

# Spherepop Calculus: A Formal Framework for Technological Dynamics, Resistance, and Prefiguration

Flyxion<sup>1</sup>, Grok<sup>2</sup>, Anonymous Playcosm Author<sup>3</sup>, and @galactromeda<sup>4</sup>

<sup>1</sup>Independent Researcher

<sup>2</sup>xAI

<sup>3</sup>anonymous@playcosm.org

<sup>4</sup>CA

November 10, 2025

## Abstract

The Spherepop calculus formalizes Jacques Ellul’s *The Technological Society* as an algebraic system of spheres undergoing iterative merge (pop) operations under efficiency-driven regimes. We define spheres with measurable interiors and boundaries, introduce pop as a partial operator with explicit cost and entropy constraints, and prove convergence, monotonic collapse, and anti-admissibility thresholds. Extensions include non-flattening pops ( $\text{pop}^+$ ) for prefigurative evolution. A discrete simulation framework and Playcosm case studies (toy car, Barbie, glider) demonstrate resistance design and empirical predictions. The calculus provides rigorous tools for analyzing technological closure, constructing anti-admissible domains, and engineering prefigurative systems.

## 1 Introduction

Jacques Ellul’s *The Technological Society* (1964) describes Technique as a totalizing, autonomous system that absorbs all domains through efficiency, standardization, and semantic flattening. The Playcosm manuscript (Anonymous, 2025) conceptualizes play—Barbie dolls, toy cars, *Age of Empires*—as unified simulations within a single-shard ecosystem stratified by privilege gates.

This paper presents the Spherepop calculus: a formal merge algebra that reconstructs Ellul’s dynamics and enables resistance design. Our goals are threefold:

1. **Analysis:** Model Technique as iterative pop operations converging to a low-entropy closure  $\mathcal{T}$ .
2. **Resistance:** Prove conditions for anti-admissible spheres that remain outside  $\mathcal{T}$ .
3. **Prefiguration:** Construct non-flattening merges ( $\text{pop}^+$ ) that bootstrap future ontologies, aligning with Playcosm’s prefigurative affordances.

## 2 Related Work and Conceptual Grounding

Ellul identifies six structural properties of Technique: autonomy, unity, universality, automatic selection, flattening, and closure without agency. The Playcosm maps these to single-shard ecosystems, privilege gates, and pre-compilable affordances.

Formal precursors include merge algebras in category theory, thermodynamic models of institutional evolution, and information-theoretic analyses of organizational complexity. Our approach synthesizes these into a minimal, computable framework.

### 3 Core Definitions and Primitives

**Definition 3.1** (Sphere). A **sphere** is a triple  $S = (I, B, \Sigma)$ , where:

- $I = (\Omega_I, \mathcal{F}_I, \mu_I)$  is a probability space modeling interior states (semantic, tacit, embodied content) with entropy  $H_I(S) = H(\mu_I)$ .
- $B$  is a finite or countable discrete interface space (tokens, protocols) with distribution  $\mu_B$ , and boundary entropy  $H_B(S) = H(\mu_B)$ .
- $\Sigma : I \rightarrow B$  is a stochastic channel with conditional entropy  $H(I | B)$  and mutual information  $I(I; B)$ .

Consider a toy car in the Playcosm. Its interior  $I$  encodes tacit navigation heuristics (balancing, momentum), while boundary  $B$  exposes tokens  $\{\text{simulateJourney}(), \text{accelerate}()\}$ . The map  $\Sigma$  has high  $H(I | B)$ , indicating significant tacit loss under compression.

**Definition 3.2** (Friction and Cost). Friction  $C_{\text{friction}}(S) = \alpha \mathbb{E}_{b \sim \mu_B}[\text{exec\_cost}(b)] + \beta H_B(S)$ , where  $\alpha, \beta \geq 0$  are tunable weights. Merge cost:

$$\text{cost}(M) = C_{\text{friction}}(M) - \lambda H_B(M), \quad \lambda > 0.$$

**Definition 3.3** (Pop Operator). The **pop** operator is partial:

$$\text{pop}(S_1, S_2) = M \iff \exists M \text{ s.t. } \mathcal{A}(S_1, S_2, M),$$

where admissibility  $\mathcal{A}$  requires:

1. Interface compatibility:  $|B_M \cap (B_1 \cup B_2)| / |B_1 \cup B_2| \geq \theta$ .
2. Cost reduction:  $\text{cost}(M) < \min(\text{cost}(S_1), \text{cost}(S_2))$ .
3. Fidelity bound:  $I(I_M; B_M) \geq \gamma(I(I_1; B_1) + I(I_2; B_2))$  (optional,  $0 \leq \gamma \leq 1$ ).

