Robust Weighting and Matching Techniques for Causal Inference in Observational Studies with Continuous Treatment



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1 Introduction

2 Balancing Weights

2.1 Introduction

2.2 Estimating the Population Mean of Potential Outcomes

2.3 Application of Convex Optimization

Assumption 2.1. Assume that the map $f : \mathbb{R} \to \overline{\mathbb{R}}$ has the following properties.

- (i) f is strictly convex.
- (ii) f is lower-semicontinuous and continuously differentiable on int(dom(f)).
- (iii) The derivative of f on int(dom(f)) is a diffeomorphism.
- (iv) The Legendre transformation f^* of f is finite.
- (v) The function $x \mapsto xt f(x)$ takes its supremum on $\operatorname{int}(\operatorname{dom}(f))$ for all $t \in \mathbb{R}$.

We consider the following optimization problem.

Problem 2.1.

$$\underset{w_1,\dots,w_n\in\mathbb{R}}{\text{minimize}} \qquad \sum_{i=1}^n T_i f(w_i)$$

subject to the constraints

$$w_i T_i \ge 0, \qquad i = 1, \dots, n,$$

$$\sum_{i=1}^n w_i T_i = 1$$

$$\left| \sum_{i=1}^n w_i T_i B_k(X_i) - \frac{1}{n} \sum_{i=1}^n B_k(X_i) \right| \le \delta_k, \qquad k = 1, \dots, K$$

Theorem 2.1. Under Assumption, the dual of the above Problem is the unconstrained optimization problem

$$\underset{\lambda \in \mathbb{R}^K}{\text{minimize}} \qquad \frac{1}{n} \sum_{i=1}^n nT_i f^*(\langle B(X_i), \lambda \rangle) - \langle B(X_i), \lambda \rangle + \langle \delta, |\lambda| \rangle,$$

where $t \mapsto f^*(t) = t(f')^{-1}(t) - f((f')^{-1}(t))$ is the Legendre transformation of f, $B(X_i) = [B_1(X_i), \ldots, B_K(X_i)]^{\top}$ denotes the K basis functions of the covariates of unit $i \in \{1, \ldots, n\}$ and $|\lambda| = [|\lambda_1|, \ldots, |\lambda_K|]^{\top}$, where $|\cdot|$ is the absolute value of a real-valued scalar. Moreover, if λ^{\dagger} is an optimal solution then

$$w_i^* = (f')^{-1}(\langle B(X_i), \lambda^{\dagger} \rangle), \quad i \in \{1, \dots, n\}$$
 (2.1)

are the unique optimal solutions to (P).

Proof. We prove the following Lemma at the end of the section.

Lemma 2.1. The dual of the optimization problem is

$$\underset{\lambda \in \mathbb{R}^{2K}}{\text{minimize}} \qquad \frac{1}{n} \sum_{i=1}^{n} n T_{i} f^{*}(\langle Q_{\bullet i}, \lambda \rangle) - \langle Q_{\bullet i}, \lambda \rangle + \langle d, \lambda \rangle$$

subject to

$$\lambda_k \ge 0 \quad \text{for all } k \in \{1, \dots, K\}, \tag{2.2}$$

where

$$\mathbf{Q} := \begin{bmatrix} \mathbf{I}_n \\ \mathbf{B}(\mathbf{X}) \\ -\mathbf{B}(\mathbf{X}) \end{bmatrix}, \quad \mathbf{B}(\mathbf{X}) := \begin{bmatrix} B(X_1), \dots, B(X_n) \end{bmatrix}, \quad and \quad d := \begin{bmatrix} 0_n \\ \delta \\ \delta \end{bmatrix}. \quad (2.3)$$

2.4 Application of Matrix Concentration Inequalities

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3 Convex Analysis

3.1 Basic Notions

3.2 Relative Interior

3.3 Conjugate Calculus

3.4 Tseng Bertsekas

We present the relevant parts of the paper [BT03]. Consider the following optimization problem

$$\underset{x \in \mathbb{R}^m}{\text{minimize}} \qquad f(x)$$

subject to the constraints

$$\mathbf{A}x \ge b,\tag{3.1}$$

Where $f: \mathbb{R}^m \to \overline{\mathbb{R}}$, **A** is a given $n \times m$ matrix, and b is a vector in \mathbb{R}^n .

