# MS&E 233 Game Theory, Data Science and Al Lecture 11

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(by courtesy) Computer Science and Electrical Engineering

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#### **Computational Game Theory for Complex Games**

- Basics of game theory and zero-sum games (T)
- Basics of online learning theory (T)
- Solving zero-sum games via online learning (T)
- HW1: implement simple algorithms to solve zero-sum games
- Applications to ML and AI (T+A)
- HW2: implement boosting as solving a zero-sum game
- Basics of extensive-form games
- Solving extensive-form games via online learning (T)
- HW3: implement agents to solve very simple variants of poker
- General games, equilibria and online learning (T)
- Online learning in general games

(3)

 HW4: implement no-regret algorithms that converge to correlated equilibria in general games

#### **Data Science for Auctions and Mechanisms**

- Basics and applications of auction theory (T+A)
- Basic Auctions and Learning to bid in auctions (T)
- HW5: implement bandit algorithms to bid in ad auctions

- Optimal auctions and mechanisms (T)
- Simple vs optimal mechanisms (T)
- HW6: calculate equilibria in simple auctions, implement simple and optimal auctions, analyze revenue empirically
- Optimizing mechanisms from samples (T)
- Online optimization of auctions and mechanisms (T)
  - HW7: implement procedures to learn approximately optimal auctions from historical samples and in an online manner

#### **Further Topics**

5

- Econometrics in games and auctions (T+A)
- A/B testing in markets (T+A)
- HW8: implement procedure to estimate values from bids in an auction, empirically analyze inaccuracy of A/B tests in markets

#### **Guest Lectures**

- Mechanism Design and LLMs, Song Zuo, Google Research
- A/B testing in auction markets, Okke Schrijvers, Central Applied Science, Meta

#### No-Regret Learning with Bandit Feedback

#### At each period *t*

- Adversary chooses a loss vector  $\ell_t \in [0, 1]^N$
- I choose an action  $i_t$  (not knowing  $\ell_t$ )
- I observe loss of my chosen action  $\ell_t^{l_t}$
- I want to guarantee small expected regret with any fixed action:

$$\max_{i \in N} E \left| \frac{1}{T} \sum_{t=1}^{T} \ell_t^{i_t} - \ell_t^i \right| \le \epsilon(T)$$

#### Constructing Un-biased Estimates of Vector

- There is a hidden loss vector  $\ell_t = \left(\ell_t^1, \dots, \ell_t^N\right)$  (potential outcomes)
- At each period I choose action (treatment) j with probability  $p_t^{j}$
- I learn the loss  $\ell_t^j$  with probability  $p_t^j$
- Remember: no-regret algorithms work well, even if we have unbiased proxies of the true losses (e.g. Monte Carlo CFR)

Question. Can I construct a random variable that guarantees that in expectation over the choice of actions?

$$E\left[\tilde{\ell}_{t}\right] = \ell_{t} \Leftrightarrow \forall j \colon E\left[\tilde{\ell}_{t}^{j}\right] = \ell_{t}^{j}$$

#### Constructing Un-biased Estimates of Vector

Question. Can I construct a random variable that guarantees that in expectation over the choice of actions?

$$E\left[\tilde{\ell}_{t}\right] = \ell_{t} \Leftrightarrow \forall j \colon E\left[\tilde{\ell}_{t}^{j}\right] = \ell_{t}^{j}$$

• Random variable can always depend on identity of chosen action  $j_t$ . When I choose j random variable can also depend on  $\ell_t^j$ 

$$\tilde{\ell}_t^j = 1\{j_t = j\}f_j(\ell_t^j) + 1\{j_t \neq j\}g_j(j_t)$$

• Let's make  $g_j$  zero, and  $f_j$  linear in  $\ell_t^j$ 

$$\tilde{\ell}_t^j = 1\{j_t = j\}a_j\ell_t^j \Rightarrow E\left[\tilde{\ell}_t^j\right] = p_t^j a_j\ell_t^j = \ell_t^j \Rightarrow a_j = \frac{1}{p_t^j}$$

#### **Inverse Propensity Estimates**

#### At each period *t*

Consider the random variables

$$\tilde{\ell}_t^j = \frac{1\{j_t = j\}}{p_t^j} \ell_t^j$$

- The vector  $\tilde{\ell}_t$  can always be calculated  $\left(0,\dots,0,\frac{\ell_t^{j_t}}{p_t^{j_t}},0,\dots,0\right)$
- The vector  $\tilde{\ell}_t$  is an unbiased proxy of the true loss vector:

$$E\big[\tilde{\ell}_t\big] = \ell_t$$

#### The EXP Algorithm with Bandit Feedback

```
Initialize pt to the uniform distribution
For t in 1..T
    Draw action jt based on distribution pt
    Observe loss of chosen action lt[jt]
    Construct un-biased proxy loss vector
      ltproxy[j] = 1(jt=j) * lt[jt] / pt[jt]
    Update probabilities based on EXP update
      pt = pt * exp(-eta * ltproxy)
      pt = pt / sum(pt)
```

### **Recap:** Regret of FTRL

(FTRL) 
$$x_t = \underset{x \in X}{\operatorname{argmin}} \left[ \sum_{\tau < t} \langle x, \ell_\tau \rangle \right] + \left[ \frac{1}{\eta} \mathcal{R}(x) \right]$$
 1-strongly convex function of  $x$  that stabilizes the maximizer

Historical performance of always choosing strategy *x* 

Theorem. Assuming the utility function at each period

$$f_t(x) = \langle x, \ell_t \rangle$$

is L-Lipschitz with respect to some norm  $\|\cdot\|$  and the regularizer is 1-strongly convex with respect to the same norm then

Regret – FTRL(T) 
$$\leq \eta L + \frac{1}{\eta T} \left( \max_{x \in X} \mathcal{R}(x) - \min_{x \in X} \mathcal{R}(x) \right)$$

Average stability induced by regularizer

Average loss distortion caused by regularizer

Problem! The loss vector  $\tilde{\ell}_t$  is not in [0,1].