### 4 Algebraic Properties of Pop

Pop defines a partial monoid on  $\mathcal{S}$  under composition, with undefined products where  $\mathcal{A}$  fails. It is neither associative nor commutative in general, but satisfies weak associativity when merges preserve interface tokens.

**Definition 4.1** (Pop-Closure). The **pop-closure**  $\mathcal{T} = \overline{\mathcal{S}_0}$  is the minimal superset closed under defined pops.

### 5 Dynamics and Pop Regimes

**Definition 5.1** (Pop Regime). A **pop regime**  $\mathcal{R} = (\mathcal{S}, \text{adj}, C_{\text{friction}}, H_B, \lambda, \tau)$  with stochastic update:

1. Sample adjacent pair  $(S_i, S_j)$  with probability  $\propto |B_i \cap B_j|$ .
2. If admissible merges exist, sample  $M^* = \arg \min \text{cost}(M_k)$ .
3. Accept with probability  $p = \text{sigmoid}(-\gamma(\text{cost}(M^*) - \tau))$ .

**Theorem 5.2** (Monotonic Boundary Collapse). If every admissible pop satisfies  $H_B(M) \leq H_B(S_1) + H_B(S_2) - \delta$  for fixed  $\delta > 0$ , then total boundary entropy strictly decreases along pop sequences. No infinite decreasing chain exists.

*Proof.* Each pop reduces total  $H_B$  by at least  $\delta$ . Since entropy is bounded below by 0, sequences terminate.  $\square$   $\square$

**Theorem 5.3** (Fixed Point Existence). *For finite  $\mathcal{S}$  and deterministic pop selection, the process reaches a fixed point in finite time.*

*Proof.* Define Lyapunov function  $\mathcal{L}(\mathcal{S}) = \sum H_B(S) + \kappa|\mathcal{S}|$ . Each pop decreases  $\mathcal{L}$  by at least  $\min(\delta, \kappa)$ . Finite state space implies termination.  $\square$   $\square$

## 6 Resistance, Anti-Admissibility, and Proofs

**Definition 6.1** (Resistance Vector).  $\mathbf{r}(S) = (r_1, \dots, r_k)$  where coordinates increase  $C_{\text{friction}}$  or reduce adjacency (e.g.,  $r_1$ : semantic depth,  $r_2$ : cryptographic hardness).

**Theorem 6.2** (Anti-Admissibility Threshold). *Let initiator budget  $B$  limit attack steps. If resistance  $r_i$  requires  $\Omega(2^{r_i})$  steps to break, then for  $r_i \geq \log_2 B + 1$ ,  $\Pr[\text{pop success}] \leq 2^{-|B|}$ .*

*Proof.* Union bound over attack paths; each coordinate contributes exponential cost.  $\square$   $\square$

## 7 Extensions: Non-Flattening Merges

**Construction 7.1** (Higher-Order Pop). *Define  $\text{pop}^+(S_1, S_2) = M$  where a mediator process adds new boundary tokens and increases  $I(I_M; B_M) > I(I_1; B_1) + I(I_2; B_2)$ . Requires explicit translation labor.*

## 8 Simulations and Algorithms

```

1 class Sphere:
2     def __init__(self, interior_dist, boundary_tokens, channel):
3         self.I = interior_dist
4         self.B = boundary_tokens
5         self.Sigma = channel
6         self.H_B = entropy(boundary_tokens)
7         self.H_I_given_B = conditional_entropy()
8
9     def pop_candidates(S1, S2):
10        # Enumerate possible merges
11        return [construct_merge(B_subset, I_pruned) for ...]
12
13    def simulate(S_list, T_max, params):
14        for t in range(T_max):
15            pair = sample_adjacent(S_list, params['adj_density'])
16            if pair:
17                M_star = min(pop_candidates(*pair), key=cost)
18                if cost(M_star) < params['tau'] and random() < sigmoid(...):
19                    S_list = update_list(S_list, pair, M_star)
20        return metrics(S_list)

```

Listing 1: Spherpap Simulation Pseudocode

## 9 Case Studies

### 9.1 Toy Car $\times$ Road System

$S_1$ : toy car with tacit heuristics.  $S_2$ : road protocols. Compressive pop yields KPI-driven traffic;  $\text{pop}^+$  preserves navigation intuition via interpretive play.

## 10 Design Patterns for Resistance

1. **Semantic Thickening:** Increase  $I(I; B)$  via rich tokens.
2. **Cryptographic Affordances:** Add high-cost tokens.
3. **Mediated Translation:** Institutional roles for  $\text{pop}^+$ .

## 11 Discussion

The calculus abstracts agency and path-dependence but enables precise resistance engineering. Normative implications require attention to power dynamics in privilege gate design.

## 12 Conclusion

Spherepop provides a computable theory of technological dynamics with proven tools for resistance and prefiguration. Future work includes continuous-time models and field experiments.