Računarska grafika (20ER7002)

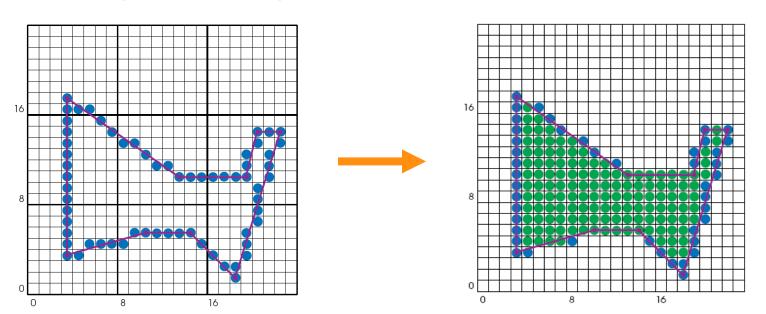
Popuna (filling) objekata

Predavanja



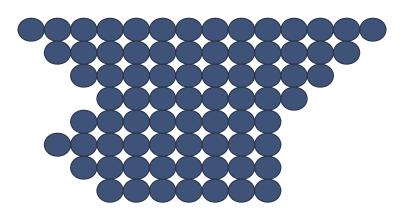
Popunjavanje oblasti (regiona)

 Oblast (region) je grupa susednih, povezanih piksela.



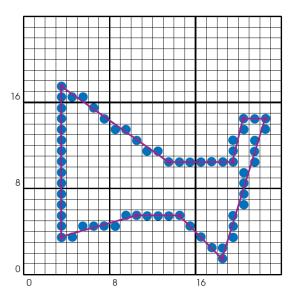
Popunjavanje oblasti (regiona)

- Uobičajeno, oblast se definiše na jedan od dva načina:
 - Svi pikseli koji pripadaju oblasti imaju istu (datu) vrednost;



Popunjavanje oblasti (regiona)

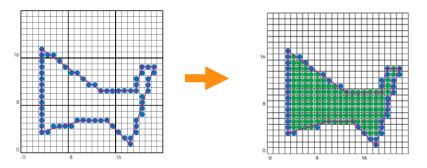
 Pikseli koji su na ivici oblasti imaju datu vrednost.



Tipovi oblasti

Prema načinu definisanja

Prema povezanosti piksela



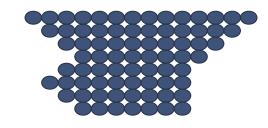
Tipovi oblasti prema načinu definisanja

Interior-defined (oblast definisana unutrašnjošću)

Boundary-defined (oblast definisana granicom)

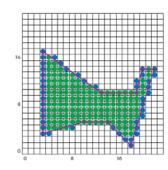
Interior-defined oblasti

- Svi pikseli u oblasti imaju vrednost old_value, i nema piksela na granici oblasti sa tom vrednošću.
- Algoritmi za popunu koji rade nad ovakvim oblastima treba da postave njihove piksele na vrednost new value.
- Ovakvi algoritmi se nazivaju algoritmima popunjavanja plavljenjem (flood-fill).



Boundary-defined oblasti

- Pikseli na granici oblasti imaju vrednost boundary_value, dok pikseli u oblasti imaju proizvoljnu drugu vrednost.
- Algoritmi koji rade nad ovakvim oblastima treba da postave sve njihove piksele na vrednost new_value
- Ovi algoritmi se nazivaju algoritmima popunjavanja oivičene oblasti (boundary-fill).



Tipovi oblasti prema povezanosti piksela

4-susedne oblasti (4-connected)

8-susedne oblasti (8-connected)

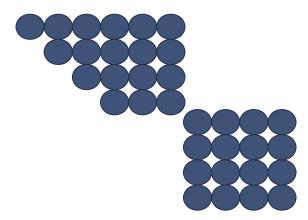
4-susedne oblasti

Od proizvoljnog piksela u oblasti do svih drugih u oblasti može se stići sekvencom horizontalnih i vertikalnih pomeraja za 1 piksel.



8-susedne oblasti

Od proizvoljnog piksela u oblasti do svih drugih u oblasti može se stići sekvencom horizontalnih, vertikalnih i dijagonalnih pomeraja za 1 piksel



Algoritmi za popunu

- Flood-fill algoritmi
- Algoritmi za popunu oivičenih oblasti

Rekurzivni Flood-fill algoritam za 4-susedne oblasti

```
void Flood_Fill4(CDC* pDC, int x, int y, COLORREF old_value, COLORREF
new value)
   if (ReadPixel(pDC,x,y) == old_value){
        WritePixel(pDC,x,y,new value);
        Flood_Fill4(pDC, x, y-1, old_value, new_value);
        Flood_Fill4(pDC, x, y+1, old_value, new_value);
        Flood Fill4(pDC,x+1, y, old value, new value);
        Flood Fill4(pDC,x-1, y, old_value, new_value);
COLORREF ReadPixel(CDC* pDC, int x, int y)
  return pDC->GetPixel(x,y);
```

