## torch

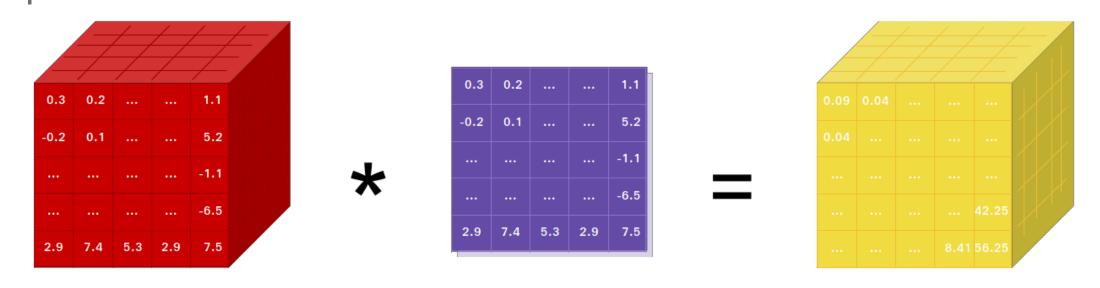
**Lecture 17** 

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## **PyTorch**

PyTorch is a Python package that provides two high-level features:

- Tensor computation (like NumPy) with strong GPU acceleration
- Deep neural networks built on a tape-based autograd system



- 1 import torch
- 2 torch.\_\_version\_\_

<sup>&#</sup>x27;2.6.0'

## A graph is created on the fly

```
W_h h W_x x
```

```
W_h = torch.randn(20, 20, requires_grad=True)
W_x = torch.randn(20, 10, requires_grad=True)
x = torch.randn(1, 10)
prev_h = torch.randn(1, 20)
```



### **Tensors**

are the basic data abstraction in PyTorch and are implemented by the torch. Tensor class. The behave in much the same was as the other array libraries we've seen so far (numpy, jax, etc.)

```
1 torch.zeros(3)
                                                 torch.manual_seed(1234)
tensor([0., 0., 0.])
                                             <torch. C.Generator object at
                                             0x3015a3410>
 1 torch.ones(3,2)
                                              1 torch.rand(2,2,2,2)
tensor([[1., 1.],
        [1., 1.],
                                             tensor([[[[0.02898, 0.40190],
        [1., 1.]])
                                                       [0.25984, 0.36664]],
 1 torch.empty(2,2,2)
                                                      [[0.05830, 0.70064],
                                                       [0.05180, 0.46814]],
tensor([[[0., 0.],
         [0., 0.]],
                                                     [[[0.67381, 0.33146],
                                                       [0.78371, 0.56306]],
        [[0., 0.],
         [0., 0.]]
                                                      [[0.77485, 0.82080],
                                                       [0.27928, 0.68171]]])
```

## **Constants**

As expected, tensors can be constructed from constant numeric values in lists or tuples.

```
1 torch.tensor([(1,1,1), [4,5]])
 1 torch.tensor(1)
tensor(1)
                                            at dim 1 (got 2)
 1 torch.tensor((1,2))
tensor([1, 2])
 1 torch.tensor([[1,2,3], [4,5,6]])
tensor([[1, 2, 3],
        [4, 5, 6]])
                                             tensor([[True]])
 1 torch.tensor([(1,2,3), [4,5,6]])
tensor([[1, 2, 3],
        [4, 5, 6]])
```

```
ValueError: expected sequence of length 3
    torch.tensor([["A"]])
ValueError: too many dimensions 'str'
 1 torch.tensor([[True]])
```

## **Tensor Types**

Data type	dtype	type()	Comment		
32-bit float	float32 or float FloatTensor		Default float		
64-bit float	float64 or double DoubleTensor				
16-bit float	float16 or half HalfTensor				
16-bit brain float	bfloat16 BFloat16Tensor				
64-bit complex float	complex64				
128-bit complex float	complex128 or cdouble				
8-bit integer (unsigned)	uint8 ByteTensor				
8-bit integer (signed)	int8 CharTensor				
16-bit integer (signed)	int16 or short ShortTensor				
32-bit integer (signed)	int32 or int	IntTensor			
64-bit integer (signed)	int64 or long	LongTensor	Default integer		
Boolean	bool	BoolTensor			

