auditory System todace ucz 5.6) q(0)= ap(0)+b p(0)+cp(0) use cos(a) + cos(b) = = (cos(a-b) + cos(a) ple) = ros(U, E) + cos(UzE) q(t)= a cos(u,t)+b(cox(u,t)+cos(u,t))+d(cox(u,t)+cos(u,t)) = a cos(U,t)+b(cos(U,t)+cos(U,t)+2cos(U,t)cos(u,t) + C ((cos3(Uzt) + cos3(Uzt) + 3 cos3(Uzt)cos(Uzt) + 3 cos3(Uzt) cos(Uzt) = a cos(u,t) + b[=+= cos(2U,t)+=+= cos(2U,t)+ cos(U,-U)+]+cos(U,+U)+] + ((=+= (os(24,t))(cos(4,t)+3 cos(4,t))+ (=+= (os(24,t))(cos(4,t)+3 cos(4,t)) = a cos(U, t)+b[...] (cos(UR) 2 Cos(Uz) + (cs(Uz)) 1 2 65 (Ust) 2 (05 (Ust) + 96 + C = (cos (Lit) + = (cos(U2t) + = (cos (Wit) + cos (2U,t))+ = (cos(2U,-U2) + (cos(2U,+U2)) + = (os(Uzt)+= cos(U, E)+ = (cos(Uzt)+cos(XLE)+= (cos(XLE)+= (cos(= $(ox(u,t)[a+\frac{3c}{4}]+cos(u,t)[a+\frac{9c}{4}]+cos(u,t)[\frac{b}{2}]+cos(u,t)[\frac{b}{2}]$ + cos((u,-u)+)[b]+cos((u,+u)+)[b]+cos((2U,-u)+)[\frac{3}{4}]+cos((2U,+u)+)[\frac{3}{4}] + cos((2),-1,)t)[3]+ (cs((21,+4)t)[3]+cos(x1,t)[4]+cos(x1,t)[4]+tos(x1

