

# Lecture 8 : Duality in Convex Optimization

October 15, 2025

# Today's Agenda: Convex Duality

## Primal Problem

$$\begin{aligned} (\mathcal{P}) \quad & \text{minimize}_x \quad f_0(x) \\ & f_i(x) \leq 0, \quad i = 1, \dots, m \\ & x \in X. \end{aligned} \tag{1}$$

- Convex domain  $X \subseteq \mathbb{R}^n$
- Every function  $f_i : X \subseteq \mathbb{R}^n \rightarrow \mathbb{R}$  (real-valued), **convex**
- Equality constraints  $Ax = b$  can be included in  $X$

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- Many developments deal with the “interior” of  $X$

## Definition : Interior

The **interior** of a set  $X$  is the set of all points  $x \in X$  so that:

$$\exists r > 0 : B(x, r) := \{y : \|y - x\| \leq r\} \subseteq X$$

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What is the interior of a set  $X$  that is **not** full-dimensional?

# Relative Interior

- **Recall: Affine hull** of  $X$  is  $\text{aff}(X) := \{\theta_1 x_1 + \cdots + \theta_k x_k : x_i \in X, \sum_{i=1}^k \theta_i = 1\}$

# Relative Interior

- **Recall:** **Affine hull** of  $X$  is  $\text{aff}(X) := \{\theta_1 x_1 + \cdots + \theta_k x_k : x_i \in X, \sum_{i=1}^k \theta_i = 1\}$

## Definition Relative Interior

The **relative interior** of a set  $X$  is:

$$\text{rel int}(X) := \{x \in X : \exists r > 0 \text{ so that } B(x, r) \cap \text{aff}(X) \subseteq X\}. \quad (2)$$

**What is the relative interior of the following sets?**

- $\{(x, y) \in \mathbb{R}^2 \mid (x, y) \in [0, 1]^2\}$
- $\{(x, y) \in \mathbb{R}^2 \mid x + y = 1, x \geq 0, y \geq 0\}$
- $\{(x, y) \in \mathbb{R}^2 \mid x^2 + y^2 = 1\}$

# Convex Duality

## Primal Problem

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- Convex domain  $X \subseteq \mathbb{R}^n$
- Every function  $f_i : X \subseteq \mathbb{R}^n \rightarrow \mathbb{R}$  (real-valued), **convex**
- Equality constraints  $Ax = b$  can be included in  $X$
- Assume  $\text{rel int}(X) \neq \emptyset$
- Assume that  $(\mathcal{P})$  has an optimal solution  $x^*$ , optimal value  $p^* = f_0(x^*)$
- **Core questions:**
  1. For  $x$  feasible for  $(\mathcal{P})$ , how to **quantify the optimality gap**  $f_0(x) - p^*$ ?
  2. How to certify that  $x^*$  is **optimal** in  $(\mathcal{P})$ ?

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## Primal Problem

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$$g(\lambda) := \inf_{x \in X} \mathcal{L}(x, \lambda).$$

## Dual Problem

$$(\mathcal{D}) \quad \sup_{\lambda \geq 0} g(\lambda).$$

**Q: Is the dual  $(\mathcal{D})$  a convex optimization problem?**

# Convex Duality

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# Geometric Interpretation

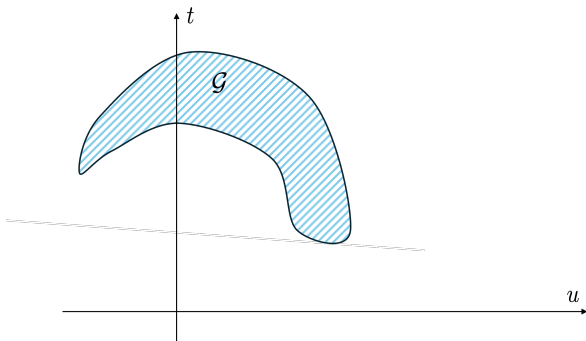
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$$f_i(x) \leq 0, \quad i = 1, \dots, m$$

- Suppose  $X = \mathbb{R}^n$  and  $(\mathcal{P})$  has just one inequality constraint, i.e.,  $m = 1$
- Let  $\mathcal{G} := \{(u, t) \in \mathbb{R}^2 : \exists x \in \mathbb{R}^n, t = f_0(x), u = f_1(x)\}$



**What do feasible points in  $(\mathcal{P})$  correspond to? Where is  $p^*$ ?**

How to express the Lagrangian  $\mathcal{L}(x, \lambda)$  using the  $t, u$  variables?

