Introduction to Linear Models

STA721 Linear Models Duke University

Merlise Clyde

August 26, 2019

► Instructor: Merlise Clyde 223 Old Chemistry Office Hours: TBA

Instructor: Merlise Clyde
 223 Old Chemistry
 Office Hours: TBA

► Teaching Assistant: Vittorio Orlandi

Instructor: Merlise Clyde
 223 Old Chemistry
 Office Hours: TBA

► Teaching Assistant: Vittorio Orlandi

► Teaching Assistant: Pritam Dey

 Instructor: Merlise Clyde 223 Old Chemistry Office Hours: TBA

► Teaching Assistant: Vittorio Orlandi

► Teaching Assistant: Pritam Dey

 Course: Theory and Application of linear models from both a frequentist (classical) and Bayesian perspective

 Instructor: Merlise Clyde 223 Old Chemistry Office Hours: TBA

► Teaching Assistant: Vittorio Orlandi

► Teaching Assistant: Pritam Dey

 Course: Theory and Application of linear models from both a frequentist (classical) and Bayesian perspective

 Prerequisites: linear algebra and a mathematical statistics course covering likelihoods and distribution theory (normal, t, F, chi-square, gamma distributions)

- Instructor: Merlise Clyde 223 Old Chemistry Office Hours: TBA
- ► Teaching Assistant: Vittorio Orlandi
- ► Teaching Assistant: Pritam Dey
- Course: Theory and Application of linear models from both a frequentist (classical) and Bayesian perspective
- Prerequisites: linear algebra and a mathematical statistics course covering likelihoods and distribution theory (normal, t, F, chi-square, gamma distributions)
- Introduce R programming as needed

- Instructor: Merlise Clyde 223 Old Chemistry Office Hours: TBA
- ► Teaching Assistant: Vittorio Orlandi
- ► Teaching Assistant: Pritam Dey
- Course: Theory and Application of linear models from both a frequentist (classical) and Bayesian perspective
- Prerequisites: linear algebra and a mathematical statistics course covering likelihoods and distribution theory (normal, t, F, chi-square, gamma distributions)
- ► Introduce R programming as needed
- ► Introduce Bayesian methods, but assume that you are co-registered in 601 or have taken it previously

- Instructor: Merlise Clyde 223 Old Chemistry Office Hours: TBA
- ► Teaching Assistant: Vittorio Orlandi
- ► Teaching Assistant: Pritam Dey
- Course: Theory and Application of linear models from both a frequentist (classical) and Bayesian perspective
- Prerequisites: linear algebra and a mathematical statistics course covering likelihoods and distribution theory (normal, t, F, chi-square, gamma distributions)
- Introduce R programming as needed
- ► Introduce Bayesian methods, but assume that you are co-registered in 601 or have taken it previously
- more info on Course Website http://stat.duke.edu/courses/Fall18/sta721



Build "regression" models that relate a response variable to a collection of covariates

► Goals of Analysis?

- ► Goals of Analysis?
 - Predictive models

- ► Goals of Analysis?
 - Predictive models
 - Causal interpretation

- Goals of Analysis?
 - Predictive models
 - Causal interpretation
 - Testing of hypotheses

- Goals of Analysis?
 - Predictive models
 - Causal interpretation
 - Testing of hypotheses
 - confirmatory or validation analyses

- Goals of Analysis?
 - Predictive models
 - Causal interpretation
 - Testing of hypotheses
 - confirmatory or validation analyses
- Observational versus Experimental data?

- Goals of Analysis?
 - Predictive models
 - Causal interpretation
 - Testing of hypotheses
 - confirmatory or validation analyses
- Observational versus Experimental data? (Confounding)

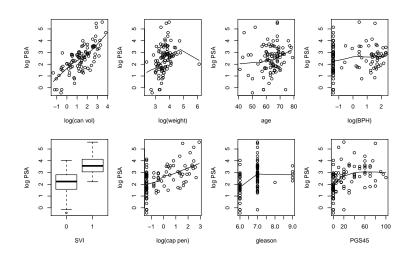
- Goals of Analysis?
 - Predictive models
 - Causal interpretation
 - Testing of hypotheses
 - confirmatory or validation analyses
- Observational versus Experimental data? (Confounding)
- Sampling Schemes

