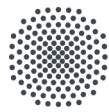


Robust Weighting and Matching Techniques for Causal Inference in Observational Studies with Continuous Treatment

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Chapter 1

Introduction

Researchers are often left with observational studies to answer questions about causality. When confounders are present the task of inferring causality can become arbitrarily complex. Propensity score methods [6], e.g. inverse probability weighting or matching, are popular methods to adjust for confounders. Usually these methods rely heavily on estimates of the true propensity score, which are known to suffer from model dependencies and misspecification [4]. This issue becomes more pressing when moving from binary to continuous treatment [3]. Therefore methods have been developed to directly target imbalances in the data [1] [2] [11]. We take a closer look at [10] and extend the analysis to settings with continuous treatment [9] [8].

Chapter 2

Balancing Weights

Assumption 1. Assume, the following conditions hold:

1.1. The minimizer $\lambda_0 = \arg \min_{\lambda \in \Theta} \mathbb{E} [-Tn\rho (B(X)^T \lambda) + B(X)^T \lambda]$ is unique, where $\Theta \subseteq \mathbb{R}^n$ is the parameter space for λ .

1.2. The parameter space $\Theta \subseteq \mathbb{R}^n$ is compact.

1.3. $\lambda_0 \in \text{int}(\Theta)$, where $\text{int}(\cdot)$ stands for the interior of a set.

1.4. There exists $\lambda_1^* \in \Theta$ such that $\|m^*(\cdot) - B(\cdot)^T \lambda_1^*\|_\infty \leq \varphi_{m^*}$, where $m^*(\cdot) := (\rho')^{-1} \left(\frac{1}{n\pi(\cdot)} \right)$.

1.5. There exists a constant $\varphi_\pi \in (0, \frac{1}{2})$ such that $\pi(x) \in (\varphi_\pi, 1 - \varphi_\pi)$ for all $x \in \mathcal{X}$

1.6. There exists $\varphi_{\rho''} > 0$ such that $-\rho'' \geq \varphi_{\rho''} > 0$

1.7. There exists $\varphi_{B(x)B(x)^T} > 0$ such that $B(x)B(x)^T \succcurlyeq \varphi_{B(x)B(x)^T} I$

1.8. There exists $\varphi_{\|B\|} > 0$ such that $\sup_{x \in \mathcal{X}} \|B(x)\|_2 \leq \varphi_{\|B\|}$.

1.9. The number of basis functions satisfies $K = o(n)$.

We study the following problem:

$$\begin{aligned}
 & \underset{w \in \mathbb{R}^n}{\text{minimize}} && \sum_{i=1}^n T_i f(w_i) \\
 & \text{subject to} && \left| \sum_{i=1}^n w_i T_i B_k(X_i) - \frac{1}{n} \sum_{i=1}^n B_k(X_i) \right| \leq \delta_k, \quad k = 1, \dots, K
 \end{aligned} \tag{2.1}$$

We aim to prove that the solution to Problem (2.1) is asymptotical consistent with the propensity score, i.e.

Theorem 2.1. *Under some (non-optimal) Assumptions, there exist constants $c_1, c_2 > 0$ and decreasing sequences $(\varepsilon_n^1), (\varepsilon_n^2) \subset (0, 1]$ that converge to 0 such that for all $\tau \in (0, 1]$ there exists a constant $c_\tau \in [0, \infty)$ only depending on τ such that for all $n \geq 1$ and $\tau \in (0, 1]$ it holds*

$$\begin{aligned} \mathbb{P} \left(\left\| w_i^* - \frac{1}{n\pi(X_i)} \right\|_\infty \leq c_1 c_\tau \varepsilon_n^1 \right) &\geq 1 - \tau, \\ \left\| w_i^* - \frac{1}{n\pi(X_i)} \right\|_{\mathbb{P}, 2} &\leq c_2 \varepsilon_n^2, \end{aligned} \quad (2.2)$$

where w^* is the solution to Problem (2.1).

