MA 260 SECTIONS 3.1-3.2 OVERVIEW and TO-DO LIST

There is a lot of review in these sections of what was seen Calculus II with 2- and 3-component vectors. All this is generalized to cover n-component vectors in \mathbb{R}^n . Vector addition, scalar multiplication, dot or scalar product, distance between vectors, and equality of vectors all work like they did when n was 2 or 3. Even the angle $R^n R^n R^n R^n$ between two vectors is extended to R^n using a result that worked for n = 2 and 3.

There is a bit of new notation and terminology. The magnitude or length of a vector \vec{v} is denoted $\|\vec{v}\|$ with double bars instead of single ones. It is also referred to as the Euclidean norm of the vector. The distance between two vectors \vec{u} and \vec{v} is denoted $d(\vec{u}, \vec{v})$. The dot product is now referred to as the Euclidean inner product.

Check out some new vector results that are expressed as inequalities in Thm 3.2.4. and Thm 3.2.5 and as equalities in Thm 3.2.6 and Thm 3.2.7.

A new concept that is introduced in Section 3.1 is that of a vector being a linear combination of a set of vectors in \mathbb{R}^n . Since the section is missing examples on this, some examples follow the definition below...

<u>DEFINITION.</u> If \vec{w} is a vector in R^n , then \vec{w} is said to be a **linear combination** of the vectors $\vec{v}_1, \vec{v}_2, ... \vec{v}_r$ in R^n If it can be expressed in the form $\vec{w} = k_1 \vec{v_1} + k_2 \vec{v_2} + ... + k_r \vec{v_r}$ where $k_1, k_2, ..., k_r$ are scalars and referred to as the **coefficients** of the linear combination. When r=1, $\vec{w}=k_1\vec{v_1}$, so that a linear combination of a single vector is just a scalar multiple of that vector.

Example 1. We learned in Calculus II, that a vector \vec{v} in R^2 can be written as $\vec{v} = (x, y) = x(1, 0) + y(0, 1) = x\vec{i} + y\vec{j}$ and, thus, is a linear combination of vectors \vec{i} and \vec{j} .

Example 2. Is the vector (6, 30, 8) a linear combination of the vectors (1, -3, -1) and (0, 4, -2)?

If po, then (6,30,8) = (1k,+0k2+3k3,-3k,+4k2+6k3, 1k,+2k2+3k3)

If we take
$$det(A) = \begin{vmatrix} 102 \\ -346 \end{vmatrix}$$
, we find $det(A) = 44 \pm 6$

Bythe latest summing-up (Equivalence) theorem, thm 2.3.8, The linear system have solution. So, yes, (6,30,8) is a linear combination of the other two vectors.

Example 3. Is $\vec{u} = (1,2,3)$ a linear combination of the vectors $\vec{v}_1 = (-1,0,3)$ and $\vec{v}_2 = (4,1,1)$?

Let $\vec{u} = (1,2,3) = k$, $(-1,0,2) + k_2(4,1,1)$. Equating corresponding components of the left and right sides of the above equation,

$$-k_1 + 4k_2 = 1$$

$$0k_1 + 1k_2 = 2 \implies k_2 = 2. \text{ then and } -k_1 + 8 = 1, k_1 = 77 \neq 1. \text{ Condraduction }$$

$$2k_1 + 1k_2 = 3 \implies 2k_1 + 2 = 3, k = \frac{1}{2} \implies \text{no pollution } .$$

thus, here it is notalinear combination of vi, vis.

Geometric Interpretation of Example 3: $\vec{u} = (1,2,3)$ is not in the plane through the arigin determined by \vec{v} , and \vec{v}_2 .

Why? Consider the vertors as parition vectors (initial paints at (0,0,0). Consider the vector was since neither vector is a scalar multiple of the other.

Hence v, and va determine a plane thru the origin. this plane contains all position vectors that are linear combinations

Read Section 3.1. Do Problems 1, 5, 7, 15-17, 19, 21-22 Take Check Quiz 13

Read Section 3.2. **Do Problems** 1(a,b), 2(a,b), 3(a,b,c,d), 7, 8, 10 (a,b), 12(a,b), 13-14, 15(a,b,c,d), 18 (a,b) Video: https://youtu.be/www.hxo39_k

Take Check Quiz 14