- Goals of Analysis?
 - Predictive models
 - Causal interpretation
 - Testing of hypotheses
 - confirmatory or validation analyses
- Observational versus Experimental data? (Confounding)
- Sampling Schemes Generalizibility

- Goals of Analysis?
 - Predictive models
 - Causal interpretation
 - Testing of hypotheses
 - confirmatory or validation analyses
- ► Observational versus Experimental data? (Confounding)
- Sampling Schemes Generalizibility
- Statistical Theory

- Goals of Analysis?
 - Predictive models
 - Causal interpretation
 - Testing of hypotheses
 - confirmatory or validation analyses
- ► Observational versus Experimental data? (Confounding)
- Sampling Schemes Generalizibility
- Statistical Theory

Prostate Example



Simple Linear Regression:

$$y_i = \beta_0 + \beta_1 x_i + \epsilon_i$$
 for $i = 1, \dots, n$

Simple Linear Regression:

$$y_i = \beta_0 + \beta_1 x_i + \epsilon_i$$
 for $i = 1, \dots, n$

$$\begin{bmatrix} y_1 \\ \vdots \\ y_n \end{bmatrix} = \begin{bmatrix} 1 \\ \vdots \\ 1 \end{bmatrix} \beta_0 + \begin{bmatrix} x_1 \\ \vdots \\ x_n \end{bmatrix} \beta_1 + \begin{bmatrix} \epsilon_1 \\ \vdots \\ \epsilon_n \end{bmatrix}$$

Simple Linear Regression:

$$y_i = \beta_0 + \beta_1 x_i + \epsilon_i$$
 for $i = 1, \dots, n$

$$\begin{bmatrix} y_1 \\ \vdots \\ y_n \end{bmatrix} = \begin{bmatrix} 1 \\ \vdots \\ 1 \end{bmatrix} \beta_0 + \begin{bmatrix} x_1 \\ \vdots \\ x_n \end{bmatrix} \beta_1 + \begin{bmatrix} \epsilon_1 \\ \vdots \\ \epsilon_n \end{bmatrix}$$

$$\begin{bmatrix} y_1 \\ \vdots \\ y_n \end{bmatrix} = \begin{bmatrix} 1 & x_1 \\ \vdots & \vdots \\ 1 & x_n \end{bmatrix} \begin{bmatrix} \beta_0 \\ \beta_1 \end{bmatrix} + \begin{bmatrix} \epsilon_1 \\ \vdots \\ \epsilon_n \end{bmatrix}$$

Simple Linear Regression:

$$y_i = \beta_0 + \beta_1 x_i + \epsilon_i$$
 for $i = 1, \dots, n$

$$\begin{bmatrix} y_1 \\ \vdots \\ y_n \end{bmatrix} = \begin{bmatrix} 1 \\ \vdots \\ 1 \end{bmatrix} \beta_0 + \begin{bmatrix} x_1 \\ \vdots \\ x_n \end{bmatrix} \beta_1 + \begin{bmatrix} \epsilon_1 \\ \vdots \\ \epsilon_n \end{bmatrix}$$

$$\begin{bmatrix} y_1 \\ \vdots \\ y_n \end{bmatrix} = \begin{bmatrix} 1 & x_1 \\ \vdots & \vdots \\ 1 & x_n \end{bmatrix} \begin{bmatrix} \beta_0 \\ \beta_1 \end{bmatrix} + \begin{bmatrix} \epsilon_1 \\ \vdots \\ \epsilon_n \end{bmatrix}$$

$$\mathbf{Y} = \mathbf{X}\boldsymbol{\beta} + \boldsymbol{\epsilon}$$

$$y_i = \beta_0 + \beta_1 x_{1i} + \beta_2 x_{2i} + \dots \beta_p x_{pi} + \epsilon_i$$

$$y_i = \beta_0 + \beta_1 x_{1i} + \beta_2 x_{2i} + \dots \beta_p x_{pi} + \epsilon_i$$

