EM Algorithm and ZIP models

Point mass: I is a point mass at CER if PCY = 0 = 1 => P(+= y)=0 For y+C

EM algorithm in general

Let
$$\Theta$$
 be an unknown parameter we want to estimate. Let Y be a set of observed data, and Z a set of undoserved latent/missing data.

L(Θ) = P(Y | Θ) = $\int P(Y | Z = Z, \Theta) P(Z = Z | \Theta) dZ$

Maximizing this likelihood is challenging when we don't observe Z .

Malgorithm:

Estep: Let
$$\theta^{(u)}$$
 be the current estimate of θ

Q(θ 1 $\theta^{(u)}$) = $E_{Z1Y, \theta^{(u)}}$ [log L(θ ; Z, Y)]

M step:
$$\Theta^{(u+1)} = argmax Q(\Theta | \Theta^{(u)})$$

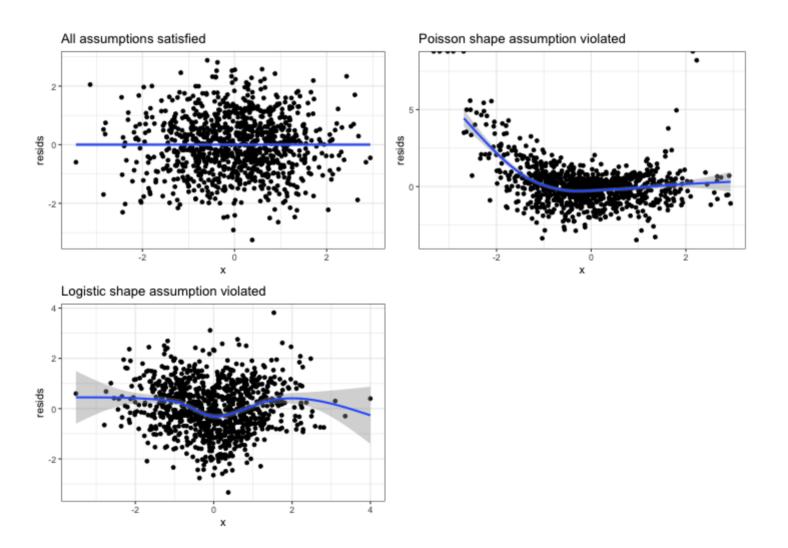
10g P(410) = log (SPLY, Z=Z10) 0Z) Motivation; = $\log \left(\frac{P(Y,Z=Z|\Theta)}{P(Z=Z|Y,\Theta_{0}|\Theta)} \right) \frac{z}{P(Z=Z|Y,\Theta_{0}|\Theta)}$ = $\log \left(\frac{P(Y,Z=Z|\Theta)}{P(Z=Z|Y,\Theta_{0}|\Theta)} \right) \frac{z}{P(Z=Z|Y,\Theta_{0}|\Theta)} \frac{z}{Z}$ Sensen's inequality. = log Eziy, Oold [P(Y, ZlO)] If P is a convex function, C(ELX]) & E[Y(X)] Z EZM, BOID [log (PCZIY, BOID)] = EZM, OGO [log P(Y, Z10)] - EZM, OGO [log P(Z)M, OGO)] P(F, XT) > E[P(X)] = EZM, OND [log L(B; Y, Z)] 20 = Q(B(D)) + H(Dd) Increasing a (Oldord) should increase leg L(O)

(visual intuition) Jensen's inequality (convex) (X) P(42) te(x)+(1-t)で(x) e(tx,+(1-t)x2) T(x,) t ∈ (0,1) Ex, + (1-t)x2 22 eltx, + (1-t)x2) representing re[E[X]) < telesin + (1-t) t(x2) (represents E[Y(X)]) P(E(X)) & E[P(X)]

Class activity

https://sta712-f22.github.io/class_activities/ca_lecture_31.html

Assessing the shape assumption



Logistic component vs. Poisson component