Assumption 3.1. Assume that the map $f: \mathbb{R}^m \to \overline{\mathbb{R}}$ has the following properties.

- (i) f is strictly convex.
- (ii) f is lower-semicontinuous and continuous dom(f).
- (iii) The convex conjugate f^* of f is finite.

Proposition 3.1. (Danskin's Theorem [BT03, page 649]) text

Definition 3.1. [Roc70, §28] By an **ordinary convex program** (P) we mean an optimization problem of the following form

$$\underset{x \in C}{\text{minimize}} \qquad f_0(x)$$

subject to the constraints

$$f_1(x) \le 0, \dots, f_r(x) \le 0, \qquad f_{r+1}(x) = 0, \dots, f_m(x) = 0,$$
 (3.2)

where $C \subseteq \mathbb{R}^n$ is a non-empty convex set, f_i is a finite convex function on C for $i \in \{1, ..., r\}$ and f_i is an affine function on C for $i \in \{r+1, ..., m\}$.

Definition 3.2. We define $[\lambda_1, \ldots, \lambda_m] \in \mathbb{R}^m$ to be a **Karush-Kuhn-Tucker (KKT) vector** for (P), if

- (i) $\lambda_i \geq 0$ for all $i \in \{1, \ldots, r\}$.
- (ii) The infimum of the proper convex function $f_0 + \sum_{i=1}^m \lambda_1 f_i$ is finite and equal to the optimal value in (P).

Theorem 3.1. (Karush-Kuhn-Tucker conditions) Let (P) be an ordinary convex program, $\overline{\alpha} \in \mathbb{R}^m$, and $\overline{z} \in \mathbb{R}^n$. Then $\overline{\alpha}$ is a KKT vector for (P) and \overline{z} is an optimal solution to (P) if and only if \overline{z} and the components α_i of $\overline{\alpha}$ satisfy the following conditions.

- (i) $\alpha_i \geq 0$, $f_i(\overline{z}) \leq 0$, and $\alpha_i f_i(\overline{z}) = 0$ for all $i \in \{1, \dots, r\}$.
- (ii) $f_i(\overline{z}) = 0$ for $i \in \{r+1,\ldots,m\}$.
- (iii) $0_n \in [\partial f_0(\overline{z}) + \sum_{\alpha_i \neq 0} \alpha_i \partial f_i(\overline{z})].$

Proof. [Roc70, Theorem 28.3]

4 Random Matrix Inequalities

4.1 Matrix Analysis

The **trace** of a square matrix, denoted by tr, is the sum of its diagonal entries, i.e. $\operatorname{tr}(\mathbf{B}) = \sum_{j=1}^{d} b_{jj}$ for $\mathbf{B} \in \mathbb{M}_d$. The trace is unitarily invariant, i.e. $\operatorname{tr}(\mathbf{B}) = \operatorname{tr}(\mathbf{Q}\mathbf{B}\mathbf{Q}^*)$ for all $\mathbf{B} \in \mathbb{M}_d$ for all unitary $\mathbf{Q} \in \mathbb{M}_d$. In particular, the existence of an eigenvalue value decomposition shows that the trace of a Hermitian matrix equals the sum of its eigenvalues. Let $f: I \to \mathbb{R}$ where $I \subseteq \mathbb{R}$ is an interval. Consider a matrix $\mathbf{A} \in \mathbb{H}_d$ whose eigenvalues are contained in I. We define the matrix $f(\mathbf{A}) \in \mathbb{H}_d$ using an eigenvalue decomposition of \mathbf{A} :

$$f(\mathbf{A}) = \mathbf{Q} \begin{bmatrix} f(\lambda_1) & & \\ & \ddots & \\ & & f(\lambda_d) \end{bmatrix} \mathbf{Q}^* \quad \text{where} \quad \mathbf{A} = \mathbf{Q} \begin{bmatrix} \lambda_1 & & \\ & \ddots & \\ & & \lambda_d \end{bmatrix} \mathbf{Q}^*. \quad (4.1)$$