Plan of Proof

It is easier to study the dual of Problem (2.1). Thus we employ results from convex analysis [5] to establish

Proposition 2.1. *The dual of Problem (2.1) is equivalent to the unconstrained optimization problem*

$$\underset{\lambda \in \mathbb{R}^K}{\text{minimize}} \quad \frac{1}{n} \sum_{j=1}^n [-T_j n \rho(B(X_j)^T \lambda) + B(X_j)^T \lambda] + |\lambda|^T \delta, \quad (2.3)$$

where $B(X_j) = (B_k(X_j))_{1 \leq k \leq K}$ denotes the K basis functions of the covariates, $\rho(t) := \frac{t}{n} - t(h')^{-1}(t) + h((h')^{-1}(t))$ with $h(x) := f\left(\frac{1}{n} - x\right)$ and $|\lambda| := (|\lambda_k|)_{1 \leq k \leq K}$. Moreover, the primal solution w_j^* satisfies

$$w_j^* = \rho' (B(X_j)^T \lambda^\dagger) \quad (2.4)$$

for $j = 1, \dots, n$, where λ^\dagger is the solution to the dual optimization problem.

The core of the subsequent analysis is based on Assumption 1.4, i.e. the existence of an oracle parameter λ_1^* in a sieve estimate of the true propensity score (or a transformation). It is then natural to enquire about the convergence of the dual solution λ^\dagger to λ_1^* . Making certain assumptions and employing matrix concentration inequalitys [7] we can establish

Proposition 2.2. *Under some (non-optimal) Assumptions, there exists a constant $c_3 > 0$ and a decreasing sequence $(\varepsilon_n^3) \subset (0, 1]$ that converges to 0 such that for all $\tau \in (0, 1]$ there exists a constant $\tilde{c}_\tau \in [0, \infty)$ only depending on τ such that for all $n \geq 1$ and $\tau \in (0, 1]$ it holds*

$$\mathbb{P} \left(\|\lambda^\dagger - \lambda_1^*\|_2 \leq c^3 \tilde{c}_\tau (\varepsilon_n^3) \right) \geq 1 - \tau. \quad (2.5)$$

It is then straightforward to prove a more general result than Theorem 2.1.

Theorem 2.2. *Under some (non-optimal) Assumptions, there exist constants $c_1, c_2 > 0$ and decreasing sequences $(\varepsilon_n^1), (\varepsilon_n^2) \subset (0, 1]$ that converge to 0 such that for all $\tau \in (0, 1]$ there exists a constant $c_\tau \in [0, \infty)$ only depending on τ such that for all $n \geq 1$ and $\tau \in (0, 1]$ it holds*

$$\begin{aligned} \mathbb{P} \left(\left\| w^*(\cdot) - \frac{1}{n\pi(\cdot)} \right\|_\infty \leq c_1 c_\tau \varepsilon_n^1 \right) &\geq 1 - \tau, \\ \left\| w^*(X) - \frac{1}{n\pi(X)} \right\|_{\mathbb{P}, 2} &\leq c_2 \varepsilon_n^2, \end{aligned}$$

where $w^*(X)$ is as in (2.4) without the index.

Proof of theorem 2.2

Proof. Motivated by Proposition 6.1 we consider

$$G(\lambda) := \frac{1}{n} \sum_{j=1}^n \left[-T_j n \rho \left(B(X_j)^T \lambda \right) + B(X_j)^T \lambda \right] + |\lambda|^T \delta. \quad (2.6)$$

Since $\rho \in C^2(\mathbb{R})$ we can employ (2.6), Corollary 6.1.1 and Proposition 6.2 to get

$$\begin{aligned}
& G(\lambda_1^* + \Delta) - G(\lambda_1^*) \\
& \geq \frac{1}{n} \sum_{j=1}^n \left[-T_j n \rho' (B(X_j)^T \lambda_1^*) + 1 \right] \Delta^T B(X_j) \\
& + \frac{1}{2} \sum_{j=1}^n -T_j \rho'' (B(X_j)^T (\lambda_1^* + \xi \Delta)) \Delta^T (B(X_j) B(X_j)^T) \Delta \\
& - |\Delta|^T \delta \\
& \geq -\|\Delta\|_2 \left(\left\| \frac{1}{n} \sum_{j=1}^n \left[-T_j n \rho' (B(X_j)^T \lambda_1^*) + 1 \right] B(X_j) \right\|_2 + \|\delta\|_2 \right) \\
& + n \|\Delta\|_2^2 \varphi_{\rho}'' \varphi_{BB^T} \\
& := -\|\Delta\|_2 (I_1 + \|\delta\|_2) + \|\Delta\|_2^2 I_2.
\end{aligned} \tag{2.7}$$