Design matrix

$$\mathbf{X} = \begin{array}{ccccc} 1 & x_{11} & \dots & x_{p1} \\ 1 & x_{12} & \dots & x_{p2} \\ \vdots & \vdots & \vdots & \vdots \\ 1 & x_{1n} & \dots & x_{pn} \end{array}$$

$$y_i = \beta_0 + \beta_1 x_{1i} + \beta_2 x_{2i} + \dots \beta_p x_{pi} + \epsilon_i$$

Design matrix

$$\mathbf{X} = \begin{array}{cccc} 1 & x_{11} & \dots & x_{p1} \\ 1 & x_{12} & \dots & x_{p2} \\ \vdots & \vdots & \vdots & \vdots \\ 1 & x_{1n} & \dots & x_{pn} \end{array}$$
$$\mathbf{Y} = \mathbf{X}\boldsymbol{\beta} + \epsilon$$

$$y_i = \beta_0 + \beta_1 x_{1i} + \beta_2 x_{2i} + \dots \beta_p x_{pi} + \epsilon_i$$

Design matrix

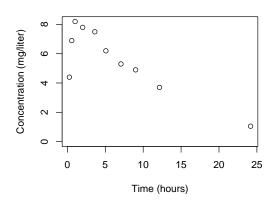
$$\mathbf{X} = \begin{array}{cccc} 1 & x_{11} & \dots & x_{p1} \\ 1 & x_{12} & \dots & x_{p2} \\ \vdots & \vdots & \vdots & \vdots \\ 1 & x_{1n} & \dots & x_{pn} \end{array}$$
$$\mathbf{Y} = \mathbf{X}\boldsymbol{\beta} + \epsilon$$

what should go into X and do we need all columns of X for inference about Y?

Nonlinear Models

Regression function may be an intrinsically nonlinear function of t

$$E[Y_i] = f(t_i, \boldsymbol{\theta})$$



Taylor's Theorem:

$$f(t_i, \theta) = f(t_0, \theta) + (t_i - t_0)f'(t_0, \theta) + (t_i - t_0)^2 \frac{f'(t_0, \theta)}{2} + R(t_i, \theta)$$

Taylor's Theorem:

$$f(t_i, \theta) = f(t_0, \theta) + (t_i - t_0)f'(t_0, \theta) + (t_i - t_0)^2 \frac{f'(t_0, \theta)}{2} + R(t_i, \theta)$$

$$y_i = \beta_0 + \beta_1 x_i + \beta_2 x_i^2 + \epsilon_i \text{ for } i = 1, ..., n$$

Taylor's Theorem:

$$f(t_i, \theta) = f(t_0, \theta) + (t_i - t_0)f'(t_0, \theta) + (t_i - t_0)^2 \frac{f'(t_0, \theta)}{2} + R(t_i, \theta)$$

$$y_i = \beta_0 + \beta_1 x_i + \beta_2 x_i^2 + \epsilon_i \text{ for } i = 1, ..., n$$

$$\begin{bmatrix} y_1 \\ \vdots \\ y_n \end{bmatrix} = \begin{bmatrix} 1 & x_1 & x_1^2 \\ \vdots & \vdots \\ 1 & x_n & x_n^2 \end{bmatrix} \begin{bmatrix} \beta_0 \\ \beta_1 \\ \beta_2 \end{bmatrix} + \begin{bmatrix} \epsilon_1 \\ \vdots \\ \epsilon_n \end{bmatrix}$$

Taylor's Theorem:

$$f(t_i, \theta) = f(t_0, \theta) + (t_i - t_0)f'(t_0, \theta) + (t_i - t_0)^2 \frac{f'(t_0, \theta)}{2} + R(t_i, \theta)$$

$$y_i = \beta_0 + \beta_1 x_i + \beta_2 x_i^2 + \epsilon_i \text{ for } i = 1, ..., n$$

$$\begin{bmatrix} y_1 \\ \vdots \\ y_n \end{bmatrix} = \begin{bmatrix} 1 & x_1 & x_1^2 \\ \vdots & \vdots \\ 1 & x_n & x_n^2 \end{bmatrix} \begin{bmatrix} \beta_0 \\ \beta_1 \\ \beta_2 \end{bmatrix} + \begin{bmatrix} \epsilon_1 \\ \vdots \\ \epsilon_n \end{bmatrix}$$

$$\mathbf{Y} = \mathbf{X}\boldsymbol{\beta} + \boldsymbol{\epsilon}$$

Taylor's Theorem:

$$f(t_i, \theta) = f(t_0, \theta) + (t_i - t_0)f'(t_0, \theta) + (t_i - t_0)^2 \frac{f'(t_0, \theta)}{2} + R(t_i, \theta)$$

$$y_i = \beta_0 + \beta_1 x_i + \beta_2 x_i^2 + \epsilon_i \text{ for } i = 1, ..., n$$

