

## § 1.6 continued

## (Applications)

Example

Find whole numbers  $x_1, x_2, x_3, x_4$  that balance the above reaction.

Solution  $x_1 \begin{pmatrix} 3 \\ 8 \\ 0 \end{pmatrix} + x_2 \begin{pmatrix} 0 \\ 2 \\ 2 \end{pmatrix} + x_3 \begin{pmatrix} -1 \\ 0 \\ 2 \end{pmatrix} + x_4 \begin{pmatrix} 0 \\ -2 \\ -1 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$

steps skipped  
 $\Rightarrow \vec{x} \in \text{Span} \left( \begin{pmatrix} 1 & 1 & 1 & 1 \\ 0 & 5 & -2 & -1 \end{pmatrix} \right)$ . The least integer solution is  $(1, 5, 3, 4)$ .

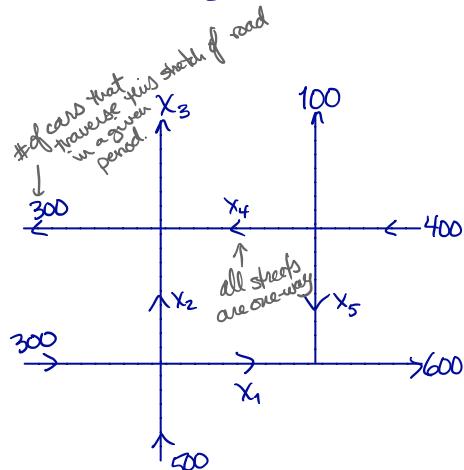
Example Describe the possible flows of traffic in the network shown.

Solution The constraints here are

linear: traffic in = traffic out

$$\Rightarrow x_2 + x_4 = x_3 + 300, \quad 400 = x_4 + x_5 + 100, \text{ etc.}$$

[steps skipped] Ultimately, we get  $\vec{x} = \begin{pmatrix} 600 - x_5 \\ 200 + x_5 \\ 400 \\ 500 - x_5 \\ x_5 \end{pmatrix}$ . So if we knew one more flow value, we'd know them all.



## §1.7 Linear dependence

We have a term for the concept of whether a list of vectors is redundant in the sense that one or more vectors can be dropped without changing the span:

Definition  $\{\vec{v}_1, \dots, \vec{v}_n\}$  is linearly independent if the only scalars  $c_1, \dots, c_n$  that make  $c_1\vec{v}_1 + \dots + c_n\vec{v}_n = \vec{0}$  are  $c_1 = c_2 = \dots = c_n = 0$ .

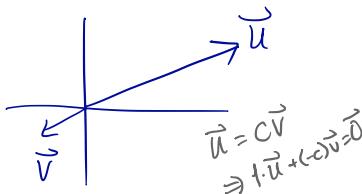
Theorem The following are equivalent:

- ①  $\vec{v}_1, \dots, \vec{v}_n$  are linearly dependent
- ② one of the vectors  $\vec{v}_1, \dots, \vec{v}_n$  can be written as a linear combination of the others.
- ③ one of the vectors may be dropped from the list without changing the span of the list.  
 $\stackrel{"\text{other than } \vec{v} = \vec{0}"}{=}$
- ④  $A\vec{x} = \vec{0}$  has a nontrivial solution, where  $A = (\vec{v}_1 \ \vec{v}_2 \ \dots \ \vec{v}_n)$  [i.e., the  $v_i$ 's are columns]

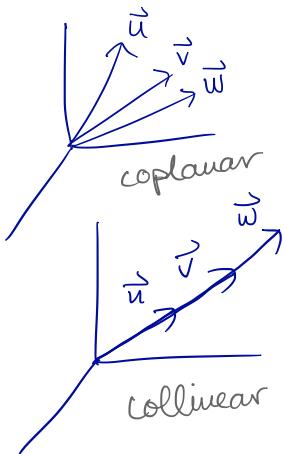
Linearly dependent

Graphically:

$$\{\vec{u}, \vec{v}\}$$

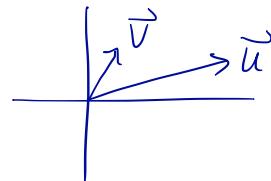


$$\{\vec{u}, \vec{v}, \vec{w}\} :$$

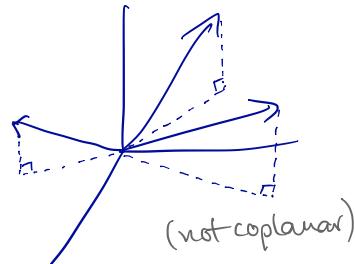


$$\{\vec{u}, \vec{v}, \vec{w}\} :$$

$$\{\vec{u}, \vec{v}\}$$



$$\{\vec{u}, \vec{v}, \vec{w}\}$$



Example Show that  $\left\{ \begin{pmatrix} 4 \\ 0 \\ 1 \end{pmatrix}, \begin{pmatrix} -2 \\ 3 \\ 2 \end{pmatrix}, \begin{pmatrix} 0 \\ 6 \\ 5 \end{pmatrix} \right\}$

is a linearly dependent list.