The second inequality is due to the Cauchy-Schwarz-Inequality and Assumptions 1.6 and 1.7. We want to establish probabilistic upper bounds of the factor associated with $-\|\Delta\|_2$. This will be done with appropriate assumptions on $\|\delta\|_2$ and a thorough analysis of I_1 . If we then restrict lower bounds of I_2 to appropriately slow convergence to 0, e.g. by assumptions on φ_{ρ}'' and φ_{BB^T} , we can choose $\|\Delta\|_2$ large enough, such that (2.7) yields $G(\lambda_1^* + \Delta) - G(\lambda_1^*) > 0$ with arbitrarily large probability for n large enough. With Proposition 6.1 it follows then immediately Proposition 2.2.

Analysis of I_1

We want to use Assumption 1.3. Thus we perform the following split:

$$\begin{aligned}
I_1 & \leq \left\| \sum_{j=1}^n T_j \left[\rho' (B(X_j)^T \lambda_1^*) - \frac{1}{n\pi(X_j)} \right] B(X_j) \right\|_2 \\
& + \left\| \frac{1}{n} \sum_{j=1}^n \left[\frac{T_j}{\pi(X_j)} - 1 \right] B(X_j) \right\|_2 \\
& =: J_1 + J_2
\end{aligned} \tag{2.8}$$

Analysis of J_1

By the Lipschitz-continuity of ρ' , Assumption 1.8 and Assumption 1.4, $T \in \{0, 1\}$ and the triangle inequality we have

$$J_1 \leq nL_{\rho'}\varphi_{\|B(x)\|}\varphi_{m^*} \quad (2.9)$$

Analysis of J_2

We want to employ Theorem 4.2. To this end we define the independent random matrices

$$\begin{aligned} A_j &:= \frac{1}{n} \left[\frac{T_j}{\pi(X_j)} - 1 \right] B(X_j), \quad j = 1, \dots, n, \\ S &:= \sum_{j=1}^n A_j \end{aligned} \quad (2.10)$$

and check conditions (4.12) and (4.3). Note that $\|S\|_2 = J_2$. By the properties of conditional expectation it holds

$$\mathbb{E} \left[\frac{T_j}{\pi(X_j)} B(X_j) \right] = \mathbb{E} \left[\mathbb{E}[T_j | X_j] \frac{1}{\pi(X_j)} B(X_j) \right] = \mathbb{E}[B(X_j)]. \quad (2.11)$$

Taking the expectation in (2.10) and using (2.11) we get $\mathbb{E}[A_j] = 0$ for all $j = 1, \dots, n$. Since

$$\left| \frac{T_j}{\pi(X_j)} - 1 \right| \leq 1 + \frac{1 - \varphi_\pi}{\varphi_\pi} = \frac{1}{\varphi_\pi} \quad (2.12)$$

by Assumption 1.5, we can employ Assumption 1.8 together with (2.12) and (2.10) to get

$$\|A_j\|_2 \leq \frac{\varphi_{\|B\|}}{n\varphi_\pi} =: L. \quad (2.13)$$

Thus, condition (4.12) is satisfied. Next we turn to the matrix variance statistic $v(S)$ (4.3). By (2.10) and (2.12) we have

$$\mathbb{E} [A_j A_j^T] \leq \left(\frac{1}{n\varphi_\pi} \right)^2 \mathbb{E} [B(X) B(X)^T] \quad (2.14)$$

and by (2.13)