Rewrite in vectors:

$$\begin{bmatrix} y_1 \\ \vdots \\ y_n \end{bmatrix} = \begin{bmatrix} 1 & x_1 & x_1^2 \\ \vdots & \vdots \\ 1 & x_n & x_n^2 \end{bmatrix} \begin{bmatrix} \beta_0 \\ \beta_1 \\ \beta_2 \end{bmatrix} + \begin{bmatrix} \epsilon_1 \\ \vdots \\ \epsilon_n \end{bmatrix}$$

$$\mathbf{Y} = \mathbf{X}\boldsymbol{\beta} + \boldsymbol{\epsilon}$$

Quadratic in x, but linear in β 's, but remainder term is in errors ϵ

Polynomial Regression:

$$y_i = \sum_{j=0}^{q} \beta_j x_i^j + \epsilon_i \text{ for } i = 1, \dots, n$$

Polynomial Regression:

$$y_i = \sum_{j=0}^q \beta_j x_i^j + \epsilon_i \text{ for } i = 1, \dots, n$$

Rewrite in vector notation:

$$\begin{bmatrix} y_1 \\ \vdots \\ y_n \end{bmatrix} = \begin{bmatrix} 1 & x_1 & x_1^2 & \dots & x_1^q \\ \vdots & \vdots & & & \\ 1 & x_n & x_n^2 & \dots & x_n^q \end{bmatrix} \begin{bmatrix} \beta_0 \\ \beta_1 \\ \beta_2 \\ \vdots \\ \beta_n \end{bmatrix} + \begin{bmatrix} \epsilon_1 \\ \vdots \\ \epsilon_n \end{bmatrix}$$

Polynomial Regression:

$$y_i = \sum_{j=0}^q \beta_j x_i^j + \epsilon_i \text{ for } i = 1, \dots, n$$

Rewrite in vector notation:

$$\begin{bmatrix} y_1 \\ \vdots \\ y_n \end{bmatrix} = \begin{bmatrix} 1 & x_1 & x_1^2 & \dots & x_1^q \\ \vdots & \vdots & & & \\ 1 & x_n & x_n^2 & \dots & x_n^q \end{bmatrix} \begin{bmatrix} \beta_0 \\ \beta_1 \\ \beta_2 \\ \vdots \\ \beta_q \end{bmatrix} + \begin{bmatrix} \epsilon_1 \\ \vdots \\ \epsilon_n \end{bmatrix}$$

$$\mathbf{Y} = \mathbf{X} oldsymbol{eta} + oldsymbol{\epsilon}$$

Polynomial Regression:

$$y_i = \sum_{j=0}^q \beta_j x_i^j + \epsilon_i \text{ for } i = 1, \dots, n$$

Rewrite in vector notation:

$$\begin{bmatrix} y_1 \\ \vdots \\ y_n \end{bmatrix} = \begin{bmatrix} 1 & x_1 & x_1^2 & \dots & x_1^q \\ \vdots & \vdots & & & \\ 1 & x_n & x_n^2 & \dots & x_n^q \end{bmatrix} \begin{bmatrix} \beta_0 \\ \beta_1 \\ \beta_2 \\ \vdots \\ \beta_q \end{bmatrix} + \begin{bmatrix} \epsilon_1 \\ \vdots \\ \epsilon_n \end{bmatrix}$$

$$\mathbf{Y} = \mathbf{X}\boldsymbol{\beta} + \boldsymbol{\epsilon}$$

How large should q be?

