

Duality

Lecture 5

October 6, 2025

Recap From Last Time

Primal-Dual Pair of Problems

	Primal (\mathcal{P})	
minimize	$c^T x$	
$(\lambda_i \rightarrow)$	$a_i^T x \geq b_i,$	$\forall i \in I_{ge}$
$(\lambda_i \rightarrow)$	$a_i^T x \leq b_i,$	$\forall i \in I_{le}$
$(\lambda_i \rightarrow)$	$a_i^T x = b_i,$	$\forall i \in I_{eq}$
	$x_j \geq 0,$	$\forall j \in J_p$
	$x_j \leq 0,$	$\forall j \in J_n$
	x_j free,	$\forall j \in J_f$
variables	$x \in \mathbb{R}^n$	

We seek **lower bounds** on λ^*

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Primal-Dual Pair of Problems

$$\begin{array}{lll}\text{Primal } (\mathcal{P}) \\ \text{minimize}_{\mathbf{x}} & \mathbf{c}^\top \mathbf{x} \\ (\lambda_i \rightarrow) & \mathbf{a}_i^\top \mathbf{x} \geq b_i, & \forall i \in I_{ge} \\ (\lambda_i \rightarrow) & \mathbf{a}_i^\top \mathbf{x} \leq b_i, & \forall i \in I_{le} \\ (\lambda_i \rightarrow) & \mathbf{a}_i^\top \mathbf{x} = b_i, & \forall i \in I_{eq} \\ & x_j \geq 0, & \forall j \in J_p \\ & x_j \leq 0, & \forall j \in J_n \\ & x_j \text{ free}, & \forall j \in J_f \\ \text{variables} & \mathbf{x} \in \mathbb{R}^n\end{array}$$

$$\begin{array}{lll}\text{Dual } (\mathcal{D}) \\ \text{maximize}_{\lambda} & \lambda^\top \mathbf{b} \\ & \lambda_i \geq 0, & \forall i \in I_{ge} \\ & \lambda_i \leq 0, & \forall i \in I_{le} \\ & \lambda_i \text{ free}, & \forall i \in I_{eq} \\ (\mathbf{x}_j \rightarrow) & \lambda^\top \mathbf{A}_j \leq c_j, & \forall j \in J_p \\ (\mathbf{x}_j \rightarrow) & \lambda^\top \mathbf{A}_j \geq c_j, & \forall j \in J_n \\ (\mathbf{x}_j \rightarrow) & \lambda^\top \mathbf{A}_j = c_j, & \forall j \in J_f \\ \text{variables} & \lambda \in \mathbb{R}^m.\end{array}$$

We seek **lower bounds** on λ^*

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Primal-Dual Pair of Problems

Primal (\mathcal{P})		Dual (\mathcal{D})	
minimize	$\underset{x}{c}^T x$	maximize	$\underset{\lambda}{\lambda}^T b$
$(\lambda_i \rightarrow)$	$a_i^T x \geq b_i, \quad \forall i \in I_{ge}$	$\lambda_i \geq 0,$	$\forall i \in I_{ge}$
$(\lambda_i \rightarrow)$	$a_i^T x \leq b_i, \quad \forall i \in I_{le}$	$\lambda_i \leq 0,$	$\forall i \in I_{le}$
$(\lambda_i \rightarrow)$	$a_i^T x = b_i, \quad \forall i \in I_{eq}$	λ_i free,	$\forall i \in I_{eq}$
	$x_j \geq 0, \quad \forall j \in J_p$	$(x_j \rightarrow) \quad \lambda^T A_j \leq c_j,$	$\forall j \in J_p$
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	x_j free, $\forall j \in J_f$	$(x_j \rightarrow) \quad \lambda^T A_j = c_j,$	$\forall j \in J_f$
variables	$x \in \mathbb{R}^n$	variables	$\lambda \in \mathbb{R}^m.$

We seek **lower bounds** on λ^*

Recall the procedure for deriving the dual:

- a dual decision variable λ_i for every primal constraint (except variable signs)
- constrain λ_i to ensure lower bound: $\lambda_i \text{ (?) } 0$
- for every primal **decision** x_j , add a dual **constraint** in the form $\lambda^T A_j \text{ (?) } c_j$
(involving the **column** A_j and the **objective coefficient** c_j corresponding to x_j)

Rules for Constructing the Dual of **Any** LP

Consider **any** linear optimization problem (minimization/maximization):

$$\begin{array}{ll} \underset{x}{\text{minimize}} & / \quad \underset{x}{\text{maximize}} \quad c^T x \\ & (\lambda \rightarrow) \quad Ax \begin{array}{l} \leq \\ \geq \\ = \end{array} b \\ & \quad \quad \quad x \begin{array}{l} \geq \\ \leq \\ = \end{array} 0 \end{array} \quad (1)$$

R1: A dual variable λ_i for every constraint, i.e., every row a_i^T of A .
 λ_i **free** for **equality** constraints ($a_i^T x = b_i$). Otherwise: $\lambda_i \text{ } \textcircled{?} 0$.