$$\mathbb{E} [A_j^T A_j] \leq L^2. \quad (2.15)$$

Since $\max\{a, b\} \leq |a| + |b|$ we can use (2.14) and (2.15) to get

$$v(S) \leq \frac{1}{n} \frac{\lambda_{\max}}{\varphi_\pi^2} + nL^2, \quad (2.16)$$

where λ_{\max} is the maximal eigenvalue of the symmetric (non-random) matrix $\mathbb{E} [B(X)B(X)^T]$. Having dealt with (4.12) and (4.3) we can establish the expectation bound (4.4) of Theorem 4.2. Together with (2.13) and (2.16) we get

$$\begin{aligned} & \mathbb{E}[J_2] \\ & \leq \sqrt{\frac{2 \log(K+1) (\lambda_{\max} + \varphi_{\|B\|}^2)}{n \varphi_\pi^2}} + \frac{\log(K+1) \varphi_{\|B\|}}{3n \varphi_\pi} \\ & \leq \frac{1}{\varphi_\pi} \sqrt{\frac{\log(K+1)}{n}} \left[\varphi_{\|B\|} \left(\sqrt{2} + \frac{1}{3} \sqrt{\frac{\log(K+1)}{n}} \right) + \sqrt{2\lambda_{\max}} \right]. \end{aligned} \quad (2.17)$$

Since $K = o(n)$ by Assumption 1.9 we can discuss the other influences on the quality of the bound (2.17). On a high-level it is readily clear that appropriate bounds on φ_π , $\varphi_{\|B\|}$ and λ_{\max} will shrink $\mathbb{E}[J_2]$ to 0 and will assist in establishing learning rates.

We could also have invoked the probability bound (4.5) of Theorem 4.2. But for the sake of simplicity we prefer the combination of the expectation bound (2.17) and the Markov inequality. With the latter we get

$$J_2 \leq \frac{1}{\tau} \frac{1}{\varphi_\pi} \sqrt{\frac{\log(K+1)}{n}} \left[\varphi_{\|B\|} \left(\sqrt{2} + \frac{1}{3} \sqrt{\frac{\log(K+1)}{n}} \right) + \sqrt{2\lambda_{\max}} \right] \quad (2.18)$$

with probability $\geq 1 - \tau$.

If we choose $\|\Delta\|_2$ to be

$$\begin{aligned} & \left(\sqrt{2} \frac{1}{\tau} \frac{1}{\varphi_\pi} \sqrt{\frac{\log(K+1)}{n^3}} \left[\varphi_{\|B\|} \left(1 + \sqrt{\frac{\log(K+1)}{n}} \right) + \sqrt{\lambda_{\max}} \right] \right. \\ & \quad \left. + L_{\rho'} \varphi_{\|B\|} \varphi_{m^*} + \frac{\|\delta\|_2}{n} \right) \frac{1}{\varphi_{\rho''} \underline{\varphi_{BB^T}}} \end{aligned} \quad (2.19)$$

we get by (2.7), (2.8), (2.9), (2.18) and Proposition 6.1

$$\begin{aligned}\mathbb{P}(\|\lambda^\dagger - \lambda_1^*\|_2 \leq C) &= \mathbb{P}\left(\inf_{\|\Delta\|_2=C} G(\lambda_1^* + \Delta) - G(\lambda_1^*) > 0\right) \\ &\geq 1 - \tau,\end{aligned}\tag{2.20}$$

where C is as in (2.19). With appropriate Assumptions (as discussed before) we can then establish Proposition 2.2.

We can invoke (2.20) to derive bounds as in Theorem 2.2:

$$\begin{aligned}\left\|w^*(X) - \frac{1}{n\pi(X)}\right\|_{\mathbb{P},2} &\leq L_{\rho'} \left[\|B(X)^T (\lambda^\dagger - \lambda_1^*)\|_{\mathbb{P},2}\right. \\ &\quad \left.+ \|m^*(X) - B(X)^T \lambda_1^*\|_{\mathbb{P},2}\right] \\ &\leq L_{\rho'} \left(\varphi_{\|B\|} \sqrt{C^2(1-\tau) + \text{diam}(\Theta)^2\tau} + \varphi_{m^*}\right)\end{aligned}$$

