-hand margin indicate marks.

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Candidates are required to give their answers in their own words as far as practicable.

- (a) Two endpoints of a line are given as (200, 120) and (225, 136). Calculate the successive pixel positions along the line path following the Bresenham's line drawing algorithm.
 7
- (b) Given a circle radius r = 14, calculate the pixel positions along the circle octant in the first quadrant from x = 0 to x = y using the midpoint circle algorithm. Assume the centre of the circle is at (0, 0).

.

2. Discuss with diagram the Bresenham's line drawing algorithm for |m| < 1 along with all the necessary derivations.

Turn Over)

- algorithm. Analyze the merits polygon filling algorithm over flood-filling and demerits of scan line
- meter p_{t+1} circle drawing algorithm. Show the steps in terms of p_k of deriving decision parain the midpoint
- diagrams with all Discuss the midpoint ellipse drawing algorithm necessary derivations and suitable
- (a) Compute 2D transformation matrix for rota-(12, 6). ting a point (12, 6) about the point (3, 2) by determine the new position of the point an angle 30° in anti-clockwise direction. Also
- b) Discuss and example. Clipping algorithm with the help of diagrams the Sutherland-Hodgeman Polygon
- mation matrices and suitable diagrams. along with the necessary derivation of transfor-Discuss different 3D transformation techniques

(a) Derive the matrix for Perspective Projection tion plane Z. with centre of projection at origin and Projec-

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- (b) Construct enough points on the Bezier curve and P2 (12, 4) to draw an accurate sketch. whose control points are P.0 (6, 3), P1 (9, 5)
- (i) What is the degree of the curve?
- (ii) What are the coordinates at u = 0.5?