statistics

$$X_1, X_2, \dots, X_n \stackrel{\text{iid}}{\sim} f(x|\theta)$$

to use the data to learn about the unknown

We want to use the data to learn about the unknown of and also to quantify our uncertainty about what we've learned.

There are two main schools of thought about how to approach this. Both use probability distributions to represent and quantify uncertainty, but they differ in which distributions they use and what kind of uncertainty they quantify.

Classical statistics

- · use the sampling distribution of an estimator to quantify uncestainty
- · capitures sampling uncertainty: the reliability of results across repeated sampling.
- · produces confidence intervals

$$P(L_n < \Theta < U_n) = 1 - \alpha$$
.

for and on fixed rendom

· "we are 90% confident that the true value lies between Ln and Un" where 'confidence" refers to a reliability guerantee about the method of inkruct estimation in repeated use.

> long-run relicbility quarantees are nice, but no one I know is in nice, but no one love with this interpretetion, and lacds of people flat out misunderstand it.

Bayesian statistics

- · use the posterior distribution OF the percueter of to quentify uncertainty
- * captures the analyst's subjective degrees of belief about the unknown parameter based on the state of their knowledge.
- · produces credible intervals

$$P(A_n \angle \Theta \angle u_n | X_{1:n}) = 1-\alpha$$
fixed rondom fixed

- "I believe there is a 90% change the true value is between In and un!
- · this inkreal doesn't necessarily have any reliability guerankes about how it will perform in the long run,

- · probability refers to long-run frequency of repeatable events
- . We want statistical procedures with guarantees about their reliability in repeated use
- we're worried about the uncertainty associated with, random sampling. Different datasets will give different estimates. If the results are highly sensitive to the data, that's worrying, and I want to quantify it.
- Bayesian philosophy (parameter random (because uncertain)

 Juta fixed (because we're conditioning on it)
- · probability refers to an observer's subjective experience of uncertainty, based on the information they have access to.
- all uncertain quantities, including personeters, missing data, etc. should be treated as random and endowed with a probability distribution that captures the statistician's degrees of brelief about the plausible values.
- · Who cares about alternative random samples I could have observed? They don't exist. I have one sample, and I want to generate the best inferences I can conditional on that information.

Payoffs to a Bayesian approach

- · intervels have a more satisfying interpretention
- in a streight forward way.

remember: X := { X, , X 2, ..., X, } The Bayesian Machinery ("The Bayesian crank") what you believed about & before $f(\theta)$ you sew data beion; you believe 611 F(Xl0) $X_{1}, X_{2}, ..., X_{n} \Theta$ data the deta behave model you believe O) Xin F(Olxin) court & after you posterior ' see the data. $f(x_1, x_2, \dots, x_n \mid \theta) = \prod_{i=1}^n f(x_i \mid \theta) = L(\theta \mid x_{i:n})$ likelihood : Bayesian $f(x_{1:n}, \theta) = f(x_{1:n}|\theta) f(\theta)$ model : $= \left[\prod_{i=1}^{N} f(x_i \mid \theta) \right] f(\theta)$ $f(\theta|x_{iin}) = \frac{f(x_{iin}, \theta)}{f(x_{iin})}$ Bayes' rule: f(Olxin) is a $= f(X_{i:n}|\theta)f(\theta)$ Function of O. in it doesn't meter f(xin) x)f(xin 10)f(0) - Kervel of the means posterior 11 is proportional to "
f(x) = 2x2,

= L(0)X(:n)f(0)

then F(x) of x2.

Example

n flips of a mystery coin with probability of heads 04041.

Prior:

⊖ ~ f(⊕) ←

- what you believed about a before you flipped the coin

We want

a convenient

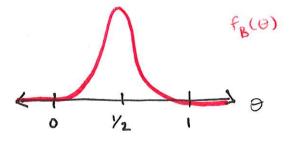
likelihood: X,,X2,...,X, \to iid Bern (0) L how the

Beliefs A: "I am totally ignorant about this coin."

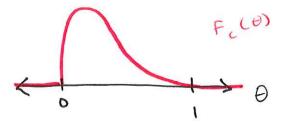
f (0)



Beliefs B: "I am fairly confident the coin is fair."



Beliefs C: " I think the coin is biosed towards tails."