$$\begin{aligned}\left\|w^*(\cdot) - \frac{1}{n\pi(\cdot)}\right\|_{\infty} &\leq L_{\rho'} \left[\|B(\cdot)^T (\lambda^\dagger - \lambda_1^*)\|_{\infty}\right. \\ &\quad \left.+ \|m^*(\cdot) - B(\cdot)^T \lambda_1^*\|_{\infty}\right] \\ &\leq L_{\rho'} (\varphi_{\|B\|} C + \varphi_{m^*})\end{aligned}$$

with probability greater than $1 - \tau$. □

The next step consists of strengthening the Assumptions to get concrete learning rates. This can be done in a series of examples.

Chapter 3

Convex Analysis

In the following we do not expect the reader to be familiar with convex analysis. However, some very well known results will be stated without proof. The interested reader can study [5] for the bedrock analysis.

We begin by defining convex sets

Definition 3.1. *A subset $\Omega \subseteq \mathbb{R}^n$ is called CONVEX if we have $\lambda x + (1 - \lambda)y \in \Omega$ for all $x, y \in \Omega$ and $\lambda \in (0, 1)$.*

Clearly, the line segment $[a, b] := \{\lambda a + (1 - \lambda)b \mid \lambda \in [0, 1]\}$ is contained in Ω for all $a, b \in \Omega$ if and only if Ω is a convex set.

Next we define convex functions.

The concept of convex functions is closely related to convex sets.

The line segment between two points on the graph of a convex function lies on or above and does not intersect the graph.

In other words: The area above the graph of a convex function f is a convex set, i.e. the *epigraph* $\text{epi}(f) := \{(x, \alpha) \in \mathbb{R}^n \times \mathbb{R} \mid f(x) \leq \alpha\}$ is a convex set in \mathbb{R}^{n+1} .

Often an equivalent characterisation of convex functions is more useful.

Theorem 3.1. *The convexity of a function $f : \mathbb{R}^n \rightarrow \overline{\mathbb{R}}$ on \mathbb{R}^n is equivalent to the following statement:*

For all $x, y \in \mathbb{R}^n$ and $\lambda \in (0, 1)$ we have

$$f(\lambda x + (1 - \lambda)y) \leq \lambda f(x) + (1 - \lambda)f(y). \quad (3.1)$$

Definition 3.2. proper convex function

Definition 3.3. (Convex Conjugate) *Given a function $f : \mathbb{R}^n \rightarrow (-\infty, \infty]$, the convex conjugate $f^* : \mathbb{R}^n \rightarrow (-\infty, \infty]$ of f is defined as*

$$f^*(x^*) := \sup_{x \in \mathbb{R}^n} (x^*)^T x - f(x) \quad (3.2)$$

Note that f in Definition 3.3 does not have to be convex. On the other hand, the convex conjugate is always convex:

Proposition 3.1. *Let $f : \mathbb{R}^n \rightarrow (-\infty, \infty]$ be a proper function. Then its convex conjugate $f^* : \mathbb{R}^n \rightarrow (-\infty, \infty]$ is convex.*

3.1 Conjugate Calculus

When studying different primal problems such as (2.1) we often turn to the dual instead. Therefore we need some reliable tools. Being able to compute specific convex conjugates is one tool required.

3.2 Fenchel Duality

Given proper convex functions $f, g : \mathbb{R}^n \rightarrow \overline{\mathbb{R}}$ and a matrix $A \in \mathbb{R}^{n \times n}$, we define the primal minimization problem as follows:

$$\text{minimize } f(x) + g(Ax) \quad \text{subject to } x \in \mathbb{R}^n. \quad (3.3)$$

The Fenchel dual problem is then

$$\text{maximize } -f^*(A^T y) - g^*(-y) \quad \text{subject to } y \in \mathbb{R}^n. \quad (3.4)$$