R2: In the dual, add a constraint for *every primal variable* x_j .
If x_j is **free**, write this as $\lambda^T A_j = c_j$. Otherwise: $\lambda^T A_j \textcircled{?} c_j$.

R3: To determine the signs $\textcircled{?}$, use this rule of thumb:

the dual variable λ_i is the (sub)gradient of the optimal objective value with respect to the constraint's right-hand-side b_i

- in a minimization, for a " \leq " constraint, the dual variable is ≤ 0
- in a minimization, for a " \geq " constraint, the dual variable is ≥ 0
- in a maximization, for a " \leq " constraint, the dual variable is ≥ 0
- in a maximization, for a " \geq " constraint, the dual variable is ≤ 0 .

Example

What is the dual of this problem? Are the two problems feasible?

$$\begin{array}{ll}\text{minimize} & x_1 + 2x_2 \\ \text{subject to} & x_1 + x_2 = 1 \\ & 2x_1 + 2x_2 = 3.\end{array}$$

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Weak duality

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minimize _{x} $c^T x$

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Dual (\mathcal{D})

maximize _{λ} $\lambda^T b$

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Theorem (Weak duality)

If x is feasible for (\mathcal{P}) and λ is feasible for (\mathcal{D}), then $\lambda^T b \leq c^T x$.

Proof. Trivially true from our construction – omitted.

Implications of Weak Duality

Corollary

The following results hold:

- (a) If the optimal objective in (\mathcal{P}) is $-\infty$, then (\mathcal{D}) ...*
- (b) If the optimal objective in (\mathcal{D}) is $+\infty$, then (\mathcal{P}) ...*

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(c) *If $x \in P$ and $\lambda \in D$, then:*

$$c^T x - \lambda^* \leq c^T x - \lambda^T b \quad \textbf{and} \quad d^* - \lambda^T b \leq c^T x - \lambda^T b.$$

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(d) *If $x \in P$, $\lambda \in D$, and $\lambda^T b = c^T x$, then x **optimal** for (\mathcal{P}) and λ **optimal** for (\mathcal{D}) .*

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(c) and (d) provide (sub)optimality certificates, but...

How do we know that the gaps in (c) are not very large?

How do we know that x and λ satisfying (d) even exist?

Strong duality

Theorem (Strong duality)

If (\mathcal{P}) has an optimal solution, so does (\mathcal{D}) , and the optimal values are equal, $\lambda^ = d^*$.*

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Proof. Many proofs possible...

- See Bertsimas & Tsitsiklis for a proof involving the simplex algorithm
- We provide a more general proof, in three steps:
 1. The **separating hyperplane theorem** (for convex sets)
 2. The Farkas Lemma
 3. Strong duality

Need a tiny bit of **real analysis** background...

A Few Real Analysis Results

Definition (Closed Set)

A set $S \subseteq \mathbb{R}^n$ is called **closed** if it contains the limit of any sequence of elements of S . That is, if $x_n \in S$, $\forall n \geq 1$ and $x_n \rightarrow x^*$, then $x^* \in S$.

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Theorem

Every polyhedron is closed.

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Theorem

Every polyhedron is closed.

Proof.

- Consider $P = \{x \in \mathbb{R}^n \mid Ax \geq b\}$ (representation is w.l.o.g.)
- Suppose that $\{x_n\}_{n \geq 1}$ is a sequence with $x_n \in P$ for every n , and $x_n \rightarrow x^*$.
- For each k , we have $x_k \in P$, and therefore, $Ax_k \geq b$.
- Then, $Ax^* = A(\lim_{k \rightarrow \infty} x_k) = \lim_{k \rightarrow \infty} Ax_k \geq b$, so x^* belongs to P . □

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Every polyhedron is closed.

*Is every **convex set** closed?*

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Theorem

Every polyhedron is closed.

Theorem (Weierstrass' Theorem)

If $f : \mathbb{R}^n \rightarrow \mathbb{R}$ is a continuous function, and if S is a nonempty, closed, and bounded subset of \mathbb{R}^n , then there exist $\underline{x}, \bar{x} \in S$ such that $f(\underline{x}) \leq f(x) \leq f(\bar{x})$ for all $x \in S$.

i.e., a continuous function achieves its minimum and maximum

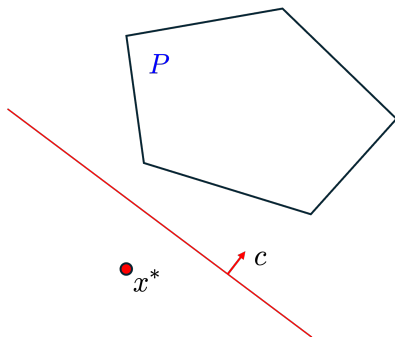
Separating Hyperplane Theorem

The first **fundamental result in optimization**

Separating Hyperplane Theorem

Theorem (**Simple** Separating Hyperplane Theorem)

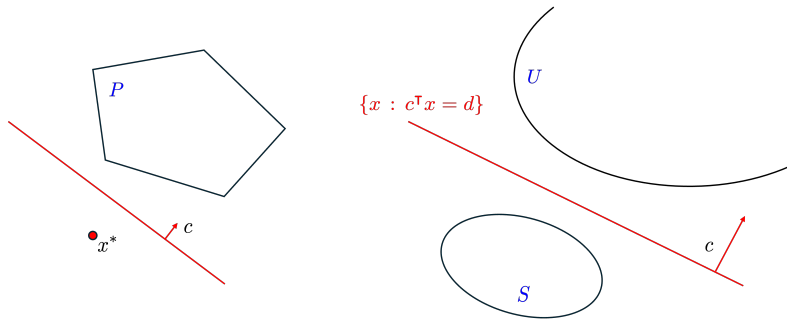
Consider a point x^* and a polyhedron P . If $x^* \notin P$, then there exists a vector $c \in \mathbb{R}^n$ such that $c \neq 0$ and $c^T x^* < c^T y$ holds for all $y \in P$.



Separating Hyperplane Theorem

Theorem (Separating Hyperplane Theorem **for Convex Sets**)

Let S and U be two nonempty, closed, convex subsets of \mathbb{R}^n such that $S \cap U = \emptyset$ and S is bounded. Then, there exists $c \in \mathbb{R}^n$ and $d \in \mathbb{R}$ such that $S \subset \{x \in \mathbb{R}^n : c^T x < d\}$ and $U \subset \{x \in \mathbb{R}^n : c^T x > d\}$.



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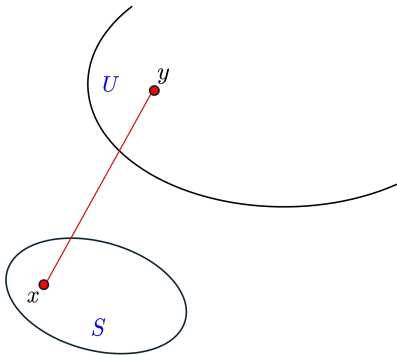
Proof.

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Proof. Consider $\|x - y\|$ with $x \in S, y \in U$

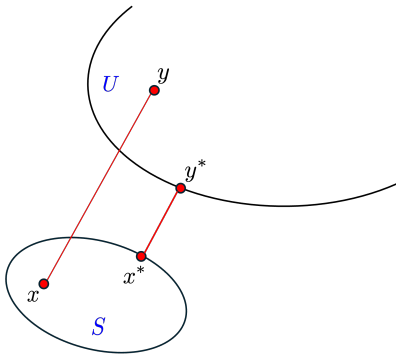


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Proof. Argue that the minimum is achieved, at x^*, y^*

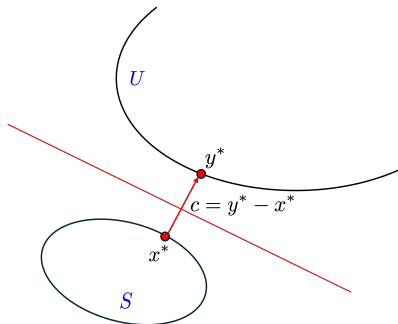


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Proof. Argue that $c = y^* - x^*$ and $d = \frac{c^T(x^* + y^*)}{2}$ give strict separating hyperplane



Separating Hyperplane Theorem - Caveats!

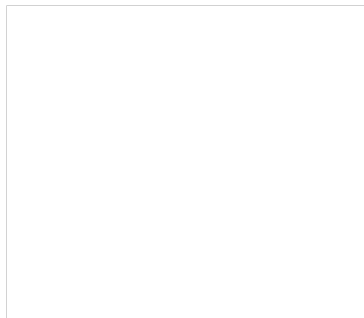
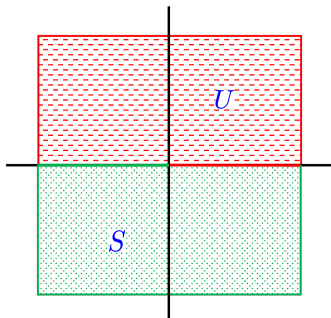
Both conditions in the theorem needed: **closed** and at least one set **bounded**

Separating Hyperplane Theorem - Caveats!

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- **Left:** two convex sets that are **not closed** but are both bounded:

$$S = [-1, 1] \times [-1, 0) \cup \{(x, y) : x \in [-1, 0], y = 0\}, \quad U = [-1, 1]^2 \setminus S$$



Separating Hyperplane Theorem - Caveats!

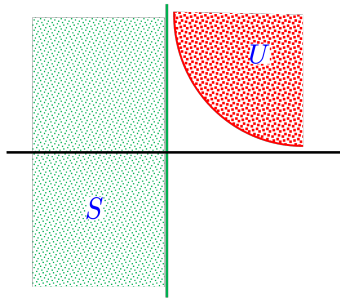
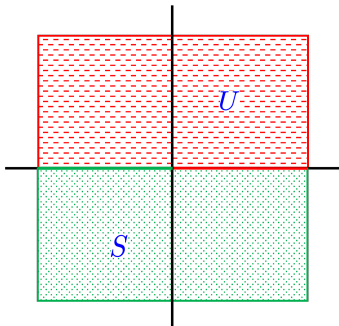
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- **Right:** two convex sets that are both closed but are **unbounded**

$$S = \{(x, y) : x \leq 0\}, \quad U = \{(x, y) : x \geq 0, y \geq 1/x\}$$

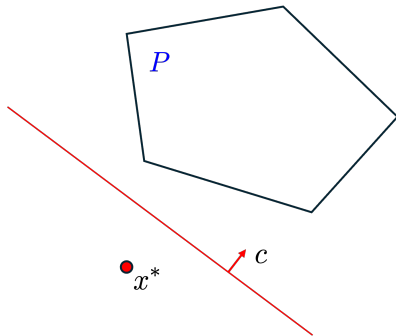


Needed For Our Purposes

We proved the first **fundamental result in optimization!**

Corollary (Needed for our purposes...)

If P is a polyhedron and $x^ \notin P$, there exists a hyperplane that strictly separates x^* from P , i.e., $\exists c \neq 0$ such that $c^T x^* < c^T x$ for any $x \in P$.*



Farkas Lemma

Time for the **second fundamental result in optimization!**

Farkas Lemma

Theorem (Farkas' Lemma)

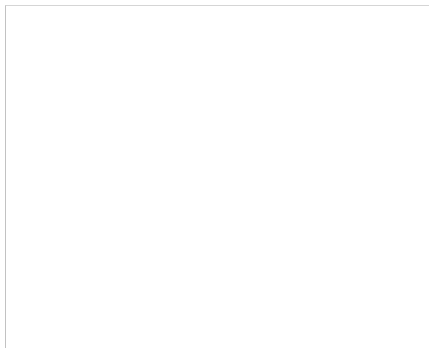
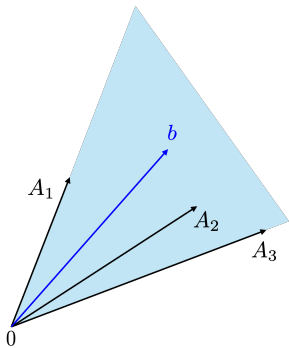
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(a) There exists some $x \geq 0$ such that $Ax = b$.

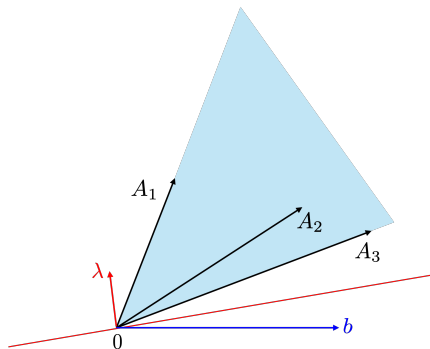
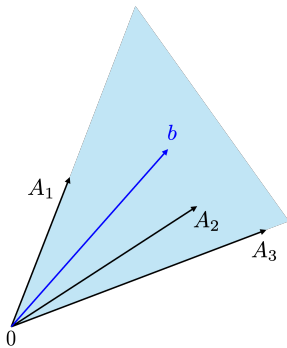


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Proof. “(a) true implies (b) false.”

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Proof. “(a) true implies (b) false.”

(a) true means $\exists x \geq 0 : Ax = b$.

(b) true means $\exists \lambda : \lambda^T A \geq 0$ and $\lambda^T b < 0$.

If (a) and (b) both true, then $\lambda^T b = \lambda^T Ax \geq 0$, which is a contradiction.

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“(a) false implies (b) true.” Want to use the separating hyperplane theorem.

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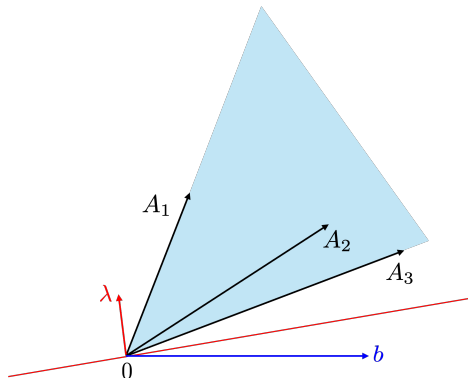
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- (a) false implies that $b \notin \{y : \exists x \geq 0 \text{ such that } y = Ax\} := S$.
- S is a convex and **closed** set (S is polyhedral)

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- (a) false implies that $b \notin \{y : \exists x \geq 0 \text{ such that } y = Ax\} := S$.
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- Limit $\theta \rightarrow \infty$ implies $\lambda^T A_i \geq 0$. ■

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We proved the **second fundamental result in optimization!**

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We proved the **second fundamental result in optimization!**

- Suppose your primal problem (\mathcal{P}) was the standard-form LP:

$$\begin{array}{ll} (\mathcal{P}) & \text{minimize} \quad c^T x \\ & \text{subject to} \quad Ax = b \\ & \quad \quad \quad x \geq 0 \end{array}$$

- What does the Farkas Lemma state about this?

Strong Duality

Consider the following primal-dual pair:

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Theorem (**Strong Duality**)

If (\mathcal{P}) has an optimal solution, so does (\mathcal{D}) , and their optimal values are equal.

Strong Duality

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Proof.

- Assume (\mathcal{P}) has optimal solution x^*
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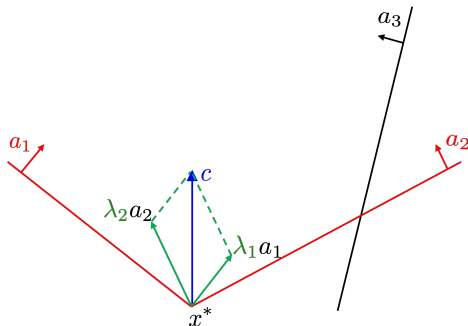
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- Let $\lambda_i = 0$ for $i \notin \mathcal{F} \Rightarrow \exists \lambda$ feasible for (\mathcal{D})
- $\lambda^T b = \sum_{i \in \mathcal{F}} \lambda_i b_i = \sum_{i \in \mathcal{F}} \lambda_i a_i^T x^* = c^T x^*$ ■

Implications

Strong duality leaves only a few possibilities for a primal-dual pair:

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Polynomially-Sized CVaR Representation

- Recall homework: ensure CVaR of portfolio payoff exceeds a lower limit
- CVaR was defined as the average over the k -smallest values (for suitable integer k)
- If payoffs in the scenarios are v_1, v_2, \dots, v_n , the key constraint is:

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- Can write one constraint for each vector in $\{0, 1\}^n$ with exactly k values of 1.
- *How to formulate with a polynomial number of variables and constraints?*

Application in Robust Optimization

- We have LP with constraints $Ax \leq b$. One of the constraints is:

$$a^T x \leq b, \tag{3}$$

where a satisfies $a \in \mathcal{A}$ and \mathcal{A} is polyhedral

- We seek decisions x that are **robustly feasible**, i.e.,

$$a^T x \leq b, \forall a \in \mathcal{A} := \{a \in \mathbb{R}^n : Ca \leq d\} \tag{4}$$

Infinitely many constraints : “semi-infinite” LP. *Any ideas?*

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