Solution: We have  $\begin{pmatrix} 4 & -2 & 0 & 0 \\ 0 & 3 & 6 & 0 \\ 1 & 2 & 5 & 0 \end{pmatrix} \rightarrow \begin{pmatrix} 4 & -2 & 0 & 0 \\ 0 & 3 & 6 & 0 \\ 0 & \frac{5}{2} & 5 & 0 \end{pmatrix} \rightarrow \begin{pmatrix} 4 & -2 & 0 & 0 \\ 0 & 3 & 6 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix}$

So  $x_3$  is free, and every nonzero value of  $x_3$  gives a nontrivial set of weights that annihilates the list. Like  $x_3=1$ ,   
  $= \text{makes equal to } 0$

$$x_2 = -\frac{6}{3}x_3 = -2, \quad x_1 = \frac{2}{4}x_2 = -1.$$

not a pivot column

## Explanation of theorem

①  $\Rightarrow$  ② Suppose  $\{\vec{v}_1, \dots, \vec{v}_n\}$  is linearly dependent, so there exist  $c_1, \dots, c_n$  not all zero with

$$c_1\vec{v}_1 + \dots + c_n\vec{v}_n = 0$$

Let  $c_k$  be one of the nonzero scalars, let's assume  $k=1$  for simplicity. Then

$$\frac{c_1\vec{v}_1}{c_1} = -\frac{c_2\vec{v}_2 - c_3\vec{v}_3 - \dots - c_n\vec{v}_n}{c_1} \Rightarrow$$

$$\vec{v}_1 = -\frac{c_2}{c_1}\vec{v}_2 - \dots - \frac{c_n}{c_1}\vec{v}_n.$$

So one of the vectors is a linear combination of the others.

②  $\Rightarrow$  ③ Suppose one vector is a linear combination of the others, like  $v_1 = c_2v_2 + \dots + c_nv_n$ . Then any lin. com. of

$\{\vec{v}_1, \dots, \vec{v}_n\}$  is also a lin. com. of  $\{\vec{v}_2, \dots, \vec{v}_n\}$  since we can sub.:

$$d_1\vec{v}_1 + \dots + d_n\vec{v}_n = d_1(c_2\vec{v}_2 + \dots + c_n\vec{v}_n) + d_2\vec{v}_2 + \dots + d_n\vec{v}_n = (d_1c_2 + d_2)\vec{v}_2 + \dots + (d_1c_n + d_n)\vec{v}_n$$

③  $\Rightarrow$  ① If  $\text{Span}(\{\vec{v}_2, \dots, \vec{v}_n\}) = \text{Span}(\{\vec{v}_1, \dots, \vec{v}_n\})$ , then since  $\vec{v}_1 \in \text{Span}(\{\vec{v}_1, \dots, \vec{v}_n\})$ , we have

$$\vec{v}_1 = c_2 \vec{v}_2 + \dots + c_n \vec{v}_n$$

for some  $c_2, \dots, c_n$ . Therefore,

$$\vec{v}_1 - c_2 \vec{v}_2 - \dots - c_n \vec{v}_n = \vec{0}$$

(this weight (1) is not zero)

which means  $\{\vec{v}_1, \dots, \vec{v}_n\}$  is linearly dependent.

④  $\Leftarrow$  ④ Since  $A\vec{x}$  is defined to be the linear combination of the columns of  $A$  with weights given by the entries of  $\vec{x}$ , the existence of a nontrivial solution of  $A\vec{x} = \vec{0}$  directly demonstrates linear dependence & vice versa.

**Exercise** Show that if  $\vec{0}$  is in a list of vectors, then the list is linearly dependent.

Solution  $\underbrace{0\vec{v}_1}_{\vec{0}} + \dots + \underbrace{1\vec{v}_1}_{\vec{0}} + \dots + \underbrace{0\vec{v}_n}_{\vec{0}} = \vec{0}$ .

Exercise Show that if  $k > m$ , then any list of  $k$  vectors is linearly dependent.

Solution We want to show  $A\vec{x} = \vec{0}$  has a nontrivial solution, where  $A$ 's columns are the vectors in our list. However, since there are  $\binom{k-m}{m}$  more columns than rows, there are at least  $k-m$  non-pivot columns. So there are infinitely many solutions to  $A\vec{x} = \vec{0}$ .

Geometric intuition: at most 1 vector fits in a line, at most two fit in the plane, 3 in space, etc., where 'fit' means that if you try to squeeze one more in, it will have to be in the span of the previous ones (assuming they weren't already linearly dependent.)