Theorem 3.2. *Let $f, g : \mathbb{R}^n \rightarrow \overline{\mathbb{R}}$ be proper convex functions and $0 \in \text{ri}(\text{dom}(g) - A(\text{dom}(f)))$. Then the optimal values of (3.3) and (3.4) are equal, i.e.*

$$\inf_{x \in \mathbb{R}^n} \{f(x) + g(Ax)\} = \sup_{y \in \mathbb{R}^n} \{-f^*(A^T y) - g^*(-y)\}. \quad (3.5)$$

Chapter 4

Matrix Concentration Inequalities

Definition 4.1. (Hermitian Dilation) *The Hermitian dilation*

$$\mathfrak{H} : \mathbb{C}^{d_1 \times d_2} \rightarrow \mathbb{H}_{d_1 \times d_2}$$

is a map from a general matrix to an Hermitian matrix defined by

$$\mathfrak{H}(B) := \begin{bmatrix} 0 & B \\ B^* & 0 \end{bmatrix} \quad (4.1)$$

Theorem 4.1. (Matrix Bernstein Inequality) *Let $(A_k)_{1 \leq k \leq n} \subseteq \mathbb{R}^{d_1 \times d_2}$ be a finite sequence of independent, random matrices. Assume that*

$$\mathbb{E}(A_k) = 0 \quad \text{and} \quad \|A_k\| \leq L \quad \text{for each } k \in \{1, \dots, n\}. \quad (4.2)$$

Introduce the random matrix

$$S := \sum_{k=1}^n A_k.$$

Let $v(S)$ be the matrix variance statistic of the sum:

$$\begin{aligned} v(S) &:= \max \left\{ \|\mathbb{E}(SS^T)\|, \|\mathbb{E}(S^T S)\| \right\} \\ &= \max \left\{ \left\| \sum_{k=1}^n \mathbb{E}(A_k A_k^T) \right\|, \left\| \sum_{k=1}^n \mathbb{E}(A_k^T A_k) \right\| \right\}. \end{aligned} \quad (4.3)$$

Then

$$\mathbb{E} \|S\| \leq \sqrt{2v(S) \log(d_1 + d_2)} + \frac{1}{3}L \log(d_1 + d_2). \quad (4.4)$$

Furthermore, for all $t \geq 0$,

$$\mathbb{P}(\|S\| \geq t) \leq (d_1 + d_2) \exp\left(\frac{-t^2/2}{v(S) + Lt/3}\right). \quad (4.5)$$

Corollary 4.1.1. (Scalar Bernstein Inequality) *Let X_1, \dots, X_n be centered, independent real random variables with $\|X_i\|_\infty \leq L$ and $\mathbb{E}(X_i^2) \leq \sigma^2$ for all $i = 1, \dots, n$. Then it holds for all $t \geq 0$*

$$\mathbb{P}\left(\left|\sum_{i=1}^n X_i\right| \geq t\right) \leq 2 \exp\left(-\frac{1}{2} \frac{t^2}{n\sigma^2 + Lt/3}\right) \quad (4.6)$$

Proof. We verify the scalar versions of (4.12) and (4.3). Since the 2- and ∞ -norm coincide in one dimension and the X_i are centered and independent we get

$$v(S) = \sum_{i=1}^n \mathbb{E}(X_i^2) \leq n\sigma^2 \quad (4.7)$$

We get (4.6) by applying Theorem 4.2. \square

Definition 4.2. Intrinsic Dimension *For a positive-semidefinite matrix A , the intrinsic dimension is the quantity*

$$\text{intdim}(A) := \frac{\text{tr}A}{\|A\|_2},$$

where tr is the trace of a matrix.