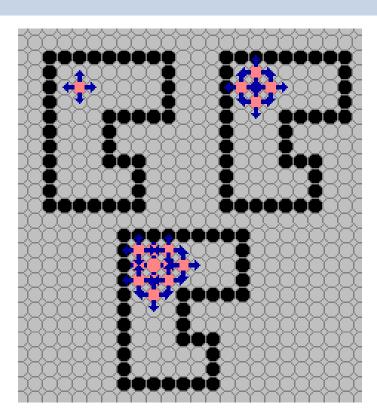
Rekurzivni Flood-fill algoritam za 8-susedne oblasti

```
void Flood Fill8(CDC* pDC, int x, int y, COLORREF old value,
COLORREF new value)
   if (ReadPixel(pDC,x,y) == old_value){
        WritePixel(pDC,x,y,new_value);
        Flood Fill8(pDC, x, y-1, old value, new value);
        Flood_Fill8(pDC, x, y+1, old_value, new_value);
        Flood_Fill8(pDC,x+1, y, old_value, new_value);
        Flood_Fill8(pDC,x-1, y, old_value, new_value);
        Flood_Fill8(pDC,x-1,y-1, old_value, new_value);
        Flood fill8(pDC,x-1,y+1, old value, new value);
        Flood fill8(pDC,x+1,y-1, old value, new value);
        Flood fill8(pDC,x+1,y+1, old value, new value);
```

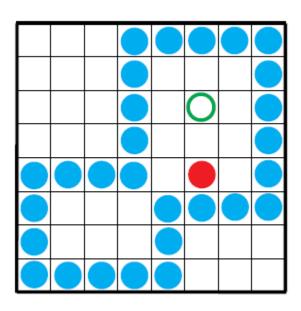
Rekurzivni algoritam za popunu oivičene 4-susedne oblasti

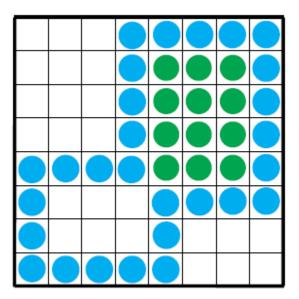
```
void Boundary_Fill4(CDC* pDC, int x, int y, COLORREF boundary_value,
COLORREF new_value)
{
    COLORREF temp_value = ReadPixel(pDC,x,y);
    if (temp_value != boundary_value) && (temp_value != new_value)){
        WritePixel(pDC,x,y,new_value);
        Boundary_Fill4(pDC, x, y-1, boundary_value, new_value);
        Boundary_Fill4(pDC, x, y+1, boundary_value, new_value);
        Boundary_Fill4(pDC,x+1, y, boundary_value, new_value);
        Boundary_Fill4(pDC,x-1, y, boundary_value, new_value);
}
```

Rekurzivni algoritam za popunu oivičene 4-susedne oblasti

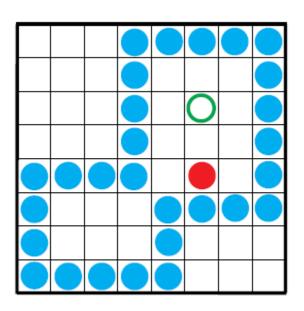


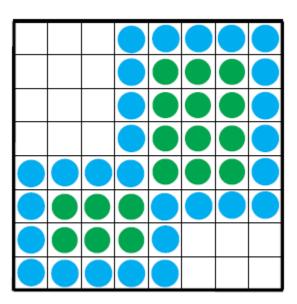
Rekurzivni algoritam za popunu oivičene 4-susedne oblasti