# Geometric Interpretation

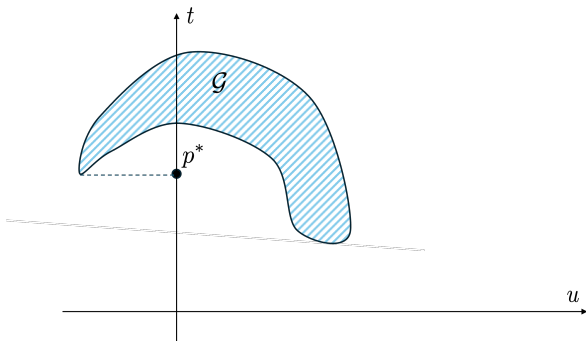
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$\mathcal{L}(x, \lambda)$  is the same as  $t + \lambda \cdot u$ .

# Geometric Interpretation

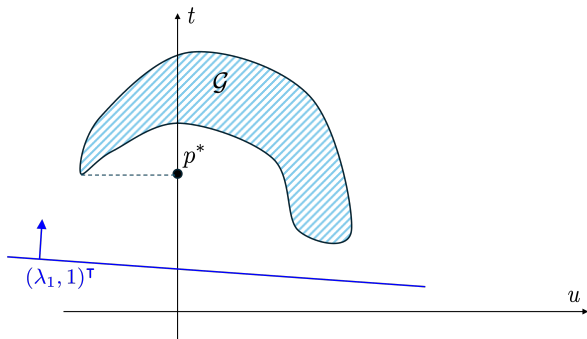
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For  $\lambda \geq 0$ , we have  $g(\lambda) = \inf_{x \in X} (f_0(x) + \lambda f_1(x)) = \inf_{(u,t) \in \mathcal{G}} (t + \lambda \cdot u)$

**What is the value of  $g(\lambda_1)$  in this figure?**

# Geometric Interpretation

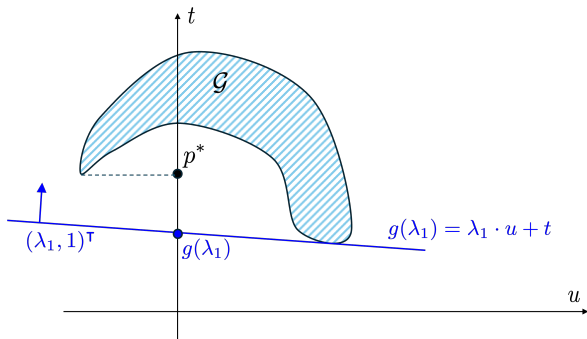
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The optimal pairs  $(u, t)$  yield a **supporting hyperplane** for  $\mathcal{G}$   
Intersection with  $t = 0$  is value of  $g(\lambda_1)$

# Geometric Interpretation

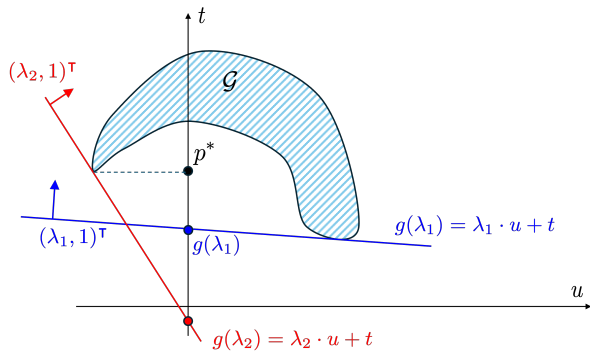
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What is the value of  $\max_{\lambda \geq 0} g(\lambda)$ ?



# Geometric Interpretation

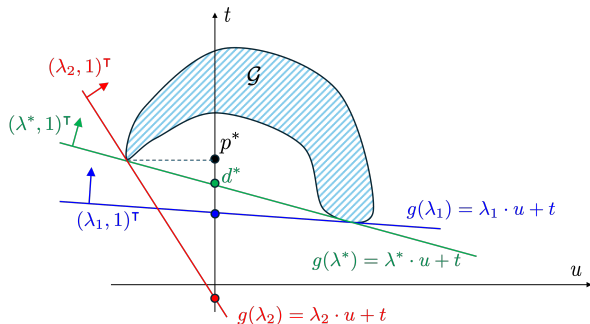
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Here, strong duality does not hold:  $d^* < p^*$ . But the set  $\mathcal{G}$  is not convex!

# Strong Duality in Convex Optimization?

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## Non-zero duality gap

Let  $X = \{(x, y) \mid y \geq 1\}$  and consider the problem:

$$\begin{aligned} & \underset{(x,y) \in X}{\text{minimize}} && e^{-x} \\ & && x^2/y \leq 0. \end{aligned}$$

- Is this a convex optimization problem?
- What are  $p^*$ ,  $\mathcal{L}$ ,  $g$ ,  $d^*$ ?
- Does  $p^* = d^*$  hold for **any** primal convex optimization problem if  $p^*$  finite?

# Conditions Leading to Strong Duality

## Primal Problem

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## Slater Condition

The functions  $f_1, \dots, f_m : X \subseteq \mathbb{R}^n \rightarrow \mathbb{R}$  satisfy **the Slater condition on  $X$**  if there exists  $x \in \text{rel int}(X)$  such that

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- A point  $x$  that is **strictly feasible**
- If **all**  $f_i(x)$  are **affine**, we do not need this (i.e., feasibility is enough)
- If **some**  $f_i$  are affine, we only require  $f_i(x) < 0$  for the **non-linear**  $f_i$

# Strong Duality in Convex Optimization

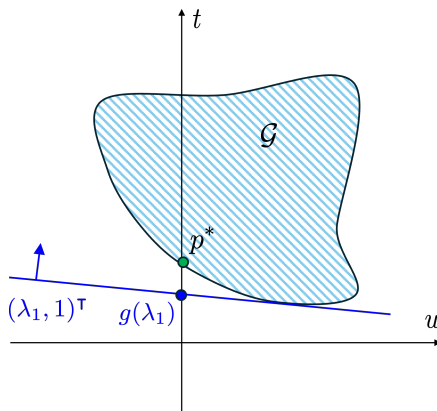
## Theorem (Strong Duality in Convex Optimization)

Let  $X \subset \mathbb{R}^n$  be convex and  $f_0, f_1, \dots, f_m : X \rightarrow \mathbb{R}$  convex functions on  $X$  satisfying the Slater condition on  $X$ . Then,  $p^* = d^*$  and the dual attains its optimal value.

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**Geometric intuition for proof:**

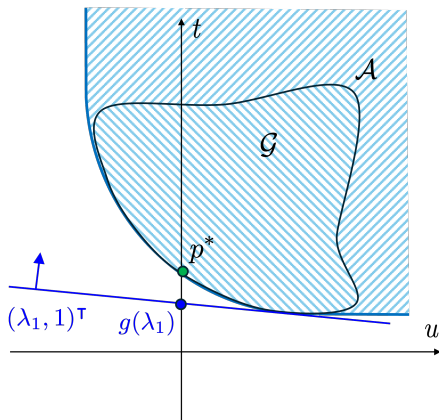
- Recall  $\mathcal{G} := \{(u, t) \in \mathbb{R}^{m+1} : \exists x \in \mathbb{R}^n, t = f_0(x), u = f_1(x)\}$  (above,  $m = 1$ )



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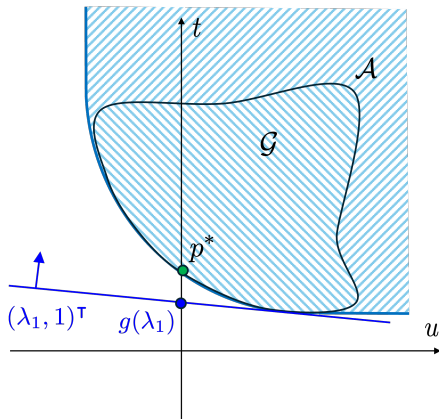


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- Same  $p^*$  if we replace  $\mathcal{G}$  with  $\mathcal{A} = \{(u, t) \in \mathbb{R}^{m+1} : \exists x \in \mathbb{R}^n, t \geq f_0(x), u \geq f_1(x)\}$

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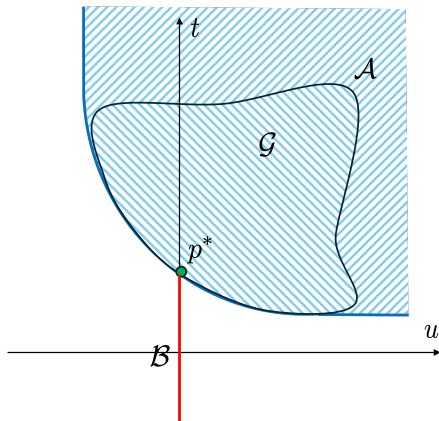


- Same  $p^*$  if we replace  $\mathcal{G}$  with  $\mathcal{A} = \{(u, t) \in \mathbb{R}^{m+1} : \exists x \in \mathbb{R}^n, t \geq f_0(x), u \geq f_1(x)\}$
- Is  $\mathcal{A}$  a convex set?

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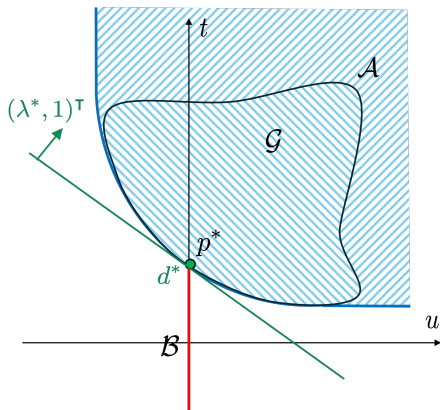


- Define  $\mathcal{B} := \{(0, t) \in \mathbb{R}^m \times \mathbb{R} \mid t < p^*\}$
- **Claim.**  $\mathcal{A} \cap \mathcal{B} = \emptyset$

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Let  $X \subset \mathbb{R}^n$  be convex and  $f_0, f_1, \dots, f_m : X \rightarrow \mathbb{R}$  convex functions on  $X$  satisfying the Slater condition on  $X$ . Then,  $p^* = d^*$  and the dual attains its optimal value.

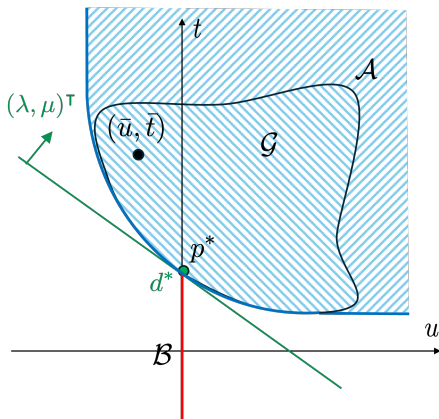


- The Separating Hyperplane Theorem will give us the optimal  $\lambda^*$  and  $p^* = d^*$

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- The Slater point will guarantee that the hyperplane is not vertical

# Strong Duality in Convex Optimization

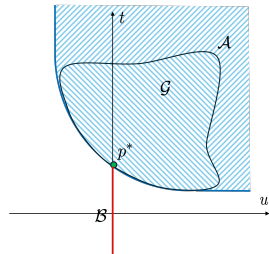
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- Define the **convex** set

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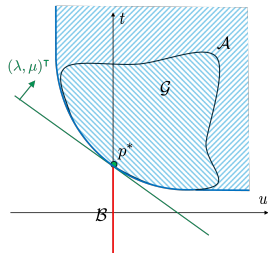
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- Define the **convex** set  $\mathcal{B} = \{(0, t) \in \mathbb{R}^m \times \mathbb{R} \mid t < p^*\}$ .

- $\mathcal{A} \cap \mathcal{B} = \emptyset$ .

- (Non-strict) Separating Hyperplane Theorem:

$$\exists (\lambda, \mu) \in \mathbb{R}^{m+1}, b \in \mathbb{R} : \begin{cases} (1) & (\lambda, \mu) \neq 0, \\ (2) & \lambda^T u + \mu t \geq b, \forall (u, t) \in \mathcal{A} \\ (3) & \lambda^T u + \mu t \leq b, \forall (u, t) \in \mathcal{B}. \end{cases}$$



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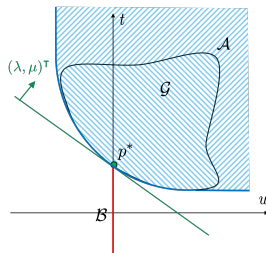
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- (2) implies  $\lambda \geq 0$  and  $\mu \geq 0$ .

Otherwise,  $\inf_{(u,t) \in A} (\lambda^T u + \mu t) = -\infty$  so  $\nless b$ .





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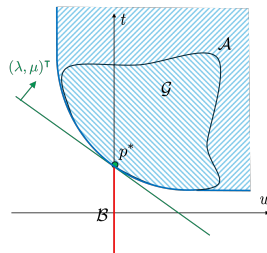
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Otherwise,  $\inf_{(u,t) \in A} (\lambda^T u + \mu t) = -\infty$  so  $\nless b$ .
- (3) simplifies to  $\mu t \leq b$  for all  $t < p^*$ , so  $\mu p^* \leq b$ .



# Strong Duality in Convex Optimization

## Theorem (Strong Duality in Convex Optimization)

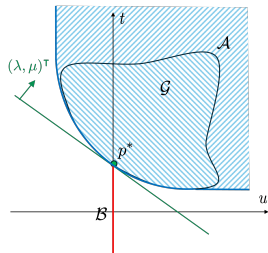
Let  $X \subset \mathbb{R}^n$  be convex and  $f_0, f_1, \dots, f_m : X \rightarrow \mathbb{R}$  convex functions on  $X$  satisfying the Slater condition on  $X$ . Then,  $p^* = d^*$  and the dual attains its optimal value.

- Separating Hyperplane Theorem:

$$\exists (\lambda, \mu) \in \mathbb{R}^{m+1}, \quad b \in \mathbb{R} : \begin{cases} (1) & (\lambda, \mu) \neq 0, \\ (2) & \lambda^T u + \mu t \geq b, \forall (u, t) \in A \\ (3) & \lambda^T u + \mu t \leq b, \forall (u, t) \in B. \end{cases}$$

- (2) implies  $\lambda \geq 0$  and  $\mu \geq 0$ .  
Otherwise,  $\inf_{(u,t) \in A} (\lambda^T u + \mu t) = -\infty$  so  $\nless b$ .
- (3) simplifies to  $\mu t \leq b$  for all  $t < p^*$ , so  $\mu p^* \leq b$ .
- Recap: We found  $\lambda \geq 0, \mu \geq 0$ :

$$\mathcal{L}(x, \lambda) := \sum_{i=1}^m \lambda_i f_i(x) + \mu f_0(x) \geq b \geq \mu p^*, \quad \forall x \in X$$



# Strong Duality in Convex Optimization

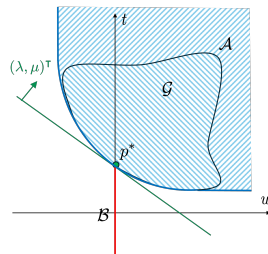
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- We found  $\lambda \geq 0, \mu \geq 0$ :

$$(4) \mathcal{L}(x, \lambda) := \sum_{i=1}^m \lambda_i f_i(x) + \mu f_0(x) \geq b \geq \mu p^*, \forall x \in X$$

- **Case 1.**  $\mu > 0$  (non-vertical hyper-plane)



# Strong Duality in Convex Optimization

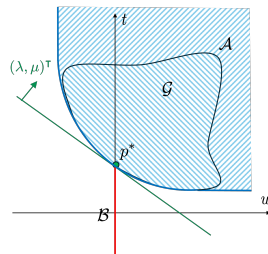
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- This implies  $g(\lambda/\mu) := \inf_{x \in X} \mathcal{L}(x, \lambda/\mu) \geq p^*$ .



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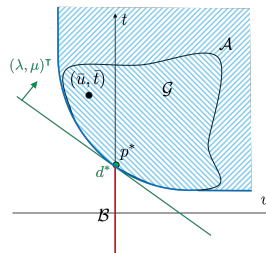
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- Weak duality:  $g(\lambda/\mu) \leq p^*$ , so  $g(\lambda/\mu) = p^*$ .
- Strong duality holds:  $p^* = d^*$ .



# Strong Duality in Convex Optimization

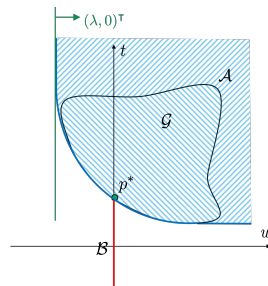
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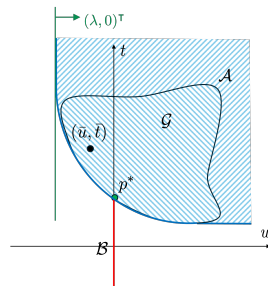
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- **Case 2.**  $\mu = 0$  (vertical hyperplane)
- $\mu = 0$  so (4) implies  $\sum_{i=1}^m \lambda_i f_i(x) \geq 0, \forall x \in X$
- $\bar{x}$  satisfies Slater condition  $\Rightarrow f_i(\bar{x}) < 0$  for  $i = 1, \dots, m$
- This together with  $\lambda \geq 0$  implies that  $\lambda = 0$
- Contradicts that  $(\lambda, \mu) \neq 0$ .



# Explicit Equality Constraints

- In applications, useful to make the **equality constraints explicit**:

$$\begin{aligned} & \text{minimize}_{x \in X} f_0(x) \\ & \text{subject to } f_i(x) \leq 0, \quad i = 1, \dots, m, \\ & \quad \quad \quad Ax = b. \end{aligned}$$

where  $f_i, i = 0, \dots, m$  are convex and  $A \in \mathbb{R}^{p \times n}$  has rank  $p$ .



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- With  $g(\lambda, \nu) := \inf_{x \in X} \mathcal{L}(x, \lambda, \nu)$ , the dual problem becomes:

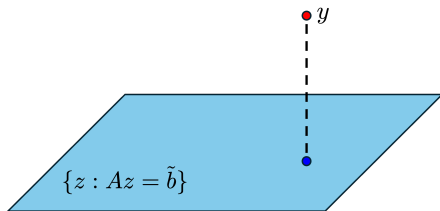
$$\begin{aligned} & \text{maximize}_{\lambda, \nu} g(\lambda, \nu) \\ & \text{subject to } \lambda \geq 0. \end{aligned}$$

**No sign constraints on  $\nu$ !**

# Minimum Euclidean Distance Problem

- Given  $y \in \mathbb{R}^n$  and affine set  $\{z : Az = \tilde{b}\}$
- $A \in \mathbb{R}^{p \times n}$ ,  $\tilde{b} \in \mathbb{R}^p$  has rank  $p$

$$\min_z \{ \|z - y\|_2^2 : Az = \tilde{b} \}$$



- Change of variables  $x := z - y$  and with  $b := \tilde{b} - Ay$ ,

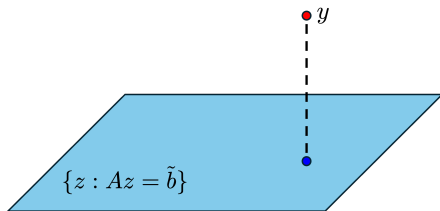
$$\min_x \{ \|x\|_2^2 : Ax = b \}$$

- What is the optimal value  $p^*$ ?

# Minimum Euclidean Distance Problem

- Given  $y \in \mathbb{R}^n$  and affine set  $\{z : Az = \tilde{b}\}$
- $A \in \mathbb{R}^{p \times n}$  is full rank  $p < n$ .  $\tilde{b} \in \mathbb{R}^p$ .

$$\min_z \{ \|z - y\|_2^2 : Az = \tilde{b} \}$$



# Quadratic Programs - Preliminaries

## Unconstrained Quadratic Program

For  $Q = Q^T$ , consider the following unconstrained problem:

$$\min f(x) := \frac{1}{2}x^T Qx + q^T x$$

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# Quadratic Programs - Preliminaries

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$$\min f(x) := \frac{1}{2}x^T Qx + q^T x$$

- What is the optimal value  $p^*$ ?

$$\nabla_x f(x) = 0 \Leftrightarrow Qx = -q$$

$$p^* = \begin{cases} -\frac{1}{2}q^T Q^\dagger q & \text{if } Q \succeq 0 \text{ and } q \in \mathcal{R}(Q) \\ -\infty & \text{otherwise.} \end{cases}$$

- $Q^\dagger$  is the (Moore-Penrose) pseudo-inverse of  $Q$
- For  $A$  with singular value decomposition  $A = U\Sigma V^T$ ,  $A^\dagger := V\Sigma^{-1}U^T$
- Equals  $(A^T A)^{-1}A^T$  if  $\text{rank}(A) = n$  and  $A^T(AA^T)^{-1}$  if  $\text{rank}(A) = m$

# QPs and QCQPs

## Quadratic Programs

A **Quadratic Program (QP)** is an optimization problem of the form:

$$\min \frac{1}{2}x^T Qx + c^T x$$

$$A_1 x = b_1$$

$$A_2 x \leq b_2$$

where  $Q = Q^T$ .

# QPs and QCQPs

## Quadratic Programs

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where  $Q = Q^T$ .

## Quadratically Constrained Quadratic Programs

A **Quadratically Constrained Quadratic Program (QCQP)** is a problem:

$$\begin{aligned} \min \quad & \frac{1}{2}x^T Q_0 x + c^T x \\ & x^T Q_i x + q_i^T x + b_i \leq 0, i = 1, \dots, m \\ & Ax = b \end{aligned}$$

where  $Q_i, i = 0, \dots, m$  are **symmetric** matrices.

**Convex** if  $Q_0 \succeq 0, Q_i \succeq 0$ . Gurobi can now handle **non-convex** QCQPs!



# Two Problems to Warm Up

## QP with Inequality Constraint

$$\begin{aligned} \underset{x}{\text{minimize}} \quad & \frac{1}{2}x^T Q x + c^T x \\ & A x \leq b \end{aligned}$$

where  $Q \succ 0$  is a **positive definite** matrix.

## QCQP

$$\begin{aligned} \underset{x}{\text{minimize}} \quad & \frac{1}{2}x^T Q_0 x + q_0^T x + r_0 \\ \text{subject to} \quad & \frac{1}{2}x^T Q_i x + q_i^T x + r_i \leq 0, \quad i = 1, \dots, m, \end{aligned}$$

where  $Q_0 \succ 0$  and  $Q_i \succeq 0$

- **What is the Lagrangian? What is the dual? Does Slater Condition hold?**

# A Non-Convex QCQP

## A Special Non-Convex QCQP

For  $A = A^T$  and  $A \not\geq 0$ , consider:

$$\begin{aligned} \text{minimize } & x^T A x + 2b^T x \\ & x^T x \leq 1 \end{aligned}$$

- Lagrangian is:

$$\mathcal{L}(x, \lambda) = x^T A x + 2b^T x + \lambda(x^T x - 1) = x^T(A + \lambda I)x + 2b^T x - \lambda,$$

$$g(\lambda) = \begin{cases} -b^T(A + \lambda I)^\dagger b - \lambda & A + \lambda I \succeq 0, \ b \in \mathcal{R}(A + \lambda I), \\ -\infty & \text{otherwise,} \end{cases}$$

where  $M^\dagger$  is the (Moore-Penrose) pseudo-inverse of  $M$

- The dual problem is

$$\begin{aligned} \text{maximize}_{\lambda \geq 0} \quad & -b^T(A + \lambda I)^\dagger b - \lambda \\ \text{subject to} \quad & A + \lambda I \succeq 0, \ b \in \mathcal{R}(A + \lambda I) \end{aligned}$$

- Readily solved because it can be expressed as

$$\text{maximize} \left\{ -\sum_{i=1}^n \frac{(q_i^T b)^2}{\lambda_i + \lambda} - \lambda : \lambda \geq -\lambda_{\min}(A) \right\}$$

where  $\lambda_i, q_i$  are eigen-decomposition of  $A$  and  $(q_i^T b)^2/0 := 0$  if  $q_i^T b = 0$  and  $\infty$  otherwise.

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- Slater condition trivially satisfied!
- We actually have **zero duality gap**,  $p^* = d^*$  !
- A more general result: strong duality for any quadratic optimization problem with two constraints  $\ell \leq x^T Q x \leq u$  if  $Q$  and  $A$  are simultaneously diagonalizable