It can take huge values, as probability of an action goes to 0!

Intuition: if probability goes to 0, then this action is chosen very infrequently. The loss vector very rarely takes this large value, i.e., the *variance* of the loss should be small.

#### Variance of Loss Vector

Variance is

$$E\left[\left(\tilde{\ell}_{t}^{j}\right)^{2}\right] - E\left[\tilde{\ell}_{t}^{j}\right]^{2} = E\left[\left(\tilde{\ell}_{t}^{j}\right)^{2}\right] - E\left[\ell_{t}^{j}\right]^{2}$$

• Second term is in [0, 1]. We will focus on first term (call it "variance")

$$E\left[\left(\tilde{\ell}_t^j\right)^2\right] = p_t^j \left(\frac{\ell_t^j}{p_t^j}\right)^2 = \frac{\left(\ell_t^j\right)^2}{p_t^j}$$

• And we collect this "variance" term only when end up choosing j

Average "Variance" = 
$$\sum_{j} p_{t}^{j} \cdot E\left[\left(\tilde{\ell}_{t}^{j}\right)^{2}\right] = \sum_{j} \left(\ell_{t}^{j}\right)^{2} \leq N$$

### Recap: Regret of FTRL

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$$x_t = \underset{x \in X}{\operatorname{argmin}} \left[ \sum_{\tau < t} \langle x, \ell_{\tau} \rangle \right] + \left[ \frac{1}{\eta} \mathcal{R}(x) \right]$$
 1-strongly convex function of  $x$  that stabilizes the maximizer

Historical performance of always choosing strategy *x* 

Can we replace *L* with the Average "Variance"?

**Theorem.** Assuming the utility function at each period

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is L Lipschitz with respect to some norm  $\|\cdot\|$  and the regularizer is 1-strongly convex with respect to the same norm then

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$$\leq \eta L + \frac{1}{\eta T} \left( \max_{x \in X} \mathcal{R}(x) - \min_{x \in X} \mathcal{R}(x) \right)$$

Average stability induced by regularizer

Average loss distortion caused by regularizer

(EXP) 
$$p_{t} = \underset{p \in \Delta}{\operatorname{argmin}} \sum_{\tau < t} \langle p, \tilde{\ell}_{\tau} \rangle + \frac{1}{\eta} \mathcal{R}(p) \begin{pmatrix} \operatorname{Negative} \\ \operatorname{Entropy} \end{pmatrix} \mathcal{R}(p) = \sum_{i=1}^{n} p_{i} \log(p_{i})$$
$$p_{t} \propto p_{t-1} \exp(-\eta \ \tilde{\ell}_{t-1})$$

**Theorem.** Assuming  $\tilde{\ell}_t$  are random proxies that, conditional on history, have expected value equal to true loss vector  $\ell_t$  and  $\tilde{\ell}_t \geq 0$ , then regret of EXP is bounded as:

Regret 
$$- \text{EXP}(T) \le \frac{\eta}{T} \sum_{t} E \left[ \sum_{j} p_{t}^{j} \left( \tilde{\ell}_{t}^{j} \right)^{2} \right] + \frac{\log(N)}{\eta T}$$

(EXP) 
$$p_t = \underset{p \in \Delta}{\operatorname{argmin}} \sum_{\tau < t} \langle p, \tilde{\ell}_{\tau} \rangle + \underbrace{\frac{1}{\eta} \mathcal{R}(p)}_{\text{Entropy}} \left( \underset{\text{Entropy}}{\operatorname{Negative}} \right) \mathcal{R}(p) = \sum_{i=1}^n p_i \log(p_i)$$

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$$- \text{EXP}(T) \le \frac{\eta}{T} \sum_{t} E \left[ \sum_{j} p_{t}^{j} E \left[ \left( \tilde{\ell}_{t}^{j} \right)^{2} \right] + \frac{\log(N)}{\eta T} \right]$$

Expected Average "Variance"?

(EXP) 
$$p_{t} = \underset{p \in \Delta}{\operatorname{argmin}} \sum_{\tau < t} \langle p, \tilde{\ell}_{\tau} \rangle + \left[ \frac{1}{\eta} \mathcal{R}(p) \right] \left( \underset{\text{Entropy}}{\operatorname{Negative}} \right) \mathcal{R}(p) = \sum_{i=1}^{n} p_{i} \log(p_{i})$$
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Regret – EXP
$$(T) \le \frac{\eta}{T} \sum_{t} N + \frac{\log(N)}{\eta T}$$

For the inverse propensity proxies

(EXP) 
$$p_{t} = \underset{p \in \Delta}{\operatorname{argmin}} \sum_{\tau < t} \langle p, \tilde{\ell}_{\tau} \rangle + \left[ \frac{1}{\eta} \mathcal{R}(p) \right] \left( \underset{\text{Entropy}}{\operatorname{Negative}} \right) \mathcal{R}(p) = \sum_{i=1}^{n} p_{i} \log(p_{i})$$
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Regret – EXP(T) 
$$\leq \eta N + \frac{\log(N)}{\eta T} \Rightarrow \text{Regret} - \text{EXP}(T) \lesssim \sqrt{\frac{N \log(N)}{T}}$$