Beliefs D: "The coin is probably unfeir, but I'm not sure how."

family of
probability
distributions
on the
inkrive!

(0,1)
that we
can adjust
in order to
evcode the
conge of
beliefs we
might have
about the
uknown of

Beta distribution

$$X \sim Beta(a, b)$$

$$f_{X}(x) = \frac{T(a+b)}{T(a)T(b)} x^{a-1} (1-x)^{b-1}, \quad 0 \leq x \leq 1.$$

$$\int_{0}^{1} \frac{\Gamma(4+b)}{\Gamma(4)\Gamma(b)} \times \int_{0}^{a-1} (1-x)^{b-1} dx = 1 = \int_{0}^{1} \frac{a-1}{(1-x)^{b-1}} dx = \frac{\Gamma(4)\Gamma(b)}{\Gamma(4+b)}$$

$$= B(a,b)$$
Reta function

$$E(X) = \int_{0}^{1} x \, \frac{F(x) \, dx}{X} = \int_{0}^{1} x \, \frac{T(a+b)}{T(a+b)} \, x^{a-1} (1-x)^{b-1} \, dx$$

$$= \frac{\Gamma(a+b)}{\Gamma(a)\Gamma(b)} \int_{b}^{1} \frac{a+1-1}{x} \frac{b^{-1}}{(1-x)} dx$$

$$= \frac{\Gamma(a+b)}{\Gamma(a)\Gamma(b)} \int_{b}^{1} \frac{a+1-1}{x} \frac{b^{-1}}{(1-x)} dx$$

$$=\frac{F(c+b)}{\Gamma(c)\Gamma(b)}\frac{\Gamma(c+1)\Gamma(b)}{\Gamma(c+b+1)}$$

$$f_{X}(x) = \frac{T(2)}{T(1)T(1)} \times {}^{0}(1-x)^{0} = \frac{1T(1)}{T(1)T(1)} \cdot 1 \cdot 1 , \quad 0 < x < 1$$

$$= 1, \quad 0 < x < 1$$

 $X \sim Unif(0,1)$

$$E(\chi^{2}) = \int_{0}^{1} \chi^{2} \frac{T(a+b)}{T(a)T(b)} \chi^{a-1} (1-\chi)^{b-1} d\chi$$

$$= \frac{T(a+b)}{T(a)T(b)} \int_{0}^{1} \chi^{a+2-1} (1-\chi)^{b-1} d\chi$$

$$= \frac{T(a+b)}{T(a)T(b)} \frac{T(a+2)}{T(a+b+2)}$$

$$= \frac{T(a+b)}{T(a)T(b)} \frac{T(a+2)}{T(a+b+2)} \frac{T(a+b)}{T(a+b+2)}$$

$$= \frac{T(a+b)}{T(a)T(b)} \frac{(a+1)T(a+1)}{(a+b+1)T(a+b+1)}$$

$$= \frac{T(a+b)}{T(a)T(b)} \frac{(a+1)T(a+b)}{(a+b+1)(a+b)}$$

$$= \frac{(a+1)A}{(a+b+1)(a+b)}$$

$$V(c)(x) = E(x^{2}) - E(x)^{2}$$

$$= \frac{(a+1)a}{(a+b+1)(a+b)} - \frac{a^{2}}{(a+b)^{2}}$$

$$= \frac{(a+b)(a^{2}+a) - c^{2}(a+b+1)}{(a+b+1)(a+b)^{2}}$$

$$= \frac{a^{2}}{(a+b+1)(a+b)^{2}}$$

$$= \frac{a^{2}}{(a+b+1)(a+b+1)(a+b)^{2}}$$

$$= \frac{a^{2}}{(a+b+1)(a+b+1)(a+b+1)}$$

 $\Theta | X_{iin} \sim Beta(a_n, b_n)$ $a_n = a_0 + \sum_{i=1}^{n} X_i$ $b_n = b_0 + n - \sum_{i=1}^{n} X_i$

$$\Theta \sim \text{Beta}(a_0,b_0)$$
 $X_i \mid \Theta \stackrel{\text{iid}}{\sim} \text{Bern}(\theta)$
 $\Theta \mid X_{1:n} \sim \text{Beta}(a_0 + \sum_{i=1}^{n} X_i, b_0 + n - \sum_{i=1}^{n} X_i)$