## **Specifying types**

Just like NumPy and Pandas, types are specified via the dtype argument and can be inspected via the dtype attribute.

```
1 a = torch.tensor([1,2,3]); a
                                                    1 c = torch.tensor([1.,2.,3.]); c
tensor([1, 2, 3])
                                                  tensor([1., 2., 3.])
 1 a.dtype
                                                    1 c.dtype
                                                  torch.float32
torch.int64
 1 b = torch.tensor([1,2,3], dtype=torch.float1
                                                    1 d = torch.tensor([1,2,3], dtype=torch.float(
tensor([1., 2., 3.], dtype=torch.float16)
                                                  tensor([1., 2., 3.], dtype=torch.float64)
                                                      d.dtype
    b.dtype
torch.float16
                                                  torch.float64
```

## Type precision

When using types with less precision it is important to be careful about underflow and overflow (ints) and rounding errors (floats).

```
1 torch.tensor([128], dtype=torch.int8)
                                                    1 torch.tensor(1/3, dtype=torch.float16)
RuntimeError: value cannot be converted to type
                                                  tensor(0.33325195, dtype=torch.float16)
int8 without overflow
                                                    1 torch.tensor(1/3, dtype=torch.float32)
  1 torch.tensor([128]).to(torch.int8)
                                                  tensor(0.33333334)
tensor([-128], dtype=torch.int8)
                                                    1 torch.tensor(1/3, dtype=torch.float64)
 1 torch.tensor([255]).to(torch.uint8)
                                                  tensor(0.33333333, dtype=torch.float64)
tensor([255], dtype=torch.uint8)
                                                    1 torch.tensor(1/3, dtype=torch.bfloat16)
    torch.tensor([300]).to(torch.uint8)
                                                  tensor(0.33398438, dtype=torch.bfloat16)
tensor([44], dtype=torch.uint8)
  1 torch.tensor([300]).to(torch.int16)
tensor([300], dtype=torch.int16)
```

## **NumPy conversion**

It is possible to easily move between NumPy arrays and Tensors via the from\_numpy() function and numpy() method.

```
1 \quad a = np.eye(3,3)
 2 torch.from numpy(a)
tensor([[1., 0., 0.],
        [0., 1., 0.],
        [0., 0., 1.]], dtype=torch.float64)
 1 b = np.array([1,2,3])
 2 torch.from_numpy(b)
tensor([1, 2, 3])
 1 c = torch.rand(2,3)
  2 c.numpy()
array([[0.28367, 0.65673, 0.23876],
       [0.73128, 0.60122, 0.30433]], dtype=float32)
 1 d = torch.ones(2,2, dtype=torch.int64)
  2 d.numpy()
array([[1, 1],
       [1, 1]
```

## Math & Logic

Just like NumPy torch tensor objects support basic mathematical and logical operations with scalars and other tensors - torch provides implementations of most commonly needed mathematical functions.

```
1 torch.ones(2,2) * 7 -1
                                               1 \times = torch.rand(2,2)
                                               2 torch.ones(2,2) @ x
tensor([[6., 6.],
        [6., 6.]]
                                             tensor([[1.22126317, 1.36931109],
                                                     [1.22126317, 1.36931109]])
 1 torch.ones(2,2) + torch.tensor([[1,2],
                                               1 torch.clamp(x*2-1, -0.5, 0.5)
tensor([[2., 3.],
        [4., 5.]
                                             tensor([[-0.49049568, 0.25872374],
                                                     [ 0.50000000, 0.47989845]])
 1 2 ** torch.tensor([[1,2], [3,4]])
                                               1 torch.mean(x)
tensor([[ 2, 4],
        [ 8, 16]])
                                             tensor(0.64764357)
 1 2 ** torch.tensor([[1,2], [3,4]]) > 5
                                               1 torch.sum(x)
                                             tensor(2.59057426)
tensor([[False, False],
        [True, True]])
                                               1 torch.min(x)
                                             tensor(0.25475216)
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```

## **Broadcasting**

Like NumPy, cases where tensor dimensions do not match use the broadcasting heuristic.

The rules for broadcasting are:

- Each tensor must have at least one dimension no empty tensors.
- Comparing the dimension sizes of the two tensors, going from last to first:
  - Each dimension must be equal, or
  - One of the dimensions must be of size 1, or
  - The dimension does not exist in one of the tensors

## **Exercise 1**

Consider the following 6 tensors:

```
1  a = torch.rand(4, 3, 2)
2  b = torch.rand(3, 2)
3  c = torch.rand(2, 3)
4  d = torch.rand(0)
5  e = torch.rand(3, 1)
6  f = torch.rand(1, 2)
```

which of the above could be multiplied together and produce a valid result via broadcasting (e.g. a\*b, a\*c, a\*d, etc.).

Explain why or why not broadcasting was able to be applied in each case.

```
1 countdown::countdown(5)
```

## Inplace modification

In instances where we need to conserve memory it is possible to apply many functions such that a new tensor is not created but the original value(s) are replaced. These functions share the same name with the original functions but have a \_ suffix.

```
1 = torch.rand(2,2)
 2 print(a)
tensor([[0.31861043, 0.29080772],
        [0.41960979, 0.37281448]])
 1 print(torch.exp(a))
                                                print(torch.exp_(a))
tensor([[1.37521553, 1.33750737],
                                            tensor([[1.37521553, 1.33750737],
                                                     [1.52136779, 1.45181489]])
        [1.52136779, 1.45181489]])
 1 print(a)
                                              1 print(a)
tensor([[0.31861043, 0.29080772],
                                            tensor([[1.37521553, 1.33750737],
                                                     [1.52136779, 1.45181489]])
        [0.41960979, 0.37281448]])
```

## Inplace arithmetic

All arithmetic functions are available as methods of the Tensor class,