## Back to Bandit Learning in Auctions

#### **Bandit Learning in Auctions**

ullet Want to choose my bids  $b_i^t$ , based on algorithm that guarantees

$$\frac{1}{T} \sum_{t=1}^{T} u_i(b^t) \ge \max_{b_i \in [N]} \frac{1}{T} \sum_{t=1}^{T} u_i(b_i, b^t) - \epsilon(T)$$

- We can apply EXP3 algorithm for each bidder
- We now have utilities, but EXP3 expects non-negative losses
   Maximizing utility = Minimizing (negative utility)
- However, to ensure losses are non-negative, add a large enough offset loss = H utility
- If for instance we know that utility  $\leq H$ , we can choose this H above

(EXP) 
$$p_{t} = \underset{p \in \Delta}{\operatorname{argmin}} \sum_{\tau < t} \langle p, \tilde{\ell}_{\tau} \rangle + \frac{1}{\eta} \mathcal{R}(p) \begin{cases} \operatorname{Negative} \\ \operatorname{Entropy} \end{cases} \mathcal{R}(p) = \sum_{i=1}^{n} p_{i} \log(p_{i})$$
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$$\leq \eta N + \frac{\log(N)}{\eta T} \Rightarrow \text{Regret} - \text{EXP}(T) \lesssim \sqrt{\frac{N \log(N)}{T}}$$

#### Sum: Vickrey-Clarke-Groves (VCG)

A universal welfare maximizing auction/mechanism!

For any mechanism design setting, it guarantees that:

- 1. It is dominant strategy truthful
- 2. It always chooses the welfare maximizing outcome/allocation
- 3. All bidders have non-negative utility
- 4. All payments are non-negative

For special case of single-item auction = Second-Price Auction

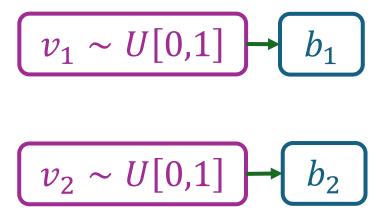
## What if we want to maximize revenue?

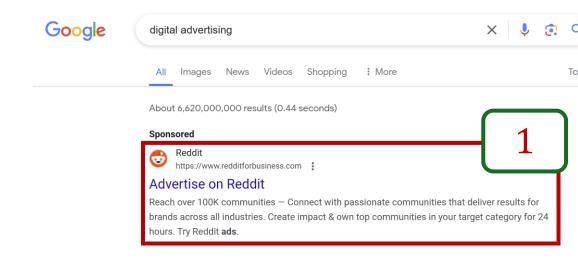
## Let's go back to basics: Single-Item Auction

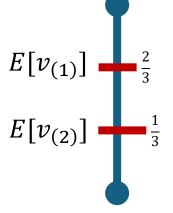
• How much revenue does the second-price auction achieve?

Rev = 
$$E[v_{(2)}] = E[\min(v_1, v_2)] = 1/3$$

Can we do better?







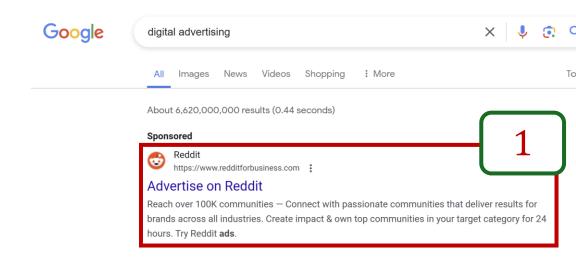
### Let's go back to basics: Single-Item Auction

What if we only had one bidder?

$$Rev = E[v_{(2)}] = 0$$

Can we do better?



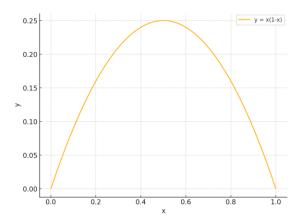


What if we post a reserve price?

### Let's go back to basics: Single-Item Auction

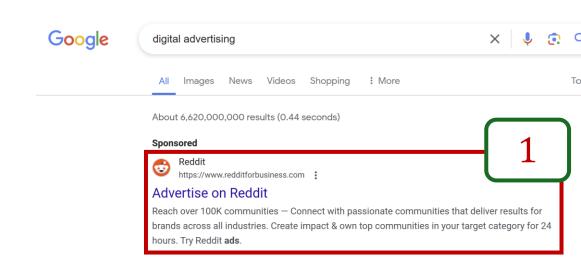
• Auctioneer: "If you bid less than r, I will not accept your bid and not show any ad on the page! If you win you must pay r."

$$Rev(r) = E[r \ 1(v \ge r)] = r \ (1 - r) \Rightarrow Rev(1/2) = 1/4$$



- Is the auction truthful?
- Is the auction efficient?

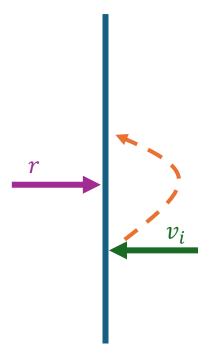




#### Truthfulness of Mechanism

Suppose I bid my value. Would I want to deviate?