Bayes estimator

$$E(\Theta | X_{1:n}) = \frac{a_n}{a_n + b_n} = \frac{a_0 + \sum x_i}{a_0 + \sum x_i}$$

$$= \frac{a_0 + \sum x_i}{a_0 + b_0 + n}$$

$$= \frac{1}{a_0 + b_0 + n} = \frac{1}{a_0 + b_0 + n} = \sum x_i$$

$$= \frac{1}{a_0 + b_0 + n} \frac{a_0 + b_0}{a_0 + b_0} a_0 + \frac{1}{a_0 + b_0 + n} \frac{n}{h} \sum_{i} X_i$$

$$= \frac{a_0 + b_0}{a_0 + b_0} \frac{a_0}{a_0 + b_0} + \frac{n}{a_0 + b_0 + n} \frac{n}{h} \sum_{i} X_i$$

$$= \frac{a_0 + b_0}{a_0 + b_0 + n} \frac{a_0}{a_0 + b_0} + \frac{n}{a_0 + b_0 + n} \sum_{i} X_i$$

$$= \frac{a_0 + b_0}{a_0 + b_0 + n} \frac{a_0 + b_0}{a_0 + b_0 + n} = 1$$

$$= \frac{n}{a_0 + b_0 + n} \sum_{i} X_i$$

$$= \frac{n}{a_0 + b_0 + n} \sum_{i} X_i$$

$$= \frac{a_0 + b_0}{a_0 + b_0 + n} \sum_{i} X_i$$

$$= \frac{n}{a_0 +$$

The posterior meen is a shrinkage estimator.

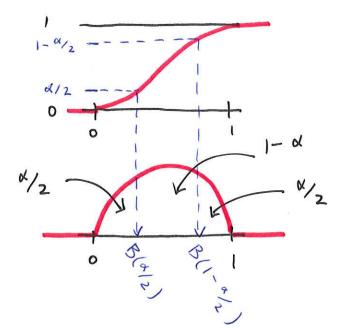
The prior mean was our best guess before we saw data.

The mie is what the date have to say.

The posterior mean is a weighted average of the two. It splits the difference "
As n > 00, prior has less influence and the likelihood dominates.

100 x (1- a) % credible intervel

Let Ba, b (u) be the quantile function of Beta(a, b)...



$$P\left(B_{a_n,b_n}\left(\frac{\alpha}{2}\right) < \Theta < B_{a_n,b_n}\left(1-\frac{\alpha}{2}\right) \middle| X_{1:n}\right) = 1-\alpha.$$

11 Given the data, I believe that there is a 100 × (1- x) % chance 0 is in this interval."

$$\Theta \sim Beta(a_0, b_0) \leftarrow X_1 \mid \Theta \sim Beta(a_0, b_0) \leftarrow A \mid X_1 \mid \Theta \mid X_1 \mid$$

$$a_n = a_n + \sum_{i=1}^n X_i$$

$$b_n = b_n + n - \sum_{i=1}^n X_i$$

Bayes estimator

$$E(\theta|X_{1:n}) = \frac{a_0 + ZX_1}{a_0 + b_0 + n}$$

$$= (1 - w_n) E(\theta) + w_n \theta_n^{(MLE)}$$

$$\xrightarrow{\beta} 0 \qquad \text{mean} \qquad \text{where} \qquad \text{where}$$

E(θ | X i:n) is a shrinkeye estimator. The influence of the prior decreases as n > 20, and the likelihood (as expressed through the mule) dominates.

Credible interval

$$P\left(B_{a_{n}/b_{n}}\left(\frac{\alpha}{2}\right) \land \Theta \land B_{a_{n}/b_{n}}\left(1-\frac{\alpha}{2}\right) \middle| X_{1:n}\right) = 1-\alpha$$

Il Given the data I have seen,

I believe there is a 100 × (1-d) %

chance that the parameter is in

this interval right here. "

