Cauchy Priors: Mixtures of Normals & MCMC

STA721 Linear Models Duke University

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Bayesian Estimation with 2 Block g-prior (Normal-Jeffreys)

Model in centered parameterization

$$\begin{aligned} \mathbf{Y} &= \mathbf{1}\beta_0 + (\mathbf{I}_n - \mathbf{P}_1)\mathbf{X}_1\boldsymbol{\beta} + \epsilon \\ p(\beta_0, \phi) &\propto 1/\phi \\ \boldsymbol{\beta} \mid \beta_0, \phi &\sim \mathsf{N}(\mathbf{0}, \frac{\mathbf{g}}{\phi}(\mathbf{X}^T(\mathbf{I}_n - \mathbf{P}_1)\mathbf{X})^{-1}) \end{aligned}$$

Log Likelihood

$$\mathcal{L}(\beta_0, \beta_1, \phi) \propto \frac{n}{2} \log(\phi) - \frac{\phi}{2} \left(n(\beta_0 - \bar{y})^2 + (\mathbf{Y}_c - \mathbf{X}_c \boldsymbol{\beta})^T (\mathbf{Y}_c - \mathbf{X}_c) \right)$$

Since

$$Y = (I - P_1)Y + P_1Y$$

Integrated Liklihood after integrating β_0

$$\mathcal{L}(eta_1,\phi) \propto rac{n-1}{2}\log(\phi) - rac{\phi}{2}(\mathbf{Y}_c - \mathbf{X}_coldsymbol{eta})^{\mathcal{T}}(\mathbf{Y}_c - \mathbf{X}_c)$$

Prior Data

Note

$$(\mathbf{X}^{\mathsf{T}}(\mathbf{I}_{n}-\mathbf{P}_{1})\mathbf{X}) = (\mathbf{X}^{\mathsf{T}}(\mathbf{I}_{n}-\mathbf{P}_{1})^{\mathsf{T}}(\mathbf{I}_{n}-\mathbf{P}_{1})\mathbf{X}) = (\mathbf{X}-\mathbf{1}_{n}\bar{\mathbf{X}}^{\mathsf{T}})^{\mathsf{T}}(\mathbf{X}-\mathbf{1}_{n}\bar{\mathbf{X}})$$

Let $(\mathbf{X} - \mathbf{1}_n \bar{\mathbf{X}}^T)^T (\mathbf{X} - \mathbf{1}\bar{\mathbf{X}}) = \mathsf{SS}_{\mathbf{X}} = \mathbf{U}^T \mathbf{U}$ Quadratic contribution to the log likelihood from prior after integrating out β_0

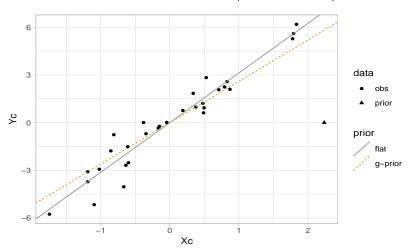
$$(\mathbf{Y}_c - \mathbf{X}_c \boldsymbol{\beta})^T (\mathbf{Y}_c - \mathbf{X}_c \boldsymbol{\beta}) + (\boldsymbol{\beta}^T \frac{\mathbf{U}^T \mathbf{U}}{g} \boldsymbol{\beta})$$
$$(\mathbf{Y}_c - \mathbf{X}_c \boldsymbol{\beta})^T (\mathbf{Y}_c - \mathbf{X}_c \boldsymbol{\beta}) + (\mathbf{0}_p - \frac{\mathbf{U}}{\sqrt{g}} \boldsymbol{\beta})^T (\mathbf{0}_p - \frac{\mathbf{U}}{\sqrt{g}} \boldsymbol{\beta})$$

Prior observations with Yc = 0.

Example: g=5, n=30

In SLR it is like an extra $Y_0=0$ at $\mathbf{X}_o=\sqrt{\frac{\mathrm{SS}_x}{g}}$:

$$(\mathbf{Y}_c - \mathbf{X}_c \boldsymbol{\beta})^T (\mathbf{Y}_c - \mathbf{X}_c \boldsymbol{\beta}) + (0 - \sqrt{\frac{SS_x}{g}} \boldsymbol{\beta})^T (0 - \sqrt{\frac{SS_x}{g}} \boldsymbol{\beta})$$



Disadvantages of Conjugate Priors

Disadvantages:

- Results may have be sensitive to prior "outliers" due to linear updating
- Problem potentially with all Normal priors, not just the g-prior.
- Cannot capture all possible prior beliefs
- Mixtures of Conjugate Priors