Polynomial Regression:

$$y_i = \sum_{j=0}^q \beta_j x_i^j + \epsilon_i \text{ for } i = 1, \dots, n$$

Rewrite in vector notation:

$$\begin{bmatrix} y_1 \\ \vdots \\ y_n \end{bmatrix} = \begin{bmatrix} 1 & x_1 & x_1^2 & \dots & x_1^q \\ \vdots & \vdots & & & \\ 1 & x_n & x_n^2 & \dots & x_n^q \end{bmatrix} \begin{bmatrix} \beta_0 \\ \beta_1 \\ \beta_2 \\ \vdots \\ \beta_q \end{bmatrix} + \begin{bmatrix} \epsilon_1 \\ \vdots \\ \epsilon_n \end{bmatrix}$$

$$\mathbf{Y} = \mathbf{X}\boldsymbol{\beta} + \boldsymbol{\epsilon}$$

How large should q be?

Use Nonlinear Regression or other Nonparametric models



Kernel Regression:

$$y_i = \beta_0 + \sum_{i=1}^J \beta_j e^{-\lambda(x_i - k_j)^d} + \epsilon_i$$
 for $i = 1, \dots, n$

where k_j are kernel locations and λ is a smoothing parameter

Kernel Regression:

$$y_i = \beta_0 + \sum_{j=1}^J \beta_j e^{-\lambda(x_i - k_j)^d} + \epsilon_i$$
 for $i = 1, \dots, n$

where k_j are kernel locations and λ is a smoothing parameter

$$\begin{bmatrix} y_1 \\ \vdots \\ y_n \end{bmatrix} = \begin{bmatrix} 1 & e^{-\lambda(x_1 - k_1)^d} & \dots & e^{-\lambda(x_1 - k_J)^d} \\ \vdots & \vdots & & & \vdots \\ 1 & e^{-\lambda(x_n - k_1)^d} & \dots & e^{-\lambda(x_n - k_J)^d} \end{bmatrix} \begin{bmatrix} \beta_0 \\ \beta_1 \\ \vdots \\ \beta_J \end{bmatrix} + \begin{bmatrix} \epsilon_1 \\ \vdots \\ \epsilon_n \end{bmatrix}$$

$${f Y}={f X}{m eta}+{m \epsilon}$$

Kernel Regression:

$$y_i = \beta_0 + \sum_{j=1}^J \beta_j e^{-\lambda(x_i - k_j)^d} + \epsilon_i$$
 for $i = 1, \dots, n$

where k_j are kernel locations and λ is a smoothing parameter

$$\begin{bmatrix} y_1 \\ \vdots \\ y_n \end{bmatrix} = \begin{bmatrix} 1 & e^{-\lambda(x_1 - k_1)^d} & \dots & e^{-\lambda(x_1 - k_J)^d} \\ \vdots & \vdots & & \vdots \\ 1 & e^{-\lambda(x_n - k_1)^d} & \dots & e^{-\lambda(x_n - k_J)^d} \end{bmatrix} \begin{bmatrix} \beta_0 \\ \beta_1 \\ \vdots \\ \beta_J \end{bmatrix} + \begin{bmatrix} \epsilon_1 \\ \vdots \\ \epsilon_n \end{bmatrix}$$

$$\mathbf{Y} = \mathbf{X}\boldsymbol{\beta} + \boldsymbol{\epsilon}$$

Linear in β given λ

Kernel Regression:

$$y_i = \beta_0 + \sum_{j=1}^J \beta_j e^{-\lambda(x_i - k_j)^d} + \epsilon_i$$
 for $i = 1, \dots, n$

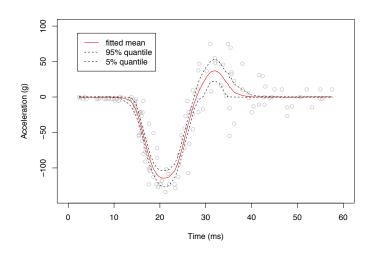
where k_j are kernel locations and λ is a smoothing parameter

$$\begin{bmatrix} y_1 \\ \vdots \\ y_n \end{bmatrix} = \begin{bmatrix} 1 & e^{-\lambda(x_1 - k_1)^d} & \dots & e^{-\lambda(x_1 - k_J)^d} \\ \vdots & \vdots & & & \vdots \\ 1 & e^{-\lambda(x_n - k_1)^d} & \dots & e^{-\lambda(x_n - k_J)^d} \end{bmatrix} \begin{bmatrix} \beta_0 \\ \beta_1 \\ \vdots \\ \beta_J \end{bmatrix} + \begin{bmatrix} \epsilon_1 \\ \vdots \\ \epsilon_n \end{bmatrix}$$

