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# Fitting mixed models

often:  $G = \sigma_u^2 I_m$

$R = \sigma_\varepsilon^2 I_n$

$$y = X\beta + Zu + \varepsilon$$

↑  
design matrix  
for fixed effects

↑  
design matrix for  
random effects

$$u \sim N(0, G)$$

$$\varepsilon \sim N(0, R)$$

$$u \perp \varepsilon$$

$$\underline{Zu + \varepsilon} \sim N(0, ZGZ^T + R)$$

$$\begin{aligned} \text{var}(Zu) \\ = Z \text{var}(u) Z^T \end{aligned}$$

$$y = X\beta + \delta$$

$$\Rightarrow \underbrace{V^{-\frac{1}{2}} y}_{y_w} = \underbrace{V^{\frac{1}{2}} X \beta}_{X_w} + \underbrace{V^{-\frac{1}{2}} \delta}_{\substack{N(0, I) \\ \delta_w}}$$

$$y_w = X_w \beta + \delta_w$$

$$\hat{\beta} = (X_w^T X_w)^{-1} X_w^T y_w$$

$$\delta \sim N(0, \underbrace{ZGZ^T + R}_V)$$

$$V^{-\frac{1}{2}} \delta \sim N(0, I)$$

$$\text{var}(V^{-\frac{1}{2}} \delta)$$

$$(X^T V^{-1} X)^{-1} X^T V^{-1} y$$

$$\begin{aligned} \text{var}(\hat{\beta}) = \\ (X^T V^{-1} X)^{-1} \end{aligned}$$

$$\text{Ex: } \gamma_{ij} = \beta_0 + \alpha_i + \beta_1 x_i + \varepsilon_{ij}$$

$$x_i \in \{0, 1\} \quad n_i = \# \text{ obs in group } i$$

$$x_1, \dots, x_{m_0} = 0 \quad x_{m_0+1}, \dots, x_m = 1$$

$$\bar{\gamma}_{i.} = \text{mean of } \gamma \text{ in group } i$$

$$\hat{\beta}_1 = (X^T V^{-1} X)^{-1} X^T V^{-1} Y$$

$$X = \begin{bmatrix} 1 & x_1 \\ \vdots & \vdots \\ 1 & x_1 \\ \vdots & \vdots \\ 1 & x_2 \\ \vdots & \vdots \\ 1 & x_2 \\ \vdots & \vdots \\ 1 & x_m \\ \vdots & \vdots \\ 1 & x_m \end{bmatrix} \left\{ \begin{array}{l} n_1 \\ n_2 \\ n_m \end{array} \right.$$

$$\hat{\beta}_1 = \frac{\sum_{i=m_0+1}^m \frac{n_i \bar{\gamma}_{i.}}{n_i \hat{\sigma}_u^2 + \hat{\sigma}_\varepsilon^2}}{\sum_{i=m_0+1}^m \frac{n_i}{n_i \hat{\sigma}_u^2 + \hat{\sigma}_\varepsilon^2}}$$

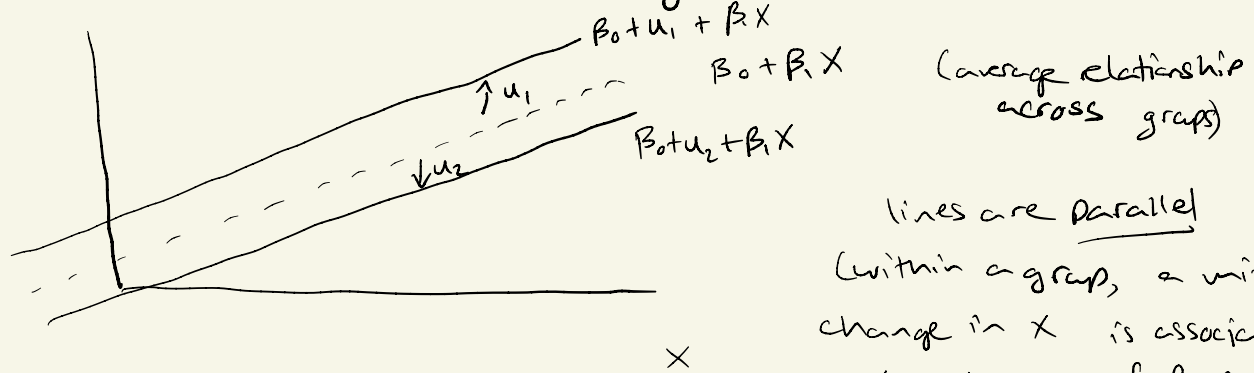
$$= \frac{\sum_{i=1}^{m_0} \frac{n_i \bar{\gamma}_{i.}}{n_i \hat{\sigma}_u^2 + \hat{\sigma}_\varepsilon^2}}{\sum_{i=1}^{m_0} \frac{n_i}{n_i \hat{\sigma}_u^2 + \hat{\sigma}_\varepsilon^2}}$$

$$\text{var}(\bar{\gamma}_{i.}) = \sigma_u^2 + \frac{\sigma_\varepsilon^2}{n}$$

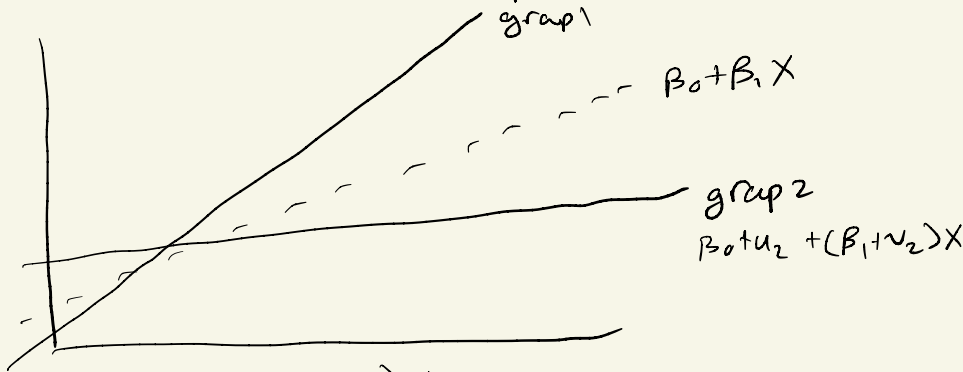
So far: random intercepts model

$$y_{ij} = \beta_0 + u_i + \beta_1 x_{ij} + \varepsilon_{ij}$$

e.g.  $X$  is a continuous explanatory variable:



what if we want different slopes?



$$y_{ij} = \beta_0 + u_i + (\beta_1 + v_i) x_{ij} + \varepsilon_{ij}$$

$$y_{ij} = \beta_0 + u_i + (\beta_1 + v_i) x_{ij} + \varepsilon_{ij}$$

$$\begin{bmatrix} u_i \\ v_i \end{bmatrix} \sim N\left(\begin{bmatrix} 0 \\ 0 \end{bmatrix}, \begin{bmatrix} \sigma_u^2 & \rho\sigma_u\sigma_v \\ \rho\sigma_u\sigma_v & \sigma_v^2 \end{bmatrix}\right)$$