Mixtures of Conjugate Priors

Theorem (Diaconis & Ylivisaker 1985)

Given a sampling model $p(y \mid \theta)$ from an exponential family, any prior distribution can be expressed as a mixture of conjugate prior distributions

- ▶ Prior $p(\theta) = \int p(\theta \mid \omega)p(\omega) d\omega$
- Posterior

$$p(\boldsymbol{\theta} \mid \mathbf{Y}) \propto \int p(\mathbf{Y} \mid \boldsymbol{\theta}) p(\boldsymbol{\theta} \mid \omega) p(\omega) d\omega$$

$$\propto \int \frac{p(\mathbf{Y} \mid \boldsymbol{\theta}) p(\boldsymbol{\theta} \mid \omega)}{p(\mathbf{Y} \mid \omega)} p(\mathbf{Y} \mid \omega) p(\omega) d\omega$$

$$\propto \int p(\boldsymbol{\theta} \mid \mathbf{Y}, \omega) p(\mathbf{Y} \mid \omega) p(\omega) d\omega$$

$$p(\boldsymbol{\theta} \mid \mathbf{Y}) = \frac{\int p(\boldsymbol{\theta} \mid \mathbf{Y}, \omega) p(\mathbf{Y} \mid \omega) p(\omega) d\omega}{\int p(\mathbf{Y} \mid \omega) p(\omega) d\omega}$$

Zellner-Siow prior (assume **X** is centered)

Zellner's g-prior $\beta \mid \phi \sim \mathsf{N}(\mathbf{0}_p, g(\mathbf{X}_c^T\mathbf{X}_c)^{-1}/\phi)$

- ► Choice of g?
- $ightharpoonup \frac{g}{1+g}$ weight given to the data
- ▶ Let $\tau = 1/g$ assign $\tau \sim G(1/2, n/2)$
- ▶ Marginal prior on $\beta \sim C(0, \phi^{-1}(\mathbf{X}_c^T\mathbf{X}_c/n)^{-1})$
- ► Can express posterior as a mixture of *g*-priors

$$p(\tau \mid \mathbf{Y}) = \frac{p(\mathbf{Y} \mid \tau)p(\tau)}{\int p(\mathbf{Y} \mid \tau)p(\tau) d\tau}$$

- Problem: no analytic expression for integral
- ▶ Need 2 one dimensional integrals to obtain posterior.
- What about credible intervals?

Markov Chain Monte Carlo

- We know that $\beta_0, \boldsymbol{\beta}, \phi \mid \mathbf{Y}, g = 1/\tau$ has a Normal-Gamma distribution
- lacktriangle We can show that $\tau \mid \beta_0, \beta, \phi, \mathbf{Y}$ has a Gamma distribution

$$p(\tau \mid \boldsymbol{\beta}, \boldsymbol{\phi}, \mathbf{Y}) \propto \mathcal{L}(\beta_0, \boldsymbol{\beta}, \boldsymbol{\phi}) \tau^{p/2} e^{(-\tau \frac{\phi}{2} \boldsymbol{\beta}^T (\mathbf{X}^T \mathbf{X}) \boldsymbol{\beta})} \tau^{1/2 - 1} e^{-\tau n/2}$$

- alternate sampling from full conditional distributions given current values of other parameters. (STA 601)
- JAGS or STAN

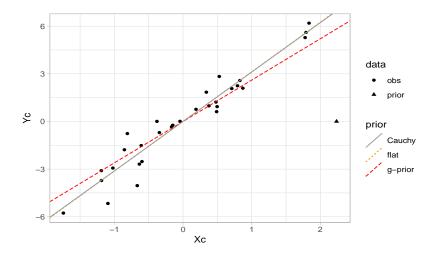
JAGS Code: library(R2jags)

```
model = function(){
 for (i in 1:n) {
      Y[i] ~ dnorm(beta0+ (X[i] -Xbar)*beta, phi)
  }
  beta0 ~ dnorm(0, .000001*phi) #precision is 2nd arg
  beta ~ dnorm(0, phi*tau*SSX) #precision is 2nd arg
  phi ~ dgamma(.001, .001)
  tau ~ dgamma(.5, .5*n)
  g <- 1/tau
  sigma <- pow(phi, -.5)
data = list(Y=Y, X=X, n =length(Y), SSX=sum(Xc^2),
            Xbar=mean(X))
ZSout = jags(data, inits=NULL,
             parameters.to.save=c("beta0", "beta", "g",
                                   "sigma"),
             model=model, n.iter=10000)
```