Rekurzivni algoritam za popunu oivičene 8-susedne oblasti

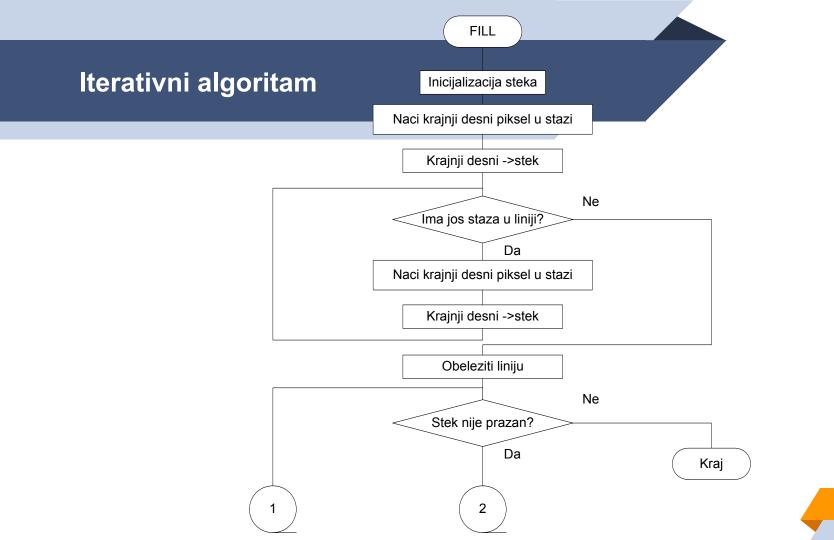


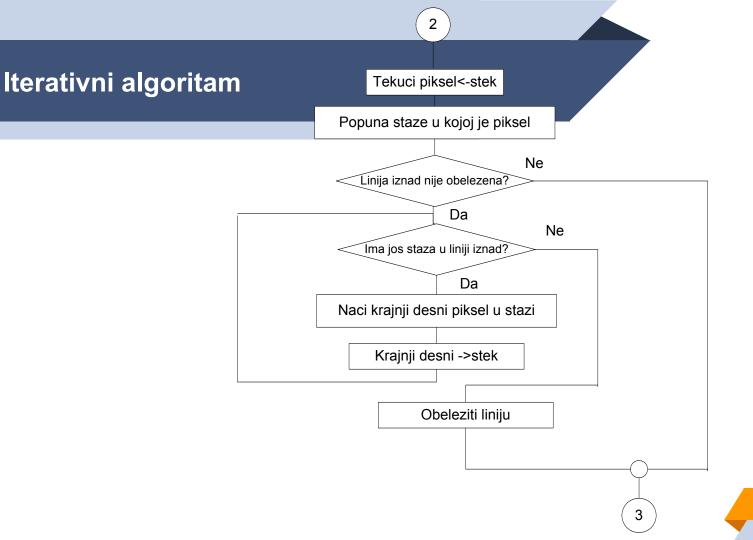


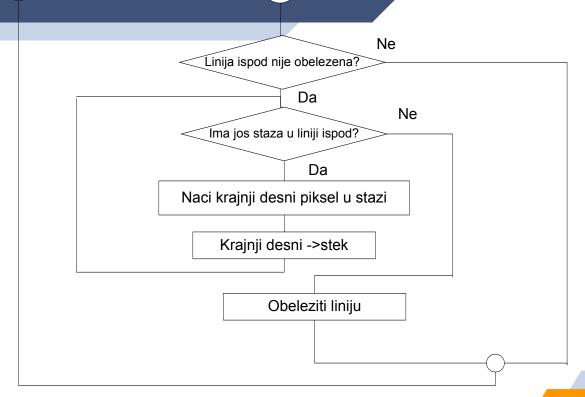
Nedostaci rekurzivnih algoritama za popunu oblasti

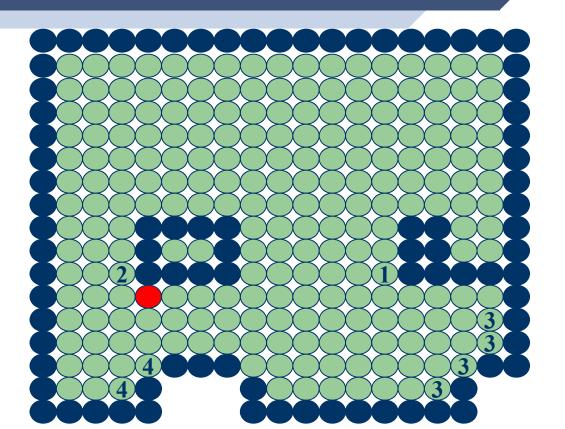
Brza popuna steka!!!

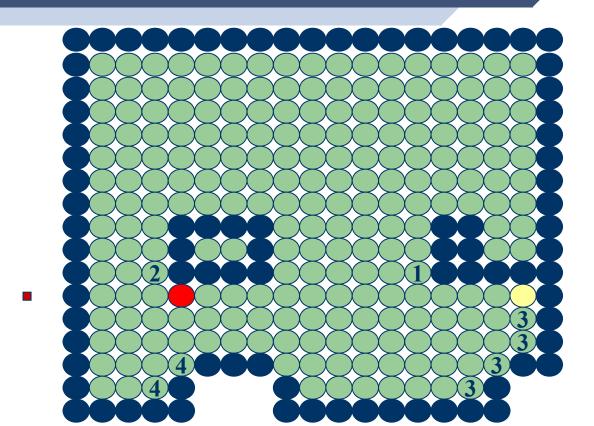
Zbog toga se koriste iterativni algoritmi.

