lab2

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1 实验二:解非线性方程

题目: 求方程 $x^3 - \cos(x) - 5x - 1 = 0$ 的根。

记 $f(x) = x^3 - \cos x - 5x - 1$,作 f(x) 的图像。从图可以看出: 方程 f(x) = 0 有 3 个根,第一个位于 [-3, -1] 内,第二个位于 [-1, 1] 内,第三个位于 [1, 3] 内。

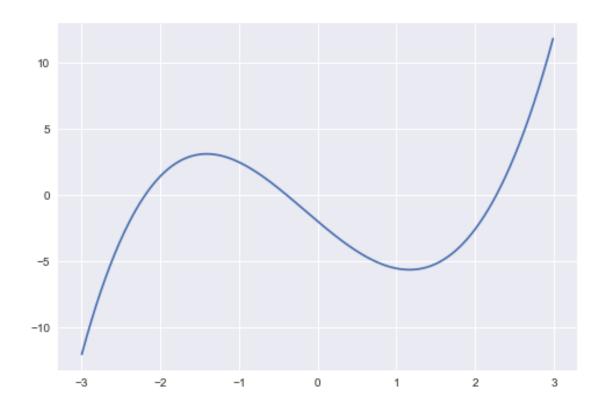
```
[92]: # Import
import numpy as np
import matplotlib.pyplot as plt
from scipy.misc import derivative
```

```
[93]: # 定义函数
def f0(x):
    y = x**3-np.cos(x)-5*x-1
    return y
```

```
[94]: x_space = np.arange(-3,3,0.01)
y_space = f0(x_space)

plt.style.use("seaborn")
plt.plot(x_space, y_space)
```

[94]: [<matplotlib.lines.Line2D at 0x24dfddabf48>]



1.1 1. 二分法求根

二分法求根的思路是:对于连续函数 f(x),若其在区间 [a,b] 上满足 $f(a) \cdot f(b) < 0$,则其在 (a,b) 内存在零点 \bar{x} 。且我们可以通过二分法求出 \bar{x} ,其思路是:

- 1. 取 $x_0 = (a+b)/2$ 。若 $f(x_0) = 0$,则输出 x_0 。否则转到下一步。
- 3. 重复第二步,构造 $[a_1,b_1],[a_2,b_2],\ldots,$ 并计算 $x_k=(a_k+b_k)/2$ 。直至 $f(x_k)=0$ 或 $|f(x_k)|<\epsilon$ 停止迭代并输出 x_k 。

可以使用以下函数实现二分法:

```
[95]: # 1.对区间二分法求根

def halfsearch(f, a, b, uplimit):
    if f(a)*f(b)>=0:
        print("f(a)*f(b) should be less than 0")
        return 0
    if (a>b):
        print("a should be less than b")
```

```
return 0
while(b-a>uplimit):
    x0 = (a+b)/2
    if f(x0)==0:
        return x0
    elif f(x0)*f(a)>0:
        a = x0
    else:
        b = x0
    x0 = (a+b)/2
    return x0
```

分别在 [-3,-1],[-1,1],[1,3] 上使用二分法, 所得结果如下所示:

```
[97]: # 要求误差为 1e-6
limit = 1e-6

print("The result between -3 and -1:", "%.6f"%halfsearch(f0,-3,-1,limit))
print("The result between -1 and 1:", "%.6f"%halfsearch(f0,-1,1,limit))
print("The result between 1 and 3:", "%.6f"%halfsearch(f0,1,3,limit))
```

```
The result between -3 and -1: -2.193133
The result between -1 and 1: -0.396959
The result between 1 and 3: 2.270829
```

1.2 2. 不动点迭代法

对于 f(x) = 0,可以将其变换为 $x = \phi(x)$ 。对于初值 x_0 ,构造序列 $x_1 = \phi(x_0), x_2 = \phi(x_1), ..., x_k = \phi(x_{k-1}), ...$ 。如果序列 $\{x_i\}_{i=0}^{\infty}$ 收敛,则其收敛值即为方程 f(x) = 0 的根。其思路是:

- 1. 对于 x_k , 计算 $x_{k+1} = \phi(x_k)$ 。
- 2. 若 $|x_{k+1} x_k| < \epsilon$,则输出 x_{k+1} 。
- 3. 若迭代次数超过一定次数, 停止算法, 输出算法不收敛。
- 4. 回到第1步进行迭代。

可以使用以下函数实现不动点法:

```
[98]: def fixpoint(f, x0, uplimit):
     xold = x0
```

```
xnew = f(xold)
cnt = 1
while abs(xnew-xold)>uplimit:
    xold = xnew
    xnew = f(xold)
    cnt = cnt+1
    if(cnt>10000 or abs(xnew)>1e10):
        return 0
return (xnew,cnt)
```

下面对于两个不同的迭代函数进行不动点迭代法。其中 $\phi_1(x) = \frac{x^3 - \cos(x) - 1}{5}, \phi_2(x) = \sqrt[3]{\cos(x) + 5x + 1}$ 。初值取分别设置为-3,-2,-1,0,1,2,3。

(1)
$$\phi_1(x) = \frac{x^3 - \cos(x) - 1}{5}$$

Fix-point Method for phi1

对 $\phi_1(x)$ 使用不动点迭代法可得到如下结果:

```
[102]: def phi0(x):
    y = (x**3-np.cos(x)-1)/5
    return y

print("Fix-point Method for phi1")
for i in [-3,-2,-1,0,1,2,3]:
    if fixpoint(phi0,i,limit) == 0:
        print("初值 = %d 时不收敛"%i)
    else:
        result, itertime = fixpoint(phi0,i,limit)
        print("Start point:", i, "Result point:", "%.6f"%result, "Iterate times:
    →", itertime)
```

```
初值 = -3 时不收敛
Start point: -2 Result point: -0.396958 Iterate times: 8
Start point: -1 Result point: -0.396958 Iterate times: 6
Start point: 0 Result point: -0.396958 Iterate times: 4
Start point: 1 Result point: -0.396958 Iterate times: 5
Start point: 2 Result point: -0.396958 Iterate times: 7
初值 = 3 时不收敛
```

```
(2) \phi_2(x) = \phi_2(x) = \sqrt[3]{\cos(x) + 5x + 1}
```

对 $\phi_2(x)$ 使用不动点迭代法可得到如下结果:

```
[103]: def phi1(x):
    y = np.cbrt(np.cos(x)+5*x+1)
    return y

print("Fix-point Method for phi2")
for i in [-3,-2,-1,0,1,2,3]:
    if fixpoint(phi1,i,limit) == 0:
        print("初值 = %d时不收敛"%i)
    else:
        result, itertime = fixpoint(phi1,i,limit)
        print("Start point:", i, "Result point:", "%.6f"%result, "Iterate times:
        \_", itertime)
```

Fix-point Method for phi2

```
Start point: -3 Result point: -2.193133 Iterate times: 16
Start point: -2 Result point: -2.193132 Iterate times: 14
Start point: -1 Result point: -2.193132 Iterate times: 17
Start point: 0 Result point: 2.270829 Iterate times: 13
Start point: 1 Result point: 2.270829 Iterate times: 12
Start point: 2 Result point: 2.270829 Iterate times: 11
Start point: 3 Result point: 2.270829 Iterate times: 12
```

1.3 3. 埃特金加速法

对于不动点迭代法中的迭代函数 $\phi(x)$,不动点迭代法使用迭代公式 $x_{k+1} = \phi(x_k)$ 。埃特金加速法使用如下的迭代公式: $y_k = \phi(x_k), z_k = \phi(y_k), x_{k+1} = x_k - \frac{(y_k - x_k)^2}{z_k - 2y_k + x_k}$ 。

更一般的,我们将使用埃特金加速法的不动点迭代法称为斯蒂芬森迭代法。其思路如下:

- 1. 对于 x_k , 计算 $x_{k+1} = x_k \frac{(\phi(x_k) x_k)^2}{\phi(\phi(x_k)) 2\phi(x_k) + x_k}$.
- 2. 若 $|x_{k+1} x_k| < \epsilon$,则输出 x_{k+1} 。
- 3. 若迭代次数超过一定次数, 停止算法, 输出算法不收敛。
- 4. 回到第1步进行迭代。

可以使用如下函数实现斯蒂芬森迭代法:

斯蒂芬森迭代法在迭代函数 $\phi_1(x) = \frac{x^3 - \cos(x) - 1}{6}, \phi_2(x) = \sqrt[3]{\cos(x) + 6x + 1}$ 和初值-3,-2,-1,0,1,2,3下的结果为:

(1)
$$\phi_1(x) = \frac{x^3 - \cos(x) - 1}{5}$$

对 $\phi_1(x)$ 使用斯蒂芬森迭代法可得到如下结果:

```
[106]: print("Aitken Method for phi1")
for i in [-3,-2,-1,0,1,2,3]:
    temp = aitken(phi0,i,limit)
    if temp==0:
        print("初值 = %d时不收敛"%i)
    else:
        result, itertime = temp
        print("Start point:", i, "Result point:", "%.6f"%result, "Iterate times:
        →", itertime)
```

```
Aitken Method for phi1
```

```
Start point: -3 Result point: -2.193133 Iterate times: 8
Start point: -2 Result point: -2.193133 Iterate times: 6
Start point: -1 Result point: -0.396958 Iterate times: 4
Start point: 0 Result point: -0.396958 Iterate times: 3
Start point: 1 Result point: -0.396958 Iterate times: 4
Start point: 2 Result point: 2.270829 Iterate times: 6
```

Start point: 3 Result point: 2.270829 Iterate times: 7

(2)
$$\phi_2(x) = \phi_2(x) = \sqrt[3]{\cos(x) + 5x + 1}$$

对 $\phi_2(x)$ 使用斯蒂芬森迭代法可得到如下结果:

```
[107]: print("Aitken Method for phi2")
for i in [-3,-2,-1,0,1,2,3]:
    temp = aitken(phi1,i,limit)
    if temp==0:
        print("初值 = %d时不收敛"%i)
    else:
        result, itertime = temp
        print("Start point:", i, "Result point:", "%.6f"%result, "Iterate times:
        →", itertime)
```

Aitken Method for phi2

```
Start point: -3 Result point: -2.193133 Iterate times: 4
Start point: -2 Result point: -2.193133 Iterate times: 3
Start point: -1 Result point: -2.193133 Iterate times: 5
Start point: 0 Result point: 2.270829 Iterate times: 4
Start point: 1 Result point: 2.270829 Iterate times: 4
Start point: 2 Result point: 2.270829 Iterate times: 3
Start point: 3 Result point: 2.270829 Iterate times: 3
```

1.4 4. 牛顿法

牛顿法对函数 f(x) 在 x_k 处做泰勒展开 $f(x^*) \approx f(x_k) + f'(x_k)(x^* - x_k)$,其中 x^* 是方程 f(x) = 0 的根。因此可以得到递推式 $x_{k+1} = x_k - \frac{f(x_k)}{f'(x_k)}$ 。牛顿法的思路如下:

- 1. 对于 x_k ,计算 $x_{k+1} = x_k \frac{f(x_k)}{f'(x_k)}$ 。
- 2. 若 $|x_{k+1} x_k| < \epsilon$, 则输出 x_{k+1} 。
- 3. 若迭代次数超过一定次数,停止算法,输出算法不收敛。
- 4. 回到第 1 步进行迭代。

牛顿法主要有两个缺点:第一、牛顿法需要计算导数 f'(x), 计算量较大。第二、牛顿法不能保证算法的收敛性。针对这两个问题,可以分别使用简化的牛顿法和牛顿下山法对牛顿法进行改进。