Theorem 4.2. (Intrinsic Matrix Bernstein) *Let $(A_k)_{1 \leq k \leq n}$ be a finite sequence of independent, random matrices with the same size. Assume that*

$$\mathbb{E}(A_k) = 0 \quad \text{and} \quad \|A_k\| \leq L \quad \text{for each } k \in \{1, \dots, n\}. \quad (4.8)$$

Introduce the random matrix

$$S := \sum_{k=1}^n A_k.$$

Let V_1 and V_2 be semidefinite upper bounds for the matrix-valued variances $\text{Var}_1(S)$ and $\text{Var}_2(S)$:

$$V_1 \succcurlyeq \text{Var}_1(S) := \mathbb{E}(S) = \sum_{k=1}^n \mathbb{E}(A_k A_k^T),$$

$$V_2 \succcurlyeq \text{Var}_2(S) := \mathbb{E}(S) = \sum_{k=1}^n \mathbb{E}(A_k^T A_k).$$

Define an intrinsic dimension bound and a variance bound

$$d := \text{intdim} \begin{bmatrix} V_1 & 0 \\ 0 & V_2 \end{bmatrix} \quad \text{and} \quad v := \max \{ \|V_1\|_2, \|V_2\|_2 \}. \quad (4.9)$$

Then it holds

$$\mathbb{E} \|S\| \leq \text{Const.} \left(\sqrt{v \log(d+1)} + L \log(d+1) \right). \quad (4.10)$$

Furthermore, for all $t \geq \sqrt{v} + \frac{L}{3}$,

$$\mathbb{P}(\|S\| \geq t) \leq 4d \exp \left(\frac{-t^2/2}{v + Lt/3} \right). \quad (4.11)$$

It turns out that for random vectors $d \leq 2$. This is remarkable, because this property of the intrinsic dimension is invariant under the dimension of the vector. This fact motivates the following result:

Corollary 4.2.1. *Let $(A_k)_{1 \leq k \leq n} \subseteq \mathbb{R}^K$ be a finite sequence of independent, random vectors. Assume that*

$$\mathbb{E}(A_k) = 0 \quad \text{and} \quad \|A_k\| \leq L \quad \text{for each } k \in \{1, \dots, n\}. \quad (4.12)$$

Let $v(S)$ be the matrix variance statistic of the sum as defined in (4.3). Then it holds

$$\mathbb{E} \|S\| \leq \text{Const.} \left(\sqrt{v(S) \log(3)} + L \log(3) \right). \quad (4.13)$$

Furthermore, for all $t \geq \sqrt{v(S)} + \frac{L}{3}$,

$$\mathbb{P}(\|S\| \geq t) \leq 8 \exp \left(\frac{-t^2/2}{v(S) + Lt/3} \right). \quad (4.14)$$

Proof. First, let's verify $d := \text{intdim} \begin{bmatrix} \text{Var}_1(S) & 0 \\ 0 & \text{Var}_2(S) \end{bmatrix} \leq 2$. Since

$$\text{tr} BB^T = B^T B \quad \text{and} \quad \left\| \begin{bmatrix} BB^T & 0 \\ 0 & B^T B \end{bmatrix} \right\|_2 = \max \{ \|BB^T\|, B^T B \} \quad (4.15)$$

for all $B \in \mathbb{R}^K$ it follows

$$\text{intdim} \begin{bmatrix} BB^T & 0 \\ 0 & B^T B \end{bmatrix} = \frac{\text{tr} BB^T + B^T B}{\max \{ \|BB^T\|, B^T B \}} \leq 2 \quad (4.16)$$

for all $B \in \mathbb{R}^K$. □

Chapter 5

Empirical Processes

Let $(\Omega, \mathcal{A}, \mathbb{P})$ be a probability space and (\mathcal{X}, Σ) a measurable space. Let $X_j : (\Omega, \mathcal{A}, \mathbb{P}) \rightarrow (\mathcal{X}, \Sigma), j = 1, \dots, n$ be independent and identically-distributed (i.i.d.) random variables with probability distribution \mathbb{P}_X and \mathcal{F} a family of measurable functions $f : (\mathcal{X}, \Sigma) \rightarrow (\mathbb{R}, \mathcal{B}(\mathbb{R}))$. Consider the map

$$f \mapsto G_n f := \sqrt{n} \left(\frac{1}{n} \sum_{i=1}^n f(X_i) - \mathbb{P}_X f \right), \quad (5.1)$$

where $\mathbb{P}_X f := \int_{\mathcal{X}} f d\mathbb{P}_X$. We call $(G_n f)_{f \in \mathcal{F}}$ the empirical process indexed by \mathcal{F} .