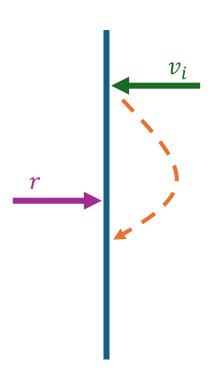
- Case 1. My value is below reserve price
- Only way to change anything is bid above
- But then I get negative utility as I pay more than value



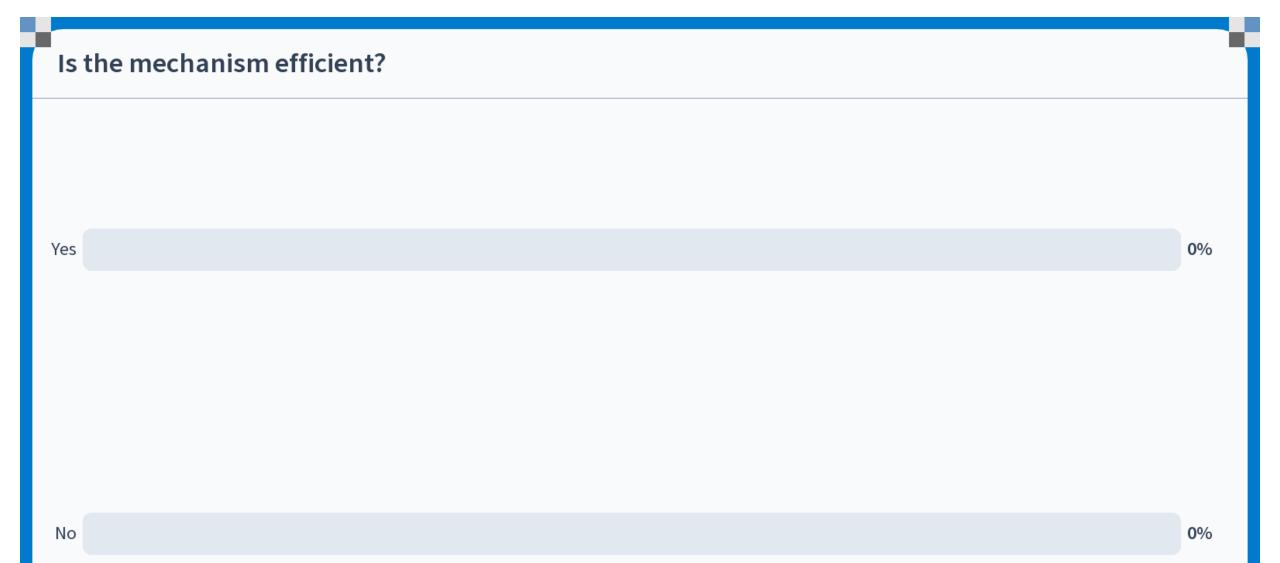
#### Truthfulness of Mechanism

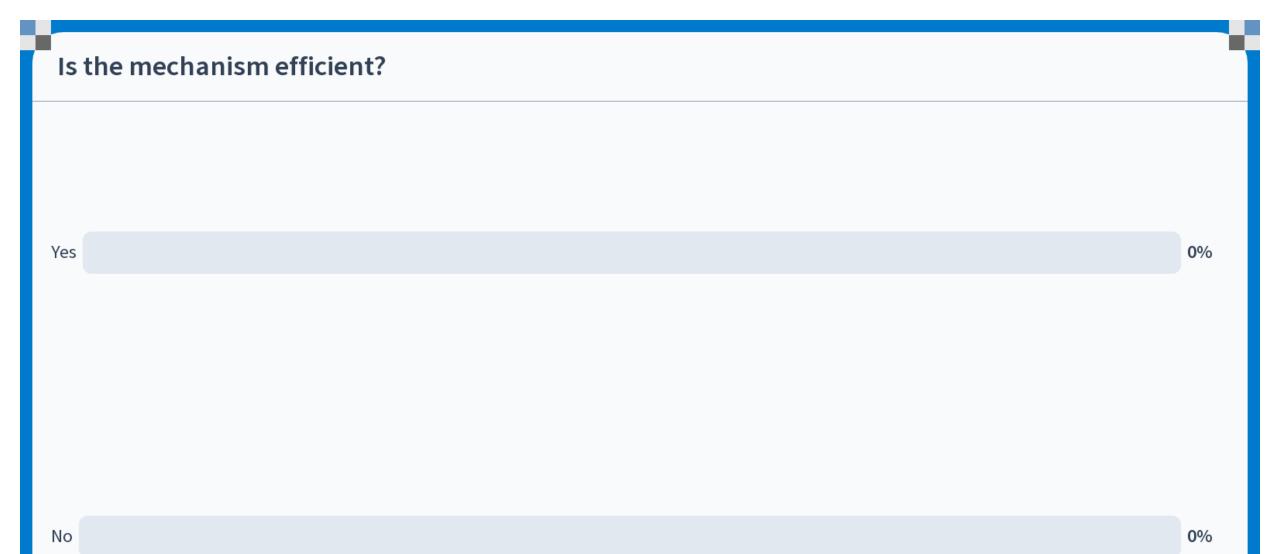
Suppose I bid my value. Would I want to deviate?