简化的牛顿法: 使用 $f'(x_0)$ 代替 $f'(x_k)$ 减少计算量。其递推式为 $x_{k+1} = x_k - \frac{f(x_k)}{f'(x_0)}$ 。

牛顿下山法: 引入压缩因子 λ ,将递推公式变为 $x_{k+1}=x_k-\lambda \frac{f(x_k)}{f'(x_k)}$,使得 $|f(x_{k+1})|<|f(x_k)|$,从

而保证其收敛性。其中, λ 的取值开始时为 1,在每次递推中不断折半,直至满足递减的条件。牛顿下山法的思路如下:

- 1. 对于 x_k , 设定 $\lambda = 1$ 。
- 1.1. 计算 $x_{k+1} = x_k \lambda \frac{f(x_k)}{f'(x_k)}$.
- 1.2. 判断 $|f(x_{k+1})| < |f(x_k)|$ 。若满足则调到第 2 步。
- $1.3.\lambda = \lambda/2$,并回到 1.1 步。
- 2. 若 $|x_{k+1} x_k| < \epsilon$,则输出 x_{k+1} 。
- 3. 若迭代次数超过一定次数, 停止算法, 输出算法不收敛。
- 4. 回到第1步进行迭代。

可以使用以下函数实现牛顿法及其改进方法:

普通牛顿法代码:

```
[108]: def newton_phi(f, x):
    y = x-f(x)/derivative(f, x, dx=1e-6)
    return y

def newton(f, x0, uplimit):
    xold = x0
    xnew = newton_phi(f,xold)
    cnt = 1
    while abs(xnew-xold)>uplimit:
        xold = xnew
        xnew = newton_phi(f,xold)
        cnt = cnt+1
        if cnt > 100000 or abs(xnew)>1e10:
            return 0
        return (xnew,cnt)
```

结果如下所示:

```
[110]: print("Newton Method for f0")
for i in [-3,-2,-1,0,1,2,3]:
    temp = newton(f0,i,limit)
    if temp == 0:
        print("初值 = %d时不收敛"%i)
```

```
Newton Method for f0

Start point: -3 Result point: -2.193133 Iterate times: 6

Start point: -2 Result point: -2.193133 Iterate times: 5

Start point: -1 Result point: -0.396958 Iterate times: 4

Start point: 0 Result point: -0.396958 Iterate times: 4

Start point: 1 Result point: -2.193133 Iterate times: 7

Start point: 2 Result point: 2.270829 Iterate times: 5

Start point: 3 Result point: 2.270829 Iterate times: 5
```

简化牛顿法代码:

```
[112]: def newton_phi_simplified(f,C,x):
    y = x-f(x)/C
    return y

def newton_simplified(f, x0, uplimit):
    xold = x0
    C = derivative(f, x0, dx=1e-6)
    xnew = newton_phi_simplified(f,C,xold)
    cnt = 1
    while abs(xnew-xold)>uplimit:
        xold = xnew
        xnew = newton_phi_simplified(f,C,xold)
        cnt = cnt+1
        if cnt > 10000 or abs(xnew)>1e10:
            return 0
        return (xnew,cnt)
```

结果如下所示:

```
[113]: print("Newton Simplified Method for f0")
for i in [-3,-2,-1,0,1,2,3]:
    temp = newton_simplified(f0,i,limit)
```

```
if temp == 0:
    print("初值 = %d时不收敛"%i)
else:
    result, itertime = temp
    print("Start point:", i, "Result point:", "%.6f"%result, "Iterate times:

→", itertime)
```

```
Newton Simplified Method for f0
Start point: -3 Result point: -2.193134 Iterate times: 25
Start point: -2 Result point: -2.193133 Iterate times: 15
Start point: -1 Result point: -0.396959 Iterate times: 44
Start point: 0 Result point: -0.396958 Iterate times: 4
初值 = 1 时不收敛
Start point: 2 Result point: 2.270829 Iterate times: 16
Start point: 3 Result point: 2.270830 Iterate times: 18
```

