HOMEWORK 1 GENERATIVE MODELS OF TEXT *

10-423/10-623 GENERATIVE AI http://423.mlcourse.org

OUT: Sept. 8, 2025 DUE: Sept. 22, 2025 TAs: Aryaman, Parv, Somil

Instructions

- Collaboration Policy: Please read the collaboration policy in the syllabus.
- Late Submission Policy: See the late submission policy in the syllabus.
- Submitting your work: You will use Gradescope to submit answers to all questions and code.
 - Written: You will submit your completed homework as a PDF to Gradescope. Please use the provided template. Submissions can be handwritten, but must be clearly legible; otherwise, you will not be awarded marks. Alternatively, submissions can be written in LaTeX. Each answer should be within the box provided. If you do not follow the template, your assignment may not be graded correctly by our AI assisted grader and there will be a 2% penalty (e.g., if the homework is out of 100 points, 2 points will be deducted from your final score).
 - **Programming:** You will submit your code for programming questions to Gradescope. We will examine your code by hand and may award marks for its submission.
- **Materials:** The data that you will need in order to complete this assignment is posted along with the writeup and template on the course website.

Question	Points
IATEX Template Alignment	0
Recurrent Neural Network (RNN) Language Models	7
Transformer Language Models	19
Sliding Window Attention	11
Programming: RoPE and GQA	22
Code Upload	0
Collaboration Questions	2
Total:	61

^{*}Compiled on Monday 8th September, 2025 at 21:47

1 IATEX Template Alignment (0 points)

1.1.	(0 points) Select one: Did you use L ^A I _E X for the entire written portion of this homework?
	○ Yes
	○ No
1.2.	(0 points) Select one: I have ensured that my final submission is aligned with the original template given to me in the handout file and that I haven't deleted or resized any items or made any other modifications which will result in a misaligned template. I understand that incorrectly responding yes to this question will result in a penalty equivalent to 2% of the points on this assignment. Note: Failing to answer this question will not exempt you from the 2% misalignment penalty.
	○ Yes

2 Recurrent Neural Network (RNN) Language Models (7 points)

2.1. (3 points) Numerical answer: Consider an RNN (Elman Network) that takes inputs $\mathbf{x}_t \in \{0, 1\}^2$, has hidden vectors $\mathbf{h}_t \in \mathbb{R}^2$, and output units $y_t \in \mathbb{R}$ for all $t \in \{1, \dots, T\}$. Assume the recurrence is given by:

$$h_t = \text{slide}(W_{hh}h_{t-1} + W_{hx}x_t + b_h)$$

$$y_t = \text{slide}(W_{yh}h_t + b_y)$$

where slide(a) = min(1, max(0, a)) is the activation function. Note that when the slide function is applied to a vector, it is applied to each element of the vector individually.

Let $W_{hh} \in \mathbb{R}^{2 \times 2}$ be defined as follows:

$$W_{hh} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

Define parameters $W_{hx} \in \mathbb{R}^{2 \times 2}$, $W_{yh} \in \mathbb{R}^{1 \times 2}$, $b_h \in \mathbb{R}^2$, $b_y \in \mathbb{R}$ to satisfy the following condition: $y_t = 1$ if $\exists r, s \leq t$ such that $x_{r,0} = 1$ and $x_{s,1} = 1$ and $y_t = 0$ otherwise. Assume $h_0 = [0,0]^T$.

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- 2.2. An autoregressive language model defines a probability distribution over sequences $\mathbf{x}_{1:T}$ of the form: $p(\mathbf{x}_{1:T}) = \prod_{t=1}^{T} p(x_t \mid x_1, \dots, x_{t-1})$.
 - 2.2.a. (2 points) **Short answer:** Suppose we are given an input $\mathbf{x}_{1:T}$ and we define a bidirectional RNN of the following form:

$$f_{t} = \sigma(W_{ff}f_{t-1} + W_{fx}x_{t} + b_{f}), \quad \forall t \in \{1, \dots, T\}$$

$$g_{t} = \sigma(W_{gg}g_{t+1} + W_{gx}x_{t} + b_{g}), \quad \forall t \in \{1, \dots, T-1\}$$

$$h_{t} = \sigma(W_{hf}f_{t} + W_{hg}g_{t} + b_{h}), \quad \forall t \in \{1, \dots, T\}$$

(Notice that f_t builds up context from the left, g_t builds up context from the right, and h_t combines the two.) Can we define an autoregressive language model of the form $p(\mathbf{x}_{1:T}) = \prod_{t=1}^{T} p(x_t \mid h_{t-1})$?

