

## §1.4 Matrix-vector products

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It is useful to have a more direct way to say "think of this matrix as representing a system of equations," with the variables included explicitly. We do this by putting them in a column to the side:

$$\begin{array}{rcl} 2x_1 - x_2 & = 5 \\ 7x_1 + x_3 & = 0 \end{array} \rightarrow \left( \begin{matrix} 2 & -1 & 0 \\ 7 & 0 & 1 \end{matrix} \right) \left( \begin{matrix} x_1 \\ x_2 \\ x_3 \end{matrix} \right) = \left( \begin{matrix} 5 \\ 0 \end{matrix} \right)$$

matrix-vector product.

To facilitate this, we define the **product** of an  $m \times n$  matrix and an  $n \times 1$  vector to be the  $m \times 1$  vector obtained as a linear combination of the columns of the matrix with weights given by the entries of the vector. So, for example,

$$\begin{pmatrix} 2 & -1 & 0 \\ 7 & 0 & 1 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} 2 \\ 7 \end{pmatrix} x_1 + \begin{pmatrix} -1 \\ 0 \end{pmatrix} x_2 + \begin{pmatrix} 0 \\ 1 \end{pmatrix} x_3$$

$$= \begin{pmatrix} 2x_1 - x_2 \\ 7x_1 + x_3 \end{pmatrix}.$$

We can also think of it like this:

$$\rightarrow \begin{pmatrix} 2 & -1 & 0 \\ 7 & 0 & 1 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} 2x_1 + (-1)x_2 + 0x_3 \end{pmatrix}$$

$$\rightarrow \begin{pmatrix} 2 & -1 & 0 \\ 7 & 0 & 1 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} = \begin{pmatrix} 7x_1 + 0x_2 + 1x_3 \end{pmatrix}$$

multiply in pairs & sum  
a.k.a. "dot"

Note that for  $m \times n$  times  $k \times 1$  to work, we need  $n = k$ :

$$(m \times n) (n \times 1) = m \times 1$$

must match!  
then get gobble up

**Example** Calculate  $\begin{pmatrix} 1 & 2 & 3 & 4 \\ 5 & 6 & 7 & 8 \end{pmatrix} \begin{pmatrix} 1 \\ 0 \\ 2 \\ 0 \end{pmatrix}$ .

Solution

$$\begin{pmatrix} 1(-1) + 2(0) + 3(2) + 4(0) \\ 5(-1) + 6(0) + 7(2) + 8(0) \end{pmatrix} = \begin{pmatrix} 5 \\ 9 \end{pmatrix}$$

← column vectors of A

**Theorem** If  $A = (\vec{a}_1, \vec{a}_2, \dots, \vec{a}_n)$  and  $\vec{b} \in \mathbb{R}^m$

then

$$A\vec{x} = \vec{b} \quad \begin{matrix} 1: \text{matrix} \\ \text{equation} \end{matrix}$$

↑  $\vec{b}$  is an  
 $m \times 1$  vector

is equivalent to  $x_1\vec{a}_1 + \dots + x_n\vec{a}_n = \vec{b}$  <sup>2: vector</sup><sub>equation</sub>

and to the system with augmented matrix  
 $(\vec{a}_1 \dots \vec{a}_n | \vec{b})$ . <sup>3: system of linear equations</sup>

**Fact**  $A\vec{x} = \vec{b}$  has a solution if and only if

$\vec{b}$  is in the span of A's columns.

Note: this follows directly from the theorem above.

Example Is  $\vec{A}\vec{x} = \vec{b}$  consistent for all  $\vec{b} \in \mathbb{R}^3$ ,

if  $A = \begin{pmatrix} 1 & 3 & 4 \\ -4 & 2 & -6 \\ -3 & -2 & -7 \end{pmatrix}$  ?

Solution

We can row reduce

$$\left( \begin{array}{ccc|c} 1 & 3 & 4 & b_1 \\ -4 & 2 & -6 & b_2 \\ -3 & -2 & -7 & b_3 \end{array} \right)$$

by hand or using  
Julia [with the  
SymPy package, for  
handling variables].

