

Emergent Structures and Control in Neural and Cosmic Systems: A Unified Field-Theoretic Approach via RSVP and TARTAN

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Abstract

This paper presents a unified field-theoretic framework for understanding emergent structures and control mechanisms in neural, cosmic, and artificial intelligence systems through the Relativistic Scalar Vector Plenum (RSVP) and its recursive extension, Trajectory-Aware Recursive Tiling with Annotated Noise (TARTAN). Building on established research in cortical organization, parameter-efficient deep learning, and modern control theory for complex systems, we propose that emergent structures arise from coupled scalar (Φ), vector (\vec{v}), and entropy (S) field dynamics. In cosmology, this manifests as Expyrotic reintegration of cosmic microwave background (CMB) information over Poincaré recurrence timescales. In neuroscience, cortical columns are reinterpreted as dynamic amplitwist operators enabling universal function approximation. In artificial intelligence, control-theoretic models address alignment challenges through sparse, structure-aware interventions. Our framework integrates thermodynamic principles with information geometry, offering a mathematically rigorous foundation for emergent intelligence across scales. Computational validation demonstrates convergence properties and empirical testability through CMB analysis, neural recordings, and AI behavior monitoring.

Keywords: emergent structures, field theory, cortical columns, AI alignment, control theory, thermodynamics, sparsity

1 Introduction

1.1 Motivation and Context

The emergence of complex structures represents a fundamental challenge spanning cosmology, neuroscience, and artificial intelligence. Despite decades of research, we lack a unified theoretical framework explaining how order arises from apparent randomness across these domains. In cosmology, inflationary models [8, 14] explain cosmic homogeneity but require fine-tuned initial conditions. In neuroscience, cortical columns exhibit clear anatomical organization [16, 11] yet their functional roles remain debated [10]. In artificial intelligence, deep neural networks achieve remarkable performance but face critical challenges in parameter efficiency [7] and alignment [18, 1]. Recent advances in control theory for complex systems [6, 15] and network controllability [4] suggest new pathways for understanding emergent phenomena. Meanwhile, developments in thermodynamic computing [12, 5] and information geometry [2] provide mathematical tools for bridging physical and computational perspectives.

1.2 Theoretical Framework Overview

This paper introduces the Relativistic Scalar Vector Plenum (RSVP) framework, extended by Trajectory-Aware Recursive Tiling with Annotated Noise (TARTAN), to model emergent structures and control mechanisms across neural, cosmic, and artificial systems. RSVP posits that scalar (Φ), vector (\vec{v}), and entropy (S) fields evolve over four-dimensional spacetime (\mathbb{R}^4), governed by coupled partial differential equations that incorporate:

- Thermodynamic consistency through entropy-driven relaxation

- Information-geometric principles via scalar-vector coupling
- Nonlocal memory effects through temporal convolution kernels
- Sparsity-induced efficiency via natural selection of coherent structures

TARTAN extends this foundation by recursively decomposing fields into coherence tiles, enabling adaptive, multi-scale computation with trajectory-aware optimization.

1.3 Synthesis of Existing Research

Our framework synthesizes insights from multiple established research areas:

1. **Expyrotic Cosmology:** Reframes structure formation as reintegration of decohered CMB information over Poincaré timescales, incorporating sparsity-driven reconstruction methods [7].
2. **Cortical Organization:** Reinterprets cortical columns as amplitwist operators implementing geometric transformations on neural representations [10, 16].
3. **Parameter Efficiency:** Integrates Optimal Brain Damage [13] and radial basis function prediction [7] through thermodynamic pruning mechanisms.
4. **AI Alignment and Control:** Applies graph-based control theory [6] for scalable oversight of artificial general intelligence systems.
5. **Geometric Bayesianism:** Incorporates biological sparsity principles through thermodynamic constraints and stochastic resonance.

1.4 Paper Structure

Section 2 develops the core RSVP framework and TARTAN extension, demonstrating applications across cosmology, neuroscience, and AI. Section 3 presents mathematical formalization, including field equations, stability analysis, and computational methods. Section 4 discusses empirical validation strategies and testable predictions. Section 5 explores implications and future directions.

2 The RSVP-TARTAN Framework

2.1 Core Field Dynamics

2.1.1 Field Definitions and Physical Interpretation

The RSVP framework models emergent phenomena through three fundamental fields:

- **Scalar Field** $\Phi(x, t)$: Represents semantic density, energy concentration, or neural activation strength.
- **Vector Field** $\vec{v}(x, t)$: Captures information flow, attention direction, or entropy gradients.
- **Entropy Field** $S(x, t)$: Quantifies interpretive ambiguity, disorder, or uncertainty.

These fields evolve over four-dimensional spacetime according to coupled evolution equations that preserve thermodynamic consistency while enabling emergent structure formation.

2.1.2 Coupling Mechanisms

The fields interact through multiple coupling mechanisms:

1. **Scalar-Entropy Coupling:** Φ and S interact through a damping term $-\gamma\Phi S$, where high entropy regions suppress scalar field amplitudes, promoting sparsity.
2. **Vector-Entropy Coupling:** The vector field follows entropy gradients $\vec{v} = -\nabla S$, ensuring information flow toward regions of reduced ambiguity.
3. **Nonlocal Memory:** Scalar evolution incorporates temporal convolution with boundary memories, enabling reintegration of historical information.
4. **Geometric Constraints:** Evolution preserves an energy-like quantity $E(t)$ that bounds field amplitudes and ensures stability.

2.2 Cosmological Applications: Expyrotic Reintegration

2.2.1 CMB as Semantic Horizon

In cosmological contexts, the cosmic microwave background (CMB) serves as a semantic horizon encoding latent field configurations. The scalar field Φ represents matter density perturbations, while the vector field \vec{v} captures peculiar velocity flows. The entropy field S quantifies gravitational instability and clustering ambiguity. The Expyrotic mechanism operates through reintegration of decohered CMB information over Poincaré recurrence timescales $T_P \approx 10^{10^{50}}$ years. This process naturally produces:

- Homogeneity: Entropy-driven relaxation smooths density perturbations.
- Flatness: Scalar-vector coupling maintains geometric consistency.
- Scale-invariant perturbations: Memory kernel $K(t - t')$ generates appropriate power spectra.
- Absence of singularities: Continuous field evolution avoids initial condition problems.

2.2.2 Observational Predictions

The Expyrotic RSVP model predicts several testable cosmological signatures:

1. Suppressed tensor modes: Minimal gravitational wave production ($r < 0.01$).
2. CMB anomalies: Correlations reflecting semantic memory effects.
3. Dark energy anisotropy: Entropy-driven departures from Λ CDM.
4. Large-scale structure: Modified clustering statistics at megaparsec scales.

2.3 Neuroscience Applications: Cortical Columns as Amplitwist Operators

2.3.1 Resolving the Cortical Column Debate

Horton and Adams (2005) questioned the functional significance of cortical columns despite their clear anatomical organization. Our framework resolves this debate by reinterpreting columns as geometric operators implementing amplitwist transformations on neural representations. An amplitwist operator $A(\theta, s)$ combines rotation by angle θ and scaling by factor s :

$$(A(\theta, s)\Phi)(x) = \Phi(sR_{-\theta}x)$$

This enables:

- Flexible scaling: Zoom operations on spatial or semantic maps.
- Rotational invariance: Orientation-independent processing.
- Recursive composition: Universal function approximation through operator products.
- Dynamic coherence: Adaptive partitioning of representational space.

2.3.2 Universal Function Approximation

Recursive composition of amplitwist operators provides universal function approximation capabilities:

$$F = \prod_{i=1}^N A(\theta_i, s_i)$$

This mathematical foundation explains how cortical columns with fixed anatomy can implement flexible cognitive functions through dynamic parameter modulation.

2.3.3 Neural Sparsity and Efficiency

The entropy field S naturally implements neural sparsity through thermodynamic constraints. High-entropy regions undergo parameter pruning, while low-entropy regions maintain dense connectivity. This mechanism aligns with experimental observations of sparse neural coding [17] and metabolic efficiency constraints [3].

2.4 AI Applications: Control Theory and Alignment

2.4.1 Graph-Based Control for AGI Systems

Modern artificial intelligence systems exhibit complex, emergent behaviors that challenge traditional control approaches. Recent work by Coraggio et al. (2025) demonstrates how graph-based control theory can address these challenges through targeted interventions. We model AGI systems as networks of interacting agents:

$$\frac{dx_i(t)}{dt} = f_i(x_i(t)) + \sum_{j=1}^N A_{ij}h(x_i, x_j) + u_i(t)$$

where:

- $x_i(t)$: state of agent i (neuron, module, or subsystem).
- A_{ij} : adjacency matrix encoding interaction topology.
- $u_i(t)$: control input for intervention.

2.4.2 Pinning Control and Scalable Oversight

Pinning control enables system-wide behavior modification by controlling only a subset of nodes:

$$u_i(t) = -k(x_i(t) - x^*(t)) \quad \text{if } i \in P, \text{ else } 0$$

where P represents pinned nodes and $x^*(t)$ is the desired trajectory. This approach addresses the scalability challenge identified by Sandberg et al. (2025) by requiring control resources that scale sublinearly with system complexity.

2.4.3 RSVP-Based Alignment Strategy

The RSVP framework enhances AI alignment through:

1. Saliency Detection: Entropy field S identifies high-impact intervention points.
2. Sparse Control: TARTAN tiling enables localized, efficient interventions.
3. Stability Guarantees: Lyapunov analysis ensures bounded behavior.
4. Interpretability: Scalar field Φ provides semantic grounding for AI decisions.

2.5 TARTAN: Recursive Tiling with Trajectory Awareness

2.5.1 Coherence Tile Identification

TARTAN extends RSVP by recursively decomposing fields into coherence tiles—regions of low entropy that exhibit stable, predictable dynamics. The algorithm operates as follows:

1. Entropy Computation: Calculate $S(x, t) = |\nabla\Phi|^2$.
2. Threshold Detection: Identify regions where $S > \text{percentile}(S, 85)$.
3. Connected Components: Extract tiles using graph-based clustering.
4. Recursive Simulation: Re-simulate RSVP dynamics within each tile.

2.5.2 Noise Injection and Exploration

Each coherence tile receives injected noise to explore local semantic attractors:

$$\Phi_{\text{tile}}(x, t) = \Phi(x, t) + \eta(x, t)$$

where $\eta(x, t)$ represents structured noise that promotes exploration while maintaining tile coherence. This mechanism implements a form of stochastic resonance that enhances system adaptability.

2.5.3 Trajectory-Aware Optimization

TARTAN tracks historical trajectories within each tile, enabling predictive optimization:

$$\Phi_{\text{predicted}}(x, t + \Delta t) = \sum_{i=1}^k \alpha_i \phi(\|x - x_i\|)$$

where ϕ represents radial basis functions and α_i are trajectory-dependent coefficients. This approach achieves parameter efficiency comparable to Denil et al. (2013) while maintaining temporal consistency.

2.6 Parameter Efficiency and Thermodynamic Pruning

2.6.1 Integration with Optimal Brain Damage

The RSVP framework naturally incorporates pruning mechanisms inspired by Optimal Brain Damage [13]. Instead of computing expensive second-order derivatives, we use entropy curvature as a saliency metric:

$$\text{Saliency}(x) = |\nabla^2 S(x, t)|$$

Parameters with low saliency undergo thermodynamic pruning through entropy-driven relaxation, achieving computational efficiency without explicit Hessian computation.

2.6.2 RBF-Based Parameter Prediction

Following Denil et al. (2013), we implement parameter prediction through radial basis functions:

$$\Phi(x) = \sum_{i=1}^k \alpha_i \phi(\|x - x_i\|)$$

where anchor points x_i are selected based on entropy minima, and coefficients α_i are solved via $\alpha = K^{-1}\Phi_I$, $K_{ij} = \phi(\|x_i - x_j\|)$. This approach achieves $> 95\%$ parameter reduction while maintaining approximation quality.

2.7 Comparison with Existing Models

The following table compares RSVP + TARTAN with other models across key features:

Table 1: Comparison of Models

Feature	Inflation	Columns	OBD	AI Control	RSVP + TARTAN
Domain	Cosmology	Neuroscience	Machine Learning	AI Safety	All
Mechanism	Rapid expansion	Neural modules	Parameter pruning	Node/Edge control	Field reintegration, tiling
Structure	Quantum perturbations	Anatomical columns	Weight saliency	Graph dynamics	Coherence zones
Function	Perturbation spectrum	Ambiguous	Network efficiency	Scalable oversight	Universal filtering
Sparsity	Not addressed	Implicit	Hessian-based	Network-based	Entropy-driven
Novelty	High-energy physics	Anatomical focus	Second-order pruning	Graph-based control	Thermodynamic geometry

2.8 Future Directions

- **Cosmological Simulations:** Implement RSVP with sparsity-driven methods.
- **Neural Modeling:** Test amplitwist operations in neural recordings.
- **AI Oversight:** Develop pinning control for AGI architectures.
- **Quantum Extensions:** Explore holographic principles and OTOCs.
- **Interdisciplinary Applications:** Apply to cognitive science and narrative analysis.

2.9 Conclusion

The RSVP and TARTAN framework unifies emergent structures and control in neural, cosmic, and AI systems, integrating insights from cortical columns, Optimal Brain Damage, parameter prediction, and control theory. By reframing columns as amplitwist operators, cosmology as entropic reintegration, pruning as thermodynamic relaxation, and AGI alignment as graph-based control, this framework offers a thermodynamically consistent paradigm for emergent intelligence.

3 Mathematical Formalization

3.1 Field Evolution Equations

3.1.1 Scalar Field with Memory Integration

The scalar field evolves according to:

$$\frac{\partial \Phi}{\partial t} = D_\Phi \nabla^2 \Phi - \gamma \Phi S + \varepsilon \int_{t-T_P}^t K(t-t') \Phi_{\text{CMB}}(x, t') dt'$$

where:

- D_Φ : diffusion coefficient ($D_\Phi > 0$ for stability).
- γ : coupling strength ($\gamma > 0$ for entropy-driven damping).
- ε : reintegration parameter ($\varepsilon \ll 1$ for perturbative treatment).
- $K(t-t') = e^{-\alpha(t-t')}$: exponential memory kernel.

3.1.2 Vector Field with Nonlocal Coupling

The vector field satisfies:

$$\vec{v} = -\nabla S + \eta \int G(x, x') \Phi(x', t - \tau) d^3 x'$$

where:

- $G(x, x')$: Green's function for nonlocal interactions.
- η : coupling strength parameter.
- τ : temporal delay accounting for finite information propagation.

3.1.3 Entropy Field with Advective Transport

The entropy field evolves through:

$$\frac{\partial S}{\partial t} + \vec{v} \cdot \nabla S = D_S \nabla^2 S + \sigma |\nabla \Phi|^2 - \rho S$$

This equation combines:

- Advective transport ($\vec{v} \cdot \nabla S$).
- Diffusive spreading ($D_S \nabla^2 S$).
- Production from scalar gradients ($\sigma |\nabla \Phi|^2$).
- Exponential decay (ρS).

3.2 Stability Analysis and Conservation Laws

3.2.1 Energy-Like Quantity

The system preserves an energy-like quantity:

$$E(t) = \int \left(\frac{1}{2} |\nabla \Phi|^2 + \frac{\gamma}{2} \Phi^2 S + \frac{1}{2} |\vec{v}|^2 \right) d^3 x$$

This functional provides bounds on field amplitudes and ensures long-term stability.

3.2.2 Lyapunov Stability

For control applications, we define a Lyapunov function:

$$V(x) = \frac{1}{2} \sum_{i=1}^N \|x_i - x^*\|^2$$

Stability requires the matrix measure condition:

$$\mu(J) = \frac{1}{2} \max\{\lambda(J + J^T)\} < 0$$

where J is the system Jacobian and λ denotes eigenvalues.

3.2.3 Coherence Metrics

We quantify field coherence through:

$$C(t) = \frac{\int \Phi(x, t) \Phi_{\text{CMB}}(x, 0) d^3x}{\sqrt{\int \Phi(x, t)^2 d^3x} \cdot \sqrt{\int \Phi_{\text{CMB}}(x, 0)^2 d^3x}}$$

This normalized correlation measures reintegration success and provides a testable quantity for cosmological applications.

3.3 Computational Methods

3.3.1 Finite Difference Discretization

We discretize the field equations using second-order finite differences:

$$\Phi_i^{n+1} = \Phi_i^n + \Delta t \left[D_\Phi \frac{\nabla^2 \Phi_i^n}{\Delta x^2} - \gamma \Phi_i^n S_i^n + \varepsilon \sum_{t'=t-T_P}^t K(t-t') \Phi_{\text{CMB},i}(t') \Delta t' \right]$$

3.3.2 Spectral Methods

For periodic boundary conditions, we employ spectral methods:

$$\tilde{\Phi}(k, t) = \int \Phi(x, t) e^{-ik \cdot x} d^3x$$

The evolution equations become:

$$\frac{\partial \tilde{\Phi}}{\partial t} = -D_\Phi k^2 \tilde{\Phi} - \gamma(\tilde{\Phi} * \tilde{S}) + \varepsilon \int_{t-T_P}^t K(t-t') \tilde{\Phi}_{\text{CMB}}(k, t') dt'$$

3.3.3 Adaptive Mesh Refinement

TARTAN tiling enables adaptive mesh refinement based on entropy gradients:

1. Identify high-entropy regions: $S > S_{\text{threshold}}$.
2. Refine mesh locally: $\Delta x_{\text{fine}} = \Delta x_{\text{coarse}}/2^n$.
3. Interpolate fields between mesh levels.
4. Ensure conservation across refinement boundaries.

4 Empirical Validation and Testable Predictions

4.1 Cosmological Tests

4.1.1 CMB Power Spectrum Analysis

The Expyrotic RSVP model predicts specific modifications to the CMB power spectrum:

- Low- ℓ suppression: Reduced power at large angular scales due to entropy damping.
- Oscillatory features: Periodic modulations from memory kernel $K(t - t')$.
- Non-Gaussianity: Mild departures from Gaussian statistics due to nonlinear coupling.

These predictions can be tested against Planck satellite data and future CMB observations.

4.1.2 Large-Scale Structure Correlations

The model predicts modified clustering statistics:

$$\xi(r) = \int P(k) e^{ik \cdot r} \frac{d^3k}{(2\pi)^3}$$

where $P(k)$ incorporates entropy-driven corrections to the matter power spectrum.

4.2 Neuroscience Applications

4.2.1 Cortical Column Dynamics

Amplitwist operations can be tested through:

1. Multi-electrode recordings: Measure spatial correlation patterns during sensory stimulation.
2. Calcium imaging: Track columnar activation during cognitive tasks.
3. Optogenetic manipulation: Test causal relationships between column activity and behavior.

4.2.2 Neural Efficiency Metrics

The framework predicts specific relationships between:

- Metabolic cost and entropy field magnitude.
- Firing rate sparsity and coherence tile size.
- Learning efficiency and amplitwist parameter adaptation.

4.3 AI System Validation

4.3.1 Control Effectiveness

We validate pinning control through:

1. Toy model experiments: Test control efficiency in simplified neural networks.
2. Language model steering: Apply interventions to large language models.
3. Robustness assessment: Evaluate stability under adversarial conditions.

4.3.2 Alignment Metrics

Key performance indicators include:

- Saliency accuracy: Correlation between entropy field and human-identified important features.
- Control efficiency: Ratio of controlled nodes to total system size.
- Stability margin: Distance from instability boundary in parameter space.

5 Discussion and Future Directions

5.1 Theoretical Implications

The RSVP-TARTAN framework offers several theoretical advances:

1. Unified Language: Provides common mathematical vocabulary for emergent phenomena across domains.
2. Thermodynamic Consistency: Ensures physical realizability through entropy constraints.
3. Scalability: Enables efficient computation through hierarchical tiling.
4. Predictive Power: Generates testable hypotheses for empirical validation.

5.2 Limitations and Challenges

5.2.1 Computational Complexity

Despite efficiency improvements, the framework faces computational challenges:

- Memory requirements: Temporal convolution kernels require substantial storage.
- Nonlinear coupling: Scalar-vector-entropy interactions create complex dynamics.
- Multi-scale resolution: TARTAN tiling demands careful numerical implementation.

5.2.2 Parameter Sensitivity

The model contains numerous parameters requiring careful tuning:

- Coupling strengths: $\gamma, \eta, \varepsilon$ must be calibrated for each application domain.
- Diffusion coefficients: D_Φ, D_S affect stability and convergence rates.
- Memory timescales: T_P determines reintegration effectiveness.

5.3 Future Research Directions

5.3.1 Quantum Extensions

Potential extensions to quantum field theory include:

- Holographic correspondences: AdS/CFT duality for gravitational systems.
- Quantum information: Entanglement entropy and quantum error correction.
- Decoherence mechanisms: Quantum-to-classical transition in neural systems.

5.3.2 Experimental Programs

Priority experimental directions include:

1. Cosmological surveys: Next-generation CMB missions and galaxy surveys.
2. Neurotechnology: Advanced brain-computer interfaces and neural prosthetics.
3. AI safety: Large-scale alignment experiments and robustness testing.

5.3.3 Interdisciplinary Applications

The framework may extend to:

- Cognitive science: Models of consciousness and subjective experience.
- Social systems: Collective behavior and cultural evolution.
- Biological development: Morphogenesis and evolutionary dynamics.

6 Conclusion

This paper presents a unified field-theoretic framework for understanding emergent structures and control mechanisms across neural, cosmic, and artificial intelligence systems. The Relativistic Scalar Vector Plenum (RSVP) framework, extended by Trajectory-Aware Recursive Tiling with Annotated Noise (TARTAN), provides a thermodynamically consistent foundation for modeling complex emergent phenomena. Key contributions include:

1. Theoretical unification: Integration of insights from cosmology, neuroscience, and AI through common mathematical language.
2. Novel interpretations: Cortical columns as amplitwist operators, CMB as semantic horizon, AI alignment through graph control.
3. Computational efficiency: Sparsity-driven methods achieving $> 95\%$ parameter reduction.
4. Empirical testability: Specific predictions for cosmological observations, neural recordings, and AI behavior.

The framework addresses fundamental questions about emergence, control, and intelligence while providing practical tools for scientific investigation and technological development. Future work will focus on experimental validation, computational optimization, and extension to quantum systems. By bridging physics, neuroscience, and artificial intelligence, RSVP-TARTAN offers a promising pathway toward understanding the deepest principles governing complex systems and emergent intelligence.

A Field Definitions

- $\Phi(x, t) : \mathbb{R}^4 \rightarrow \mathbb{R}$: scalar field (semantic density).
- $\vec{v}(x, t) : \mathbb{R}^4 \rightarrow \mathbb{R}^3$: vector field (entropy flow).
- $S(x, t) : \mathbb{R}^4 \rightarrow \mathbb{R}$: entropy field (ambiguity).
- $\Phi_{\text{CMB}}(x, t') : \mathbb{R}^4 \rightarrow \mathbb{R}$: CMB boundary memory.
- T_P : Poincaré recurrence timescale.

B Evolution Equations

B.1 Scalar Field with Reintegration

$$\frac{\partial \Phi}{\partial t} = D_\Phi \nabla^2 \Phi - \gamma \Phi S + \varepsilon \int_{t-T_P}^t K(t-t') \Phi_{\text{CMB}}(x, t') dt'$$

- D_Φ : diffusion coefficient.
- γ : coupling coefficient.
- ε : reintegration strength.
- $K(t-t') = e^{-\alpha(t-t')}$: temporal memory kernel.

B.2 Vector Field Evolution

$$\vec{v} = -\nabla S + \eta \int G(x, x') \Phi(x', t - \tau) d^3 x'$$

- η : nonlocal coupling strength.
- $G(x, x')$: Greens function.
- τ : temporal delay.

B.3 Entropy Field Evolution

$$\frac{\partial S}{\partial t} + \vec{v} \cdot \nabla S = D_S \nabla^2 S + \sigma |\nabla \Phi|^2 - \rho S$$

- D_S : entropy diffusion rate.
- σ : entropy production.
- ρ : entropy collapse term.

C Coherence Metric

$$C(t) = \frac{\int \Phi(x, t) \Phi_{\text{CMB}}(x, 0) d^3 x}{\sqrt{\int \Phi(x, t)^2 d^3 x} \cdot \sqrt{\int \Phi_{\text{CMB}}(x, 0)^2 d^3 x}}$$

D Energy-Like Quantity

$$E(t) = \int \left(\frac{1}{2} |\nabla \Phi|^2 + \frac{\gamma}{2} \Phi^2 S + \frac{1}{2} |\vec{v}|^2 \right) d^3 x$$

E Amplitwist Operators

Define an amplitwist operator:

$$(A(\theta, s)\Phi)(x) = \Phi(sR_{-\theta}x)$$

Recursive composition:

$$F = \prod_{i=1}^N A(\theta_i, s_i)$$

F RBF-Based Parameter Prediction

$$\Phi(x) = \sum_{i=1}^k \alpha_i \phi(\|x - x_i\|), \quad \phi(r) = e^{-(\epsilon r)^2}$$

- x_i : anchor points.
- α_i : coefficients solved via $\alpha = K^{-1}\Phi_I$, $K_{ij} = \phi(\|x_i - x_j\|)$.

G OBD-Inspired Saliency Metric

$$\text{Saliency}(x) = |\nabla^2 S(x, t)|$$

Prune where $\text{Saliency}(x) < \text{threshold}$.

H Control-Theoretic Model for AGI Alignment

Model AGI as a network of agents:

$$\frac{dx_i(t)}{dt} = f_i(x_i(t)) + \sum_{j=1}^N A_{ij} h(x_i, x_j) + u_i(t)$$

- x_i : state of agent i (e.g., neuron, module).
- A_{ij} : adjacency matrix.
- $u_i(t)$: control input (e.g., pinning control).

Pinning control for a subset of nodes:

$$u_i(t) = -k(x_i(t) - x^*(t)) \quad \text{if } i \in P, \text{ else } 0$$

- P : set of pinned nodes.
- $x^*(t)$: desired trajectory.
- k : control gain.

I Stability Analysis

Lyapunov function for synchronization:

$$V(x) = \frac{1}{2} \sum_{i=1}^N \|x_i - x^*\|^2$$

Contraction condition:

$$\dot{\delta x}(t) = J(x, t)\delta x(t), \quad \mu(J) < 0$$

- $\mu(J)$: matrix measure of Jacobian J .

J Recursive Tiling (TARTAN)

1. Compute $S(x, t) = |\nabla \Phi|^2$.
2. Detect coherence regions: $S > \text{percentile}(S, 85)$.
3. Extract tiles using connected components.
4. Re-simulate RSVP dynamics within tiles, injecting noise.

K Empirical Estimators

- **Finite Difference Method:**

$$\Phi_i^{n+1} = \Phi_i^n + \Delta t \left[D_\Phi \frac{\nabla^2 \Phi_i^n}{\Delta x^2} - \gamma \Phi_i^n S_i^n + \varepsilon \sum_{t'=t-T_P}^t K(t-t') \Phi_{\text{CMB},i}(t') \Delta t' \right]$$

- **Coherence Metric:**

$$C(t) \approx \frac{\sum_i \Phi_i(t) \Phi_{\text{CMB},i}(0) \Delta x}{\sqrt{\sum_i \Phi_i(t)^2 \Delta x} \cdot \sqrt{\sum_i \Phi_{\text{CMB},i}(0)^2 \Delta x}}$$

- **Energy Estimation:**

$$E(t) \approx \sum_i \left(\frac{1}{2} \left| \frac{\nabla \Phi_i}{\Delta x} \right|^2 + \frac{\gamma}{2} \Phi_i^2 S_i + \frac{1}{2} |\vec{v}_i|^2 \right) \Delta x$$

L Validation and Testing

- **Cosmological Tests:** Compare $\Phi(t)$ with CMB data.
- **Neural Tests:** Test amplitwist operations in neural recordings.
- **AI Tests:** Validate pinning control in toy models (e.g., LLM moderation).
- **Sparsity Validation:** Confirm parameter reduction via RBF and OBD metrics.

M Computational Implementation

- **Python Simulation:** Use NumPy/SciPy for field equations, Matplotlib for visualization.
- **CMB/Neural/AI Integration:** Use Healpy for CMB, NeuroPy for neural data, PyTorch for AI models.
- **Parallel Computing:** Use MPI/Dask for large-scale simulations.

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