

# Lecture 3: Designing simulations

# Class activity

$$Y_i = \beta_0 + \beta_1 X_i + \varepsilon_i$$

That is, how important is the assumption that  $\varepsilon_i \sim N(0, \sigma^2)$ ?

Continue simulation from last time, but experiment with different values of  $n$  and different distributions for the noise term.

[https://sta279-f23.github.io/class\\_activities/ca\\_lecture\\_3.html](https://sta279-f23.github.io/class_activities/ca_lecture_3.html)

# Class activity

$$Y_i = \beta_0 + \beta_1 X_i + \varepsilon_i$$

How does confidence interval coverage change when you change the distribution of  $\varepsilon_i$ ?

# Class activity

```
1 nsim <- 1000
2 n <- 100 # sample size
3 beta0 <- 0.5 # intercept
4 beta1 <- 1 # slope
5 results <- rep(NA, nsim)
6
7 for(i in 1:nsim){
8   x <- runif(n, min=0, max=1)
9   noise <- rchisq(n, 1)
10  y <- beta0 + beta1*x + noise
11
12  lm_mod <- lm(y ~ x)
13  ci <- confint(lm_mod, "x", level = 0.95)
14
15  results[i] <- ci[1] < 1 & ci[2] > 1
16 }
17 mean(results)
```

```
[1] 0.949
```

# ADEMP: A useful framework for simulation studies

- **Aims:** Why are we doing the study?
- **Data generation:** How are the data simulated?
- **Estimand/target:** What are we estimating for each simulated dataset?
- **Methods:** What methods are we using for model fitting, estimation, etc?
- **Performance measures:** How do we measure performance of our chosen methods?

# ADEMP

For the normal errors simulation study:

- **Aims:**
- **Data generation:**
- **Estimand/target:**
- **Methods:**
- **Performance measures:**