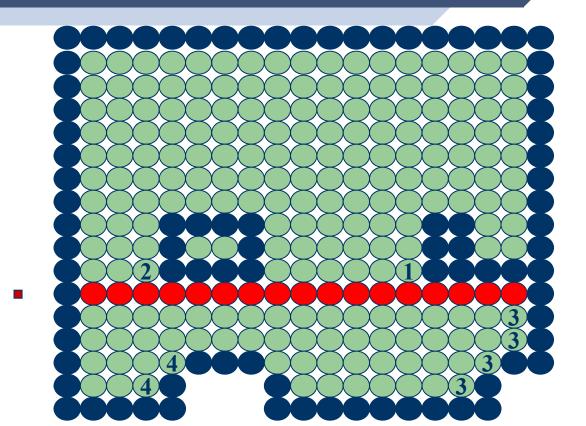


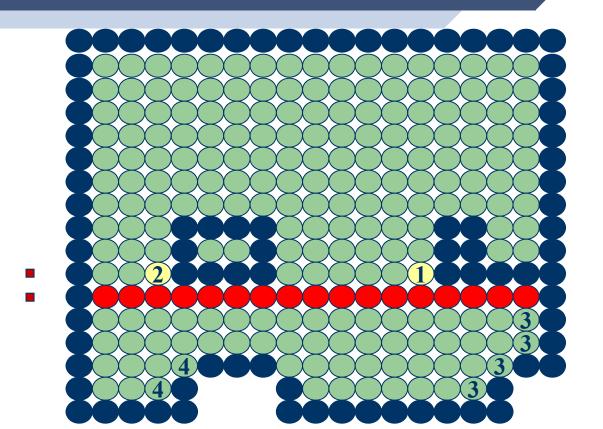


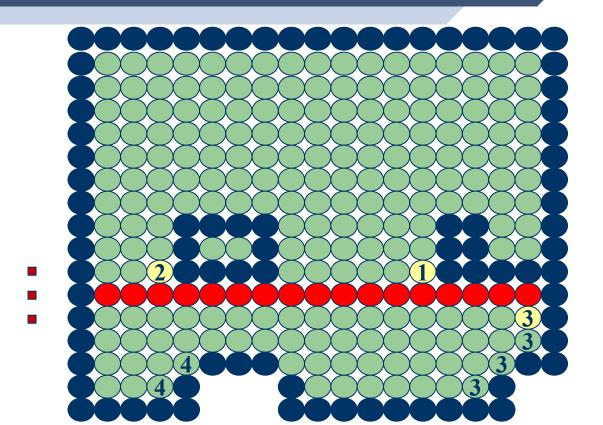


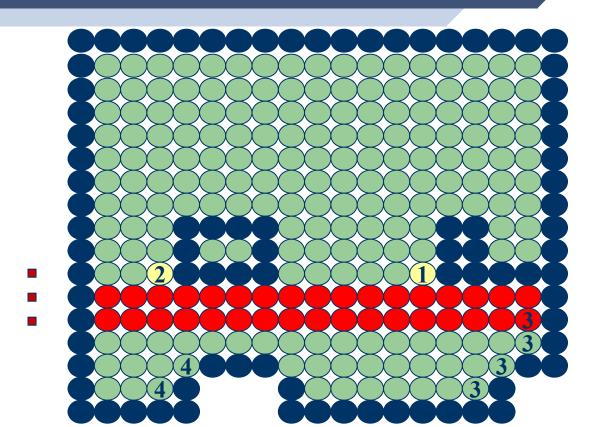


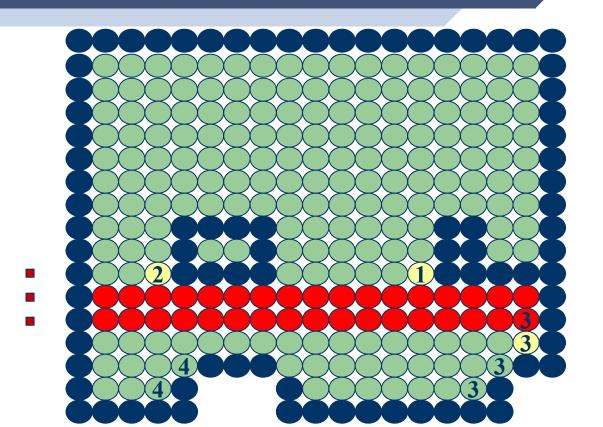


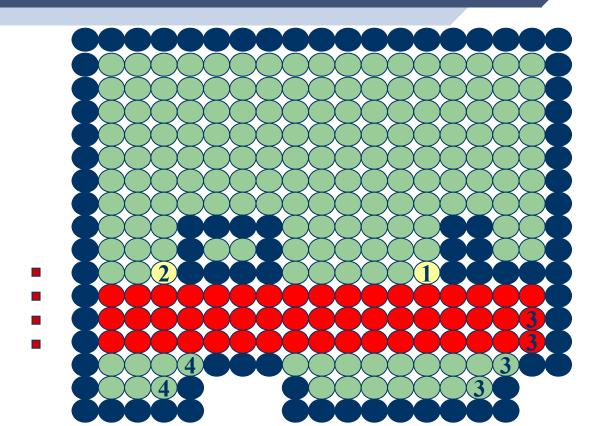


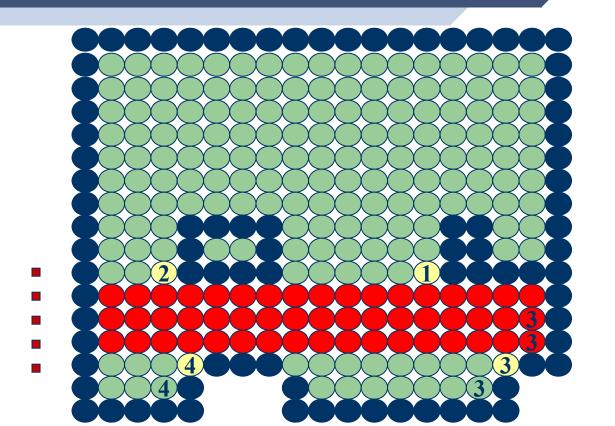


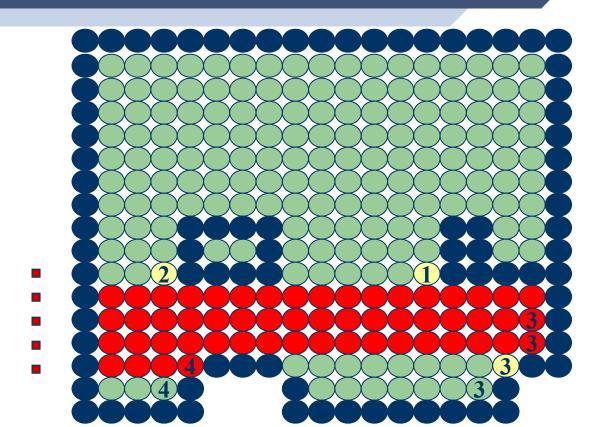


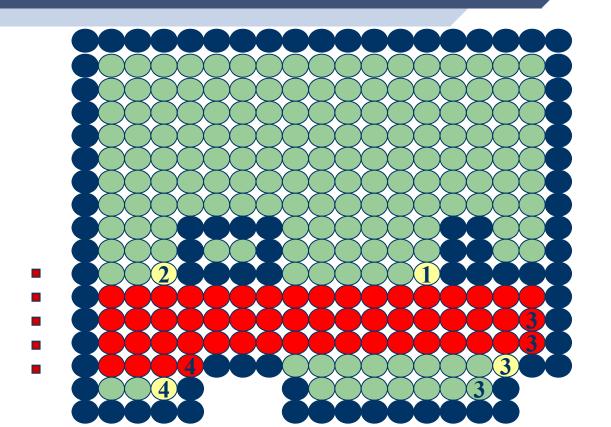


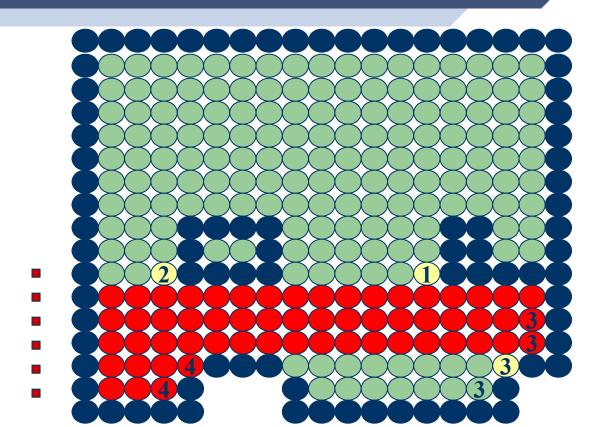


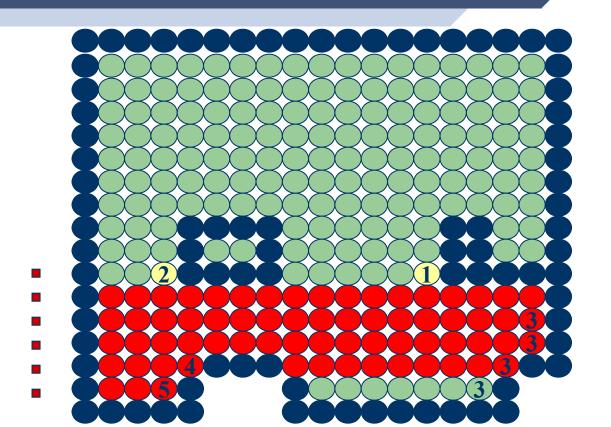