If so, how can we compute $p(x_t \mid BiRNN(\mathbf{x}_{1:t-1}))$ using this RNN? If we can't define an autoregressive LM, why not? Assume that **no** weight matrix can be set to all zeros.

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2.2.b. (2 points) **Short answer:** Suppose BiRNN($\mathbf{x}_{1:t-1}$) computes a bidirectional RNN on the subsequence $\mathbf{x}_{1:t-1}$ and then returns h_{t-1} . Can we define an autoregressive language model of the form $p(\mathbf{x}_{1:T}) = \prod_{t=1}^{T} p(x_t \mid \text{BiRNN}(\mathbf{x}_{1:t-1}))$?

If so, how can we compute $p(x_t \mid \text{BiRNN}(\mathbf{x}_{1:t-1}))$ using this RNN? If we can't define an auroregessive LM, why not?

(Notice that here we are only looking at the part of the bidirectional RNN which goes from left to right and looks at all the words before t.)



3 Transformer Language Models (19 points)

3.1. Transformers use scaled-dot-product attention:

$$s_{t,j} = \mathbf{k}_j^T \mathbf{q}_t / \sqrt{|\mathbf{k}|}, \forall j, t$$
$$\mathbf{a}_t = \operatorname{softmax}(\mathbf{s}_t), \forall t$$

where the values, queries, and keys are respectively given by: $\mathbf{v}_j = \mathbf{W}_v^T \mathbf{x}_j$, $\mathbf{q}_j = \mathbf{W}_q^T \mathbf{x}_j$, and $\mathbf{k}_j = \mathbf{W}_k^T \mathbf{x}_j$ for all j and \mathbf{v}_j , \mathbf{q}_j , $\mathbf{k}_j \in \mathbb{R}^{d_k}$.

3.1.a. (2 points) **Short answer:** In the attention mechanism, queries, keys, and values are all derived from the same input representations. Conceptually, why do we need all three, and how does the dot product of queries and keys determine what information from the values gets passed forward?

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3.1.b. (4 points) **Numerical answer:** Consider the 3-token sentence "the dog ran". Let each token have a one-hot input embedding in \mathbb{R}^3 :

$$X = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$
 (rows correspond to "the", "dog", "ran").

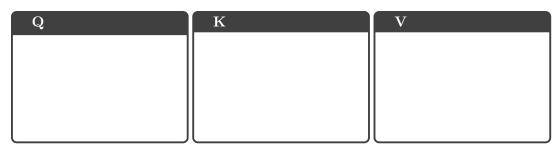
We use the following projection matrices (single head with $d_k=d_v=2$, sequence length T=3):

$$\mathbf{W}_q = \begin{bmatrix} 1 & 0 \\ 0 & 1 \\ 1 & 1 \end{bmatrix}, \qquad \mathbf{W}_k = \begin{bmatrix} 1 & 0 \\ 1 & 1 \\ 0 & 1 \end{bmatrix}, \qquad \mathbf{W}_v = \begin{bmatrix} 2 & 0 \\ 0 & 3 \\ 1 & 1 \end{bmatrix}.$$

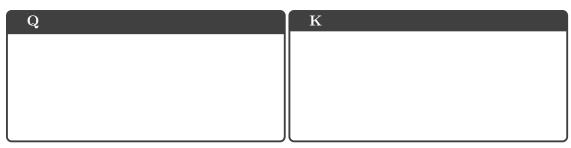
Compute one attention pass (single head), following the steps on the next page.

(i) Compute the values of the projections:

$$\mathbf{Q} = \mathbf{X}\mathbf{W}_q, \qquad \mathbf{K} = \mathbf{X}\mathbf{W}_k, \qquad \mathbf{V} = \mathbf{X}\mathbf{W}_v.$$



(ii) Compute the score matrix $\mathbf{S} = \frac{\mathbf{Q}\mathbf{K}^{\top}}{\sqrt{d_k}}$ and the attention matrix $\mathbf{A} = \operatorname{softmax}(\mathbf{S})$ computed *row-wise*. (Report your answer rounded to 3 decimal places.)



(iii) Compute the output X' = AV. (Report your answer rounded to 3 decimal places.)



(iv) In 1–2 sentences, state what each row of X' represents. (Hint: With these numbers, token "ran" should assign its highest attention to token "dog".)



- 3.2. As mentioned in 3.1., Transformers use scaled-dot product attention.
 - 3.2.a. (2 points) Short answer: Multiplicative attention instead defines the attention weights as:

$$\tilde{s}_{t,j} = \mathbf{k}_j^T \mathbf{W}_s \mathbf{q}_t / \sqrt{|\mathbf{k}|}, \forall j, t$$
$$\tilde{\mathbf{a}}_t = \operatorname{softmax}(\tilde{\mathbf{s}}_t), \forall t$$

where $\mathbf{W}_s \in \mathbb{R}^{d_k \times d_k}$ is a learned parameter matrix. Could a Transformer with multiplicative attention learn a function that a Transformer with scaled dot product attention cannot?