```
1 a = torch.ones(2, 2)
 2 b = torch.rand(2, 2)
 1 a+b
                                              1 a.add_(b)
tensor([[1.37689185, 1.01077938],
                                            tensor([[1.37689185, 1.01077938],
        [1.94549370, 1.76611161]])
                                                     [1.94549370, 1.76611161]])
 1 print(a)
                                              1 print(a)
tensor([[1., 1.],
                                            tensor([[1.37689185, 1.01077938],
        [1., 1.]])
                                                     [1.94549370, 1.76611161]])
 1 print(b)
                                              1 print(b)
tensor([[0.37689191, 0.01077944],
                                            tensor([[0.37689191, 0.01077944],
        [0.94549364, 0.76611167]])
                                                     [0.94549364, 0.76611167]])
```

## Changing tensor shapes

The shape of a tensor can be changed using the view() or reshape() methods. The former guarantees that the result shares data with the original object (but requires contiguity), the latter may or may not copy the data.

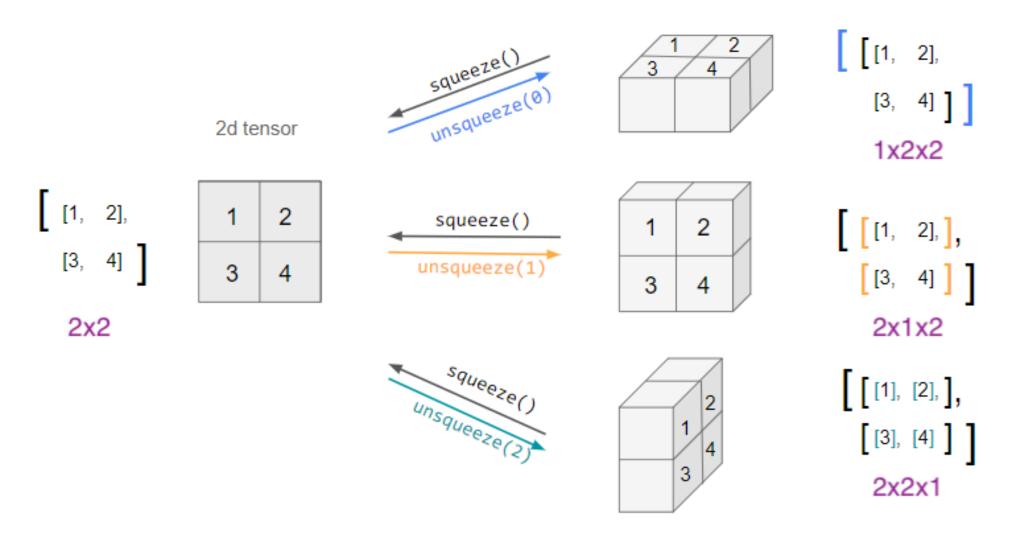
```
1 \times = torch.zeros(3, 2)
                                      1 \times = torch.zeros(3, 2)
                                                                             z = y \cdot reshape(6)
 2 y = x.view(2, 3)
                                      2 y = x_{\bullet}t()
                                                                          2 x.fill (1)
                                                                        tensor([[1., 1.],
                                      1 \times \text{view}(6)
  1 y
                                                                                 [1., 1.],
                                                                                 [1., 1.]])
tensor([[0., 0., 0.],
                                    tensor([0., 0., 0., 0., 0.,
         [0., 0., 0.]
                                    0.1)
                                                                          1 y
                                      1 y_{\bullet} view(6)
  1 x.fill_(1)
                                                                        tensor([[1., 1., 1.],
                                                                                 [1., 1., 1.]
tensor([[1., 1.],
                                    RuntimeError: view size is not
                                    compatible with input tensor's
        [1., 1.],
                                                                          1 z
         [1., 1.]
                                    size and stride (at least one
                                                                        tensor([0., 0., 0., 0., 0.,
                                    dimension spans across two
 1 y
                                       contiguous subspaces). Use
                                                                        0.1)
                                    .reshape(...) instead.
tensor([[1., 1., 1.],
        [1., 1., 1.]
```

## Adding or removing dimensions

The squeeze() and unsqueeze() methods can be used to remove or add length 1 dimension(s) to a tensor.

```
1 \times = torch.zeros(3,2)
 1 \times = torch.zeros(1,3,1)
 1 x.squeeze().shape
                                               1 x.unsqueeze(0).shape
torch.Size([3])
                                             torch.Size([1, 3, 2])
 1 x.squeeze(0).shape
                                               1 x.unsqueeze(1).shape
torch.Size([3, 1])
                                             torch.Size([3, 1, 2])
 1 x.squeeze(1).shape
                                               1 x.unsqueeze(2).shape
torch.Size([1, 3, 1])
                                             torch.Size([3, 2, 1])
 1 x.squeeze(2).shape
torch.Size([1, 3])
```

#### 3d tensor



## **Exercise 2**

Given the following tensors,

```
1 a = torch.ones(4,3,2)
2 b = torch.rand(3)
3 c = torch.rand(5,3)
```

what reshaping is needed to make it possible so that a \* b and a \* c can be calculated via broadcasting?

```
1 countdown::countdown(3)
```

# Autograd

## **Tensor expressions**

Gradient tracking can be enabled using the requires\_grad argument at initialization, alternatively the requires\_grad flag can be set on the tensor or the enable\_grad() context manager used (via with).