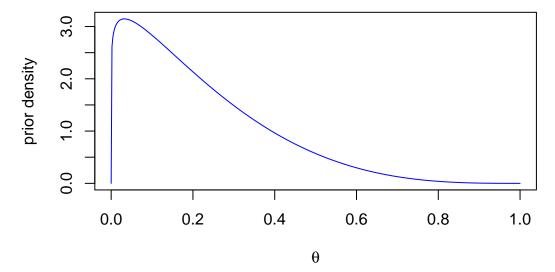
Coin flipping example

I am presented with a mystery coin that may or may not be fair, and I want to estimate the probability that it comes up heads. I model the flips as iid realizations from a Bernoulli distribution, and I take a Bayesian approach where I put a prior on the probability of heads, and then access the posterior distribution after observing some data:

$$\begin{split} \theta &\sim \text{Beta}(a_0,\,b_0) \\ X_i \,|\, \theta \stackrel{\text{iid}}{\sim} \text{Bern}(\theta) \\ \theta \,|\, X_{1:n} &\sim \text{Beta}(a_n,\,a_n). \end{split}$$

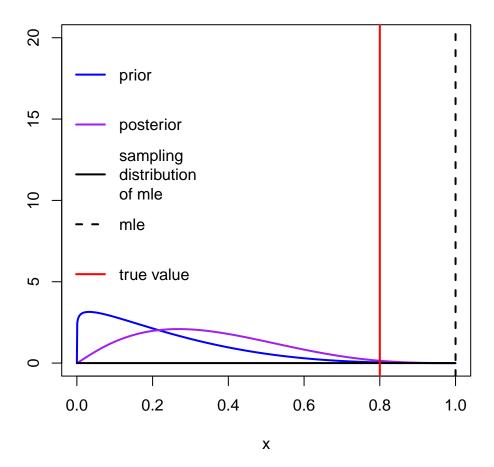
 a_0 and b_0 are hyperparameters that I adjust so that the shape of the beta distribution matches my prior beliefs. After I observe some data, by a happy accident, the posterior distribution is also a member of the beta family, but the hyperparameters have been updated to reflect what I've learned about θ after observing some data.

Let's say that, for whatever reason, I believe it is likely that the coin is biased toward the Tails side $(X_i = 0)$. Maybe the mystery coin was handed to me by someone that has played this trick before, and the last time we did this dance, the coin was biased toward Tails. Maybe they're doing it again to screw with me. So, I pick numbers $a_0 = 1.1$ and $b_0 = 4$ so that my prior has an appropriate shape:



Unfortunately, the guy is screwing with me, but not the way I think. In fact the coin is biased toward Heads, and the true probability is $\theta_0 = 0.8$. So my initial beliefs are way off the mark, but let's see how they change as I start flipping the coin and learning from data:





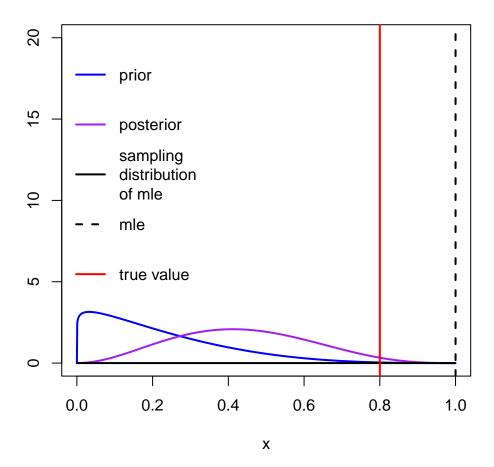
my_sample

[1] 1

mean(my_sample)

[1] 1





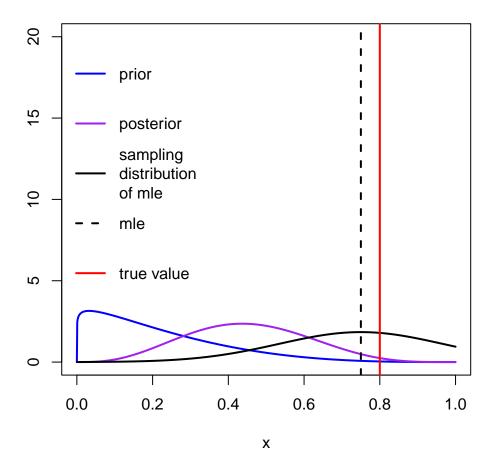
my_sample

[1] 1 1

mean(my_sample)