The definition of $f(\mathbf{A})$ does not depend on which eigenvalue decomposition we choose. Any matrix function that arises in this fashion is called a **standard matrix function**.

Proposition 4.1. Let $f, g : I \to \mathbb{R}$ be real-valued functions on an interval $I \subseteq \mathbb{R}$, and let $\mathbf{A} \in \mathbb{H}_d$ be a Hermitian matrix whose eigenvalues are contained in I.

- (i) If λ is an eigenvalue of of \mathbf{A} , then $f(\lambda)$ is an eigenvalue of $f(\mathbf{A})$.
- (ii) $f(a) \le g(a)$ for all $a \in I$ implies $f(\mathbf{A}) \preccurlyeq g(\mathbf{A})$.

4.2 Matrix Khintchin Inequality

Theorem 4.1. [MJC⁺14, Corollary 7.3] Suppose that p = 1 or $p \geq 3/2$. Consider a finite sequence $(\mathbf{Y}_k)_{k\geq 1}$ of independent, random, Hermitian matrices and a deterministic sequence $(\mathbf{A}_k)_{k\geq 1}$ for which

$$\mathbf{E}[\mathbf{Y}_k] = 0$$
 and $\mathbf{Y}_k^2 \leq \mathbf{A}_k^2$ almost surely for all $k \geq 1$. (4.2)

Then

$$\mathbf{E}\left[\left\|\sum_{k\geq 1}\mathbf{Y}_{k}\right\|_{2p}^{2p}\right]^{1/(2p)} \leq \sqrt{p-\frac{1}{2}}\left\|\left(\sum_{k\geq 1}(\mathbf{A}_{k}^{2}+\mathbf{E}[\mathbf{Y}_{k}^{2}])\right)^{1/2}\right\|_{2p}.$$
(4.3)

In particular, when $(\xi_k)_{k\geq 1}$ is an independent sequence of Rademacher random variables,

$$\mathbf{E}\left[\left\|\sum_{k\geq 1}\xi_k\mathbf{A}_k\right\|_{2p}^{2p}\right]^{1/(2p)} \leq \sqrt{2p-1}\left\|\left(\sum_{k\geq 1}\mathbf{A}_k^2\right)^{1/2}\right\|_{2p}.$$
(4.4)

4.3 Matrix Moment Inequality

Theorem 4.2. Assume $n \geq 3$

(i) Suppose that $p \geq 1$, and fix $r \geq p \vee 2\log(n)$. Consider a finite sequence $(\mathbf{S}_k)_{k\geq 1}$ of independent, random, positive-semidefinite matrices with dimension $n \times n$. Then

$$\mathbf{E}\left[\left\|\sum_{k\geq 1}\mathbf{S}_{k}\right\|^{p}\right]^{1/p} \leq \left[\left\|\sum_{k\geq 1}\mathbf{E}[\mathbf{S}_{k}]\right\|^{1/2} + 2\sqrt{er}\mathbf{E}\left[\max_{k\geq 1}\left\|\mathbf{S}_{k}\right\|^{p}\right]^{1/(2p)}\right]^{2}.$$
 (4.5)