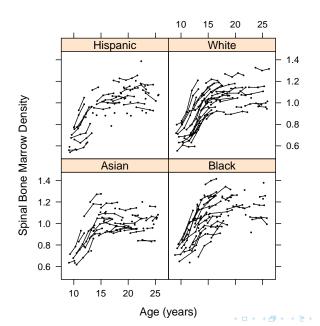
$$\mathbf{Y}=$$
 $\mathbf{X}oldsymbol{eta}+oldsymbol{\epsilon}$

Linear in β given λ Learn λ and J

Kernel Regression Example



Hierarchical Models - Spinal Bone Density



Generic Model in Matrix Notation is

$$\mathbf{Y} = \mathbf{X} \, \boldsymbol{eta} + \boldsymbol{\epsilon}$$

Generic Model in Matrix Notation is

$$\mathbf{Y} = \mathbf{X} \boldsymbol{\beta} + \boldsymbol{\epsilon}$$

- **Y** $(n \times 1)$ vector of response (observe)
- $ightharpoonup X(n \times p)$ design matrix (observe)
- $ightharpoonup eta (p \times 1)$ vector of coefficients (unknown)
- $lackbox{\epsilon} (n imes 1)$ vector of "errors" (unobservable)

Generic Model in Matrix Notation is

$$\mathbf{Y} = \mathbf{X} \boldsymbol{\beta} + \boldsymbol{\epsilon}$$

- **Y** $(n \times 1)$ vector of response (observe)
- $ightharpoonup X(n \times p)$ design matrix (observe)
- $ightharpoonup eta (p \times 1)$ vector of coefficients (unknown)
- $lackbox{\epsilon} (n imes 1)$ vector of "errors" (unobservable)

Generic Model in Matrix Notation is

$$\mathbf{Y} = \mathbf{X} \boldsymbol{\beta} + \boldsymbol{\epsilon}$$

- **Y** $(n \times 1)$ vector of response (observe)
- $ightharpoonup X(n \times p)$ design matrix (observe)
- $\triangleright \beta (p \times 1)$ vector of coefficients (unknown)
- $lackbox{ }\epsilon\ (extit{n} imes 1) ext{ vector of "errors" (unobservable)}$

Goals:

▶ What goes into X? (model building and model selection)

Generic Model in Matrix Notation is

$$\mathbf{Y} = \mathbf{X} \boldsymbol{\beta} + \boldsymbol{\epsilon}$$

- **Y** $(n \times 1)$ vector of response (observe)
- $ightharpoonup X(n \times p)$ design matrix (observe)
- $\triangleright \beta (p \times 1)$ vector of coefficients (unknown)
- $lackbox{ }\epsilon\ (extit{n} imes 1) ext{ vector of "errors" (unobservable)}$

- ▶ What goes into X? (model building and model selection)
- What if several models are equally good? (model averaging or ensembles)

Generic Model in Matrix Notation is

$$\mathbf{Y} = \mathbf{X} \boldsymbol{\beta} + \boldsymbol{\epsilon}$$

- **Y** $(n \times 1)$ vector of response (observe)
- $ightharpoonup X(n \times p)$ design matrix (observe)
- $\triangleright \beta (p \times 1)$ vector of coefficients (unknown)
- $lackbox{\epsilon} (n imes 1)$ vector of "errors" (unobservable)

- ▶ What goes into X? (model building and model selection)
- What if several models are equally good? (model averaging or ensembles)
- ▶ What about the future? (Prediction)

Generic Model in Matrix Notation is

$$\mathbf{Y} = \mathbf{X} \boldsymbol{\beta} + \boldsymbol{\epsilon}$$

- **Y** $(n \times 1)$ vector of response (observe)
- $ightharpoonup X(n \times p)$ design matrix (observe)
- $ightharpoonup eta (p \times 1)$ vector of coefficients (unknown)
- $lackbox{\epsilon} (n imes 1)$ vector of "errors" (unobservable)