[1] 1



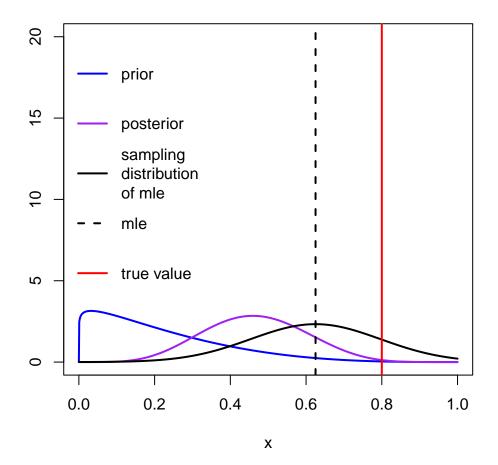


my_sample

[1] 1 1 1 0

mean(my_sample)



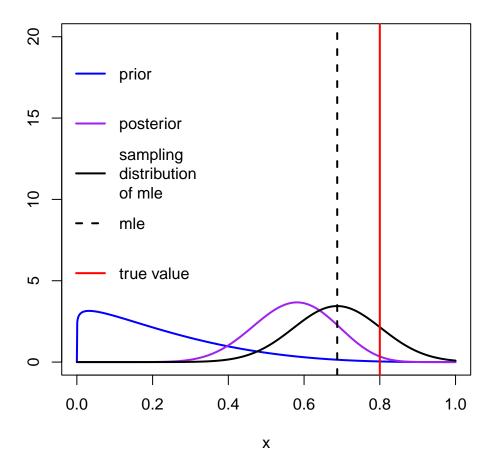


my_sample

[1] 1 1 1 0 0 1 1 0

mean(my_sample)



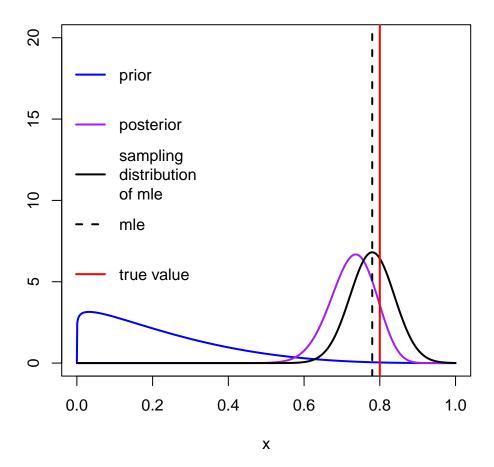


my_sample

[1] 1 1 1 0 0 1 1 0 1 1 0 1 1 1 0

mean(my_sample)

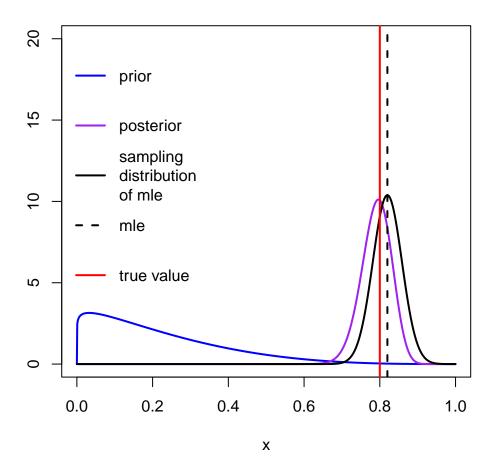




my_sample

mean(my_sample)

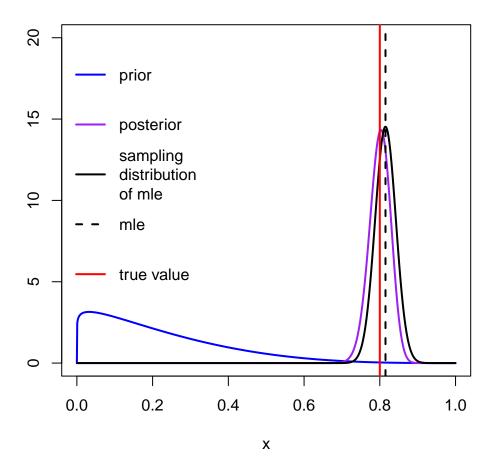




my_sample

mean(my_sample)

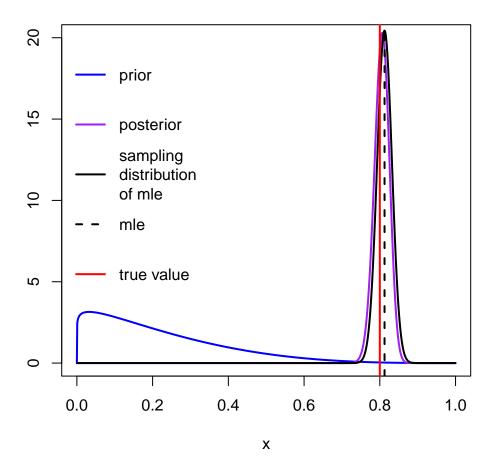




The sample proportion (mle):

mean(my_sample)

n = 400



The sample proportion (mle):

mean(my_sample)

[1] 0.8125

What did we see?