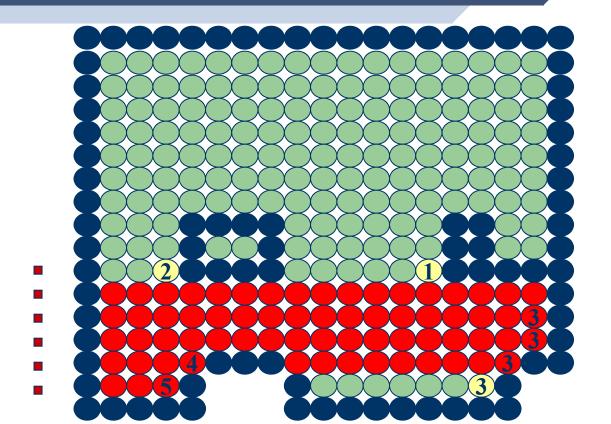


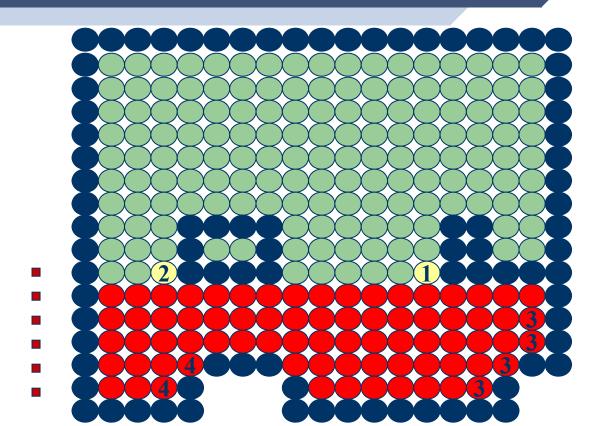


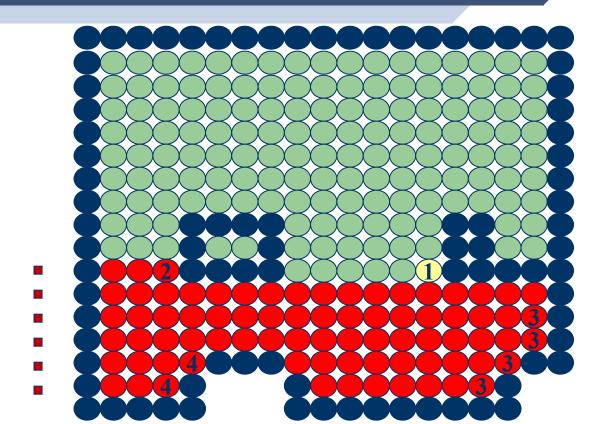


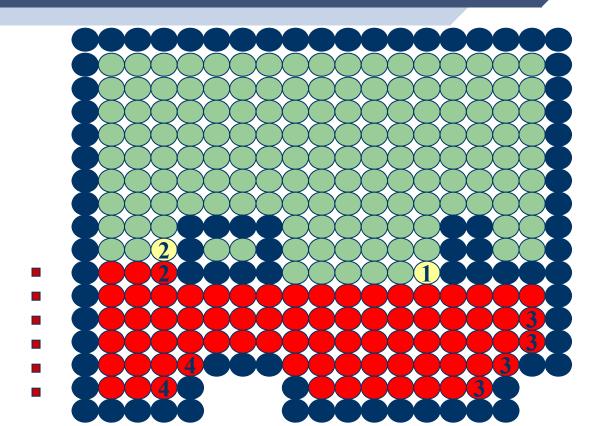


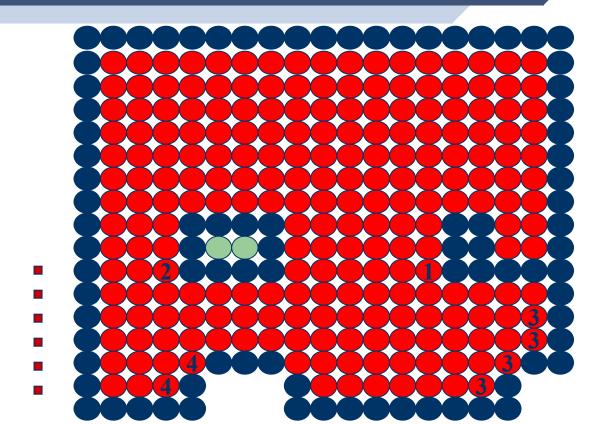






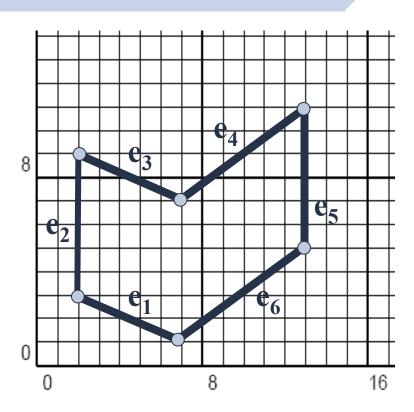




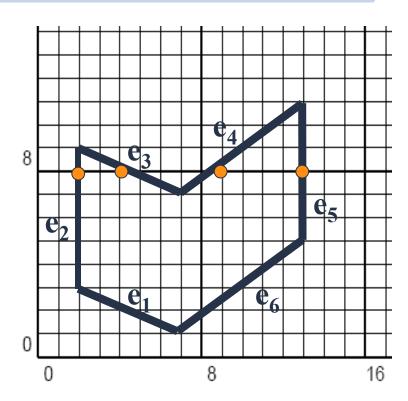


Popuna grafičkih primitiva

- Popuna poligona
- Popuna kruga
- Popuna elipse

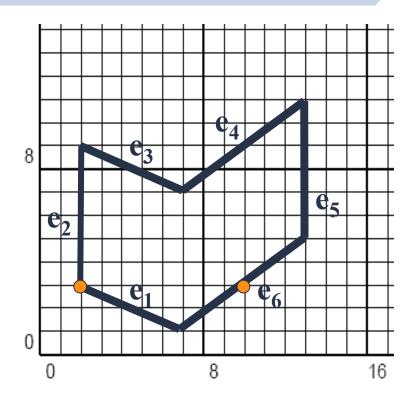


$$y = 8$$



$$x = 2,4,9,13$$

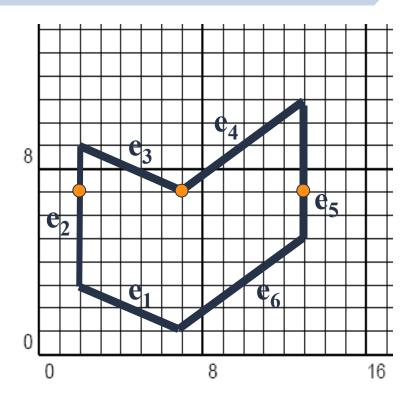