Since  $b_1 - \frac{1}{2}b_2 + b_3$  is

not always zero, the system is not always  
consistent.

Note that the only way A could 'stop'  
what happened in this example is by having

```
In [1]: using SymPy
using IntroLinearAlgebra
```

  

```
In [2]: @vars b_1 b_2 b_3 # declare b_1, b_2, b_3
          # to be symbols
```

```
Out[2]: (b_1,b_2,b_3)
```

```
In [3]: M = [1 3 4 b_1; -4 2 -6 b_2; -3 -2 -7 b_3]
```

  

```
Out[3]: ⎡ 1   3   4   b₁ ⎤
          ⎢ -4  2  -6  b₂ ⎥
          ⎣ -3 -2 -7  b₃ ⎦
```

```
In [4]: M = rowadd(M,2,1,4)
```

```
Out[4]: ⎡ 1   3   4   b₁ ⎤
          ⎢ 0   14  10  4b₁ + b₂ ⎥
          ⎣ -3 -2 -7  b₃ ⎦
```

```
In [5]: M = rowadd(M,3,1,3)
```

```
Out[5]: ⎡ 1   3   4   b₁ ⎤
          ⎢ 0   14  10  4b₁ + b₂ ⎥
          ⎣ 0   7   5   3b₁ + b₃ ⎦
```

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In [6]: M = rowadd(M,3,2,-1//2)
```

```
Out[6]: ⎡ 1   3   4   b₁ ⎤
          ⎢ 0   14  10  4b₁ + b₂ ⎥
          ⎣ 0   0   0   b₁ - b₂/2 + b₃ ⎦
```

a pivot in each row. So:

**Theorem** The following are equivalent:

- { (a matter of definition)  
interesting! → } (a) The columns of  $A$  span  $\mathbb{R}^m$   
(b) Each  $b \in \mathbb{R}^m$  is a linear combination of  
the columns of  $A$   
(c)  $A\vec{x} = b$  has a solution for all  $b \in \mathbb{R}^m$   
(d)  $A$  has a pivot position in each row

### Linearity

The matrix-vector product is linear, meaning

that:

- ①  $A(\vec{u} + \vec{v}) = A\vec{u} + A\vec{v}$ , for all  $A, \vec{u}, \vec{v}$ , and
- ②  $A(c\vec{u}) = cA\vec{u}$  for all  $A, \vec{u}$ , and  $c$ .

Why? If  $A = (\vec{a}_1 \dots \vec{a}_n)$ , then  $A(\vec{u} + \vec{v}) = \vec{a}_1(u_1 + v_1) + \dots + \vec{a}_n(u_n + v_n) = (\vec{a}_1 u_1 + \vec{a}_1 v_1) + \dots + (\vec{a}_n u_n + \vec{a}_n v_n) = A\vec{u} + A\vec{v}$ .

Similarly for  $A(c\vec{u}) = c(A\vec{u})$ .

**Exercise** Suppose the columns of a  $3 \times 3$  matrix  $A$  do not span  $\mathbb{R}^3$ . Show that  $A\vec{x} = \vec{b}$  has either 0 solutions or infinitely many solutions.

**Exercise** Suppose that the columns of a  $5 \times 8$  matrix  $A$  span  $\mathbb{R}^5$ . How many solutions does  $A\vec{x} = \vec{b}$  have, for any  $\vec{b}$ ?

**Exercise** What is the minimum number of vectors needed to span  $\mathbb{R}^4$ ?

**Exercise** Find a column of

$$\begin{pmatrix} 2 & 0 & 4 & 7 \\ -1 & 3 & 2 & 4 \\ -6 & 5 & 1 & 1 \end{pmatrix}$$

that can be removed & still have the remaining columns span  $\mathbb{R}^3$ .

rows, columns  
rref( $M$ [[  
true, true, true, false]])  
# colon means "take 'em all"  
# array TTTF means "keep 1,2,3, drop 4"

$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$