- Case 2. My value is above reserve price
- I get non-negative utility
- Only way to change anything is bid below
- But then I get zero utility as I lose







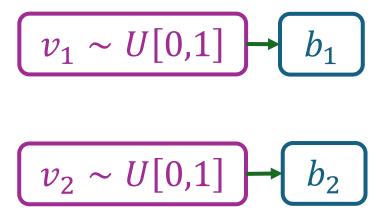


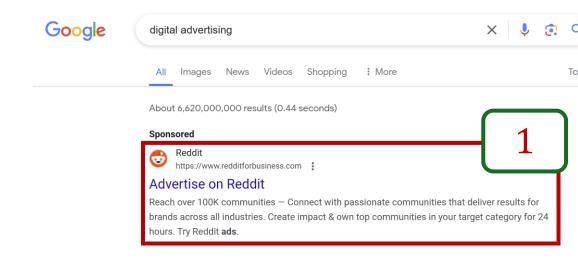
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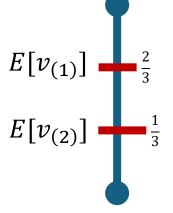
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Rev = 
$$E[v_{(2)}] = E[\min(v_1, v_2)] = 1/3$$

Can we do better?





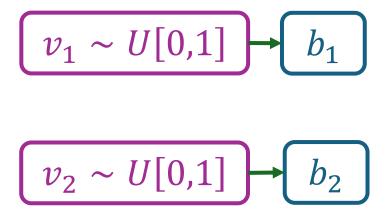


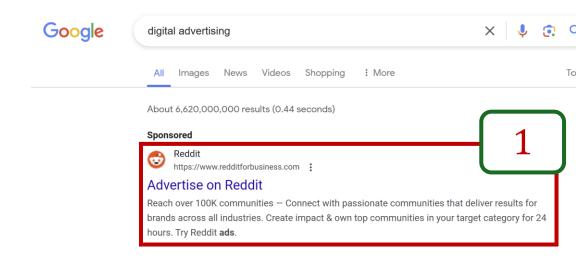
## Let's go back to basics: Single-Item Auction

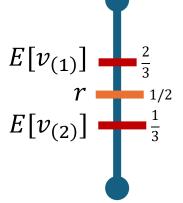
• Auctioneer: "If you bid less than r, I will not accept your bid! If you win you must pay  $\max(\mathbf{b}_2, r)$ ."

$$Rev(1/2) = E[\max(v_{(2)}, r) 1(v_{(1)} \ge r)] = 5/12$$

Can we do better?







## How do we optimize over all possible mechanisms!

#### Single-Parameter Settings

- ullet Each bidder has some value  $v_i$  for being allocated
- Bidders submit a reported value  $b_i$  (without loss of generality)
- Mechanism decides on an allocation  $x \in X \subseteq \text{Reals}^n$
- Mechanism fixes a probabilistic allocation rule:  $x(b) \in \Delta(X)$

• First question. Given an allocation rule, when can we find a payment rule 
$$p$$
 so that the overall mechanism is truthful?

• If we can find such a payment, we will say that x is implementable

#### Some Shorthand Notation

- Let's fix bidder i and what other bidders bid  $b_{-i}$
- For simplicity of notation, we drop index i and  $b_{-i}$
- What properties does the function

$$x(v) \equiv x_i(v, b_{-i})$$

need to satisfy, so that x is implementable?