Note: Two functions are equivalent if they produce the same output for every input in the domain.

3.2.b. (2 points) Short answer: Concatenated attention defines the attention weights as:

$$\hat{s}_{t,j} = \mathbf{w}_s^T[\mathbf{k}_j; \mathbf{q}_t], \forall j, t$$
$$\hat{\mathbf{a}}_t = \text{softmax}(\hat{\mathbf{s}}_t), \forall t$$

where $\mathbf{w}_s \in \mathbb{R}^{2d_k}$ is a parameter vector, and $[\mathbf{a}; \mathbf{b}]$ is the concatenation of vectors \mathbf{a} and \mathbf{b} . Do there exist parameters, that can be learned, \mathbf{w}_s such that $\hat{s}_{t,j}$ will approximately equal the angle θ between the two vectors \mathbf{k}_j , \mathbf{q}_t , or to $\cos(\theta)$? (Briefly justify your answer—a formal proof is not required.)

3.2.c. (2 points) **Short answer:** Additive attention defines the attention weights as:

$$\hat{s}_{t,j} = \mathbf{w}_s^T \tanh(\mathbf{W}_s[\mathbf{k}_j; \mathbf{q}_t]), \forall j, t$$
$$\hat{\mathbf{a}}_t = \operatorname{softmax}(\hat{\mathbf{s}}_t), \forall t$$

where the parameters are $\mathbf{w}_s \in \mathbb{R}^{d_k}$ and $\mathbf{W}_s \in \mathbb{R}^{d_k \times 2d_k}$, dimensionality d_k is a hyperparameter, and $[\mathbf{a}; \mathbf{b}]$ is the concatenation of vectors \mathbf{a} and \mathbf{b} . Do there exist learnable parameters \mathbf{w}_s , \mathbf{W}_s , that can be learned, such that $\hat{s}_{t,j}$ will approximately equal the angle θ between the two vectors \mathbf{k}_j , \mathbf{q}_t , or to $\cos(\theta)$? (Briefly justify your answer—a formal proof is not required.)

3.3. Self-attention is typically computed via matrix multiplication. Here we consider multi-headed attention without a causal attention mask.

$$\mathbf{X} = [\mathbf{x}_1, \dots, \mathbf{x}_N]^T$$

$$\mathbf{V}^{(i)} = \mathbf{X} \mathbf{W}_v^{(i)}$$

$$\mathbf{K}^{(i)} = \mathbf{X} \mathbf{W}_k^{(i)}$$

$$\mathbf{Q}^{(i)} = \mathbf{X} \mathbf{W}_q^{(i)}$$

$$\mathbf{S}^{(i)} = \mathbf{Q}^{(i)} (\mathbf{K}^{(i)})^T / \sqrt{d_k}$$

$$\mathbf{A}^{(i)} = \operatorname{softmax}(\mathbf{S}^{(i)})$$

$$\mathbf{X}'^{(i)} = \mathbf{A}^{(i)} \mathbf{V}^{(i)}$$

$$\mathbf{X}' = \operatorname{concat}(\mathbf{X}'^{(1)}, \dots, \mathbf{X}'^{(h)})$$

where N is the sequence length, h is the number of attention heads, and each row involving i is defined $\forall i \in \{1, ..., h\}$.

3.3.a. (3 points) **Short answer:** Is the score matrix $S^{(i)}$ always symmetric? If yes, show that it is. If not, describe a condition that would ensure it is symmetric.

3.3.b. (4 points) **Short answer:** Suppose we have two attention heads, h=2, we let $d_k=d_m/h$, and we have a single input \mathbf{X} . Let \mathbf{X}' be the output of multi-headed attention on \mathbf{X} with the parameters:

$$\mathbf{W}_{v}^{(1)}, \mathbf{W}_{k}^{(1)}, \mathbf{W}_{q}^{(1)}, \mathbf{W}_{v}^{(2)}, \mathbf{W}_{k}^{(2)}, \mathbf{W}_{q}^{(2)} \in \mathbb{R}^{d_{m} \times d_{k}}$$

Now suppose we take those same parameters and concatenate along the rows to yield new parameters:

$$\mathbf{W}_v' = \text{concat}(\mathbf{W}_v^{(1)}, \mathbf{W}_v^{(2)}), \ \mathbf{W}_k' = \text{concat}(\mathbf{W}_k^{(1)}, \mathbf{W}_k^{(2)}), \ \mathbf{W}_q' = \text{concat}(\mathbf{W}_q^{(1)}, \mathbf{W}_q^{(2)}) \in \mathbb{R}^{d_m \times d_m}$$

And let \mathbf{X}'' be the output of single-headed attention on \mathbf{X} with the parameters $\mathbf{W}'_v, \mathbf{W}'_k, \mathbf{W}'_q$. In this case, does $\mathbf{X}'' = \mathbf{X}'$? Justify your answer.

4 Sliding Window Attention (11 points)

4.1. The simplest way to define sliding window attention is by setting the causal mask M to only include a window of $\frac{1}{2}w + 1$ tokens, where w determines the window size, with the rightmost window element being the current token (i.e. on the diagonal). Then our attention computation is:

$$\mathbf{X}' = \operatorname{softmax}((\mathbf{Q}\mathbf{K}^T / \sqrt{d_k}) + \mathbf{M})\mathbf{V}$$
 (1)

For example, if we have a sequence of length N=6, and size w=4, then our mask matrix is:

$$\mathbf{M} = \begin{bmatrix} 0 & -\infty & -\infty & -\infty & -\infty & -\infty \\ 0 & 0 & -\infty & -\infty & -\infty & -\infty \\ 0 & 0 & 0 & -\infty & -\infty & -\infty \\ -\infty & 0 & 0 & 0 & -\infty & -\infty \\ -\infty & -\infty & 0 & 0 & 0 & -\infty \\ -\infty & -\infty & -\infty & 0 & 0 & 0 \end{bmatrix}$$

4.1.a. (1 point) **Short answer:** If we implement sliding window using the matrix multiplications described in Equation 1, what is the time complexity in terms of N and w? Let d_k be a constant that does not need to be included in your answer. (For this and subsequent questions, assume that the cost of multiplying two matrices $\mathbf{X} \in \mathbb{R}^{m \times n}$ and $\mathbf{Y} \in \mathbb{R}^{n \times p}$ is O(mnp).)



4.1.b. (1 point) **Short answer:** If we implement sliding window using the matrix multiplications described in Equation 1, what is the space complexity in terms of N and w? Let d_k be a constant that does not need to be included in your answer.



4.2. Let's define causal sliding window attention again, but this time, compute X' from Equation (1) more efficiently.

Pseudocode: Fill in the blanks with pseudocode/math to create a function that takes in the queries, keys, and values and the window size w and computes the X' of Equation (1):

```
SLIDINGWINDOWATTENTION(\mathbf{Q}, \mathbf{K}, \mathbf{V}, w)
```

Your pseudocode/math must have lower asymptotic computational than the naive matrix multiplication approach described above. The function softmax(x) can be applied to a vector x or a matrix X row-wise. The function tensor() can be used to construct vectors, matrices, tensors of arbitrary shape specified by a shape parameter and initializes their values to a scalar $init_values$. In the pseudocode below, X_i means indexing into the vector / matrix X at index i. The range() function follows standard Python convention. For instance, range(0, N) iterates over the values 0 (inclusive) to N (exclusive).

```
def SlidingWindowAttention (Q, K, V, w):
   N, d_k = Q.shape()
   X' = tensor(shape=(N, d_k), init_values=0)
   w' = w//2 + 1
   for j in range (0, N):
        # a stores attention scores only for this local window
        a = tensor(shape= (1a) , init_values= (1b) )
        # loop over local window indices
        for i in range ( (2) ):
            # map local index to the corresponding token index
            token_idx = (3)
            # ignore if token_idx is out of bounds
            if (4) :
                # compute attention score
                a_i = (5)
        a = softmax(a)
        # loop again to build the weighted sum
        for i in range(__(2)__):
            token_idx = (3)
            if (4) :
                # accumulate weighted value
               X_i' +=  (6)
        # delete a and trigger garbage collection
        # so it can be reused in the next iteration
        del a
        gc.collect()
    return X^{\prime}
```

	1 point) Write psuedocode/math to fill in blank (1a).
4.2.b. (1 point) Write psuedocode/math to fill in blank (1b).
	1 point) Write psuedocode/math to fill in blank (2). Note that both blanks will be filled with he same line.
	1 point) Write psuedocode/math to fill in blank (3). Note that both blanks will be filled with he same line.
	and statute time.
	1 point) Write psuedocode/math to fill in blank (4).
4.2.e. (
4.2.e. (1 point) Write psuedocode/math to fill in blank (4).

4.2.h. (1 point) Short answer: What is the space complexity of your pseudocode in terms of N and w? Note both N and w need to be in your answer.
4.2.i. (1 point) Short answer: What is the time complexity of your pseudocode in terms of N and w? Note both N and w need to be in your answer.

5 Programming: RoPE and GQA (22 points)

Introduction

In this section, you will take a run-of-the-mill GPT model and upgrade it to incorporate two of the key ingredients found in state-of-the-art large language models (LLMs), such as LLAMA-2.

The first ingredient are rotary position embeddings (RoPE). These will replace the existing absolute position embeddings with a relative position embedding that rotates small segments of each key and query vector.

The second ingredient is grouped-query attention (GQA). Although the GQA mechanism is fundamentally still causal attention, it enables the model to use less memory and run faster.

You will experiment with how these two model improvements lead to changes in model performance. And you will even evaluate how they perform in tandem.

Upon completion of this section, you will unfortunately not be able to claim to have trained a *large* language model, for the dataset we provide here (the complete works of Shakespeare) is rather small if not trite. However, you can reasonably claim to have built your own LLAMA-2 model.

Dataset

The dataset for this homework is a collection of the complete works of Shakespeare. The dataset file is input.txt, and is around 1.1MB in size.

Starter Code

The starter code was originally authored by Andrej Karpathy, of OpenAI fame, and released as minGPT. It offers a clear glimpse into the inner workings of a GPT model. We have simplified the codebase and provided to you a modified version. Ours contains the following files:

```
hw1/
requirements.txt
input.txt
chargpt.py
mingpt/
model.py
trainer.py
utils.py
test_model.py
```

Here is what you will find in each file:

- 1. requirements.txt: A list of packages that need to be installed for this homework. This homework only requires 2 packages torch and einops.
- 2. input.txt: The dataset—the works of Shakespeare.
- 3. chargpt.py: The main entry point used to train your transformer. It can be run with the command python chargpt.py. Append flags to this command to adjust the transformer configuration. You will modify this file when changing prompts.

- 4. mingpt/model.py: Is the other file you will modify (more extensively) for this homework. This file contains the construction of the GPT model. A vanilla, working transformer implementation is already provided. You will implement the classes RotaryPositionalEmbeddings and GroupedQueryAttention. You will also need to make changes to the class CausalSelfAttention while implementing RoPE. (Hint: Locations in the code where changes ought to be made are marked with a TODO.)
- 5. mingpt/trainer.py: Code for the training loop of the transformer.
- 6. mingpt/utils.py: Helper functions for saving logs and configs.
- 7. test_model.py: A file containing unit tests (the same ones used on Gradescope). To run them, simply execute python test_model.py in your terminal. Please note however that from an assessment perspective, we will continue to manually grade all of your code submissions and that manual evaluation will be the bulk of your grade on the programming portion of the homework.

Flags

All the parameters printed in the config can be modified by passing flags to chargpt.py. Table 1 contains a list of flags you may find useful while implementing HW1. You can change other parameters as well in a similar manner. Simply specify the config node (i.e. one of {system,data,model,trainer}), followed by a period '.', followed by the parameter you wish to modify.

Configuration Parameter	Example Flag Usage
Model sequence length	data.block_size=16
	(model.block_size is autoset based on this flag)
Directory where model is stored	system.work_dir=out/new_chargpt
Number of query heads	model.n_query_head=6
(hyperparameter for GQA)	
Number of key-value heads	model.n_kv_head=3
(hyperparameter for GQA)	(n_query_head must be divisible by n_kv_head)
	(For standard multi-head attention n_query_head = n_kv_head)
Directory from which to load a model	model.pretrained_folder=out/chargpt3
trained in a previous run	
Whether to enable RoPE embeddings	model.rope=True
Number of iterations to train the	trainer.max_iters=200
model	
Device type (useful for debugging),	trainer.device=cpu
one of "cpu", "cuda"	

Table 1: Useful flags for chargpt.py

Model

The default model in chargpt.py is a GPT model with 6 transformer layers. Each attention layer uses h=6 attention heads. The maximum sequence length is N=16. Because the vocabulary is comprised of only characters, the vocabulary size is only 65. The embedding dimension is $d_{model}=192$ and the key/value/query dimension size is $d_k=d_{model}/h=32$.

Rotary Position Embeddings (RoPE)

In this section, you will implement Rotary Position Embeddings (RoPE) (Su et al., 2021).

Background: Absolute position embeddings are added to the word embeddings in the first layer of a standard Transformer language model. Subsequent layers propagate position information up from the bottom.

Traditional attention is defined as below.

$$\mathbf{q}_{j} = \mathbf{W}_{q}^{T} \mathbf{x}_{j}, \forall j$$

$$\mathbf{k}_{j} = \mathbf{W}_{k}^{T} \mathbf{x}_{j}, \forall j$$

$$s_{t,j} = \mathbf{k}_{j}^{T} \mathbf{q}_{t} / \sqrt{d_{k}}, \forall j, t$$

$$\mathbf{a}_{t} = \operatorname{softmax}(\mathbf{s}_{t}), \forall t$$

where $d_k = |\mathbf{k}_j|$ is the size of the query/key/value vectors.

RoPE: Rotary Position Embeddings (RoPE) (Su et al., 2021) incorporate positional information directly into the attention computation, in every layer. If the input to the next attention layer is $\mathbf{X} = [\mathbf{x}_1, \dots, \mathbf{x}_N]^T$, then we introduce two functions $f_q(\mathbf{x}_j, j)$ and $f_k(\mathbf{x}_j, j)$, which compute the position-aware queries and keys respectively. Then the attention scores are computed as below:

$$\begin{aligned} \mathbf{q}_j &= \mathbf{W}_q^T \mathbf{x}_j, \forall j \\ \widetilde{\mathbf{q}}_j &= \mathbf{R}_{\Theta,j} \mathbf{q}_j \\ s_{t,j} &= \widetilde{\mathbf{k}}_j^T \widetilde{\mathbf{q}}_t / \sqrt{d_k}, \forall j, t \\ \mathbf{a}_t &= \operatorname{softmax}(\mathbf{s}_t), \forall t \end{aligned}$$

where $\mathbf{W}_k, \mathbf{W}_q \in \mathbb{R}^{d_{model} \times d_k}$. Herein we use $d = d_k$ for brevity.

To implement this efficiently in PyTorch, we want to construct a new matrix $\widetilde{\mathbf{Y}} = g(\mathbf{Y}; \Theta)$ such that $\widetilde{\mathbf{Y}}_{m,\cdot} = \mathbf{R}_{\Theta,m}\mathbf{y}_m$ for a matrix of embeddings $\mathbf{Y} = [\mathbf{y}_1,\dots,\mathbf{y}_N]^T \in \mathbb{R}^{N\times d}$, and $\Theta = \{\theta_i = 10000^{-2(i-1)/d}, i \in [1,2,\dots,d/2]\}$ (in practice this \mathbf{Y} would be either the queries \mathbf{Q} or the keys \mathbf{K}). We can construct the new matrix as follows:

$$\begin{split} \widetilde{\mathbf{Y}} &= g(\mathbf{Y}; \Theta) \\ &= \begin{bmatrix} Y_{1,1} & \cdots & Y_{1,\frac{d}{2}} & Y_{1,\frac{d}{2}+1} & \cdots & Y_{1,d} \\ \vdots & & \vdots & & \vdots & & \vdots \\ Y_{N,1} & \cdots & Y_{N,\frac{d}{2}} & Y_{N,\frac{d}{2}+1} & \cdots & Y_{N,d} \end{bmatrix} \odot \begin{bmatrix} \cos 1\theta_1 & \cdots & \cos 1\theta_{\frac{d}{2}} & \cos 1\theta_1 & \cdots & \cos 1\theta_{\frac{d}{2}} \\ \vdots & & \vdots & & \vdots & & \vdots \\ \cos N\theta_1 & \cdots & \cos N\theta_{\frac{d}{2}} & \cos N\theta_1 & \cdots & \cos N\theta_{\frac{d}{2}} \end{bmatrix} \\ &+ \begin{bmatrix} -Y_{1,\frac{d}{2}+1} & \cdots & -Y_{1,d} & Y_{1,1} & \cdots & Y_{1,\frac{d}{2}} \\ \vdots & & \vdots & & \vdots \\ -Y_{N,\frac{d}{2}+1} & \cdots & -Y_{N,d} & Y_{N,1} & \cdots & Y_{N,\frac{d}{2}} \end{bmatrix} \odot \begin{bmatrix} \sin 1\theta_1 & \cdots & \sin 1\theta_{\frac{d}{2}} & \sin 1\theta_1 & \cdots & \sin 1\theta_{\frac{d}{2}} \\ \vdots & & \vdots & & \vdots \\ \sin N\theta_1 & \cdots & \sin N\theta_{\frac{d}{2}} & \sin N\theta_1 & \cdots & \sin N\theta_{\frac{d}{2}} \end{bmatrix} \end{split}$$

Or more compactly:

$$\mathbf{C} = \begin{bmatrix} 1\theta_1 & \cdots & 1\theta_{\frac{d}{2}} & 1\theta_1 & \cdots & 1\theta_{\frac{d}{2}} \\ \vdots & & \vdots & & \vdots \\ N\theta_1 & \cdots & N\theta_{\frac{d}{2}} & N\theta_1 & \cdots & N\theta_{\frac{d}{2}} \end{bmatrix}$$
$$\widetilde{\mathbf{Y}} = g(\mathbf{Y}; \Theta)$$
$$= \begin{bmatrix} \mathbf{Y}_{\cdot,1:d/2} & \mathbf{Y}_{\cdot,d/2+1:d} & \odot \cos(\mathbf{C}) \\ + & -\mathbf{Y}_{\cdot,d/2+1:d} & \mathbf{Y}_{\cdot,1:d/2} & \odot \sin(\mathbf{C}) \end{bmatrix}$$

Now we can compute RoPE embeddings efficiently as below:

$$\begin{split} \mathbf{Q} &= \mathbf{X} \mathbf{W}_q & \mathbf{K} &= \mathbf{X} \mathbf{W}_k \\ \widetilde{\mathbf{Q}} &= g(\mathbf{Q}; \Theta) & \widetilde{\mathbf{K}} &= g(\mathbf{K}; \Theta) \\ \mathbf{S} &= \widetilde{\mathbf{Q}} \widetilde{\mathbf{K}}^T / \sqrt{d_k} \\ \mathbf{A} &= \operatorname{softmax}(\mathbf{S}) \end{split}$$

You do not have to understand all the math in the paper, but you may go through it to understand the intuition behind RoPE.

Implementation: You will implement RoPE within minGPT. To do so, you should make changes to the RotaryPositionalEmbeddings and the CausalSelfAttention classes in mingpt/model.py. Within RotaryPositionalEmbeddings, you will first implement _build_cache, and within the forward computation, your first steps should be building the cache if it has not been built yet.

RoPE Empirical Questions

For all empirical plots in this section, you are free to use wandb, matplotlib, or another similar plotting tool.

rations with a sequence lenger of 256 on the same more	th of 16, followed and the condition to	ed by an additional the sample on the f	1 600 iterations with	a seque
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י	rations with a sequence lenger ength of 256 on the same more peare play. Do not use the definition of the sequence of the sequ	rations with a sequence length of 16 , follower ength of 256 on the same model. Condition to be peare play. Do not use the default line provide	rations with a sequence length of 16, followed by an additional	

	Does this include a KV-cache? If yes, identify which lines of code are doing so, and how the
	work. If not, explain how the model handles attention at each timestep.
5.4.	(4 points) Plot the training loss for both your RoPE implementation and the vanilla minGPT over 1200 total training iterations on the same plot, and train as follows: 600 iterations with a sequence length of 16, and then continue training this model for another 600 iterations, but no with a sequence length of 256.
	[Expected runtime on Colab T4 to run both: approximately 10 minutes]

Grouped Query Attention (GQA)

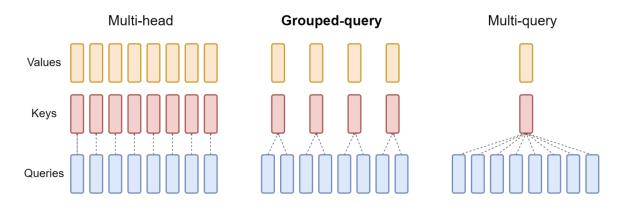


Figure 1: Schematic representation of attention mechanisms, showcasing Multi-head attention with individual keys and values for each head, Grouped-query attention with queries grouped to share common keys and values, and Multi-query attention utilizing a singular key and value for all queries.

In this section, you will implement Grouped Query Attention (GQA) (Ainslie et al., 2023).

GQA: Grouped Query Attention (GQA) is a technique in neural network architectures that modifies the attention mechanism used in models such as transformers. It involves dividing the query heads into groups, each sharing a single key head and value head. This approach can interpolate between Multi-Query Attention (MQA) and Multi-Head Attention (MHA), offering a balance between computational efficiency and model quality [Figure 1].

We define the following variables:

- h_q : Number of query heads.
- h_{kv} : Number of key/value heads.
- $g = h_q/h_{kv}$: the size of each group (i.e. number of query vectors per key/value vector). Note that we assume h_q is divisible by h_{kv} .

Our parameter matrices for GQA are all the same size: $\mathbf{W}_q^{(i,j)}, \mathbf{W}_k^{(i)}, \mathbf{W}_v^{(i)} \in \mathbb{R}^{d_{model} \times d_k}$ where $i \in \{1, \dots, h_{kv}\}, j \in \{1, \dots, g\}$, and $d_k = d_{model}/h_q$. However, we now have different numbers of query, key, and value heads:

$$\mathbf{X} = [\mathbf{x}_1, \dots, \mathbf{x}_T]^T$$

$$\mathbf{V}^{(i)} = \mathbf{X}\mathbf{W}_v^{(i)}, \forall i \in \{1, \dots, h_{kv}\}$$

$$\mathbf{K}^{(i)} = \mathbf{X}\mathbf{W}_k^{(i)}, \forall i \in \{1, \dots, h_{kv}\}$$

$$\mathbf{Q}^{(i,j)} = \mathbf{X}\mathbf{W}_q^{(i,j)}, \forall i \in \{1, \dots, h_{kv}\}, \forall j \in \{1, \dots, g\}$$

Above, we define g times more query vectors than key/value vectors. Then we compute the scaled dot-product between each query vector (i,j) and its corresponding key (i) to get a similarity score. The similarity scores are used to compute an attention matrix, but with only h_{kv} heads

$$\begin{split} \mathbf{S}^{(i,j)} &= \mathbf{Q}^{(i,j)}(\mathbf{K}^{(i)})^T/\sqrt{d_k}, \quad \forall i \in \{1,\dots,h_{kv}\}, \forall j \in \{1,\dots,g\} \\ \mathbf{A}^{(i,j)} &= \operatorname{softmax}(\mathbf{S}^{(i,j)}), \quad \forall i \in \{1,\dots,h_{kv}\}, \forall j \in \{1,\dots,g\} \\ \mathbf{X}'^{(i,j)} &= \mathbf{A}^{(i,j)}\mathbf{V}^{(i)}, \quad \forall i \in \{1,\dots,h_{kv}\}, \forall j \in \{1,\dots,g\} \\ \mathbf{X}' &= \operatorname{concat}(\mathbf{X}'^{(i,j)}), \quad \forall i \in \{1,\dots,h_{kv}\}, \forall j \in \{1,\dots,g\} \\ \mathbf{X} &= \mathbf{X}'\mathbf{W}_o \qquad \qquad (\text{where } \mathbf{W}_o \in \mathbb{R}^{d_{model} \times d_{model}}) \end{split}$$

Implementation Details: You will implement GQA in the GroupedQueryAttention class in mingpt/model.py. Much of your code will be similar to that in CausalSelfAttention.

Hint: You may find it easier to implement GroupedQueryAttention in a similar way to CausalSelfAttention.

• Initialization:

- Familiarize yourself with the configuration settings that initialize the attention mechanism, including the number of query heads, key/value heads, and embedding dimensions. Note that config is defined in the get_config method in chargpt.py.
- Ensure the embedding dimension is divisible by the number of query and key/value heads.

• Regularization:

- Incorporate dropout layers for attention and residuals to prevent overfitting.

• Dimensionality and Projections:

 Implement the linear projection layers for queries, keys, and values, considering the dimensionality constraints of the parameter matrices and the grouped nature of the mechanism.

Rotary Positional Embeddings:

If rotary positional embeddings are enabled, integrate RoPE with query and key projections.

Forward Pass:

- In the forward method, transform the input according to the query, key, and value projections.
- Apply the attention mechanism by computing grouped scaled dot-product attention
- Mask the attention to ensure causality (preventing future tokens from being attended to).
- Aggregate the attention with the values and project the output back to the embedding dimension.

• Memory Efficiency:

 Monitor and record the CUDA memory allocation before and after the attention operation to analyze the memory efficiency of the GQA. A reference code to monitor memory is present in CausalSelfAttention class.

GQA Empirical Questions

The questions below assume you are using absolute position embeddings, not RoPE.

[Expecte	d runtime on C	Colab T4: app	roximately 1	minute]		
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5.7.	(4 points) Plot the following four configurations on the same plot : 1. vanilla minGPT (no RoPE nor GQA), 2. RoPE only (no GQA), 3. GQA only (no RoPE), 4. RoPE and GQA. For each, plo the training loss over 1200 total training iterations : 600 iterations with a sequence length of 16 followed by 600 iterations with a sequence length of 256 .
	[Expected runtime on Colab T4 to run all four: approximately 16 minutes]

6 Code Upload (0 points)

6.1. (0 ₁	points) Did you upload your code to the appropriate programming slot on Gradescope
Hir	nt: The correct answer is 'yes'.
	○ Yes
	○ No
For	this homework, you should upload only model.py.

7 Collaboration Questions (2 points)

After you have completed all other components of this assignment, report your answers to these questions regarding the collaboration policy. Details of the policy can be found in the syllabus.

2	(1 point) Did you find or come across code that implements any part of this assignment? If
	include full details.