When n was small, the posterior distribution was straddling the prior and the mle ("splitting the difference"). As n grew, the prior had less influence on the posterior. The posterior was agreeing more and more with the sampling distribution of the MLE. And the sampling distribution of the MLE was concentrating more and more around the true value because we know that it is a consistent estimator.

So, even though my initial beliefs were "wrong," with enough data I get wise. Furthermore, we start to see a strange agreement between Bayesian inference (enshrined in the posterior distribution) and classical inference (enshrined in the sampling distribution). Is there something to this?

you observe one data point from a Poisson distribution. How do you update your beliefs about the rate perometer after receiving this information?

Prior
$$\Theta \sim Gamma(a_0, b_0)$$

Nikelihood $X_1 | \Theta \sim Poisson(\Theta)$

Posterior $\Theta | X_1 \sim ?$

$$f(\theta) = \frac{b_0^{a_0}}{\Gamma(a_0)} \theta^{a_0-1} e^{-b_0\theta}, \quad \theta > 0$$

$$f(x, |\theta) = e^{-\theta} \frac{\theta^{x_1}}{x_1!}$$
, $x_1 \in \mathbb{N}$

$$f(\theta)(x') = \frac{f(x')}{f(x')\theta(x')}$$

$$\Theta[X] \sim Gamma(a, b, b)$$
 $b_1 = b_0 + 1$

What if we observe a second observation $X_2/\theta \sim Poisson(\theta)$ independent of the first one? How do we further update our beliefs in light of yet more information?

Easy: the old posterior becomes the new prior, and we turn the creak one more time...

$$\Theta \mid X_1$$
 ~ Gamma (a_1, b_1)
 $X_2 \mid \theta$ ~ Poisson (θ)
 $\Theta \mid X_1, X_2$ ~ Gamma (a_2, b_2)

$$a_2 = a_1 + x_2 = a_0 + x_1 + x_2 = a_0 + \sum_{i=1}^{2} x_i$$
 $b_2 = b_1 + 1 = b_0 + 1 + 1 = b_0 + 2$

So in general . . .

$$\Theta \sim Gamma(a_0, b_0)$$
 $Gamma(a_0, b_0)$ $Gamma($

Bayesian inference is inherently recursive. As new information arrives, you synamically update your beliefs by iteratively applying

Bayes' rule.

Original observe updated observe updated observe updated observe belief
$$\times_2$$
 belief \times_3 belief \times_3 $f(\theta|X_{1:3}) \longrightarrow f(\theta|X_{1:3}) \longrightarrow$

Just keep turning the crank!

Under certain conditions, we have this as n-> 00:

$$f(\theta | x_{1:n}) \approx N(\hat{\theta}_{n}^{(MLE)}, se^{2})$$

Implications

- · posterior mean behaves like the MLE
- Bayesian credible intervals and classical confidence intervals agree So... what's all the fighting about?
 - · philosophical purity. Most statisticians take a pragmatic, il whatever works" approach, but some get really excited about these debates.
 - "asymptotically, we're all dead." Things behaving when n > 00 is a nice sanity check, but in reality n is always some finite number. In this "pre-asymptotic" regime, Bayesian and classical methods can differ substantially. You may prefer one over the other for its regularization properties, the quality of the UQ, case of implementation, etc.
- The BVM theorem applies to low-dimensional, numerical data coming from a parametric distribution that is exactly true.

 This is a bad description of modern problems in data science and statistics:
 - -> our data are big and high-dimensional
 - -> out data are no longer just lists of numbers
 In a spreadsheet. They are text, images, points
 on strange manifolds, etc.
 - In this environment, there is no general guarantee that Boyes and classical give the same results. So the debate remains live. 332! HOZ!