Can we find a truthful payment function

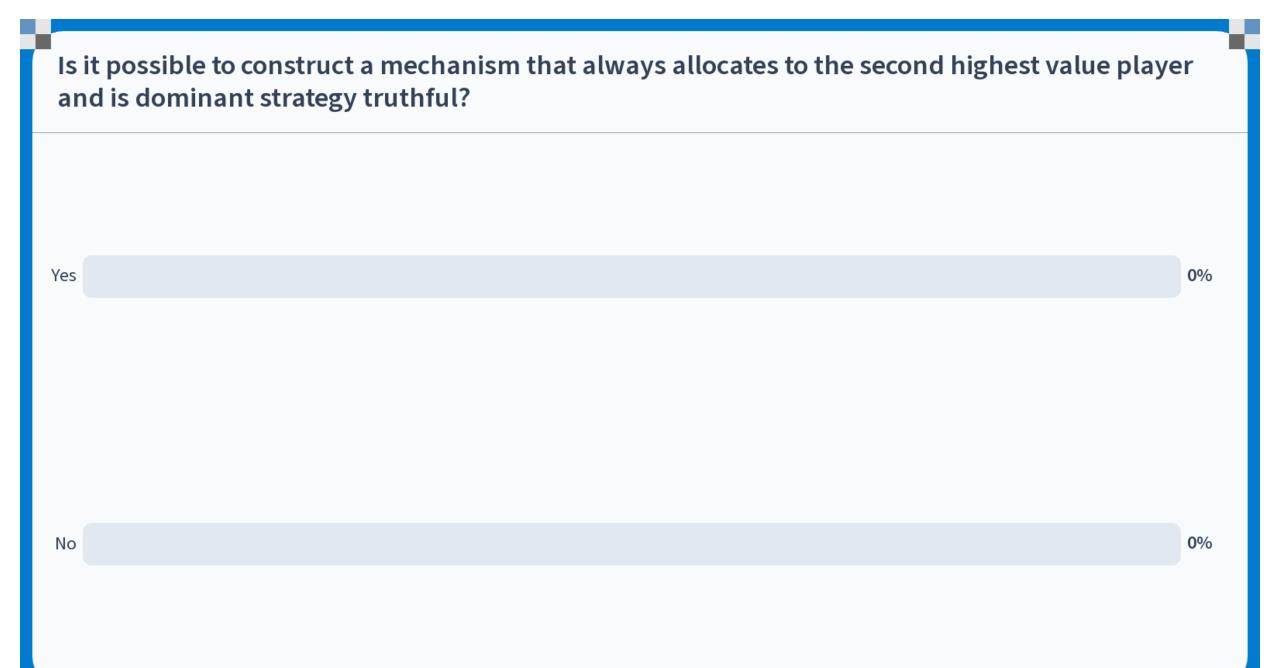
$$p(v) \equiv p(v, b_{-i})$$

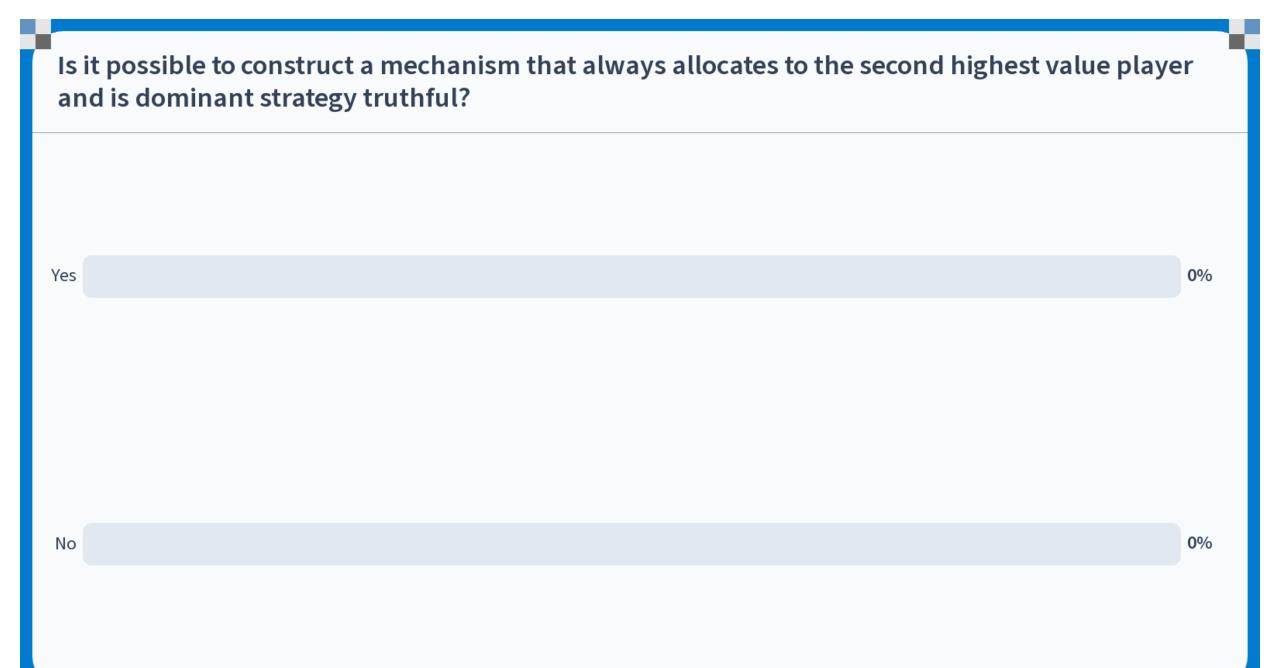
Is it possible to construct a mechanism that always allocates to the second highest value player and is dominant strategy truthful?

Is it possible to construct a mechanism that always allocates to the second highest value player and is dominant strategy truthful?

Yes

No





#### Suppose it is possible

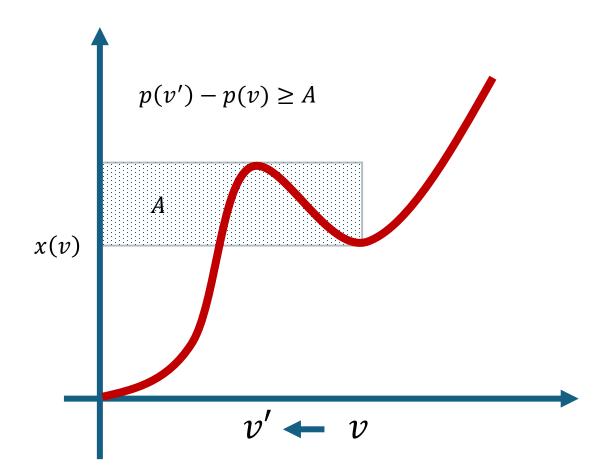
Suppose that we both bid truthfully

Suppose that I am the highest value bidder

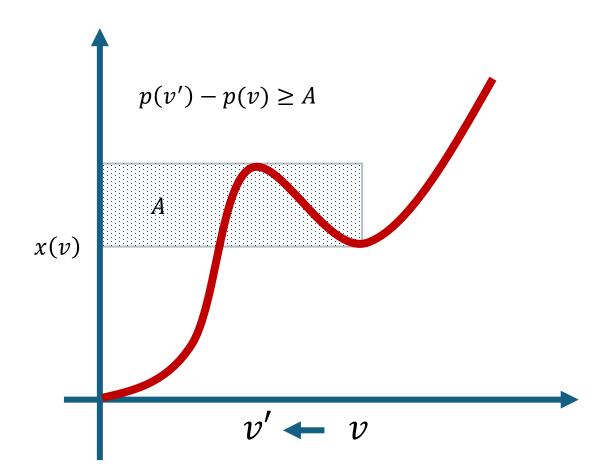
• No matter what the payment rule is, I can always reduce my bid to the second highest bid minus  $\epsilon$ 