- ► What goes into X? (model building and model selection)
- What if several models are equally good? (model averaging or ensembles)
- ▶ What about the future? (Prediction)
- lacktriangle uncertainty quantification assumptions about ϵ

Generic Model in Matrix Notation is

$$\mathbf{Y} = \mathbf{X} \boldsymbol{\beta} + \boldsymbol{\epsilon}$$

- **Y** $(n \times 1)$ vector of response (observe)
- $ightharpoonup X(n \times p)$ design matrix (observe)
- $\triangleright \beta (p \times 1)$ vector of coefficients (unknown)
- $ightharpoonup \epsilon \ (n imes 1)$ vector of "errors" (unobservable)

Goals:

- ► What goes into X? (model building and model selection)
- What if several models are equally good? (model averaging or ensembles)
- ▶ What about the future? (Prediction)
- ightharpoonup uncertainty quantification assumptions about ϵ

All models are wrong, but some may be useful (George Box)



$$\sum_{i} (Y_i - \mathbf{x}_i^T \boldsymbol{\beta})^2 = (\mathbf{Y} - \mathbf{X}\boldsymbol{\beta})^T (\mathbf{Y} - \mathbf{X}\boldsymbol{\beta}) = \|\mathbf{Y} - \mathbf{X}\boldsymbol{\beta}\|^2$$

Goal: Find the best fitting "line" or "hyper-plane" that minimizes

$$\sum_{i} (Y_i - \mathbf{x}_i^T \boldsymbol{\beta})^2 = (\mathbf{Y} - \mathbf{X} \boldsymbol{\beta})^T (\mathbf{Y} - \mathbf{X} \boldsymbol{\beta}) = \|\mathbf{Y} - \mathbf{X} \boldsymbol{\beta}\|^2$$

Optimization problem

$$\sum_{i} (Y_i - \mathbf{x}_i^T \boldsymbol{\beta})^2 = (\mathbf{Y} - \mathbf{X} \boldsymbol{\beta})^T (\mathbf{Y} - \mathbf{X} \boldsymbol{\beta}) = \|\mathbf{Y} - \mathbf{X} \boldsymbol{\beta}\|^2$$

- Optimization problem
- May over-fit ⇒ add other criteria that provide a penalty "Penalized Least Squares"

$$\sum_{i} (Y_i - \mathbf{x}_i^T \boldsymbol{\beta})^2 = (\mathbf{Y} - \mathbf{X} \boldsymbol{\beta})^T (\mathbf{Y} - \mathbf{X} \boldsymbol{\beta}) = \|\mathbf{Y} - \mathbf{X} \boldsymbol{\beta}\|^2$$

- Optimization problem
- May over-fit ⇒ add other criteria that provide a penalty "Penalized Least Squares"
- ▶ Robustness to extreme points ⇒ replace quadratic loss with other functions

$$\sum_{i} (Y_i - \mathbf{x}_i^T \boldsymbol{\beta})^2 = (\mathbf{Y} - \mathbf{X} \boldsymbol{\beta})^T (\mathbf{Y} - \mathbf{X} \boldsymbol{\beta}) = \|\mathbf{Y} - \mathbf{X} \boldsymbol{\beta}\|^2$$

- Optimization problem
- May over-fit ⇒ add other criteria that provide a penalty "Penalized Least Squares"
- ▶ Robustness to extreme points ⇒ replace quadratic loss with other functions
- no notion of uncertainty of estimates

$$\sum_{i} (Y_i - \mathbf{x}_i^T \boldsymbol{\beta})^2 = (\mathbf{Y} - \mathbf{X} \boldsymbol{\beta})^T (\mathbf{Y} - \mathbf{X} \boldsymbol{\beta}) = \|\mathbf{Y} - \mathbf{X} \boldsymbol{\beta}\|^2$$

- Optimization problem
- May over-fit ⇒ add other criteria that provide a penalty "Penalized Least Squares"
- ▶ Robustness to extreme points ⇒ replace quadratic loss with other functions
- no notion of uncertainty of estimates
- no structure of problem (repeated measures on individual, randomization restrictions, etc)

