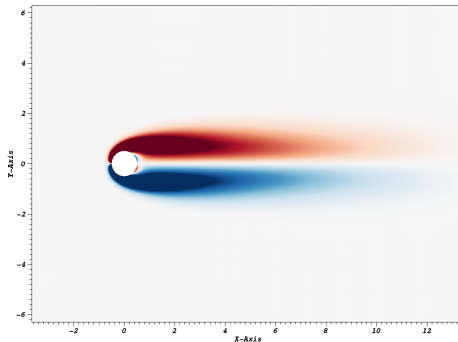


Numerical Simulation of Compressible Flows with Immersed Boundaries Using Discontinuous Galerkin Methods



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Bachelor thesis by Simone Stange
Prof. Dr.-Ing. habil. Martin Oberlack
Betreuer: Dr.-Ing Björn Müller





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 - The Discontinuous Galerkin Method
 - The Immersed Boundary Method
- 2 Verification of BoSSS for Inviscid Flows
 - Robustness
 - Convergence
- 3 Evaluation of BoSSS for Viscid Flows
 - Theory
 - Simulations
- 4 Conclusion and Outlook



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- ▶ Aim of this thesis:
 - ▶ Verification of CNS extension for BoSSS for inviscid flows
 - ▶ Validation for viscous flows
 - ▶ Both using immersed boundaries
- ▶ CNS extension of BoSSS (Bounded Support Spectral Solver) numerically solves the Compressible Navier-Stokes equations using a Discontinuous Galerkin method
- ▶ CNS has already been verified and validated for:
 - ▶ Inviscid flows using immersed boundaries by [1, Müller 2014], though not for the flow around a cylinder
 - ▶ Viscous flows using curved elements by [2, Ayers 2015]



- ▶ Compressible flow
- ▶ Ideal gas
 - ▶ Heat capacity ratio $\gamma = \frac{c_p}{c_v} = 1.4$
- ▶ Newtonian fluid
 - ▶ Stress tensor $\tau_{ij} = \mu \left[\left(\frac{\partial u_i}{\partial x_j} + \frac{\partial u_j}{\partial x_i} \right) - \frac{2}{3} \frac{\partial u_k}{\partial x_k} \delta_{ij} \right]$
- ▶ Mach number $Ma = \frac{v_\infty}{a_\infty} = 0.2$
- ▶ Reynolds number $Re = \frac{\rho_\infty V_\infty L}{\mu_\infty} \propto \frac{\text{inertia forces}}{\text{viscous forces}}$
- ▶ Prandtl number $Pr = \frac{\mu_\infty c_p}{k_\infty} \propto \frac{\text{viscous diffusion rate}}{\text{thermal diffusion rate}}$

Non-dimensional 2D Compressible Navier-Stokes Equations

- ▶ 2D
- ▶ Non-dimensional conserved flow variables: density ρ , momentum ρu , ρv , energy ρE

$$\frac{\partial U}{\partial t} + \left(\frac{\partial F_c^x(U)}{\partial x} + \frac{\partial F_c^y(U)}{\partial y} \right) - \left(\frac{\partial F_v^x(U, \nabla U)}{\partial x} + \frac{\partial F_v^y(U, \nabla U)}{\partial y} \right) = 0$$

$$U = \begin{pmatrix} \rho \\ \rho u \\ \rho v \\ \rho E \end{pmatrix} \quad F_c^x = \begin{pmatrix} \rho u \\ \rho u^2 + p \\ \rho uv \\ u(\rho E + p) \end{pmatrix} \quad F_c^y = \begin{pmatrix} \rho v \\ \rho uv \\ \rho v^2 + p \\ v(\rho E + p) \end{pmatrix}$$

▶ Temporal derivative

▶ Convective fluxes

▶ Viscous fluxes

$$F_v^x = \frac{1}{\text{Re}} \begin{pmatrix} 0 \\ \tau_{xx} \\ \tau_{xy} \\ \tau_{xx}U + \tau_{xy}V + \frac{\gamma}{\text{Pr}(\gamma - 1)} \kappa \frac{\partial T}{\partial x} \end{pmatrix} \quad F_v^y = \frac{1}{\text{Re}} \begin{pmatrix} 0 \\ \tau_{xy} \\ \tau_{yy} \\ \tau_{xy}U + \tau_{yy}V + \frac{\gamma}{\text{Pr}(\gamma - 1)} \kappa \frac{\partial T}{\partial y} \end{pmatrix}$$

The Discontinuous Galerkin Space Discretisation

- ▶ Discrete weak formulation of $\frac{\partial c}{\partial t} + \nabla \cdot \mathbf{f}(c) = 0$
- ▶ Discretisation Ω_h of Ω
- ▶ Multiplication of PDE by set of cell-local test functions $\Phi_{i,j}$
- ▶ Integration over cell \mathcal{K}_i and integration by parts
- ▶ Modal approximation for $c(\mathbf{x}, t) |_{\mathcal{K}_i} \approx \sum_{k=0}^M c_{i,k}(t) \Phi_{i,k}(\mathbf{x})$ with Galerkin approach (identical Ansatz and test functions)
- ▶ Discontinuous approach \rightarrow flux function $f = f(c^-, c^+, \mathbf{n})$

$$\Rightarrow \int_{\mathcal{K}_i} \frac{\partial c_i}{\partial t} \Phi_{i,j} dV + \sum_{e=1}^{E_i} \int_{\mathcal{E}_{i,e}} f(c^-, c^+, \mathbf{n}) \Phi_{i,j} dA - \int_{\mathcal{K}_i} \mathbf{f}(c_i) \cdot \nabla \Phi_{i,j} dV = 0$$

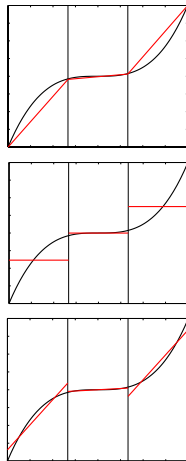


Figure: Adapted from [1]

► Division into

- the physical region:
 $\mathcal{A} = \{\vec{x} \in \Omega_h : \varphi(\vec{x}) > 0\},$
- the void region: $\mathcal{B} = \{\vec{x} \in \Omega_h : \varphi(\vec{x}) < 0\},$
- the immersed boundary:
 $\mathcal{I} = \{\vec{x} \in \Omega_h : \varphi(\vec{x}) = 0\}$

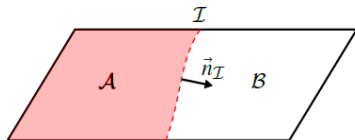


Figure: Cut cell with physical (red) and void region (white) [3]

► Restrict problem domain to physical region:

$$\int_{\mathcal{A}_i} \frac{\partial c_i}{\partial t} \Phi_{i,j} dV + \sum_{e=1}^{E_i} \int_{\mathcal{E}_{i,e}^{\mathcal{A}}} f(c^-, c^+, \mathbf{n}) \Phi_{i,j} dA + \int_{\mathcal{I}_i} f(c^-, c^+, \mathbf{n}_{\mathcal{I}}) \Phi_{i,j} dA - \int_{\mathcal{A}_i} \mathbf{f}(c_i) \cdot \nabla \Phi_{i,j} dV = 0$$

► Solution via explicit Euler time discretisation

- Time step size depends on cell with smallest volume
→ Cell agglomeration

- ▶ Agglomeration threshold
 $0 \leq \alpha \leq 1$
- ▶ Cells $\mathcal{K}_s^{\text{src}}$ with
 $\text{frac}(\mathcal{A}_i) = \frac{\text{meas}(\mathcal{A}_i)}{\text{meas}(\mathcal{K}_i)} \leq \alpha$ get
agglomerated to
neighbouring cell $\mathcal{K}_s^{\text{tar}}$
- ▶ Neighbouring cells are
weakly coupled via fluxes
→ basis $\vec{\Phi}_i$ can be extended
from the target cell into the
source cell

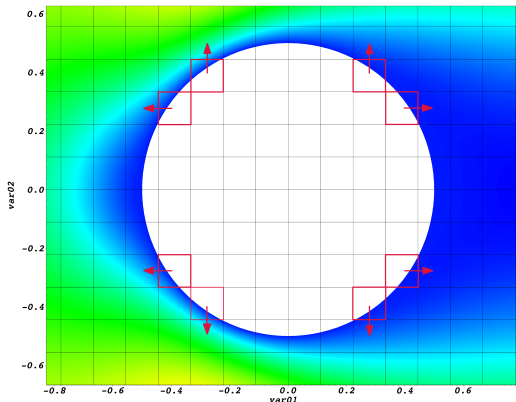


Figure: Cell agglomeration for $\alpha = 0.3$



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Problem Specification



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- ▶ Supersonic inlet
- ▶ Adiabatic slip wall
- ▶ Flow properties:
 - ▶ Symmetrical flow
 - ▶ Isentropic inviscid flow with
$$\frac{p}{\rho^\gamma} = \text{const}$$
$$\rightarrow \text{Entropy } s = 0$$

- ▶ Domain:

- ▶ $0 \leq y \leq 40$
- ▶ $-40 \leq x \leq 40$
- ▶ Cylinder with radius $r = 1$ at $(0, 0)$
 - \rightarrow Level set $\varphi = x^2 + y^2 - 1$ set as **adiabatic slip wall**

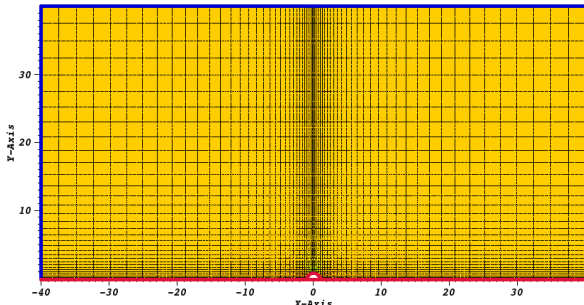


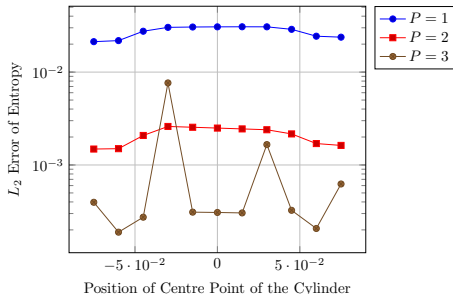
Figure: Mesh with 64 Cells per Direction



- ▶ Variation of polynomial degree $1 \leq P \leq 3$
- ▶ Variation of position of the cylinder's centre point from -0.075 to $+0.075$ with step size 0.015
 - Level set $\varphi = (x - \text{shift})^2 + y^2 - 1$
- ▶ Mesh as shown before (64 cells per direction)
- ▶ Constant agglomeration threshold $\alpha = 0.5$
 - several different cell agglomerations occur

Aim: Proving the robustness of the solver

- ▶ Constant error of entropy for degrees 1 and 2
→ Only slight influence by cell agglomeration
- ▶ Large error differences for degree 3
 - ▶ For some cases huge effort in getting calculations to work (early breakup)
 - ▶ Discordant cases should be examined more closely



→ Sufficiently robust for lower degrees, higher degree calculations strongly influenced by cell agglomeration



- ▶ Variation of polynomial degree $0 \leq P \leq 4$
- ▶ Variation of mesh size: 32, 64 and 128 cells per direction
- ▶ Constant level set $\varphi = x^2 + y^2 - 1$
- ▶ Constant agglomeration threshold $\alpha = 0.3$

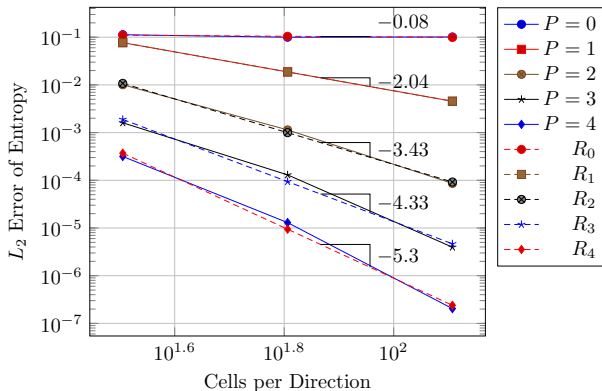
Aim: Proving convergence rate of $\mathcal{O}(h^{P+1})$

Convergence Study – Evaluation



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- ▶ Bad convergence rate for $P = 0$
- ▶ Convergence of roughly $\mathcal{O}(h^{P+1})$ for $1 \leq P \leq 4$



Convergence rate for higher degrees as expected
→ Convergence verified



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Theory – Viscid Flow Around a Cylinder

- ▶ $Re \leq 40 - 50$: laminar steady regime
- ▶ $40 - 50 \leq Re \leq 190$: laminar vortex shedding (Kármán vortex street)
- ▶ $190 \leq Re$: increasing 3D effects
- ▶ Characteristic values:
 - ▶ Coefficient of drag C_D
 - ▶ Coefficient of lift C_L
 - ▶ Wake separation length W^*
 - ▶ Strouhal number (frequency of vortex shedding)

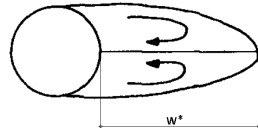


Figure: Laminar steady regime [4]

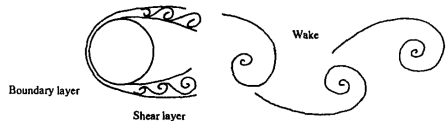


Figure: Kármán Vortex Street [4]

Simulation Properties



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- ▶ Domain:
 - ▶ $-20 \leq x \leq 20$
 - ▶ $-20 \leq y \leq 20$
 - ▶ Cylinder with radius $r = 0.5$ at $(0, 0)$
 - Level set $\varphi = x^2 + y^2 - 0.25$ set as **isothermal wall**
- ▶ Variation of mesh size: 40, 60 and 80 cells per direction
- ▶ Variation of polynomial degree $1 \leq P \leq 3$
- ▶ Constant agglomeration threshold $\alpha = 0.3$
- ▶ Supersonic inlet
- ▶ Isothermal wall

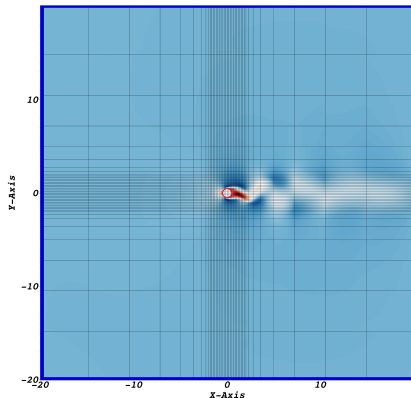


Figure: Coarsest mesh with 40×40 cells



► Steady flow simulations for $Re = 20$ and $Re = 40$:

- Coefficient of drag C_D
- Wake separation length W^*
→ found from evaluating x at $y = 0$ where
 x -velocity $u = 0$

► Unsteady flow simulations for $Re = 100$ and
 $Re = 200$:

- Coefficient of drag C_D
- Coefficient of lift C_L
- St found from evaluating frequency of C_L

$$C_D = \frac{d}{q_\infty L_\infty}$$

$$C_L = \frac{l}{q_\infty L_\infty}$$

$$St = \frac{fL_\infty}{V_\infty}$$

d : drag force

l : lift force

q_∞ : dynamic pressure

L_∞ : cylinder diameter

V_∞ : flow velocity

Simulation at $Re = 20$ I



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Re = 20	Source	2D/3D	W^*	C_D
Numerical – Incompressible	Dennis and Chang	2D	0.94	2.05
	Fornberg	2D	0.91	2.00
	Linnick and Fasel	2D	0.93	2.06
Experimental	Coutanceau and Bouard	-	0.93	-
	Tritton	-	-	2.09
Numerical – Compressible	Brehm, Hader and Fasel (Ma = 0.1)	3D	0.96	2.02
	Ayers	2D	0.975	2.06
	Present Results:	2D	0.928	2.136

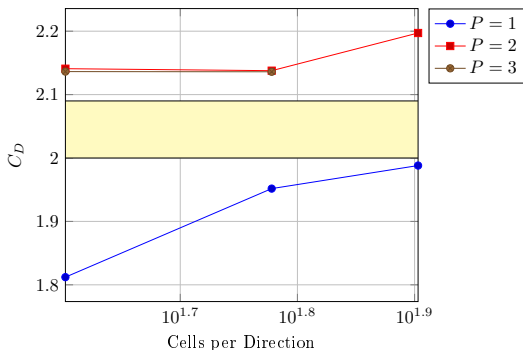
- W^* coincides with literature, C_D much too high

Simulation at Re = 20 II



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- ▶ None of the values lies in the range found in literature
- ▶ Simulation for $P = 2$, $CpD = 80$ should be examined again
→ perhaps mistake during simulation (e.g. at restart)
- ▶ Overall, $P = 1$ behaviour as expected, $P = 2$ and 3 yield much too high results



Simulation at $Re = 40$ I



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Re = 40	Source	2D/3D	W^*	C_D
Numerical – Incompressible	Dennis and Chang	2D	2.35	1.52
	Fornberg	2D	2.24	1.50
	Linnick and Fasel	2D	2.28	1.54
Experimental	Coutanceau and Bouard	-	2.13	-
	Tritton	-	-	1.59
Numerical – Compressible	Brehm, Hader and Fasel (Ma = 0.1)	3D	2.26	1.51
	Ayers	2D	2.250	1.605
	Present Results:	2D	2.201	1.608

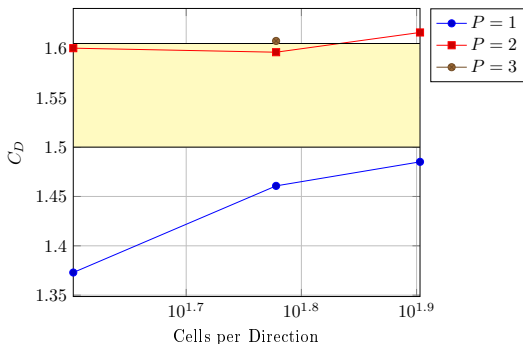
- W^* coincides with literature, C_D slightly high

Simulation at Re = 40 II



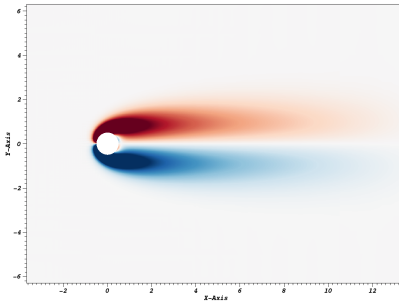
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- ▶ Better results than for Re=20
- ▶ Simulation for $P = 2$,
CpD = 80 once again yields
discordant values
- ▶ $P = 2$ and $P = 3$ quite high
compared to literature

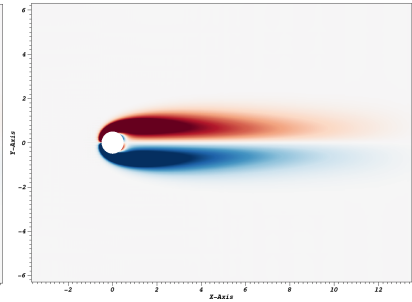


Comparison of $Re = 20$ and $Re = 40$

	W^*	C_D
$Re = 20$	0.928	2.136
$Re = 40$	2.201	1.608



(a) $Re = 20$



(b) $Re = 40$

Simulation at $Re = 100$ I



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Re = 100	Source	2D/3D	St	C_D	C_L
Numerical – Incompressible	Gresho, Chan, Lee, et al.	2D	0.18	1.76	-
	Linnick and Fasel ($\lambda = 0.056$)	2D	0.169	1.38 ± 0.010	± 0.337
	Linnick and Fasel ($\lambda = 0.023$)	2D	0.1696	1.34 ± 0.009	± 0.333
	Persillon and Braza	2D	0.165	1.253	-
	Saiki and Biringen	2D	0.171	1.26	-
	Persillon and Braza	3D	0.164	1.240	-
	Liu, Zheng and Sung	3D	0.165	1.35 ± 0.012	± 0.339
Experimental	Berger and Wille	-	0.16 – 0.17	-	-
	Clift, Grace and Weber	-	-	1.24	-
	Williamson	-	0.164	-	-
Numerical – Compressible	Brehm, Hader and Fasel ($Ma = 0.1$)	3D	0.165	1.32 ± 0.01	± 0.32
	Ayers	2D	0.167	1.371 ± 0.011	± 0.333
	Present Results:	2D	0.1669	1.3593 ± 0.00805	± 0.3291

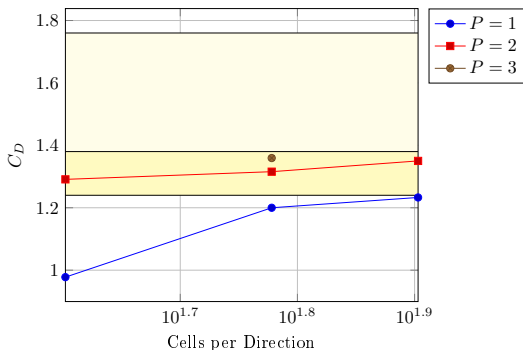
- All values coincide with literature

Simulation at $Re = 100$ II



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- ▶ Higher degree values lie in expected range
- ▶ Values which should be most accurate ($P = 2$, $CpD = 80$ and $P = 3$, $CpD = 60$) produce rather high results
- ▶ $P = 2$ seems to converge against $P = 3$, $CpD = 60$ value



Simulation at $Re = 200$ I



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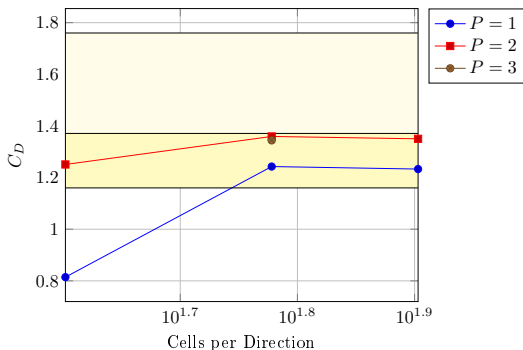
Re = 200	Source	2D/3D	St	C_D	C_L
Numerical – Incompressible	Belov, Martinelli and Jameson	2D	0.193	1.19 ± 0.042	± 0.64
	Gresho, Chan, Lee et al.	2D	0.21	1.76	-
	Linnick and Fasel ($\lambda = 0.056$)	2D	0.199	1.37 ± 0.046	± 0.70
	Linnick and Fasel ($\lambda = 0.023$)	2D	0.197	1.34 ± 0.044	± 0.69
	Miyake, Sakamoto, Tokunaga et al.	2D	0.196	1.34 ± 0.043	± 0.67
	Persillon and Braza	2D	0.198	1.321	-
	Saiki and Biringen	2D	0.197	1.18	-
	Persillon and Braza	3D	0.181	1.306	-
	Liu, Zheng and Sung	3D	0.192	1.31 ± 0.049	± 0.69
Experimental	Berger and Wille	-	0.18 – 0.19	-	-
	Clift, Grace and Weber	-	-	1.16	-
	Williamson	-	0.181	-	-
Numerical – Compressible	Brehm, Hader and Fasel ($Ma = 0.1$)	3D	0.192	1.3 ± 0.04	± 0.66
	Ayers	2D	0.201	1.371 ± 0.011	± 0.70
	Present Results:	2D	0.2002	1.344 ± 0.0462	± 0.6887

Simulation at $Re = 200$ II

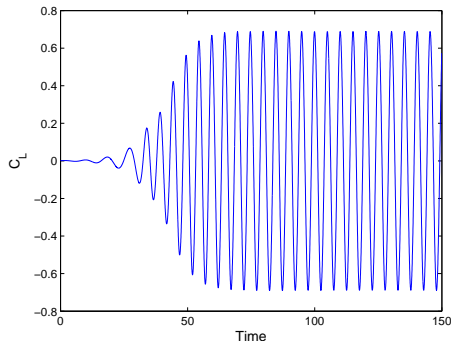
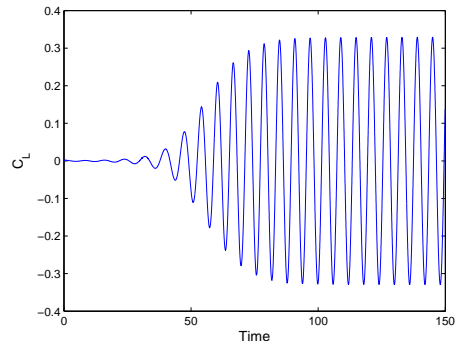


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- ▶ All values seen in table coincide with literature
- ▶ Compared to 3D results by [5, Brehm et al.] all values slightly higher
- ▶ All C_D values (except for the least accurate one) lie in expected range
- ▶ $P = 2$ seems to converge against higher value than $P = 1$

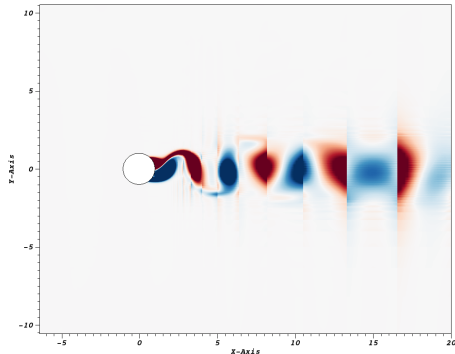
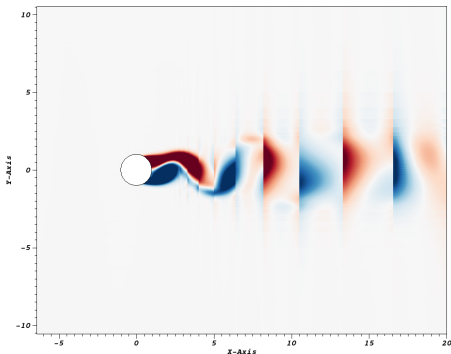


Comparison of $Re = 100$ and $Re = 200$ I



- ▶ Higher amplitude and frequency for C_L at $Re = 200$ compared to $Re = 100$
- ▶ Steady state is reached earlier

Comparison of $Re = 100$ and $Re = 200$ II



	St	C_D	C_L
$Re = 100$	0.1669	1.359 ± 0.00805	± 0.3291
$Re = 200$	0.2002	1.344 ± 0.0462	± 0.6887



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- ▶ Inviscid flow – Robustness:
 - ▶ Satisfying for lower degrees
 - ▶ Improvable for high-order degrees
- ▶ Inviscid flow – Convergence:
 - ▶ Convergence rate of $\mathcal{O}(h^{P+1})$ proven
- ▶ Viscid flow – Laminar steady regime
 - ▶ Wake separation length accurate
 - ▶ Strange behaviour for C_D values at $P = 2$ simulations
 - ▶ $\text{Re} = 40$ has yielded better results than $\text{Re} = 20$
 - ▶ Comparison showed physically correct behaviour
- ▶ Viscid flow – Laminar vortex shedding
 - ▶ Accurate results
 - ▶ $P = 1$ and $P = 2$ seem to converge against different values
 - ▶ Comparison showed physically correct behaviour



- ▶ Improvement of robustness
- ▶ Examination of agglomeration error
- ▶ Detailed convergence study for viscid flows
- ▶ Examination of 3D influences at higher Reynolds numbers

The End



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videos ende, fragen

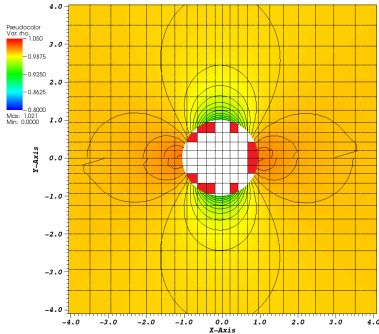
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PhD thesis, TU Darmstadt, 2014.
- [2] [Ayers, 2015] L. F. Ayers
Validation of a discontinuous Galerkin based compressible CFD solver
Bachelor thesis, TU Darmstadt, 2015.
- [3] [Müller, 2016] B. Müller, S. Krämer-Eis, F. Kummer et al.
A high-order Discontinuous Galerkin method for compressible flows with immersed boundaries
International Journal of Numerical Methods in Engineering, 2016, submitted.



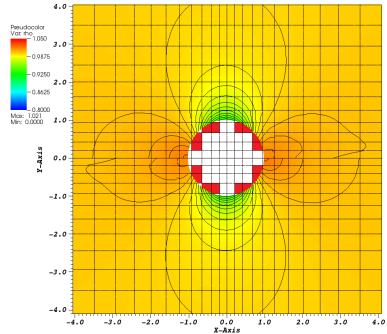
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Vortex dynamics in the cylinder wake
Annual review of fluid mechanics, 1996.
- [5] [Brehm et al., 2015] C. Brehm, C. Hader and H. Fasel
A locally stabilized immersed boundary method for the compressible
Navier–Stokes equations
Journal of Computational Physics, 2015.



Appendix



(c) Degree 2, shift -0.06



(d) Degree 2, shift -0.03

► Visualised agglomerated cells

Degrees of Freedom for Viscid Simulations



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DoFs		CpD		
		40	60	80
DG	1	4800	10800	19200
	2	9600	21600	38400
	3	16000	36000	64000

Table: Degrees of Freedom for Different Simulation Properties

Values for $Re = 20$ I



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C_D		CpD		
		40	60	80
DG	1	1.812	1.952	1.988
	2	2.141	2.138	2.197
	3	2.136	2.136	-

Table: C_D Values for Each Simulation
($Re = 20$)

W^*		CpD		
		40	60	80
DG	1	0.956	1.044	0.927
	2	0.887	0.943	0.916
	3	0.921	0.928	-

Table: Wake Separation Lengths for Each
Simulation ($Re = 20$)

Values for $Re = 20$ II



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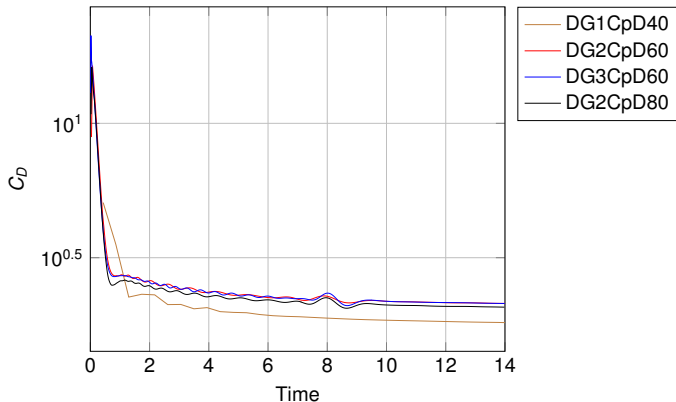


Figure: Coefficient of Drag over Time ($Re = 20$)

Values for $Re = 40$ I



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C_D		CpD		
		40	60	80
DG	1	1.373	1.461	1.485
	2	1.600	1.596	1.616
	3	-	1.608	-

Table: C_D Values for Each Simulation
($Re = 40$)

W^*		CpD		
		40	60	80
DG	1	2.342	2.338	2.236
	2	2.115	2.182	2.182
	3	-	2.201	-

Table: Wake Separation Lengths for Each
Simulation ($Re = 40$)

Values for $Re = 40$ II



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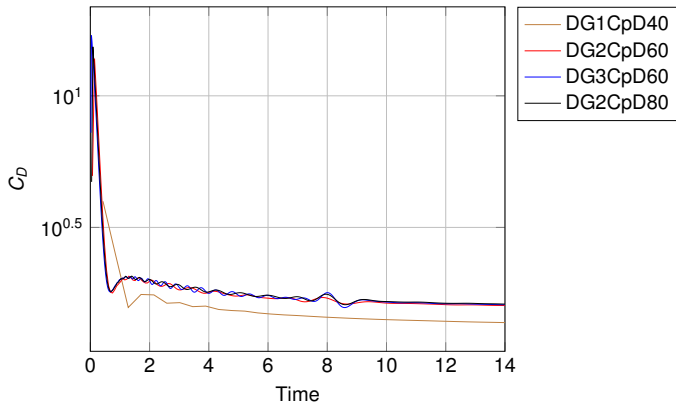


Figure: Coefficient of Drag over Time ($Re = 40$)

Values for $Re = 100$ I



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C_D		CpD		
		40	60	80
DG	1	0.9777 ± 0.0003	1.2 ± 0.0834	1.233 ± 0.0118
	2	1.291 ± 0.0082	1.3156 ± 0.0089	1.3501 ± 0.0079
	3	-	1.3593 ± 0.00805	-

Table: C_D Values for Each Simulation

C_L		CpD		
		40	60	80
DG	1	± 0.00155	± 0.291	± 0.2789
	2	± 0.2672	± 0.3154	± 0.3135
	3	-	± 0.3291	-

Table: C_L Values for Each Simulation

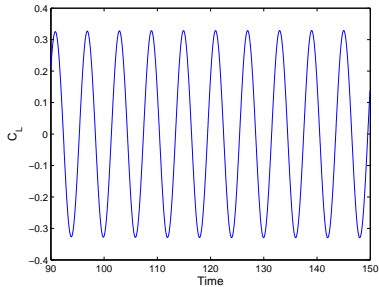
St		CpD		
		40	60	80
DG	1	0.1001	0.1506	0.1502
	2	0.1669	0.1669	0.1670
	3	-	0.1669	-

Table: Strouhal Numbers for Each Simulation

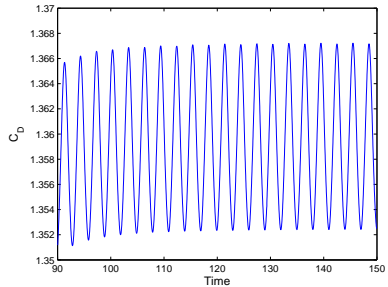
Values for $Re = 100$ II



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(a) Lift Coefficient over Time for
 $90\text{ s} < t < 150\text{ s}$



(b) Drag Coefficient over Time for
 $90\text{ s} < t < 150\text{ s}$

Values for $Re = 200$ I



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C_D		CpD		
		40	60	80
DG	1	0.8144 ± 0.0028	1.2427 ± 0.0281	1.2256 ± 0.0309
	2	1.2508 ± 0.0339	1.3593 ± 0.0080	1.3501 ± 0.0079
	3	-	1.344 ± 0.0462	-

Table: C_D Values for Each Simulation

C_L		CpD		
		40	60	80
DG	1	$\pm 3.2629 \cdot 10^{-5}$	± 0.5304	± 0.2789
	2	± 0.5653	± 0.6433	± 0.6376
	3	-	± 0.6887	-

Table: C_L Values for Each Simulation

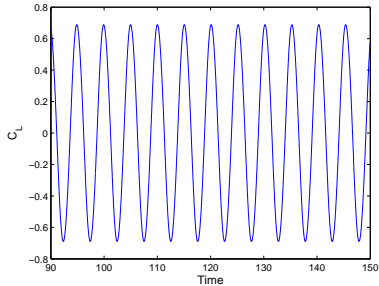
St		CpD		
		40	60	80
DG	1	0	0.1836	0.1838
	2	0.2003	0.2002	0.2002
	3	-	0.2002	-

Table: Strouhal Numbers for Each Simulation

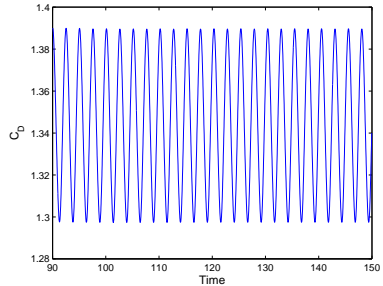
Values for $Re = 200$ II



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(c) Lift Coefficient over Time for
 $90\text{ s} < t < 150\text{ s}$



(d) Drag Coefficient over Time for
 $90\text{ s} < t < 150\text{ s}$