 By doing so, I am paying at most the second highest bid and I am winning deterministically

$$v \cdot x(v) - p(v) \ge v \cdot x(v') - p(v')$$

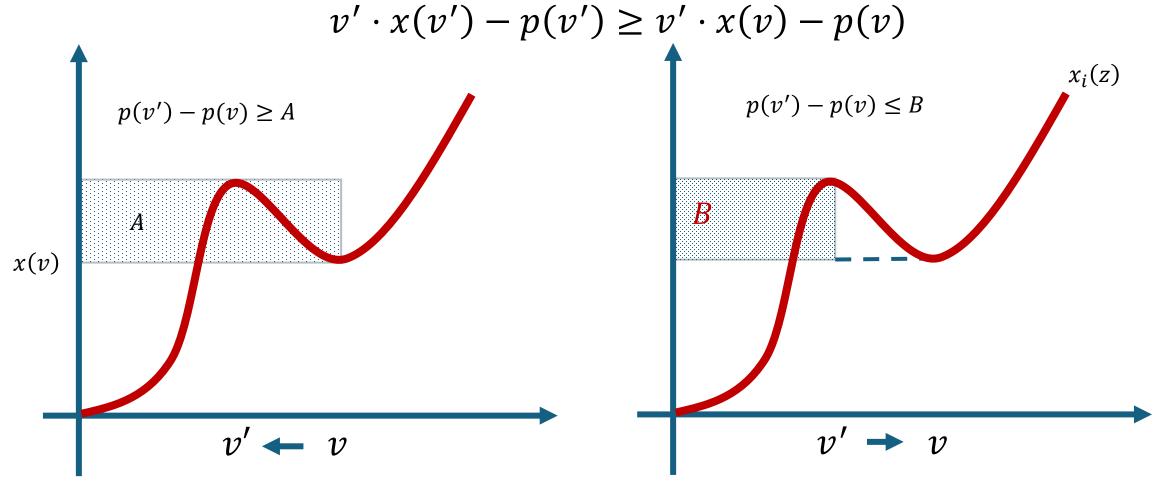


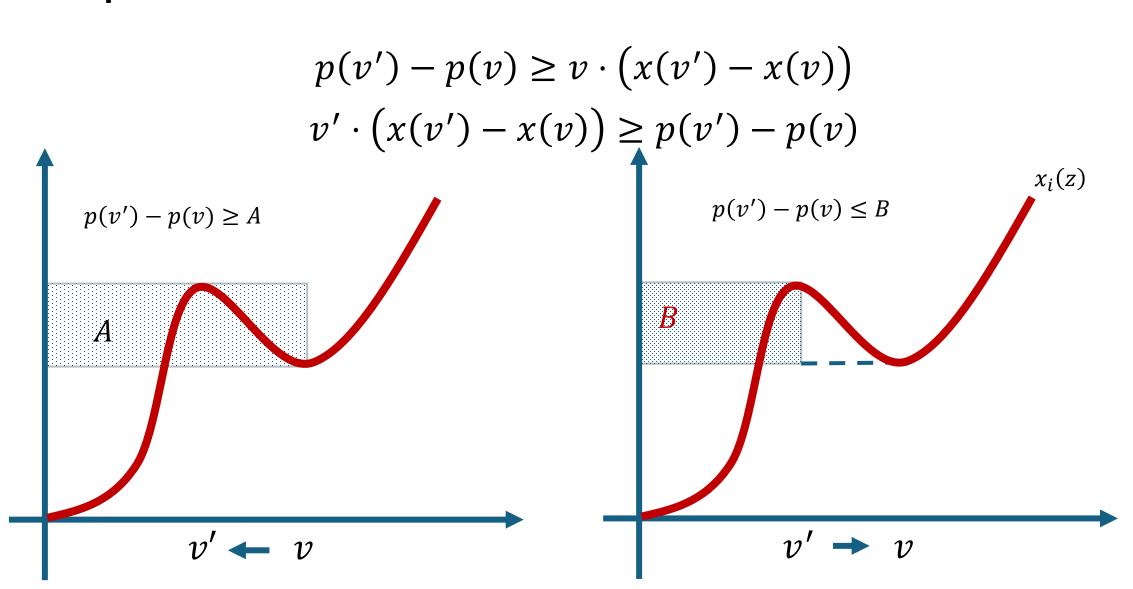
$$p(v') - p(v) \ge v \cdot (x(v') - x(v))$$