```
1 x = torch.linspace(0, 2, steps=21, requires grad=True)
 2 x
tensor([0.00000000, 0.10000000, 0.20000000, 0.30000001, 0.40000001, 0.50000000,
0.60000002, 0.69999999, 0.80000001,
   0.90000004, 1.00000000, 1.10000002, 1.20000005, 1.29999995, 1.39999998,
1.500000000,
        1.60000002, 1.70000005, 1.79999995, 1.89999998, 2.00000000],
requires grad=True)
 1 \quad v = 3*x + 2
 2 y
tensor([2.00000000, 2.29999995, 2.59999990, 2.90000010, 3.20000005, 3.50000000,
3.80000019, 4.09999990, 4.40000010,
   4.69999981, 5.00000000, 5.30000019, 5.60000038, 5.89999962, 6.19999981,
6.50000000,
        6.80000019, 7.10000038, 7.39999962, 7.69999981, 8.00000000], grad fn=
<AddBackward0>)
```

## Computational graph

Basics of the computation graph can be explored via the next\_functions attribute

```
1 y.grad_fn
<AddBackward0 object at 0x30c815390>
1 y.grad_fn.next_functions
((<MulBackward0 object at 0x30bb8e740>, 0), (None, 0))
1 y.grad_fn.next_functions[0][0].next_functions
((<AccumulateGrad object at 0x30c817f10>, 0), (None, 0))
1 y.grad_fn.next_functions[0][0].next_functions[0][0].next_functions
()
```

## Autogradient

In order to calculate the gradients we use the backward() method on the *output* tensor (must be a scalar), this then makes the grad attribute available for the input (leaf) tensors.

## A bit more complex

#### 1 x.grad

```
tensor([0.23227984, 0.72686875, 0.11874896, 0.39512146, 0.71987736, 0.75950843, 0.53108865, 0.64494550, 0.72242016, 0.44158769, 0.36338443, 0.88182861, 0.98741043, 0.73160070, 0.28143251, 0.06507802, 0.00649202, 0.50345892, 0.30815977, 0.37417805, 0.42968810])
```

#### 1 m.grad

## High-level autograd API

allows for the automatic calculation and evaluation of the jacobian and hessian for a function defined using tensors.

```
1 def f(x, y):
 2 return 3*x + 1 + 2*y**2 + x*y
 1 for \times in [0.,1.]:
      for y in [0.,1.]:
    print("x = ", x, "y = ", y)
        inputs = (torch.tensor([x]), torch.tensor([y]))
        print(torch.autograd.functional.jacobian(f, inputs),"\n")
x = 0.0 y = 0.0
(tensor([[3.]]), tensor([[0.]]))
x = 0.0 y = 1.0
(tensor([[4.]]), tensor([[4.]]))
x = 1.0 y = 0.0
(tensor([[3.]]), tensor([[1.]]))
x = 1.0 y = 1.0
(tensor([[4.]]), tensor([[5.]]))
```

```
1 inputs = (torch.tensor([0.]), torch.tensor([0.]))
2 torch.autograd.functional.hessian(f, inputs)

((tensor([[0.]]), tensor([[1.]])), (tensor([[1.]]), tensor([[4.]])))

1 inputs = (torch.tensor([1.]), torch.tensor([1.]))

2 torch.autograd.functional.hessian(f, inputs)

((tensor([[0.]]), tensor([[1.]])), (tensor([[1.]]), tensor([[4.]])))
```

# Demo 1 - Linear Regression w/ PyTorch

## A basic model