Goal: Find the best fitting "line" or "hyper-plane" that minimizes

$$\sum_{i} (Y_i - \mathbf{x}_i^T \boldsymbol{\beta})^2 = (\mathbf{Y} - \mathbf{X} \boldsymbol{\beta})^T (\mathbf{Y} - \mathbf{X} \boldsymbol{\beta}) = \|\mathbf{Y} - \mathbf{X} \boldsymbol{\beta}\|^2$$

- Optimization problem
- May over-fit ⇒ add other criteria that provide a penalty "Penalized Least Squares"
- ▶ Robustness to extreme points ⇒ replace quadratic loss with other functions
- no notion of uncertainty of estimates
- no structure of problem (repeated measures on individual, randomization restrictions, etc)

Need Distribution Assumptions of Y (or ϵ) for testing and uncertainty measures



Goal: Find the best fitting "line" or "hyper-plane" that minimizes

$$\sum_{i} (Y_i - \mathbf{x}_i^T \boldsymbol{\beta})^2 = (\mathbf{Y} - \mathbf{X} \boldsymbol{\beta})^T (\mathbf{Y} - \mathbf{X} \boldsymbol{\beta}) = \|\mathbf{Y} - \mathbf{X} \boldsymbol{\beta}\|^2$$

- Optimization problem
- May over-fit ⇒ add other criteria that provide a penalty "Penalized Least Squares"
- ▶ Robustness to extreme points ⇒ replace quadratic loss with other functions
- no notion of uncertainty of estimates
- no structure of problem (repeated measures on individual, randomization restrictions, etc)

Need Distribution Assumptions of Y (or ϵ) for testing and uncertainty measures \Rightarrow Likelihood and Bayesian inference



► for many problems frequentist and Bayesian methods will give similar answers (more a matter of taste in interpretation)

- for many problems frequentist and Bayesian methods will give similar answers (more a matter of taste in interpretation)
- ► For small problems, Bayesian methods allow us to incorporate prior information which provides better calibrated answers

- for many problems frequentist and Bayesian methods will give similar answers (more a matter of taste in interpretation)
- ► For small problems, Bayesian methods allow us to incorporate prior information which provides better calibrated answers
- for problems with complex designs and/or missing data Bayesian methods are often easier to implement (do not need to rely on asymptotics)

- for many problems frequentist and Bayesian methods will give similar answers (more a matter of taste in interpretation)
- ► For small problems, Bayesian methods allow us to incorporate prior information which provides better calibrated answers
- for problems with complex designs and/or missing data Bayesian methods are often easier to implement (do not need to rely on asymptotics)
- ► For problems involving hypothesis testing or model selection frequentist and Bayesian methods can be strikingly different.

- for many problems frequentist and Bayesian methods will give similar answers (more a matter of taste in interpretation)
- ► For small problems, Bayesian methods allow us to incorporate prior information which provides better calibrated answers
- for problems with complex designs and/or missing data Bayesian methods are often easier to implement (do not need to rely on asymptotics)
- For problems involving hypothesis testing or model selection frequentist and Bayesian methods can be strikingly different.
- Frequentist methods often faster (particularly with "big data") so great for exploratory analysis and for building a "data-sense"

- for many problems frequentist and Bayesian methods will give similar answers (more a matter of taste in interpretation)
- ► For small problems, Bayesian methods allow us to incorporate prior information which provides better calibrated answers
- for problems with complex designs and/or missing data Bayesian methods are often easier to implement (do not need to rely on asymptotics)
- For problems involving hypothesis testing or model selection frequentist and Bayesian methods can be strikingly different.
- Frequentist methods often faster (particularly with "big data") so great for exploratory analysis and for building a "data-sense"
- ▶ Bayesian methods sit on top of Frequentist Likelihood

- for many problems frequentist and Bayesian methods will give similar answers (more a matter of taste in interpretation)
- ► For small problems, Bayesian methods allow us to incorporate prior information which provides better calibrated answers
- for problems with complex designs and/or missing data Bayesian methods are often easier to implement (do not need to rely on asymptotics)
- For problems involving hypothesis testing or model selection frequentist and Bayesian methods can be strikingly different.
- Frequentist methods often faster (particularly with "big data") so great for exploratory analysis and for building a "data-sense"
- ▶ Bayesian methods sit on top of Frequentist Likelihood Important to understand advantages and problems of each perspective!

