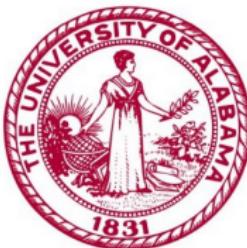


Probabilistic tsunami hazard maps for the western US coastline

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Introduction

Tsunami: a series of waves induced by vertical displacement of ocean water

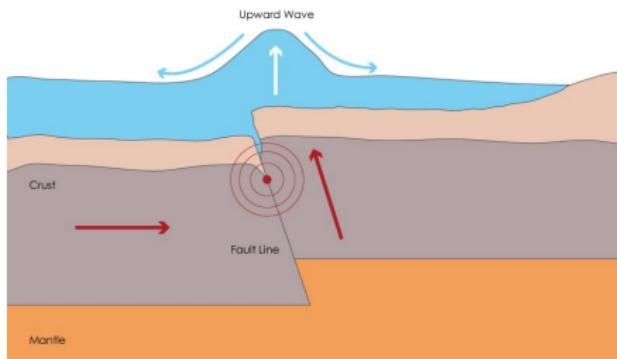


Figure 1: Schematic of tsunami generation due to a submarine earthquake.



Figure 2: Crescent City (California) harbor after the 2011 Tohoku tsunami.

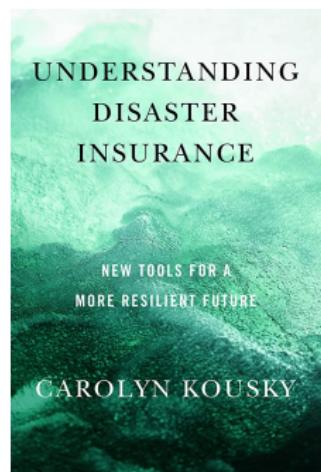
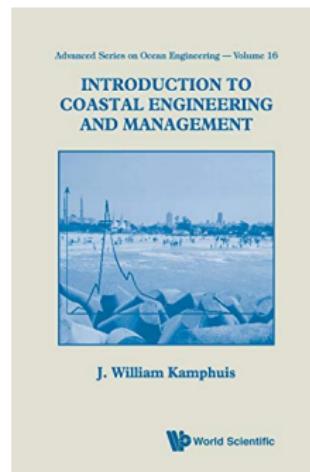
Introduction

Quantifying tsunami hazard means providing the answer to the question:

"What is the probability that we observe a tsunami height of X meters close to the shore?"

Why is this important?

- Coastal defenses, e.g., seawalls, breakwaters, etc.
- Flood insurance policies



Introduction

For a location of interest where empirical tsunami data exist:

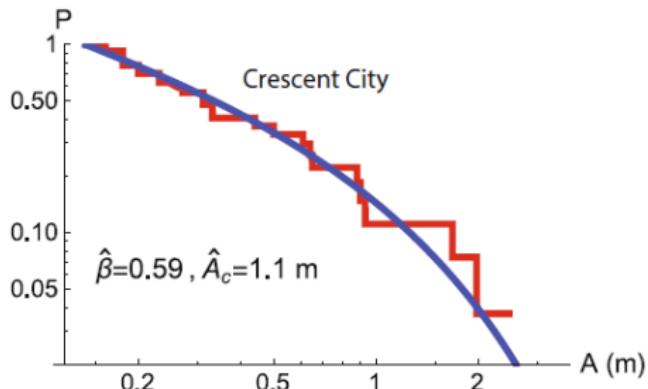


Figure 3: Tapered Pareto distribution for observed tsunami amplitude data at Crescent City (from Geist and Parsons, 2016).

Tsunamis are rare - for most cases only a few events have been recorded!

Introduction

An alternative: numerical physics-based simulation of earthquake, tsunami generation and propagation

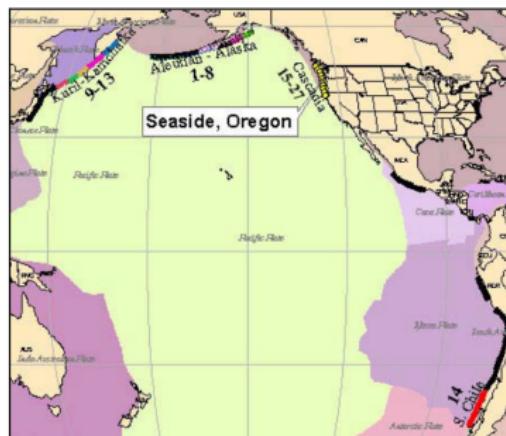
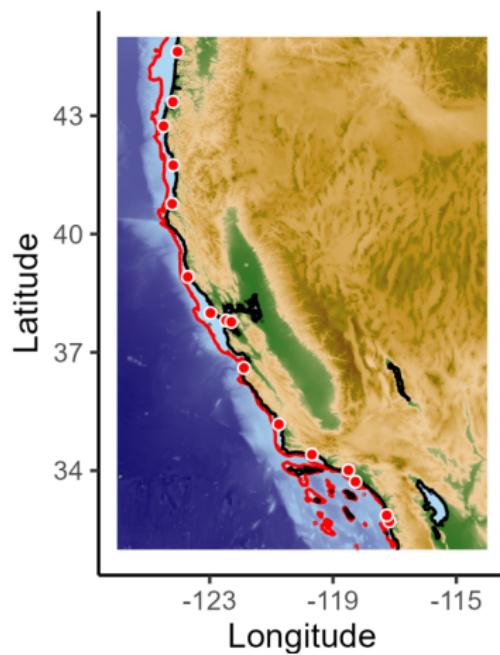


Figure 4: Numerical tsunami model domain for Seaside, Oregon (from Wong et al., 2005).

Tedious and time-consuming task...

This work

Instead... a spatial Bayesian hierarchical model to map tsunami hazard for the West Coast



Data & Pre-processing

Tsunami amplitude observations were retrieved from NOAA's (National Oceanic and Atmospheric Administration) Global Historical Tsunami Database



- Events are between **1900-2021**
- Source validity is **definite tsunami**
- Cause of tsunami is **earthquake**
- Entry is **not doubtful**
- Tide gauges with **at least 10** such events

Figure 5: Tide gauge used for measuring sea levels.

Methodology

A two-level hierarchical model:

$$\eta_{ij} \stackrel{iid}{\sim} TP(\beta_j, \theta_j), \quad (1)$$

for $i = 1, \dots, n_j$ and $j = 1, \dots, J = 16$ (number of stations). TP stands for Tapered Pareto with cumulative distribution function:

$$F(\eta; \beta, \theta) = 1 - \left(\frac{u}{\eta} \right)^\beta \exp \left(\frac{u - \eta}{\theta} \right) \quad (2)$$

where $u > 0$ is the minimum value of amplitude variable η , i.e., the threshold of record completeness, $\beta > 0$ is the shape parameter, and $\theta \geq u$ is the upper cutoff parameter.

$$\beta \sim G_{\gamma_\beta}, \text{ and } \theta \sim G_{\gamma_\theta} \quad (3)$$

Parameters $\beta = (\beta_1, \dots, \beta_J)'$ and $\theta = (\theta_1, \dots, \theta_J)'$ are assumed to follow probability distributions $G_{\gamma_\beta}(\cdot)$ and $G_{\gamma_\theta}(\cdot)$ which can facilitate information sharing across stations.

Methodology (hierarchical Bayes' rule)

$$\underbrace{p(\beta, \theta, \gamma | \eta)}_{\text{posterior}} \propto \underbrace{p(\eta | \beta, \theta) p(\beta | \gamma_\beta) p(\theta | \gamma_\theta)}_{\text{likelihood}} \underbrace{p(\gamma_\beta) p(\gamma_\theta)}_{\text{prior}},$$

where

$$\begin{aligned} p(\eta | \beta, \theta) &= \prod_{j=1}^J \prod_{i=1}^{n_j} f(\eta_{ij} | \beta_j, \theta_j), \\ p(\beta | \gamma_\beta) &= f_N(\beta; \mathbf{m}_\beta, \mathbf{K}_\beta), \\ p(\theta | \gamma_\theta) &= f_N(\theta; \mathbf{m}_\theta, \mathbf{K}_\theta), \end{aligned}$$

while f_N is the **Multivariate Normal** density. The covariance matrices are of the form:

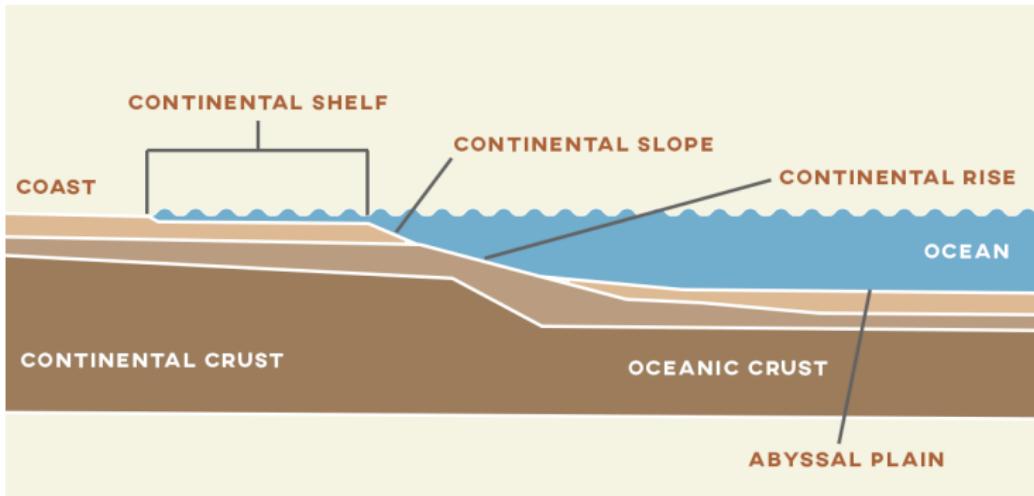
$$\mathbf{K}_{(i,j)} = \alpha^2 \exp \left(-\frac{|d_{ij}|}{\rho} \right) \quad (4)$$

whereas the mean vectors are expressed as:

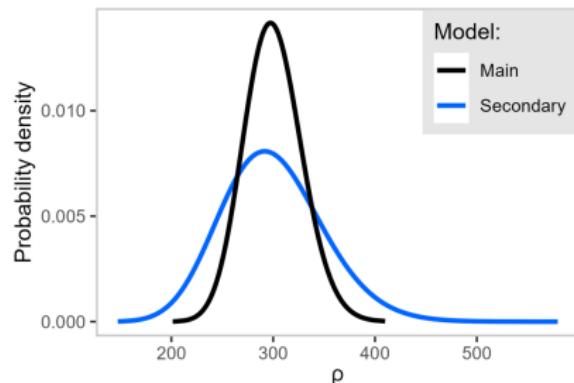
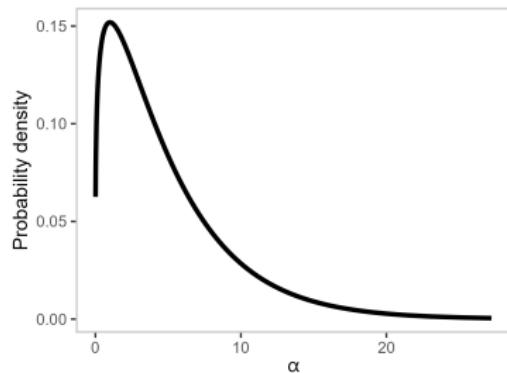
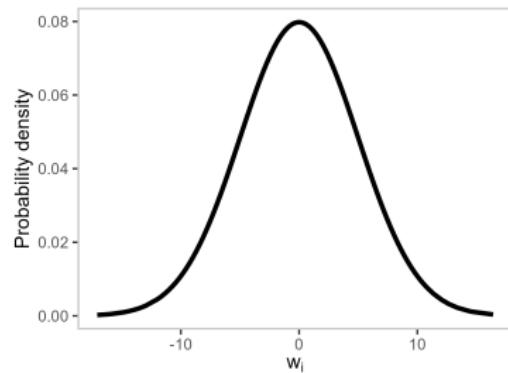
$$\mathbf{m} = w_0 + w_1 \mathbf{y_1} + \cdots + w_q \mathbf{y_q} \quad (5)$$

Methodology (covariates)

$q = 3$, i.e., z-scores of **Latitude**, **Longitude**, and width of the **Continental Shelf**



Methodology (priors)



Stan Application

```
functions{
    // Function to return Tapered Pareto log-likelihood for (log-)b and (log-)ac parameterization
    real tp_lpdf(vector y, real u, real b, real ac) {
        vector[rows(y)] lp;
        real loglike;
        int N;

        N = rows(y);

        for(i in 1:N){
            lp[i] = log(exp(b) / y[i] + 1 / exp(ac));
        }
        loglike = sum(lp) + exp(b) * N * log(u) - exp(b) * sum(log(y)) + (u * N) / exp(ac) - 1 / exp(ac) * sum(y);
        return(loglike);
    }
}

transformed parameters{
    // mean function for b
    vector[M] gfb = w0b * x[, 1] + w1b * x[, 2] + w2b * x[, 3] + w3b * x[, 4];

    // mean function for ac
    vector[M] gfac = w0ac * x[, 1] + w1ac * x[, 2] + w2ac * x[, 3] + w3ac * x[, 4];

    // covariance matrix for b and its Cholesky decomposition
    matrix[M, M] Kb = kernel(M, dist, ab, rhob);
    matrix[M, M] Lb = cholesky_decompose(Kb);

    // covariance matrix for ac and its Cholesky decomposition
    matrix[M, M] Kac = kernel(M, dist, aac, rhoac);
    matrix[M, M] Lac = cholesky_decompose(Kac);

    // non-centered parameterization
    vector[M] b = gfb + Lb * zb;
    vector[M] ac = gfac + Lac * zac;
}
```

Maps

Sampling for unmonitored sites:

$$\boldsymbol{\beta}_{v^*} | \boldsymbol{\beta}_v \sim MVN_{s-16}, (\bar{\boldsymbol{\beta}}_{v^*}, \bar{\boldsymbol{K}}_{\boldsymbol{\beta}_{v^*}})$$

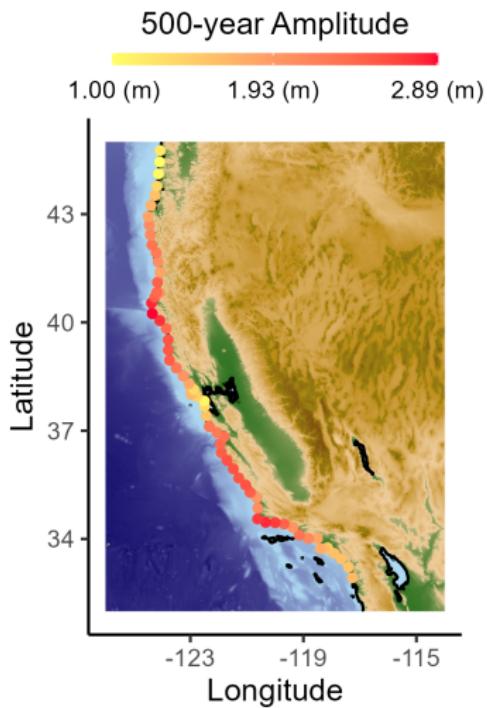
$$\bar{\boldsymbol{\beta}}_{v^*} = \mathbf{m}_{\boldsymbol{\beta}_{v^*}} + \boldsymbol{K}_{\boldsymbol{\beta}_{v,v^*}} \times \boldsymbol{K}_{\boldsymbol{\beta}_v}^{-1} \times (\boldsymbol{\beta}_v - \mathbf{m}_{\boldsymbol{\beta}_v})$$

$$\bar{\boldsymbol{K}}_{\boldsymbol{\beta}_{v^*}} = \boldsymbol{K}_{\boldsymbol{\beta}_{v^*}} - \boldsymbol{K}_{\boldsymbol{\beta}_{v,v^*}} \times \boldsymbol{K}_{\boldsymbol{\beta}_v}^{-1} \times \boldsymbol{K}_{\boldsymbol{\beta}_{v,v^*}}$$

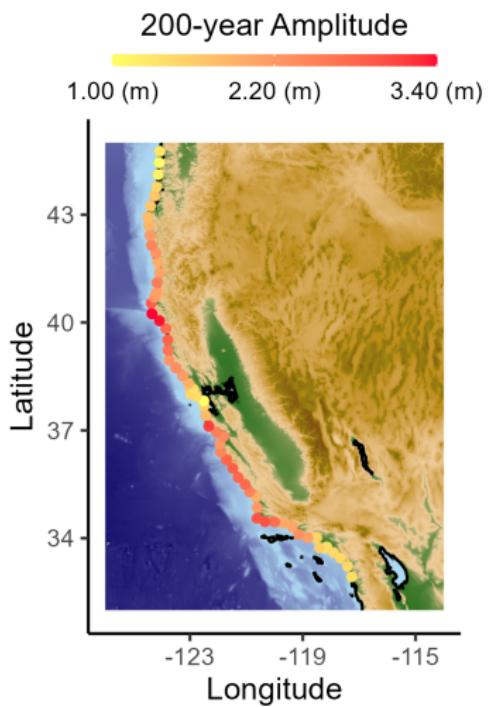
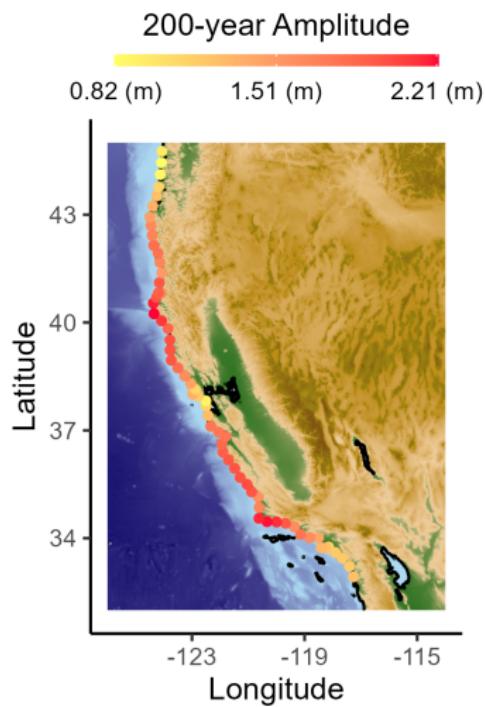
From probability to “return period (T)”:

$$T = \frac{1}{\lambda p} = \frac{\tau}{p}$$

where τ is the mean interarrival time.



More maps...



Future research

So far:

$$K_{(i,j)} = \alpha^2 \exp\left(-\frac{|d_{ij}|}{\rho}\right)$$

$$p(\boldsymbol{\eta} \mid \boldsymbol{\beta}, \boldsymbol{\theta}) = \prod_{j=1}^J \prod_{i=1}^{n_j} f(\eta_{ij} \mid \beta_j, \theta_j)$$

Preferably, we want:

- Anisotropic kernel
- Copulas