```
1  x = np.linspace(-math.pi, math.pi, 50)
2  y = np.sin(x)
3
4  lm = smf.ols(
5    "y~x+I(x**2)+I(x**3)",
6    data=pd.DataFrame({"x": x, "y": y})
7  ).fit()
8
9  print(lm.summary())
```

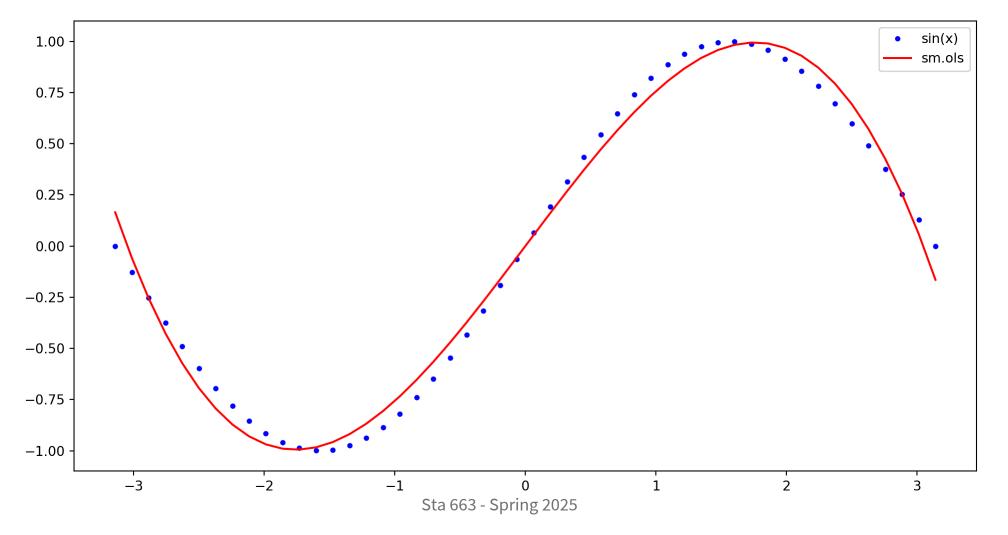
OLS Regression Results

Dep. Variable:		y R-s	quared:		0.990
Model:		OLS Adj	OLS Adj. R-squared:		0.989 1455.
Method:	Least Squ	ares F-statistic:			
Date:	Wed, 19 Mar	2025 Pro	b (F—statistic)	:	1.44e-45 60.967 -113.9
Time:	09:3	3:38 Log	Log-Likelihood: AIC:		
No. Observations:		50 AIC			
Df Residuals:		46 BIC	:		-106.3
Df Model:		3			
Covariance Type:	nonro	bust			
coe	f std err	t	P> t	[0.025	0.975]
Intercept -7.958e-1	7 0.016	-5.03e-15	1.000	-0 <b>.</b> 032	0.032
x 0.847	6 0.014	59.444	0.000	0.819	0.876
I(x ** 2) 3.692e-1	7 0.003	1.07e-14	1.000	-0.007	0.007
I(x ** 3) -0.091	2 0.002	-42.977	0.000	-0.095	-0.087

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## **Predictions**

```
1 plt.figure(figsize=(10,5), layout="constrained")
2 plt.plot(x, y, ".b", label="sin(x)")
3 plt.plot(x, lm.predict(), "-r", label="sm.ols")
4 plt.legend()
5 plt.show()
```



## Making tensors

```
1 yt = torch.tensor(y)
 2 Xt = torch.tensor(lm.model.exog)
 3 bt = torch.randn((Xt.shape[1], 1), dtype=torch.float64, requires_grad=True)
 1 yt.shape
torch.Size([50])
 1 Xt.shape
torch.Size([50, 4])
    bt.shape
torch.Size([4, 1])
 1 yt pred = (Xt @ bt).squeeze()
 1 loss = (yt_pred - yt).pow(2).sum()
 2 loss.item()
```

2119.277704016523

## **Gradient descent**

```
learning_rate = 1e-6
loss.backward() # Compute the backward pass
with torch.no_grad():
bt -= learning_rate * bt.grad # Make the step

bt.grad = None # Reset the gradients
```

```
1 yt_pred = (Xt @ bt).squeeze()
2 loss = (yt_pred - yt).pow(2).sum()
3 loss.item()
```

2069.4881821807053

## Putting it together