$$x = 2,2,10$$

Treba izbaciti jednu 2





$$x = 2,7,7,13$$

Ne treba izbaciti jednu 7

Treba uzeti oba principa ali treba razlikovati ova dva slučaja:

Ako se dvostruki presek nalazi na lokalnom minimumu ili maksimumu, treba uzeti presek kao dve tačke. U ostalim slučajevima treba uzimati presek kao jednu tačku.

$$x_{i+1} = x_i + \frac{1}{n}$$

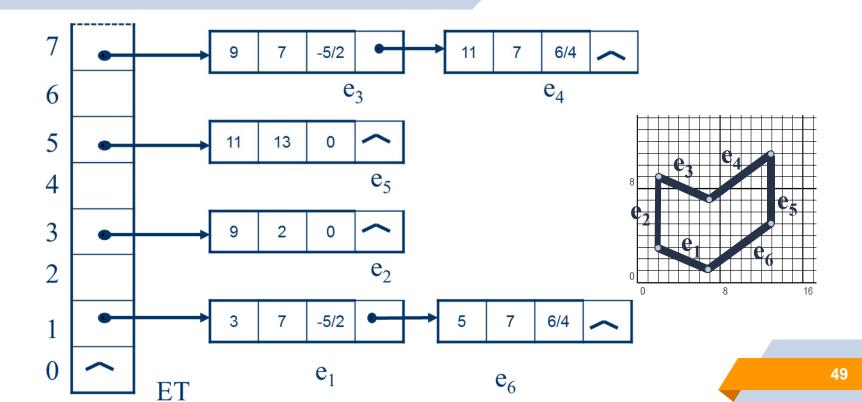
n – nagib linije

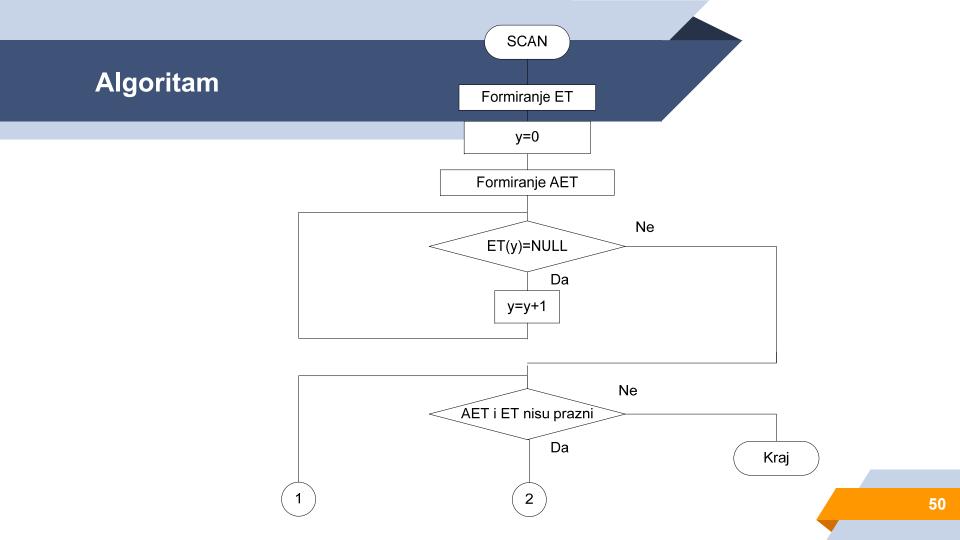
Koriste se dve tabele:

- Tabela ivica ET (Edge Table) tabela pointera na sken linije
- Tabela aktivnih ivica AET (Active Edge Table)



AET





Algoritam

2

Ulancavanje ET(y) u AET. Prva je stranica cije je ymin=y

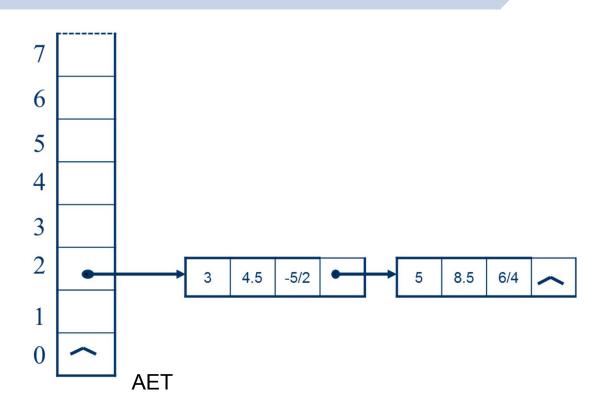
Izbacivanje iz AET onih ivica kod kojih je y=ymax

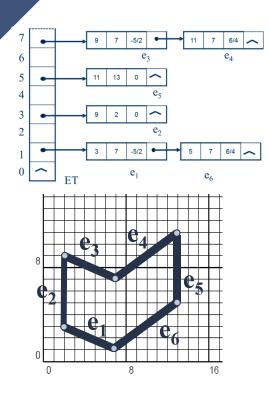
Sortiranje AET po x u rastuci redosled

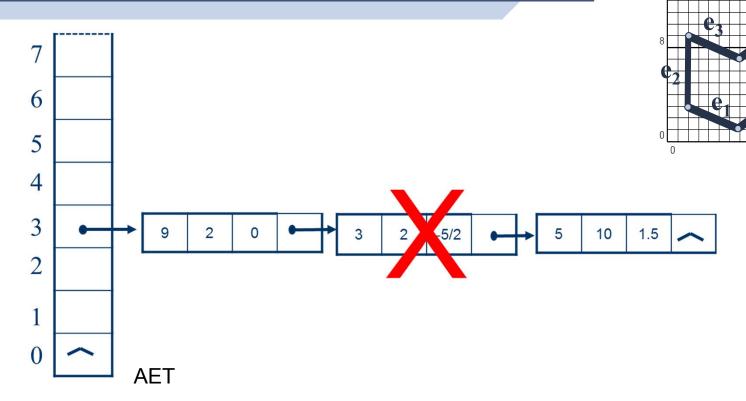
Popuniti piksele između svaka dva elementa u AET