Lemma 5.1. (Bernstein Inequality for Empirical Processes) *For any bounded, measurable function f it holds for all $t > 0$*

$$\mathbb{P}(|G_n f| > t) \leq 2 \exp \left(- \frac{1}{4} \frac{t^2}{\mathbb{P}_X(f^2) + t \|f\|_{\infty} / \sqrt{n}} \right) \quad (5.2)$$

Proof. By the Markov inequality it holds for all $\lambda > 0$

$$\mathbb{P}(G_n f > t) \leq e^{-\lambda t} \mathbb{E} \exp(\lambda G_n f) \quad (5.3)$$

□

Chapter 6

Simple yet useful Calculations

Proposition 6.1. *Let $f : \mathbb{R}^n \rightarrow \mathbb{R}$ be continuous such that a minimum x^* exists and is unique. Then for all $y \in \mathbb{R}^n$ and $C > 0$ it follows*

$$\inf_{\|\Delta\|=C} f(y + \Delta) - f(y) > 0 \quad \Rightarrow \quad \|x^* - y\| \leq C. \quad (6.1)$$

Proof. Since $\mathcal{C} := \{\|\Delta\| \leq C\}$ is compact and

$$f(x^*) \leq f(y) < \inf_{\|\Delta\|=C} f(y + \Delta),$$

the continuous function $f(y + \cdot)$ has a minimum in $\text{int}(\mathcal{C}) := \{\|\Delta\| < C\}$. Since x^* is the unique minimum of f there exists $\Delta^* \in \text{int}(\mathcal{C})$ such that $x^* - y = \Delta^*$. We conclude that $\|x^* - y\| \leq C$. \square

Theorem 6.1. (Multivariate Taylor Theorem) *Let $f \in C^2(\mathbb{R}^n, \mathbb{R})$. Then for all $x, \Delta \in \mathbb{R}^n$ there exists $\xi \in [0, 1]$ such that it holds*

$$\begin{aligned} f(x + \Delta) = f(x) &+ \sum_{i=1}^n \frac{\partial f(x)}{\partial x_i} \Delta_i + \sum_{\substack{i,j=1 \\ i \neq j}}^n \frac{\partial^2 f(x + \xi \Delta)}{\partial x_i \partial x_j} \Delta_i \Delta_j \\ &+ \frac{1}{2} \sum_{i=1}^n \frac{\partial^2 f(x + \xi \Delta)}{\partial x_i^2} \Delta_i^2 \end{aligned} \quad (6.2)$$

Corollary 6.1.1. *Let $f \in C^2(\mathbb{R})$. Then for all $a, x, \Delta \in \mathbb{R}^n$ there exist $\xi \in [0, 1]$ such that it holds*

$$f(a^T(x + \Delta)) - f(a^T x) = f'(a^T x) \Delta^T a + \frac{1}{2} f''(a^T(x + \xi \Delta)) \Delta^T A \Delta, \quad (6.3)$$

where $A := aa^T \in \mathbb{R}^{n \times n}$.

Proof. By the chain rule we have for all $a, x, \Delta \in \mathbb{R}^n$ and $\xi \in [0, 1]$

$$\frac{\partial^2 f(a^T(x + \xi\Delta))}{\partial x_i \partial x_j} = f''(a^T(x + \xi\Delta)) a_i a_j. \quad (6.4)$$

Since $A := aa^T$ is symmetric we have

$$\Delta^T A \Delta = 2 \sum_{\substack{i,j=1 \\ i \neq j}}^n a_i a_j \Delta_i \Delta_j + \sum_{i=1}^n a_i^2 \Delta_i^2. \quad (6.5)$$

Plugging (6.4) and (6.5) into (6.2) yields (6.3). \square

Proposition 6.2. *For all $x, y \in \mathbb{R}$ it holds*

$$|x + y| - |x| \geq -|y| \quad (6.6)$$

Proof. Checking all 6 combinations of $x+y, x, y$ being nonnegative or negative yields the result. \square

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