```
1 yt = torch.tensor(y).unsqueeze(1)
2 Xt = torch.tensor(lm.model.exog)
   bt = torch.randn((Xt.shape[1], 1), dtype=torch.float64, requires_grad=True)
 4
   learning_rate = 1e-5
   for i in range(5001):
     yt_pred = Xt @ bt
 8
 9
     loss = (yt_pred - yt).pow(2).sum()
10
     if i % 500 == 0:
11
       print(f"Step: {i},\tloss: {loss.item()}")
12
13
     loss.backward()
14
15
16
     with torch.no grad():
17
       bt -= learning_rate * bt.grad
       bt.grad = None
18
```

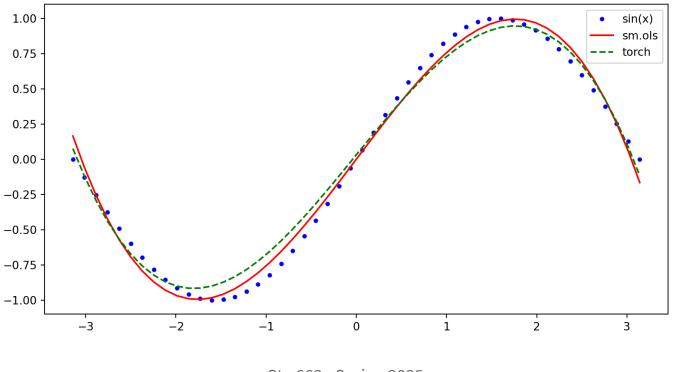
## Putting it together

```
Step: 0, loss: 70161.1580804254
Step: 500, loss: 14.791178300540242
Step: 1000, loss: 8.825181658035252
Step: 1500, loss: 5.311942717260374
Step: 2000, loss: 3.2416251317783518
Step: 2500, loss: 2.020671792951764
Step: 3000, loss: 1.300022038356929
Step: 3500, loss: 0.8742816442183533
Step: 4000, loss: 0.6225166364100523
Step: 4500, loss: 0.473473387453477
Step: 5000, loss: 0.38513809895450724
 1 print(bt)
tensor([[ 0.03141952],
        [0.78487683],
        [-0.00520719],
        [-0.08261045]], dtype=torch.float64,
requires grad=True)
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```

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## **Comparing results**

```
1 lm.params1 btIntercept -7.958044e-17<br/>x 8.476289e-01<br/>I(x ** 2) 3.691708e-17<br/>I(x ** 3) -9.120167e-02tensor([[ 0.03141952],<br/>[ 0.78487683],<br/>[ -0.00520719],<br/>[ -0.08261045]],<br/>dtype: float64
```



# Demo 2 - Using a torch model

## A simple model

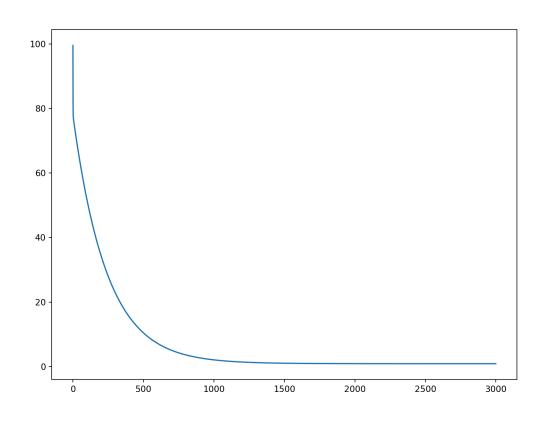
```
class Model(torch.nn.Module):
       def __init__(self, beta):
            super().__init__()
           beta.requires_grad = True
 4
            self.beta = torch.nn.Parameter(beta)
 5
 6
       def forward(self, X):
           return X @ self.beta
 8
 9
   def training_loop(model, X, y, optimizer, n=1000):
       losses = []
11
       for i in range(n):
12
13
           y_pred = model(X)
14
           loss = (y_pred.squeeze() - y.squeeze()).pow(2).sum()
15
            loss.backward()
16
17
           optimizer.step()
18
19
           optimizer.zero_grad()
20
21
            losses.append(loss.item())
22
       return losses
23
```

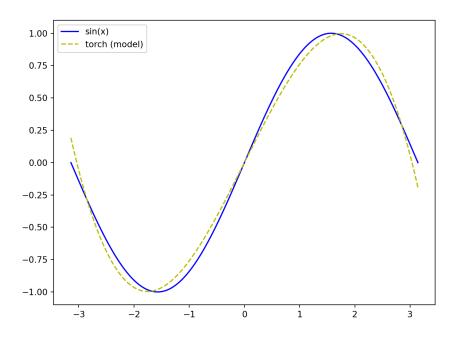
## **Fitting**

## Results

```
1 m.beta
```

Parameter containing: tensor([-4.07514189e-10, 8.52953434e-01, 1.22972355e-10, -9.25917700e-02], requires\_grad=True)