HPD intervals

```
confint(lm(Y ~ Xc))
                 2.5 % 97.5 %
##
## (Intercept) -0.3985359 0.2048303
## Xc
       2.7945824 3.4555162
HPDinterval(as.mcmc(ZSout$BUGSoutput$sims.matrix))
##
               lower upper
## beta 2.7823047 3.4453690
## beta0 -0.3764027 0.2095465
## deviance 70.2043917 78.4813041
    19.4503373 3782.7134974
## g
## sigma 0.6171029 1.0504892
## attr(,"Probability")
## [1] 0.95
```

Compare



beta0

sigma

g

##

##

1200

3000 ## deviance 1600

pD = 3.3 and DIC = 76.6

3000

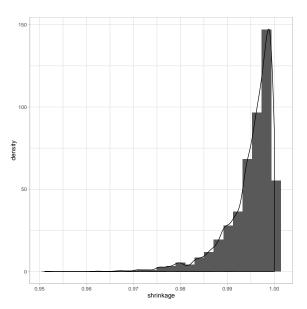
DIC info (using the rule, pD = var(deviance)/2)

```
## Inference for Bugs model at "/var/folders/n4/nj1122xj6bn5_xgbptv7bm140000gp/T//RtmpwzlWaF/model8022471
## 3 chains, each with 10000 iterations (first 5000 discarded), n.thin = 5
## n.sims = 3000 iterations saved
##
           mu.vect sd.vect 2.5% 25%
                                           50% 75% 97.5% Rhat
          3.112 0.170 2.782 2.997 3.115 3.225 3.445 1.001
## beta
## beta0 -0.099 0.152 -0.384 -0.204 -0.099 0.001 0.204 1.002
## g
     2263.147 38967.029 48.273 146.129 282.298 697.063 9018.709 1.001
## sigma
         0.827 0.114 0.636 0.747 0.816 0.896 1.079 1.001
## deviance 73.347
                     2.563 70.390 71.458 72.680 74.500 79.882 1.002
          n.eff
##
## beta
          3000
```

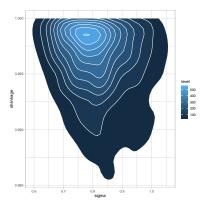
For each parameter, n.eff is a crude measure of effective sample size, ## and Rhat is the potential scale reduction factor (at convergence, Rhat=1).

DIC is an estimate of expected predictive error (lower deviance is better).

Posterior Distribution of shrinkage



Joint Distribution of σ and g/(1+g)



Cauchy Summary

- ► Cauchy rejects prior mean if it is an "outlier"
- robustness related to "bounded" influence (more later)
- requires numerical integration or Monte Carlo sampling (MCMC)

How Good are these Estimators?

Quadratic loss for estimating $oldsymbol{eta}$ using estimator $oldsymbol{a}$

$$L(\beta, \mathbf{a}) = (\beta - \mathbf{a})^T (\beta - \mathbf{a})$$

- Consider our expected loss (before we see the data) of taking an "action" a
- Under OLS or the Reference prior the Expected Mean Square Error

$$\begin{aligned} \mathsf{E}_{\mathbf{Y}}[(\boldsymbol{\beta} - \hat{\boldsymbol{\beta}})^T (\boldsymbol{\beta} - \hat{\boldsymbol{\beta}}) &= \sigma^2 \mathsf{tr}[(\mathbf{X}^T \mathbf{X})^{-1}] \\ &= \sigma^2 \sum_{i=1}^p \lambda_j^{-1} \end{aligned}$$

where λ_i are eigenvalues of $\mathbf{X}^T\mathbf{X}$.

- ▶ If smallest $\lambda_i \rightarrow 0$ then MSE $\rightarrow \infty$
- Note: estimate is unbiased!

Is the *g*-prior better?

Explore Frequentist properties of using a Bayesian estimator

$$\mathsf{E}_{\mathsf{Y}}[(\beta-\hat{\beta}_{\mathsf{g}})^{\mathsf{T}}(\beta-\hat{\beta}_{\mathsf{g}})$$

but now
$$\hat{oldsymbol{eta}}_g = g/(1+g)\hat{oldsymbol{eta}}$$

when is the *g* prior better than the Reference prior or OLS? Is it always better?

Estimator Properties

- Bias
- Variability
- ightharpoonup MSE = Bias² + Variance (multivariate analogs)
- Problems with OLS, g-priors & mixtures of g-priors with collinearity
- ► Solutions:
 - removal of terms
 - other shrinkage estimators