(ii) Suppose that $p \geq 2$, and fix $r \geq p \vee 2\log(n)$. Consider a finite sequence $(\mathbf{Y}_k)_{k\geq 1}$ of independent, symmetric, random, self-adjoint matrices with dimension $n \times n$. Then

$$\mathbf{E}\left[\left\|\sum_{k\geq 1}\mathbf{Y}_{k}\right\|^{p}\right]^{1/p} \leq \sqrt{er}\left\|\left(\sum_{k\geq 1}\mathbf{E}[\mathbf{Y}_{k}^{2}]\right)^{1/2}\right\| + 2er\mathbf{E}\left[\max_{k\geq 1}\left\|\mathbf{S}_{k}\right\|^{p}\right]^{1/p}.$$
 (4.6)

4.4 Intrinsic Dimension

Definition 4.1. For a positive-semidefinite matrix **S**, the **intrinic dimension** is the quantity

$$\operatorname{intdim}(\mathbf{A}) := \frac{\operatorname{tr} \mathbf{A}}{\|\mathbf{A}\|}.$$

Lemma 4.1. (Intrinsic dimension) Let $\varphi : [0, \infty) \to \mathbb{R}$ be a convex function with $\varphi(0) = 0$. For any positive-semidefinite matrix \mathbf{S} it holds that

$$\operatorname{tr}(\varphi(\mathbf{S})) \leq \operatorname{intdim}(\mathbf{S}) \cdot \varphi(\|\mathbf{S}\|).$$

Proof. [Tro15, Lemma 7.5.1] Since φ is convex on any interval [0, L] with L > 0 and $\varphi(0) = 0$, it holds

$$\varphi(a) \le \left(1 - \frac{a}{L}\right)\varphi(0) + \frac{a}{L}\varphi(L) = \frac{a}{L}\varphi(L) \quad \text{for all } a \in [0, L].$$
 (4.7)

Since **S** is positive-semidefinite, the eigenvalues of **S** fall in the interval [0, L], where $L = ||\mathbf{S}||$.

$$\operatorname{tr}(\varphi(\mathbf{S})) = \sum_{i=1}^{d} \varphi(\lambda_i) \le \frac{\sum_{i=1}^{d} \lambda_i}{\|\mathbf{S}\|} \varphi(\|\mathbf{S}\|) = \frac{\operatorname{tr}(\mathbf{S})}{\|\mathbf{S}\|} \varphi(\|\mathbf{S}\|) = \operatorname{intdim}(\mathbf{S}) \cdot \varphi(\|\mathbf{S}\|). \tag{4.8}$$

5 Empirical Processes

Let $(\Omega, \mathcal{A}, \mathbf{P})$ be a probability space and (\mathcal{X}, Σ) a measurable space. Let $X_j : (\Omega, \mathcal{A}, \mathbf{P}) \to (\mathcal{X}, \Sigma), j = 1, \ldots, n$ be independent and identically-distributed (i.i.d.) random variables with probability distribution \mathbf{P}_X and \mathcal{F} a family of measurable functions $f : (\mathcal{X}, \Sigma) \to (\mathbb{R}, \mathcal{B}(\mathbb{R}))$. Consider the map

$$f \mapsto G_n f := \sqrt{n} \left(\frac{1}{n} \sum_{i=1}^n f(X_i) - \mathbf{P}_X f \right),$$
 (5.1)

where $\mathbf{P}_X f := \int_{\mathcal{X}} f d\mathbf{P}_X$. We call $(G_n f)_{f \in \mathcal{F}}$ the empirical process indexed by \mathcal{F} . Furthermore

$$||G_n f||_{\mathcal{F}} := \sup_{f \in \mathcal{F}} |G_n f|. \tag{5.2}$$

Lemma 5.1. (Bernstein Inequality for Empirical Processes) For any bounded, measurable function f it holds for all t > 0

$$\mathbf{P}(|G_n f| > t) \le 2 \exp\left(-\frac{1}{4} \frac{t^2}{\mathbf{P}_X(f^2) + t \|f\|_{\infty} / \sqrt{n}}\right)$$
 (5.3)