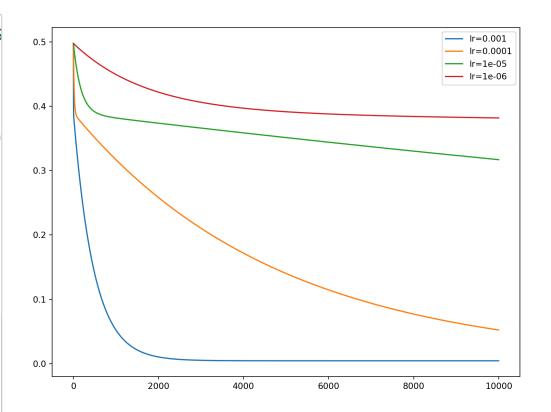


## An all-in-one model

```
class Model(torch.nn.Module):
       def __init__(self, X, y, beta=None):
 2
            super().__init__()
 3
           self.X = X
 4
           self_y = y
           if beta is None:
 6
              beta = torch.zeros(X.shape[1])
           beta.requires_grad = True
            self.beta = torch.nn.Parameter(beta)
 9
10
11
       def forward(self, X):
12
            return X @ self.beta
13
14
       def fit(self, opt, n=1000, loss_fn = torch.nn.MSELoss()):
15
         losses = []
16
         for i in range(n):
17
              loss = loss_fn(self.forward(self.X).squeeze(), self.y.squeeze())
              loss.backward()
18
19
              opt.step()
20
              opt.zero_grad()
              losses.append(loss.item())
21
```

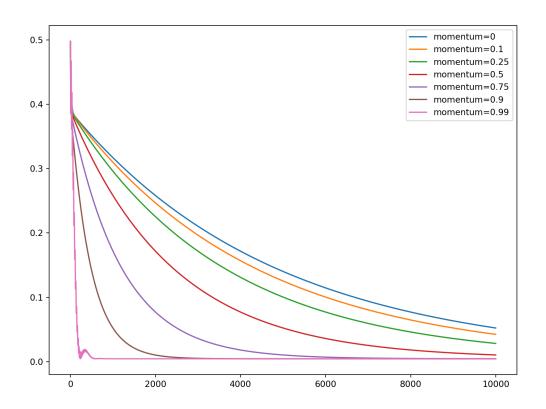
## Learning rate and convergence

```
plt.figure(figsize=(8,6), layout="cons
  for lr in [1e-3, 1e-4, 1e-5, 1e-6]:
    m = Model(X, y)
    opt = torch.optim.SGD(m.parameters()
    losses = m.fit(opt, n=10000)
    plt.plot(losses, label=f"{lr=}")
9
  plt.legend()
  plt.show()
```



## Momentum and convergence

```
plt.figure(figsize=(8,6), layout="constrain(
   for momentum in [0, 0.1, 0.25, 0.5, 0.75, 0
     m = Model(X, y)
     opt = torch.optim.SGD(
       m.parameters(),
       lr = 1e-4,
       momentum = momentum
 9
     losses = m.fit(opt, n=10000)
10
11
     plt.plot(losses, label=f"{momentum=}")
12
13
   plt.legend()
14
   plt.show()
```



## **Optimizers and convergence**

```
plt.figure(figsize=(8,6), layout="constraine")
   opts = (torch.optim.SGD,
            torch.optim.Adam,
            torch.optim.Adagrad)
   for opt_fn in opts:
     m = Model(X, y)
     opt = opt_fn(m.parameters(), lr=1e-4)
 9
     losses = m.fit(opt, n=10000)
10
11
     plt.plot(losses, label=f"{opt_fn=}")
12
13
   plt.legend()
   plt.show()
```

