

# STA261 Lecture 5 — 2017-07-24

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## maximum likelihood summary

The joint pmf/pdf is treated as a function of the parameter(s)  $\theta$ , given the data.

This function is called a “likelihood”  $L(\theta)$ .

A likelihood can be thought of as the “probability” of the data.

The parameter value  $\hat{\theta}$  that maximizes  $L(\theta)$  is the maximum likelihood estimator.

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The examples we’ve done so far have all had a closed form solution, but this isn’t necessary or even “better” in any sense.

## exponential distributions revisited

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We'll see over the next few classes that this is in one particular sense the best possible estimator for  $\lambda$ .

## exponential distribution - different kind of dataset

The observed data:  $x_1, x_2, \dots, x_n$ . These often might be times-to-events, such as failure times of equipment, or the death/remission times of people in a medical study.

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What we would more typically see is data as on the next page. "Today" I extract the historical data on the equipment I am interested in...

## “survival” data

ID	Age	Status
A023	6.8	Failed
A324	7.2	Operating
A620	10.1	Taken Out of Service
A092	2.4	Operating
A526	5.5	Operating
A985	8.1	Failed
A723	1.5	Operating
⋮	⋮	⋮

## likelihood for “survival data”

The model for failure times is  $X \sim \text{Exp}(\lambda)$ .

What is the likelihood of the data?

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The likelihood for a unit to not have failed yet at time  $x_i$  is:  $P(X > x_i) = e^{-\lambda x_i}$

## likelihood, line by line

ID	Age	Status	Contribution to Likelihood
A023	6.8	Failed	$\lambda e^{-6.8\lambda}$
A324	7.2	Operating	$e^{-7.2\lambda}$
A620	10.1	Taken Out of Service	$e^{-10.1\lambda}$
A092	2.4	Operating	$e^{-2.4\lambda}$
A526	5.5	Operating	$e^{-5.5\lambda}$
A985	8.1	Failed	$\lambda e^{-8.1\lambda}$
A723	1.5	Operating	$e^{-1.5\lambda}$
$\vdots$	$\vdots$	$\vdots$	$\vdots$

## censored data, and the likelihood function

When the failure time is unknown, because it hasn't happened yet, we say the failure time is *censored*. Define the *censoring indicator*  $c_i$  to be 1 if the unit failed and 0 otherwise.

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Putting it all together, given times  $x_1, \dots, x_n$  and censoring indicators  $c_1, \dots, c_n$ , the likelihood of the data is:

$$L(\lambda) = \prod_{i=1}^n \left( \lambda e^{-\lambda x_i} \right)^{c_i} \left( e^{-\lambda x_i} \right)^{1-c_i}$$

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**Proposition 5.0:** The MLE for  $\lambda$  is  $\hat{\lambda} = \sum_{i=1}^n c_i / \sum_{i=1}^n x_i$



## occurrence-exposure example

Here are 50 simulated “ages” from an  $\text{Exp}(0.1)$  population, “censored” at 9.0 “years”

```
## [1] 9.00 6.40 2.32 4.69 8.36 3.48 0.33 5.45 7.26 2.00 5.26
## [12] 9.00 0.07 6.10 2.13 9.00 9.00 9.00 9.00 9.00 9.00 6.72
## [23] 4.42 9.00 7.56 4.57 6.25 7.97 9.00 9.00 9.00 0.04 9.00
## [34] 4.97 0.52 5.40 4.53 9.00 4.60 9.00 3.80 8.93 9.00 4.24
## [45] 3.73 9.00 9.00 9.00 9.00 9.00 0.45
```

The “naive” mean life estimate (the average of the failed units only): 4.418.

The MLE: 10.418.

## MLE result I published in 2016

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- ▶ the unit fails the moment  $Z(t)$  reaches some threshold

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So I went looking for the method that everyone used to estimate the rate in these situations. But nobody had ever done this before.

(Many OR / stats professors like to propose models, but often do not dirty themselves with actual data.)

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The probabilities of having endured 0, or 1+ shocks by age  $t_i$  are:

$$P(N(t_i) = 0) = e^{-\lambda t_i}$$

$$P(N(t_i) > 0) = 1 - e^{-\lambda t_i}$$

## likelihood

The likelihood for  $\lambda$  is therefore:

$$L(\lambda) = \prod_{i=1}^n \left( e^{-\lambda t_i} \right)^{1-d_i} \left( 1 - e^{-\lambda t_i} \right)^{d_i}$$

## likelihood

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$$\ell(\lambda) = -\lambda \sum_{i=1}^n t_i (1 - d_i) + \sum_{i=1}^n d_i \log \left( 1 - e^{-\lambda t_i} \right)$$

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This can only be maximized numerically. *As usual.*

properties of MLEs



## why maximum likelihood is so popular

They are easy to develop, and under a few conditions (most often satisfied), the method of maximum likelihood produces estimators that are:

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1. consistent
2. invariant
3. asymptotically normal

## the score, and information functions

Likelihood theory deals so much with the following functions that they are given names:

Score:

$$S(\theta) = S(\theta; \mathbf{X}) = \frac{\partial}{\partial \theta} \log L(\theta; \mathbf{X})$$

Information:

$$\mathcal{I}(\theta) = \mathcal{I}(\theta; \mathbf{X}) = E \left( \left( \frac{\partial}{\partial \theta} \log L(\theta; \mathbf{X}) \right)^2 \right)$$

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*Technical note: when  $\theta$  is a vector, the score is the gradient vector, and the information is a matrix of all the partial second derivatives.*

## properties of score and information

Likelihood theory is littered with “under certain regularity conditions” statements, handed down from one generation to the next. From my failing hands I pass the torch...

**Proposition 5.1:**  $E(S(\theta)) = 0$

**Theorem 5.2:**  $\mathcal{I}(\theta) = \text{Var}(S(\theta))$  and  $\mathcal{I}(\theta) = -E\left(\frac{\partial^2}{\partial \theta^2} \log L(\theta; \mathbf{X})\right)$