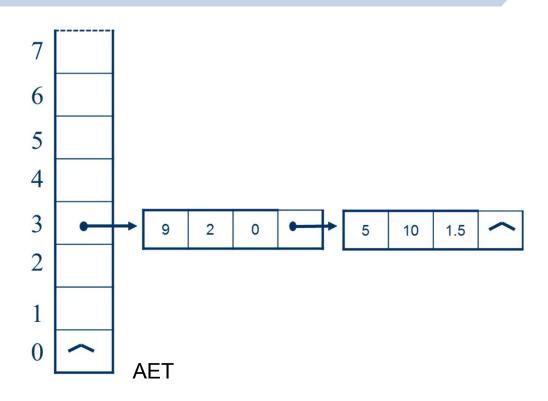
U svim elementima AET x=x+1/n

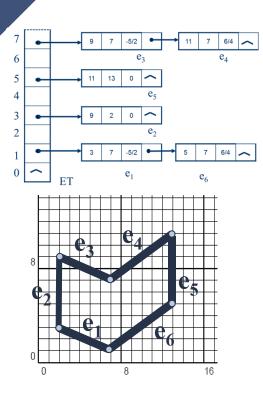
y=y+1

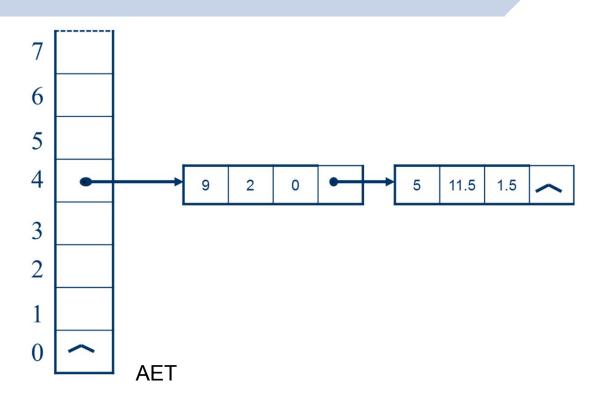


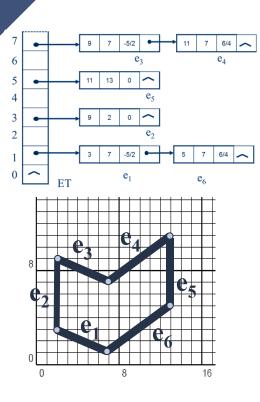


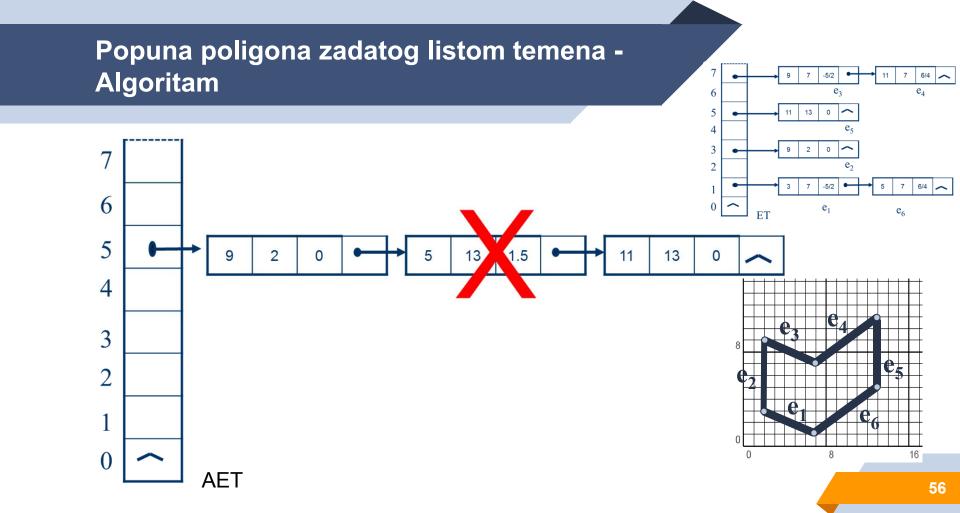


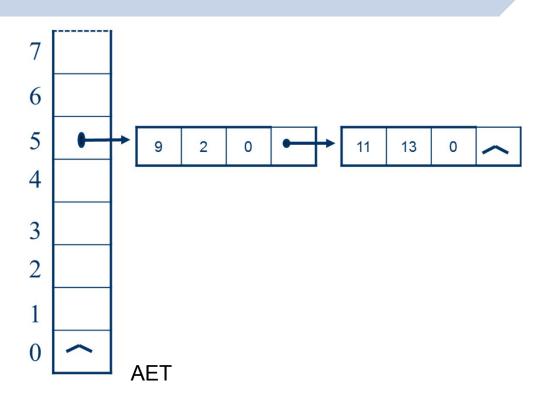


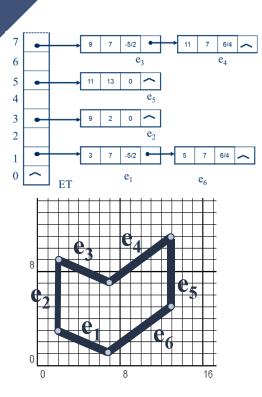


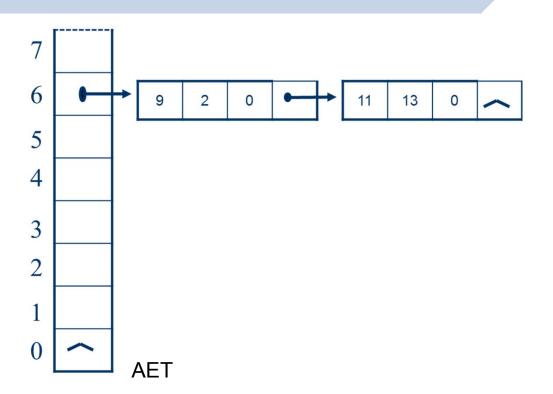


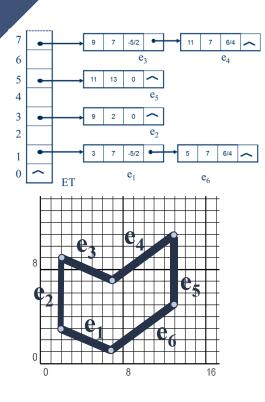




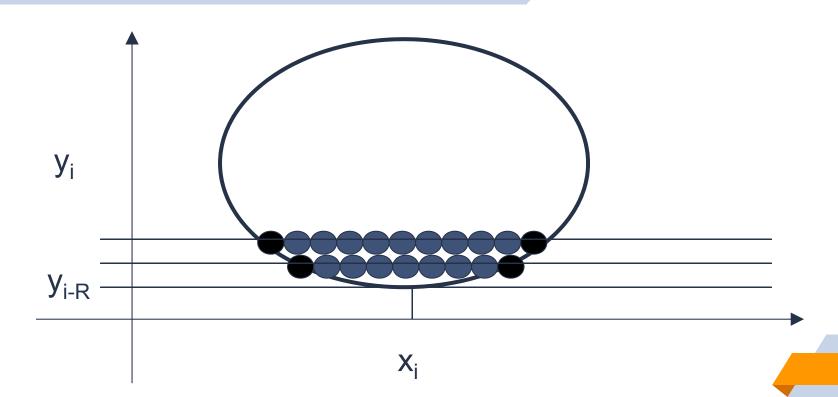








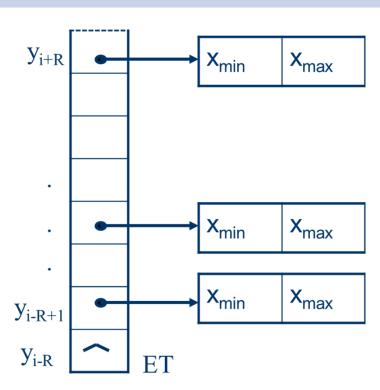
Popuna elipse i kruga



Popuna elipse i kruga

- Obzirom da znamo da svaka sken linija može 2 puta da preseče kružnicu ili elipsu, nema potrebe za AET.
- Obzirom da je reč o simetričnim figurama, možemo to da iskoristimo u algoritmu.

Popuna kruga i elipse – Algoritam



PITANJA

