

Lecture 12: Searching and Sorting Algorithms

01204212 Abstract Data Types and Problem Solving

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Outline

- Searching Algorithms
 - Linear Search
 - Binary Search
- Sorting Algorithms
 - Selection Sort
 - Insertion Sort
 - Bubble Sort
 - Merge Sort
 - Quick Sort
 - **—** ...





Searching and Sorting

- Fundamental problems in computer science and programming
- Sorting done to make searching easier
- Multiple different algorithms to solve the same problem
 - How do we know which algorithm is better?
- Examples will use arrays of integers to illustrate algorithms
- We will look at searching first!



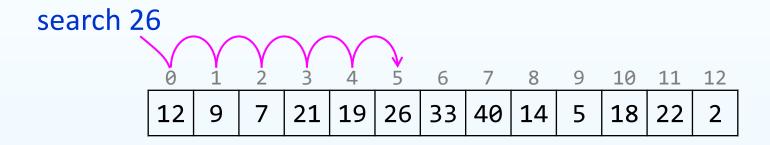
Searching

- We have learned ADTs that provide a search operation on different data structures such as linked lists, arrays, BSTs/AVL trees, and hash tables
- However, in this lecture, the search scheme is operated on an array of integers:
 - Given a list of data, searching is to find the location of a particular value or report that value is not present
 - Only focus on linear search and binary search



Linear Search

Linear search is a method that sequentially checks each element of the list until a match is found or the whole list has been searched



```
int linear_search(int arr[], int n, int value) {
  int i;
  for (i=0; i<n; i++)
    if (arr[i] == value)
      return i;
  return -1;
}</pre>
```



Binary Search

Binary search is a method that finds the position of a target value within a sorted array

- 1. Start at the middle
- 2. Check that element:
 - 2.1 If it is match; return that position
 - 2.2 If the value looking for is less than; recursively check at the middle of the left-half interval
 - 2.3 If the value looking for is greater than; recursively check at the middle of the right-half interval
- 3. Terminate when the value is found, or the interval is empty





Binary Search



```
int binary_search(int arr[], int l, int r, int value) {
  int m;
  if (1 <= r) {
   m = 1 + (r-1)/2; //same as (1+r)/2 but avoid overflow
    if (arr[m] == value)
     return m;
    if (arr[m] > value)
      return binary_search(arr, 1, m-1, value); //left
    return binary_search(arr, m+1, r, value); //right
                        Running time
  return -1;
```





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Sorting

 Sorting is a process that organizes a collection of data into either ascending or descending order

Formally,

- Input: A sequence of n numbers $\langle a_1, a_2, ..., a_n \rangle$
- Output: A permutation (reordering) $\langle a_1', a_2', ..., a_n' \rangle$ of the input sequence such that $a_1' \leq a_2' \leq \cdots \leq a_n'$

Example:

– Given an input (6, 3, 1, 7), the algorithm should produce (1, 3, 6, 7)



Structure of Data

- We rarely sort separated values
- Usually, the numbers to be sorted are part of a collection of data called a record
- Each record contains a key that is the value to be sorted



- Note that when the keys are rearranged, the data associated with the keys must also be rearranged (time consuming !!)
- Pointers can be used instead (space consuming !!)

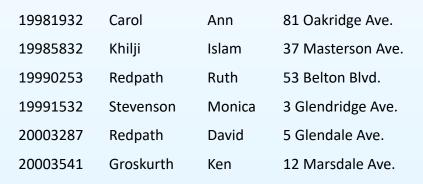


Structure of Data

We will sort a number of records based on a key:

19991532	Stevenson	Monica	3 Glendridge Ave.
19990253	Redpath	Ruth	53 Belton Blvd.
19985832	Kilji	Islam	37 Masterson Ave.
20003541	Groskurth	Ken	12 Marsdale Ave.
19981932	Carol	Ann	81 Oakridge Ave.
20003287	Redpath	David	5 Glendale Ave.

Numerically by ID Number



Lexicographically by surname, then given name

19981932	Carol	Ann	81 Oakridge Ave.
20003541	Groskurth	Ken	12 Marsdale Ave.
19985832	Kilji	Islam	37 Masterson Ave.
20003287	Redpath	David	5 Glendale Ave.
19990253	Redpath	Ruth	53 Belton Blvd.
19991532	Stevenson	Monica	3 Glendridge Ave.



Why Study Sorting?

- There are a variety of situations that we can encounter:
 - Do we have randomly ordered keys?
 - Are all keys distinct?
 - Need guaranteed performance?
- Examples:
 - Sorting price from lowest to highest
 - Sorting flights from earliest to latest
 - Sorting grades from highest to lowest
 - Sorting songs based on artist, album, playlist, etc.
- Various algorithms are better suited to some of these situations





Some Definitions

Internal sort

 The data to be sorted is all stored in the main memory of computer

External sort

 Some of the data to be sorted might be stored in some external, slower, device

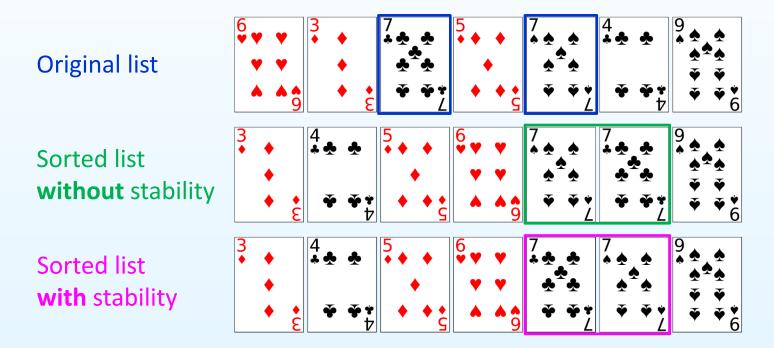
In-place sort

- The amount of extra space required to sort the data is at most $\Theta(1)$ (i.e., fixed number of local variables)



Stability

- A sorting algorithm is stable if whenever there are two records R and S with the same key and with R appearing before S in the original list
 - Preserve relative order of record with equal keys







Some Common Sorting Algorithms

- Selection sort
- Insertion sort
- Bubble sort
- Merge sort
- Quick sort
- Heap sort
- Counting sort
- Radix sort
- Bucket sort



Classification of Sorting Algorithm

Sorting algorithms can be categorized based on various criterions:

- Based on the number of swaps
 - Selection sort requires the minimum number of swaps
- Based on the running time
 - Require $O(n^2)$: selection, insertion, bubble sorts
 - Require $O(n \log n)$: merge, quick, heap sorts
 - Require O(n): counting, radix, bucket sorts
- Based on stability
 - With stability: insertion, bubble, merge sorts
 - Without stability: quick, heap sorts
- Based on extra space requirement
 - In place: selection, insertion, bubble, quick sorts
 - Out place: merge sort





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Selection Sort

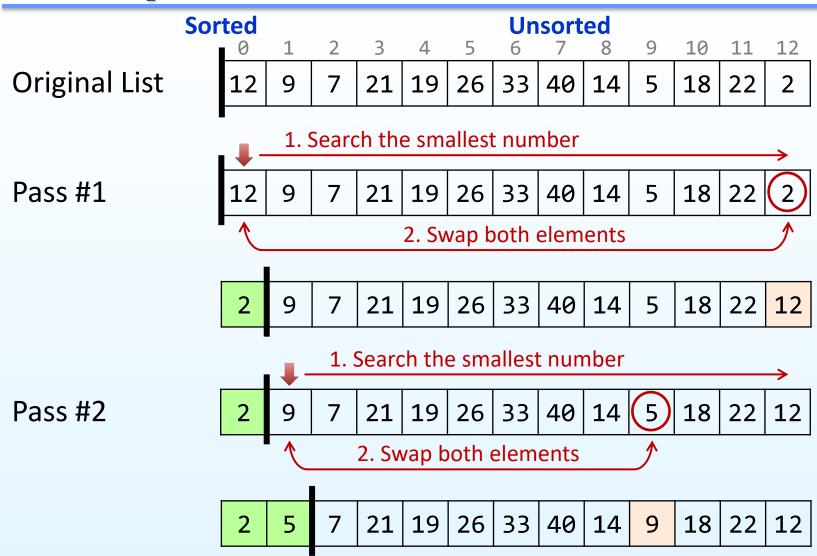


Selection sort is one of the easiest approaches to sorting

Idea:

- Partition the input list of n elements into a sorted and unsorted part (initially sorted part is empty)
- Select the smallest element and swap it with the first element of the unsorted part
- Increase the size of the sorted part by one
- Repeat this n-1 times to sort the list











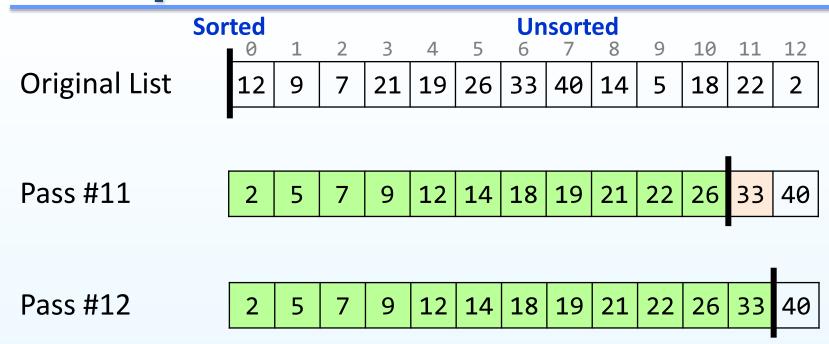








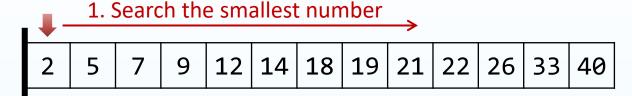






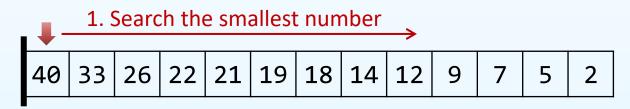
Time Complexity Analysis

Best case



$$T(n) = n + (n-1) + (n-2) + \dots + 3 + 2 = \frac{n(n+1)}{2} - 1 = \Omega(n^2)$$

Worst case



$$T(n) = n + (n-1) + (n-2) + \dots + 3 + 2 = \frac{n(n+1)}{2} - 1 = O(n^2)$$

Average case

$$T(n) = \Theta(n^2)$$





Extra Space Requirement

- Selection sort is an in-place algorithm
- It performs all computation in the original array and no other array is used
- Hence, the extra space works out to be O(1)



Important Notes

- Selection sort is not a very efficient algorithm when data set are large
 - This indicated by the average and worst case complexities
- However, selection sort uses minimum number of swap operations O(n) among all the sorting algorithms
- Traditional selection sort is not a stable algorithm, but we can modify for stable one



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Insertion Sort

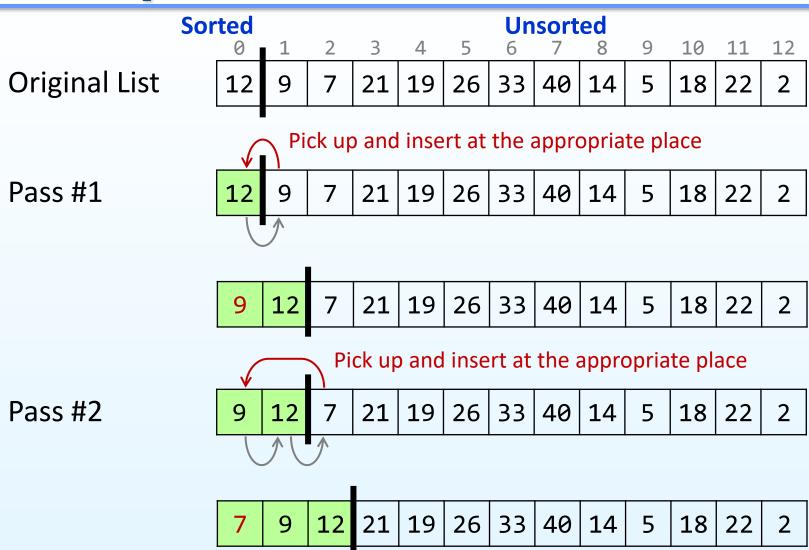
Insertion sort is the most common sorting technique used by card players

Idea:

- Partition the input list of n elements into a sorted and unsorted part
 - Initial sorted part with the first element of the list
- In each pass, the first element of the unsorted part is picked up, transferred to the sorted sub-list, and inserted at the appropriate place
- Repeat at most n-1 passes to sort the list

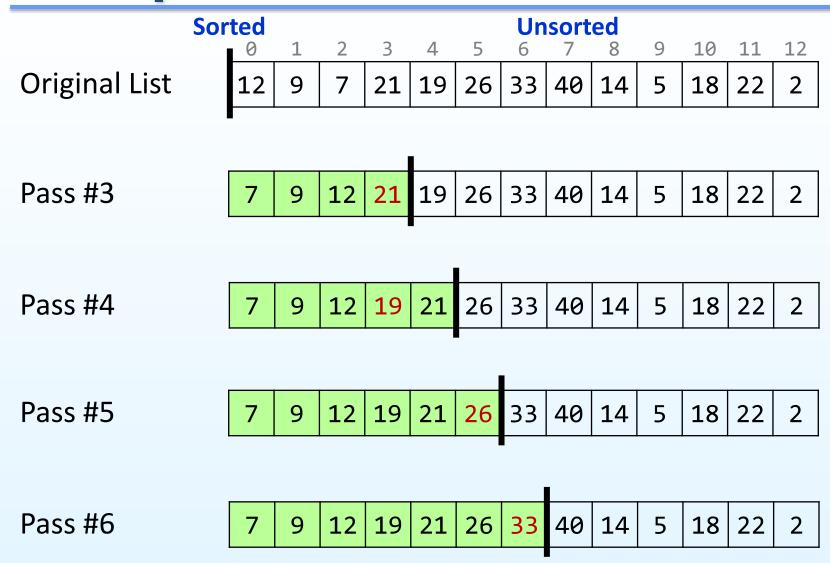












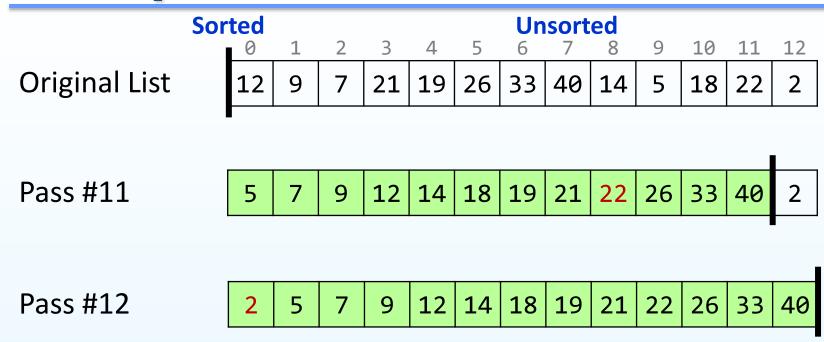








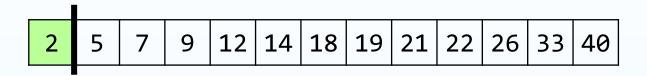






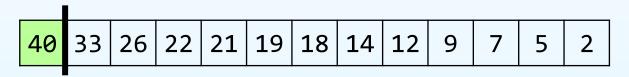
Time Complexity Analysis

Best case



$$T(n) = 1 + 1 + 1 + \dots + 1 + 1 = n - 1 = \Omega(n)$$

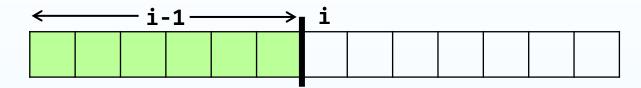
Worst case



$$T(n) = 1 + 2 + 3 + \dots + (n-2) + (n-1) = \frac{(n-1)n}{2} = O(n^2)$$

Time Complexity Analysis

Average case



Probability of placing the i^{th} element at each position 0 to i-1 is $\frac{1}{i}$

Then, the running time of placing the i^{th} element is

$$1 \cdot \frac{1}{i} + 2 \cdot \frac{1}{i} + 3 \cdot \frac{1}{i} + \dots + i \cdot \frac{1}{i} = \frac{1}{i} \sum_{j=1}^{i} j$$

Therefore, the average running time for n elements of the list is

$$T(n) = \sum_{i=1}^{n} \frac{1}{i} \sum_{j=1}^{i} j = \sum_{i=1}^{n} \frac{1}{i} \cdot \frac{i(i+1)}{2} = \frac{1}{2} \left(\frac{n(n+1)}{2} + n \right) = \Theta(n^2)$$



Extra Space Requirement

- Insertion sort is an in-place algorithm
- It performs all computation in the original array and no other array is used
- Hence, the extra space works out to be O(1)



Important Notes

- Insertion sort is not a very efficient algorithm when data set are large
 - This indicated by the average and worst case complexities
- However, insertion sort is adaptive, and number of comparisons are less if array is partially sorted



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Bubble Sort

Bubble sort is the easiest sorting algorithm; it inspired by observing the behavior of air bubbles over foam

Idea:

- Use n-1 passes through a list
- In each pass,
 - Compare the adjacent elements of the list
 - Swap the two elements if they are in the wrong order
 - Place the next largest element to its proper position



Original List

_	0	1	2	3	4	5	6	7	8	9	10	11	12
	12	9	7	21	19	26	33	40	14	5	18	22	2
_				r				,					
	12 [*]	* 9	7	21	19	26	33	40	14	5	18	22	2
	9	12	₹7	21	19	26	33	40	14	5	18	22	2
	9	7	12	21	19	26	33	40	14	5	18	22	2
	9	7	12	21	19	26	33	40	14	5	18	22	2
	9	7	12	19	21	26	33	40	14	5	18	22	2
	9	7	12	19	21	26	33	40	14	5	18	22	2
	9	7	12	19	21	26	33	40	14	5	18	22	2
	9	7	12	19	21	26	33	40	14	5	18	22	2
	9	7	12	19	21	26	33	14	40	₹5	18	22	2
	9	7	12	19	21	26	33	14	5	40	18	22	2
	9	7	12	19	21	26	33	14	5	18	40	22	2
	9	7	12	19	21	26	33	14	5	18	22	40	₹2
70	9	7	12	19	21	26	33	14	5	18	22	2	40





Original List

0	1	2	3	4	5	6	7	8	9	10	11	12
12	9	7	21	19	26	33	40	14	5	18	22	2
9 ₹	₹7	12	19	21	26	33	14	5	18	22	2	40
7	9	12	19	21	26	33	14	5	18	22	2	40
7	9	12	19	21	26	33	14	5	18	22	2	40
7	9	12	19	21	26	33	14	5	18	22	2	40
7	9	12	19	21	26	33	14	5	18	22	2	40
7	9	12	19	21	26	33	14	5	18	22	2	40
7	9	12	19	21	26	33 [*]	14	5	18	22	2	40
7	9	12	19	21	26	14	33	₹ 5	18	22	2	40
7	9	12	19	21	26	14	5	33	18	22	2	40
7	9	12	19	21	26	14	5	18	33	22	2	40
7	9	12	19	21	26	14	5	18	22	33	₹ 2	40
7	9	12	19	21	26	14	5	18	22	2	33	40



Original List

0	1	2	3	4	5	6	7	8	9	10	11	12
12	9	7	21	19	26	33	40	14	5	18	22	2
7	9	12	19	21	26	14	5	18	22	2	33	40
7	9	12	19	21	26	14	5	18	22	2	33	40
7	9	12	19	21	26	14	5	18	22	2	33	40
7	9	12	19	21	26	14	5	18	22	2	33	40
7	9	12	19	21	26	14	5	18	22	2	33	40
7	9	12	19	21	26	14	5	18	22	2	33	40
7	9	12	19	21	14	26	₹ 5	18	22	2	33	40
7	9	12	19	21	14	5	26	18	22	2	33	40
7	9	12	19	21	14	5	18	26	22	2	33	40
7	9	12	19	21	14	5	18	22	26	2	33	40
7	9	12	19	21	14	5	18	22	2	26	33	40



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Pass #4

Pass #5

Pass #6

Pass #7

Pass #8

Pass #9

Pass #10

Pass #11

0	1	2	3	4	5	6	7	8	9	10	11	12
12	9	7	21	19	26	33	40	14	5	18	22	2
		4.2	40	4.4	_	10	24		22	26	2.2	40
_ 7	9	12	19	14	5	18	21	2	22	26	33	40
7	9	12	14	5	18	19	2	21	22	26	33	40
7	9	12	5	14	18	2	19	21	22	26	33	40
7	9	5	12	14	2	18	19	21	22	26	33	40
7	5	9	12	2	14	18	19	21	22	26	33	40
5	7	9	2	12	14	18	19	21	22	26	33	40
5	7	2	9	12	14	18	19	21	22	26	33	40
5	2	7	9	12	14	18	19	21	22	26	33	40
2	5	7	9	12	14	18	19	21	22	26	33	40



Time Complexity Analysis

Best case

$$T(n) = (n-1) + (n-2) + \dots + 3 + 2 + 1 = \frac{(n-1)n}{2} = \Omega(n^2)$$

Better implementation

```
for pass ← 1 to n-1 do
    sorted = true
    for i ← 1 to n-pass do
        if (arr[i-1] > arr[i]) then
            swap(arr[i-1], arr[i])
            sorted = false
        if sorted then
            break
```

$$T(n) = (n-1) = \Omega(n)$$





Time Complexity Analysis

Worst case

$$T(n) = (n-1) + (n-2) + \dots + 3 + 2 + 1 = \frac{n(n+1)}{2} - 1 = O(n^2)$$

Average case

$$T(n) = \Theta(n^2)$$



Extra Space Requirement

- Bubble sort is an in-place algorithm
- It performs all computation in the original array and no other array is used
- Hence, the extra space works out to be O(1)



Important Notes

- Bubble sort is beneficial when
 - Array elements are less, and
 - The array is nearly sorted



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Merge Sort

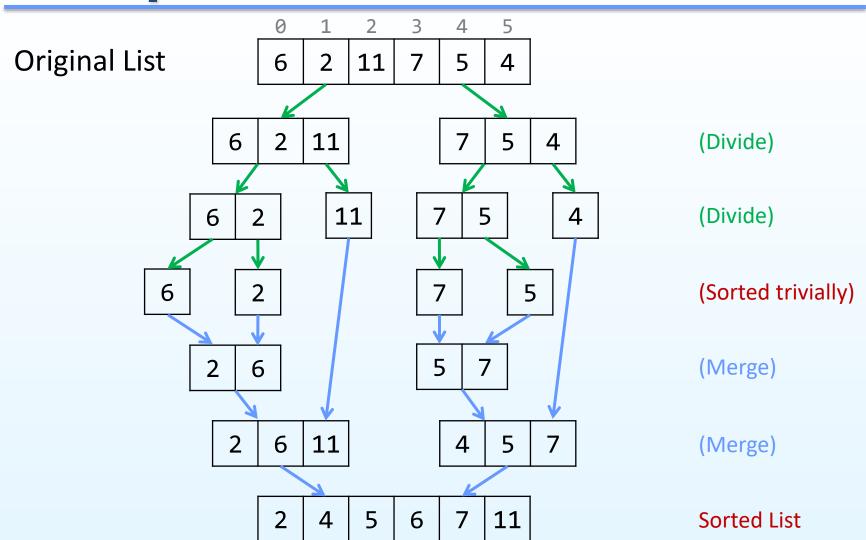
Merge sort uses a divide and conquer paradigm for sorting

Idea:

The algorithm is defined recursively:

- If the list is of size 1, it is sorted—we are done
- Otherwise,
 - 1. Divide an unsorted list into two sub-lists, and sort each sub-list recursively using merge sort
 - 2. Merge the two sorted sub-lists into a single sorted list

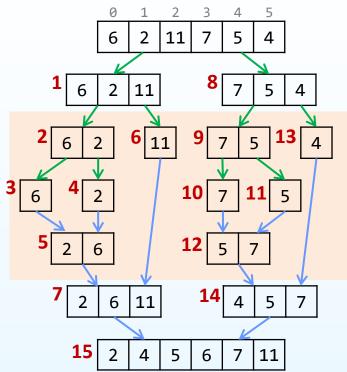








Implementation



```
void merge_sort(int arr[], int 1, int r) {
   int m;
   if (1 < r) {
        m = 1 + (r-1)/2;
        merge_sort(arr, 1, m);
        merge_sort(arr, m+1, r);
        merge(arr, 1, m, r);
   }
}</pre>
```

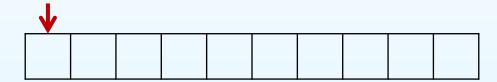


Merging Two Lists

- Consider the two sorted arrays and an empty array
- Define three indices at the start of each array
- Method: compare and copy the least value

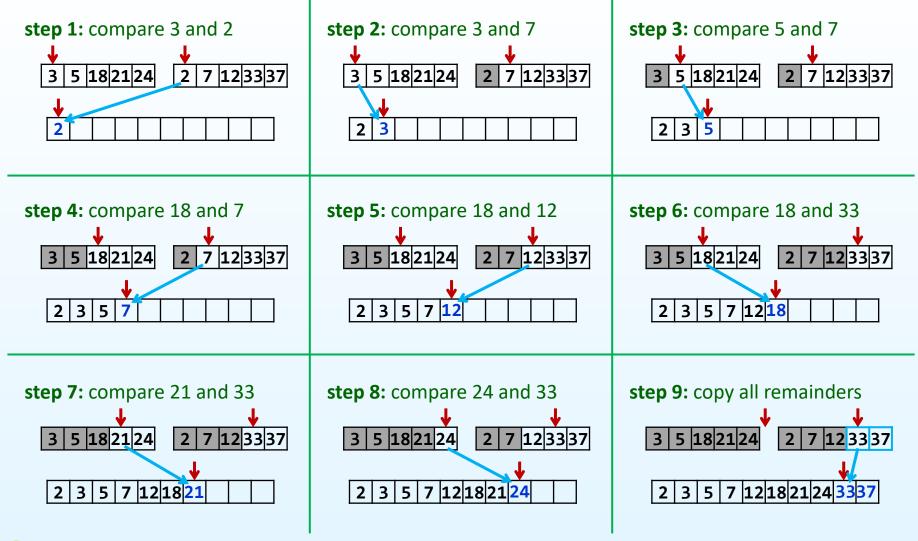








Merging Two Lists







The merge() Function

```
void merge sort(int arr[], int l, int r) {
 int m;
 if (1 < r) {
   m = 1 + (r-1)/2;
   merge_sort(arr, 1, m);
   merge sort(arr, m+1, r);
   merge(arr, 1, m, r);
                  |11| 7
              11
                11
          2
                              5 7
           6 11
```

```
l m r r arr 2 6 11 4 5 7 → L 2 6 11 R 4 5 7

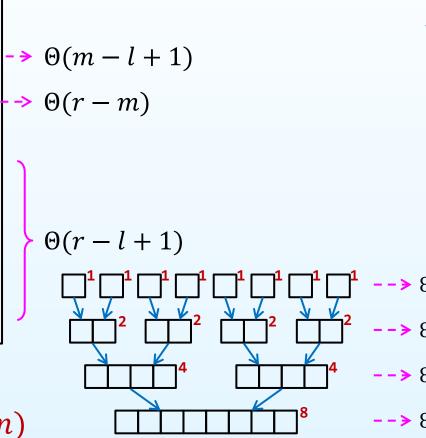
→ arr ? ? ? ? ? ?
```

```
void merge(int arr[], int l, int m, int r) {
  int i, j, k;
  int nl = m-l+1, L[nl];
  int nr = r-m, R[nr];
  // Copy data to temporary L and R arrays
  for (i=0; i<nl; i++)
    L[i] = arr[l+i];
  for (j=0; j<nr; j++)</pre>
    R[j] = arr[m+1+j];
  // Merge the L and R arrays back into arr
  i = 0; i = 0; k = 1;
  while (i < nl && j < nr)</pre>
    arr[k++] = (L[i] < R[j])? L[i++] : R[j++];
  // Copy the remaining elements, if any
  while (i < nl)</pre>
    arr[k++] = L[i++];
  while (j < nr)</pre>
    arr[k++] = R[j++];
```

Analysis of Merging

```
void merge(int arr[], int l, int m, int r) {
  int i, j, k;
  int nl = m-l+1, L[nl];
 int nr = r-m, R[nr];
 // Copy data to temporary L and R arrays
 for (i=0; i<nl; i++)
    L[i] = arr[l+i]; -----
 for (j=0; j<nr; j++)
   R[j] = arr[m+1+j]; -----
 // Merge the L and R arrays back into arr
  i = 0; i = 0; k = 1;
 while (i < nl \&\& j < nr)
   arr[k++] = (L[i] <= R[j])? L[i++] : R[j++];
 // Copy the remaining elements, if any
 while (i < nl)</pre>
   arr[k++] = L[i++];
 while (j < nr)</pre>
   arr[k++] = R[j++];
```

Merging n elements takes $\Theta(n)$ Memory requirements are also $\Theta(n)$





Time Complexity Analysis

Recurrence relation:

$$T(n) = 2T\left(\frac{n}{2}\right) + \Theta(n)$$

 $=\Theta(n\log n)$ for all best, worst, and average cases



Extra Space Requirement

- Merge sort use additional memory for left and right subarrays
- Hence, the extra space works out to be $\Theta(n)$

Important Notes

- Merge sort uses a divide and conquer paradigm
- Merge sort is a recursive sorting algorithm
- Merge sort is a stable sorting algorithm
- Merge sort is not an in-place sorting algorithm



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Quick Sort

Quick sort uses a divide and conquer paradigm for sorting

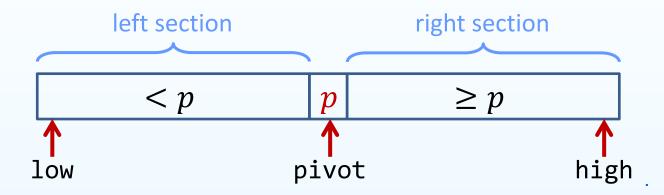
Idea:

- 1. First, select a pivot element
- 2. Partition the list into two parts (elements smaller than and greater than or equal to the pivot)
- 3. Then, sort each part independently (recursively)
- Finally, combine the sorted subsequences by a simple concatenation



Partition

 Partitioning places the pivot in its correct position within the sorted list



- Arranging the elements around the pivot p generates two smaller sorting problems:
 - Sort the left section and the right section
 - When these two smaller sorting problems are solved recursively, our bigger sorting problem is solved

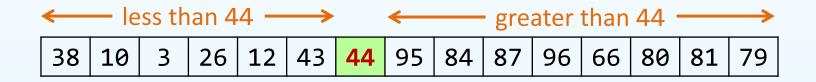




Partition

For example, given

we can select the middle entry (44) as pivot, and sort the remaining entries into two sections:



Notice that 44 is now in the correct location if the list was sorted

 Proceed by applying the sorting algorithm recursively to the left and right sections independently



The quick_sort() Function

problem of size n

80	38	95	84	66	10	79	44	26	87	96	12	43	81	3
				l				l				l		1



38	10	3	26	12	43	44	95	84	87	96	66	80	81	79
		_			. –			•						

sub-problem of size n_l

sub-problem of size n_r

```
void quick_sort(int arr[], int low, int high) {
  int pivot;
  if (low < high) {
    pivot = partition(arr, low, high);
    quick_sort(arr, low, pivot-1);
    quick_sort(arr, pivot+1, high);
  }
}</pre>
```



Pivot Selection

For example, given

If we select 44 (the middle element) as pivot, we get:

38	10	3	26	12	43	44	94	84	84	96	66	80	81	79
				l			1					l		

If we select 10 (randomly) as pivot, we get:

3	10	95	84	66	80	79	44	26	87	96	12	43	81	38
---	----	----	----	----	----	----	----	----	----	----	----	----	----	----

If we select 66 (randomly) as pivot, we get:

38	3	10	44	26	12	43	66	80	87	96	95	79	81	84
	_)							



Pivot Selection

Somehow, we have to select a pivot, and we hope that we will get a good partitioning:

- We can choose a pivot randomly, or
- We can choose the first element as the pivot, or
- We can choose the middle element as the pivot, or
- We can choose the last element as the pivot, or
- We can use a combination of the above criterions, or
- ...





Pivot Selection: Median-of-Three

- If we know the median of the elements, we will get the perfect partition
- However, it is difficult to find the median
- So consider another strategy:
 - Choose the median of the first, middle, and last elements
- This will usually give a better approximation of the actual median

44 is selected since it is the median of 80, 44, and 3



Pivot Selection: Median-of-Three







Select 38 for partitioning the left sub-list

Select 95 for partitioning the right sub-list

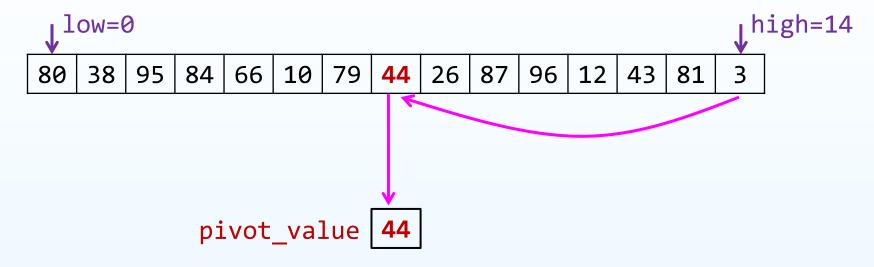






- First, find a pivot
 - Using the median-of-three method, we get 44

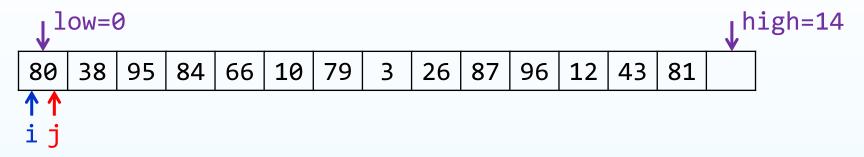




- Copy the pivot value to a temporary memory
- Replace the pivot with the last element



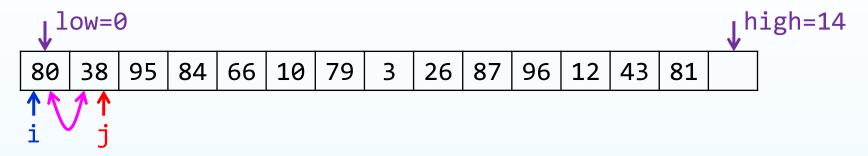
We call quick_sort(arr, 0, 14)



We define the blue i and red j indices to indicate elements that are greater than and less than the pivot, respectively

Start i and j at low

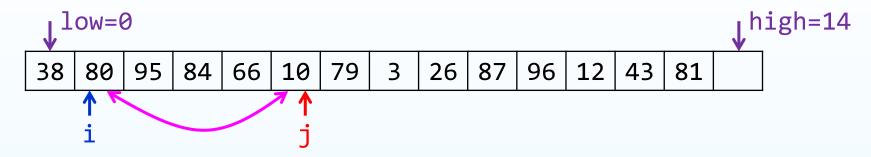




- Move j up to until finding the next element that is less than the pivot
- Swap the elements pointed by i and j
 - Then, move i up by one



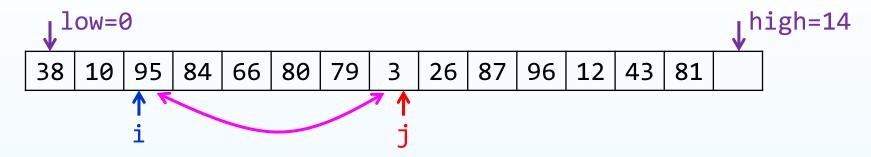




- Move j up to until finding the next element that is less than the pivot
- Swap the elements pointed by i and j
 - Then, move i up by one



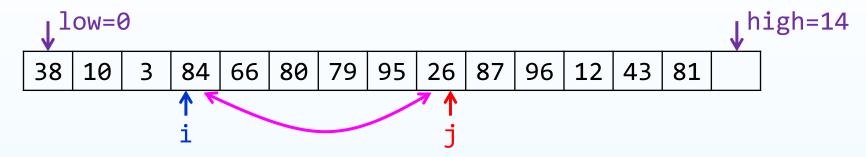




- Move j up to until finding the next element that is less than the pivot
- Swap the elements pointed by i and j
 - Then, move i up by one



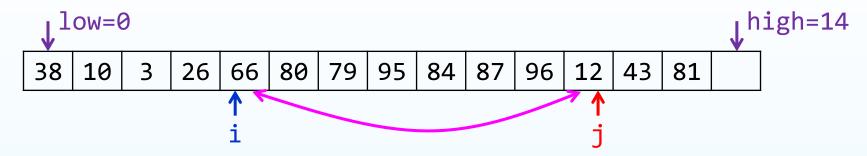




- Move j up to until finding the next element that is less than the pivot
- Swap the elements pointed by i and j
 - Then, move i up by one



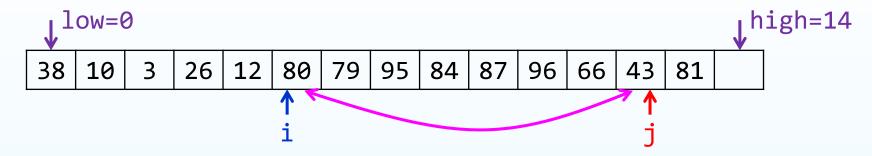




- Move j up to until finding the next element that is less than the pivot
- Swap the elements pointed by i and j
 - Then, move i up by one



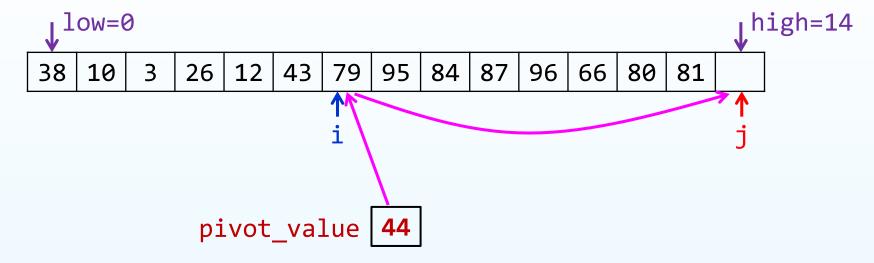




- Move j up to until finding the next element that is less than the pivot
- Swap the elements pointed by i and j
 - Then, move i up by one



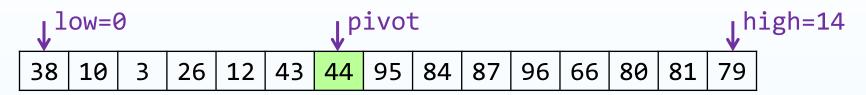




- Move j up to until finding the next element that is less than the pivot
 - However, the iteration will be terminated when j reaches high
- Afterwards, move the element pointed by i to the end
- Finally, copy the pivot value to locate at i







- We get the correct location of the pivot in the sorted list
 - Partitioning returns pivot
 - The list is divided into the left and right sub-lists
- We then call quick_sort(arr, low, pivot-1) and quick_sort(arr, pivot+1, high) to sort each partition separately





The partition() Function

```
_high=14
                       | pivot
 low=0
                          95
                             84
                                 87
                                         66
                                             80
                                                 81
38
   10
        3
           26
              12
                  43
                      44
                                     96
```

```
int partition(int arr[], int low, int high) {
 // Select a pivot (may use the median-of-three method)
  int pivot = find pivot(arr, low, high);
  int i = low, j = low;
 // Temporarily store the pivot value at the end of the array
  swap(&arr[pivot], &arr[high]);
 for (j=low; j<high; j++) {</pre>
    // If found smaller element, swap it with the current greater element
    if (arr[j] < arr[high])</pre>
      swap(&arr[i++], &arr[j]); // Increment i by one after swapping
  // Move the pivot value back to the correct position, return that index
  swap(&arr[i], &arr[high]);
  return i; // Return the pivot index
```

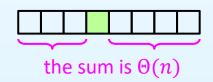




Analysis of Partitioning

```
int partition(int arr[], int low, int high) {
  // Select a pivot (may use the median-of-three method)
  int pivot = find_pivot(arr, low, high); -----
  int i = low, j = low;
  // Temporarily store the pivot value at the end of the array
  swap(&arr[pivot], &arr[high]);
  for (j=low; j<high; j++) {</pre>
    // If found smaller element, swap it with the current greater element
    if (arr[j] < &arr[high])</pre>
      swap(&arr[i++], &arr[j]); // Increment i by one after swapping
  // Move the pivot value back to the correct position, return that index
  swap(&arr[i], &arr[high]);
  return i; // Return the pivot index
```

Partitioning n elements takes $\Theta(n)$







Time Complexity Analysis

```
void quick_sort(int arr[], int first, int last) {
  int pivot;
  if (first < last) {
    pivot = partition(arr, first, last)
    quick_sort(arr, first, pivot-1);
    quick_sort(arr, pivot+1, last);
  }
}</pre>
```

Best case

$$T(n) = 2T\left(\frac{n}{2}\right) + \Theta(n) = \Omega(n\log n)$$

Worst case

$$T(n) = T(0) + T(n-1) + \Theta(n) = O(n^2)$$

Average case

$$T(n) = \Theta(n \log n)$$





Any Question?