Proof. By the Markov inequality it holds for all $\lambda > 0$

$$\mathbf{P}(G_n f > t) \le e^{-\lambda t} \mathbf{E} \exp(\lambda G_n f)$$
(5.4)

Lemma 5.2. For any finite class \mathcal{F} of bounded, measurable, square-integrable functions, with $|\mathcal{F}|$ elements, it holds

$$\mathbf{E} \|G_n f\|_{\mathcal{F}} \lesssim \max_{f \in \mathcal{F}} \frac{\|f\|_{\infty}}{\sqrt{n}} \log \left(1 + |\mathcal{F}|\right) + \max_{f \in \mathcal{F}} \|f\|_{\mathbf{P}, 2} \sqrt{\log \left(1 + |\mathcal{F}|\right)}. \tag{5.5}$$

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6 Simple yet useful Calculations

Theorem 6.1. (Multivariate Taylor Theorem) Let $f \in C^2(\mathbb{R}^n, \mathbb{R})$. Then for all $x, \Delta \in \mathbb{R}^n$ there exists $\xi \in [0, 1]$ such that it holds

$$f(x + \Delta) = f(x) + \sum_{i=1}^{n} \frac{\partial f(x)}{\partial x_i} \Delta_i + \sum_{\substack{i,j=1\\i \neq j}} \frac{\partial^2 f(x + \xi \Delta)}{\partial x_i \partial x_j} \Delta_i \Delta_j$$

$$+ \frac{1}{2} \sum_{i=1}^{n} \frac{\partial^2 f(x + \xi \Delta)}{\partial x_i^2} \Delta_i^2$$
(6.1)

Corollary 6.1.1. Let $f \in C^2(\mathbb{R})$. Then for all $a, x, \Delta \in \mathbb{R}^n$ there exist $\xi \in [0, 1]$ such that it holds

$$f(a^{T}(x+\Delta)) - f(a^{T}x) = f'(a^{T}x) \Delta^{T}a + \frac{1}{2}f''(a^{T}(x+\xi\Delta)) \Delta^{T}A \Delta,$$
 (6.2)

where $A := aa^T \in \mathbb{R}^{n \times n}$.

Proof. By the chain rule we have for all $a, x, \Delta \in \mathbb{R}^n$ and $\xi \in [0, 1]$

$$\frac{\partial^2 f(a^T(x+\xi\Delta))}{\partial x_i \partial x_i} = f''(a^T(x+\xi\Delta)) a_i a_j.$$
(6.3)

Since $A := aa^T$ is symmetric we have

$$\Delta^T A \ \Delta = 2 \sum_{\substack{i,j=1\\i\neq j}}^n a_i a_j \Delta_i \Delta_j + \sum_{i=1}^n a_i^2 \Delta_i^2.$$
 (6.4)

Plugging (6.3) and (6.4) into (6.1) yields (6.2).

Proposition 6.1. For all $x, y \in \mathbb{R}$ it holds

$$|x+y| - |x| \ge -|y| \tag{6.5}$$

Proof. Checking all 6 combinations of x + y, x, y being nonnegative or negative yields the result.

Notation Index

#A cardinality of the set A

 $\mathbf{E}[X|Y]$ conditional expectation of the random variable X with respect to $\sigma(Y)$

 $\mathbf{E}[X]$ expectation of the random variable X

Var[X] variance of the random variable X

 $\overline{\mathbb{R}} = \mathbb{R} \cup \{+\infty\}$ extension of the real numbers

 $\xrightarrow{\mathcal{D}}$ convergence of distributions

P generic probability measure

 $\mathbf{P}_X = \mathbf{P} \circ X^{-1}$ distribution of the random variable X

 \mathbb{R} set of real numbers

 $x \vee y, x \wedge y, x^+, x^-$ maximum, minimum, positive part, negative part of real numbers

 $X\sim \mu\,$ the random variable has distribution $\mu\,$

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