牛顿下山法代码:

```
[116]: def newton_phi_downhill(f, x, lam):
           y = x-lam*f(x)/derivative(f, x, dx=1e-6)
           return y
       def newton_downhill(f, x0, uplimit):
           xold = np.inf
           xnew = x0
           cnt = 0
           while abs(xnew-xold)>uplimit:
               xold = xnew
               lam = 1
               x_temp = newton_phi_downhill(f,xold,lam)
               while(abs(f(x_temp))>abs(f(xold))):
                   lam = lam/2
                   x_temp = newton_phi_downhill(f,xold,lam)
               xnew = x_temp
               cnt = cnt+1
               if cnt > 10000 or abs(xnew)>1e10:
                   return 0
```

```
return (xnew,cnt)
```

结果如下所示:

```
[117]: print("Newton Downhill Method for f0")
for i in [-3,-2,-1,0,1,2,3]:
    temp = newton_downhill(f0,i,limit)
    if temp == 0:
        print("初值 = %d时不收敛"%i)
    else:
        result, itertime = temp
        print("Start point:", i, "Result point:", "%.6f"%result, "Iterate times:
    →", itertime)
```

```
Start point: -3 Result point: -2.193133 Iterate times: 6
Start point: -2 Result point: -2.193133 Iterate times: 5
Start point: -1 Result point: -0.396958 Iterate times: 4
Start point: 0 Result point: -0.396958 Iterate times: 4
Start point: 1 Result point: -0.396958 Iterate times: 5
Start point: 2 Result point: 2.270829 Iterate times: 5
```

Start point: 3 Result point: 2.270829 Iterate times: 5

1.5 5. 埃特金加速法的收敛速度

Newton Downhill Method for f0

埃特金加速法的收敛速度和不动点法的收敛速度可如下表所示。

对于迭代函数 $\phi_1(x) = \frac{x^3 - \cos(x) - 1}{5}$,其结果为

初值	不动点法的根	不动点法的迭代次数	斯蒂芬森法的根	斯蒂芬森法的迭代次数
-3	NaN	NaN	-2.193133	8
-2	-0.396958	8	-2.193133	6
-1	-0.396958	6	-2.193133	4
0	-0.396958	4	2.270829	3
1	-0.396958	5	2.270829	4
2	-0.396958	7	2.270829	6
3	NaN	NaN	2.270829	7

其中 NaN 代表不收敛,下同

对于迭代函数 $\phi_2(x) = \sqrt[3]{\cos(x) + 5x + 1}$,其结果为

初值	不动点法的根	不动点法的迭代次数	斯蒂芬森法的根	斯蒂芬森法的迭代次数
-3	-2.193133	16	-2.193133	4
-2	-2.193132	14	-2.193133	3
-1	-2.193132	17	-0.396958	5
0	2.270829	13	-0.396958	4
1	2.270829	12	-0.396958	4
2	2.270829	11	2.270829	3
3	2.270829	12	2.270829	3

1.6 6. 牛顿法的收敛速度

牛顿法的收敛速度可如下表所示。

初值	普通牛顿法(根/迭代次数)	简化牛顿法(根/迭代次数)	牛顿下山法 (根/迭代次数)
1/4 1777	HAT MA (IN) ZITUSA)	TATE I MIZ (IX) ZITUSX)	
-3	(-2.193133,6)	(-2.193134,25)	(-2.193133,6)
-2	(-2.193133,5)	(-2.193133,15)	(-2.193133,5)
-1	(-0.396958,4)	(-0.396959,44)	(-0.396958,4)
0	(-0.396958,4)	(-0.396958,4)	(-0.396958,4)
1	(-2.193133,7)	(NaN,NaN)	(-0.396958,5)
2	(2.270829,5)	(2.270829,16)	(2.270829,5)
3	(2.270829,5)	(2.270830,18)	(2.270829,5)

[]: