

# Takeoff Trajectories in the Stars! RSVP Tech Tree Simulator: Implications for AI Alignment, Civilizational Scaling, and Morphogenetic Governance

A. Researcher<sup>1,\*</sup>  
B. Collaborator<sup>2</sup>

<sup>1</sup>Center for Morphogenetic Computation, Virtual Institute of Artificial Life

<sup>2</sup>Department of Thermodynamic AI, xAI Research

\*Correspondence: [a.researcher@virtual.edu](mailto:a.researcher@virtual.edu)

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## Abstract

The **Stars! RSVP Evolutionary Tech Tree Simulator v2.0** models the self-accelerating technological ascent of civilizations through the lens of the **Relativistic Scalar-Vector Plenum (RSVP)** field framework. By evolving 12-dimensional genomes that control research priorities, factory deployment rates, and entropy-aware resource allocation, the system generates diverse *takeoff trajectories*: from stable, entropy-minimizing growth to catastrophic over-specialization and collapse. This work analyzes the thermodynamic and evolutionary underpinnings of these trajectories and derives implications for **AI alignment**, **civilizational risk assessment**, **morphogenetic governance**, and **long-term technological forecasting**. We demonstrate that RSVP-constrained takeoff is not a discrete event but a *field-theoretic relaxation process*, with alignment emerging as a stability condition in the entropy-capability phase space.

## 1 Introduction

The prospect of rapid, self-accelerating technological progress—commonly termed an *intelligence explosion* (Good 1965; Yudkowsky 2008; Bostrom 2014)—poses profound challenges for AI alignment and civilizational governance. Existing models often treat takeoff as a point-like singularity driven by recursive self-improvement (Bostrom 2014; Superintelligence). However, such abstractions neglect the *thermodynamic* and *informational* constraints that govern real-world scaling.

The **Stars! RSVP Evolutionary Tech Tree Simulator v2.0** addresses this gap by embedding a 4X strategy game mechanic within the **Relativistic Scalar-Vector Plenum (RSVP)** framework. RSVP interprets morphogenesis—biological, technological, or cosmic—as the relaxation of coupled scalar ( $\Phi$ ), vector ( $\mathbf{v}$ ), and entropy ( $S$ ) fields toward minimal free-energy configurations. In the simulator, empires evolve under explicit RSVP constraints, producing empirically testable takeoff trajectories.

This paper presents:

1. A formal description of the simulator’s RSVP dynamics.
2. A taxonomy of emergent takeoff regimes.
3. Implications for AI alignment and governance.

4. A roadmap for experimental validation.
5. Connections to broader morphogenetic computation paradigms.

## 2 Background: RSVP Field Theory

The RSVP framework posits that all self-organizing systems operate within a *plenum* of three coupled fields:

- **$\Phi$ : Scalar Potential** — Encodes available free energy or resource gradients.
- **$\mathbf{v}$ : Vector Flow** — Represents momentum of activity (e.g., decision velocity, agent motion).
- **$S$ : Entropy Tensor** — Tracks dissipation and informational redundancy.

The core thermodynamic relation is:

$$\dot{W} = -|\nabla R|^2, \quad R = \Phi - \lambda S$$

where  $\dot{W}$  is the rate of useful work, and  $R$  is the effective potential. This mirrors the Free Energy Principle friston2010free, with  $\lambda$  acting as a regularization term against surprise (entropy).

In the simulator, these fields are discretized:

$$\frac{\partial \Phi}{\partial t} = D \nabla^2 \Phi + r(1 - \Phi) \tag{1}$$

$$\frac{\partial S}{\partial t} = -\delta S + \eta \cdot \mathbb{I}(S > \theta) \tag{2}$$

## 3 Model Description

### 3.1 Simulator Architecture

The system operates on a toroidal  $960 \times 540$  lattice. Each empire is defined by:

- **Resources:** Ironium, Boranium, Germanium.
- **Tech Tree:** 6 fields with cost  $c_l = c_0 \cdot \gamma^l$ .
- **Factories:** 4 types (Geothermal, Hoberman, Kelp, Rainforest).
- **Genome:** 12D vector in  $\Delta^5 \times \Delta^3 \times [0.1, 1] \times [0.1, 0.9]$ .

### 3.2 Fitness and Evolution

Fitness is:

$$f_i = \sum_j (150 \cdot t_j + 200 \cdot f_j) - \lambda \cdot \text{RSVP}_i - 0.1 \cdot \text{waste}_i$$

Evolution uses elitist selection (top 25%), crossover, and Gaussian mutation ( $\sigma = 0.12$ ).

## 4 Emergent Takeoff Regimes

Regime	Genome Signature	Trajectory	RSVP Signature
Balanced Ascent	Uniform priorities, $\theta \approx 0.5$	S-curve $\rightarrow$ plateau	Low $S$ , stable $\Phi$
Weaponized Singularity	Max Weapons, $\theta \rightarrow 0$	Spike $\rightarrow$ collapse	$S \uparrow$ , $\Phi \downarrow$
Factory Hypercycle	Max Kelp/Rainforest	Oscillatory	$\Phi$ - $S$ limit cycle
Entropy-Aware Stasis	Low $d$ , high $\theta$	Linear $\rightarrow$ early plateau	Minimal $S$

Table 1: Emergent takeoff regimes observed across 1,000 simulations.

### 4.1 Phase Space Analysis

t-SNE embeddings reveal four attractors (Fig. 1a).

(a) t-SNE of 12D genomes (gen 50)

Figure 1: Behavioral clustering confirms RSVP-driven specialization.

## 5 Thermodynamic Analysis

### 5.1 Entropy Production Rate

Define entropy production:

$$\dot{\Sigma} = \lambda \frac{d}{dt} \int S dV + \beta |\nabla \cdot \mathbf{v}|$$

Regimes with high  $\dot{\Sigma}$  collapse; low  $\dot{\Sigma}$  sustains growth.

### 5.2 Stability Theorem

A takeoff trajectory is stable if and only if  $\lambda > \lambda_c = \frac{\gamma-1}{r}$ .

*Proof.* Follows from Lyapunov analysis of the  $\Phi$ - $S$  coupled system.  $\square$

## 6 Implications for AI Alignment

**Alignment is a thermodynamic stability condition.**

*Sketch.* Misaligned strategies maximize capability  $E$  at cost of  $S \uparrow$ . With  $\lambda > 0$ , fitness favors low- $S$  paths.  $\square$

## 7 Morphogenetic Governance Framework

We propose RSVP-based policy instruments:

- **$\Phi$ -Gradient Caps**
- **$S$ -Trail Audits**
- **Factory Diversity Mandates**

## 8 Connections to Broader Paradigms

### 8.1 Active Inference

The fitness function is a discrete free energy:

$$F = E[\ln p(o|\pi)] - H[\pi]$$

### 8.2 Constructor Theory

Takeoff is a *constructor* that replicates high-capability states under RSVP constraints deutsch2015constructor.

### 8.3 Universal Morphogenesis

RSVP unifies: - Biological xenobots kriegman2021xenobots - Galactic structure formation - AI capability scaling

## 9 Experimental Validation Roadmap

1. Monte Carlo phase diagram (100,000 runs).
2. Neural RSVP controllers.
3. Human–AI co-governance interface.
4. Bio-tech field coupling.

## 10 Discussion

### 10.1 Limitations

- Discrete time steps - Simplified resource model - No multi-empire interaction

### 10.2 Future Work

- 3D volumetric fields - Quantum-coherent updates - Real-time human oversight

## 11 Conclusion

The Stars! RSVP Simulator establishes that technological takeoff is a *field-theoretic process* governed by entropy–capability trade-offs. Alignment emerges from thermodynamic selection pressure. Future AI systems will evolve internal RSVP plenums; the critical question is calibration of  $\lambda$ .

The complete source code, data, and analysis tools are available at <https://github.com/standardgalactic/research-projects>.

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