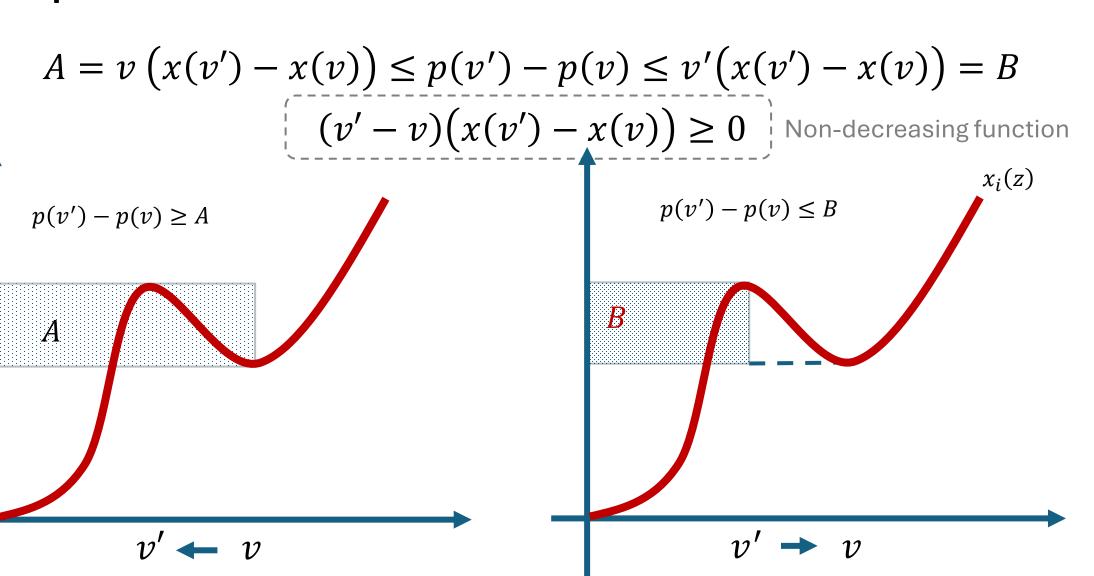


$$p(v') - p(v) \ge v \cdot (x(v') - x(v))$$

$$v' \cdot x(v') - p(v') \ge v' \cdot x(v) - p(v)$$







Any implementable allocation rule must be monotone!

"If not allocated with value v, I should not be allocated if I report a lower value!"

#### Uniqueness of Payment Rule

• I should not want to pretend to have value  $v+\epsilon$ , for infinitesimal  $\epsilon$ 

$$u(v) \ge v \cdot x(v + \epsilon) - p(v + \epsilon)$$

$$= (v + \epsilon) \cdot x(v + \epsilon) - p(v + \epsilon) - \epsilon \cdot x(v + \epsilon)$$

$$= u(v + \epsilon) - \epsilon \cdot x(v + \epsilon)$$

Dividing over by  $\epsilon$ , restricts the rate of change of utility

$$\frac{u(v+\epsilon)-u(v)}{\epsilon} \le x(v+\epsilon)$$

#### Uniqueness of Payment Rule

• I should not want to pretend to have value  $v-\epsilon$ , for infinitesimal  $\epsilon$ 

$$u(v) \ge v \cdot x(v - \epsilon) - p(v - \epsilon)$$

$$= (v - \epsilon) \cdot x(v - \epsilon) - p(v - \epsilon) + \epsilon \cdot x(v - \epsilon)$$

$$= u(v - \epsilon) + \epsilon \cdot x(v - \epsilon)$$

Dividing over by  $\epsilon$ , restricts the rate of change of utility

$$\frac{u(v) - u(v - \epsilon)}{\epsilon} \ge x(v - \epsilon)$$

#### Uniqueness of Payment Rule

I should not want to deviate locally up or down infinitesimally

$$\frac{u(v+\epsilon) - u(v)}{\varepsilon} \le x(v+\epsilon)$$

$$\frac{u(v) - \epsilon}{\varepsilon} \ge x(v-\epsilon)$$

- If u was differentiable, then taking the limit of the above as  $\epsilon \to 0$   $x(v) \le u'(v) \le x(v) \Rightarrow u'(v) = x(v)$
- Under any truthful payment rule, utility is uniquely determined by allocation

$$u(v) - u(0) = \int_0^v x(z) dz$$

Under any truthful payment rule 
$$u(v) = u(0) + \int_0^v x(z) dz$$

#### Discontinuity of Allocation Rule

 Even though allocation rule can be discontinuous, because it is monotone, it is Riemann integrable

$$\int_{0}^{v} x(z) dz = \lim_{\epsilon \to 0} \sum_{k=0}^{v/\epsilon} x(\epsilon \cdot (k+1)) \cdot \epsilon$$

$$\geq \lim_{\epsilon \to 0} \sum_{k=0}^{v/\epsilon} u(\epsilon \cdot (k+1)) - u(\epsilon \cdot k) = u(v) - u(0)$$

$$\int_{0}^{v} x(z) dz = \lim_{\epsilon \to 0} \sum_{k=0}^{v/\epsilon} x(\epsilon \cdot (k-1)) \cdot \epsilon$$

$$\leq \lim_{\epsilon \to 0} \sum_{k=0}^{v/\epsilon} u(\epsilon \cdot k) - u(\epsilon \cdot (k-1)) = u(v) - u(0)$$

Under any truthful payment rule 
$$u(v) = u(0) + \int_0^v x(z) dz$$

#### What does that imply about payments

Since utility is value minus payment

$$v x(v) - p(v) = -p(0) + \int_0^v x(z) dz$$

- Non-Negative-Transfers (NNT). We never have negative payments  $p(0) \geq 0$
- Individually Rational (IR). We never give bidders negative utility  $p(0) \leq 0$
- Thus, payment at 0 should be zero!

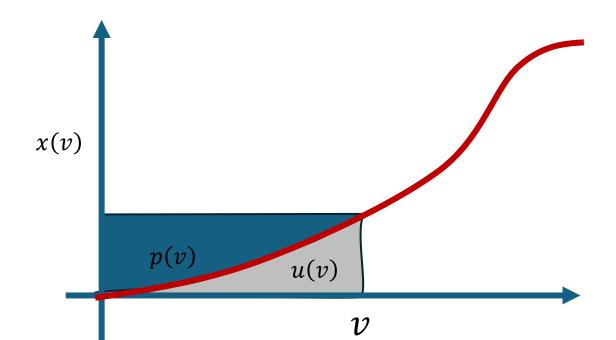
## Under any truthful payment rule that satisfies NNT and IR

$$p(v) = v \cdot x(v) - \int_0^v x(z) dz$$

# Given an allocation rule, the payment is uniquely determined!

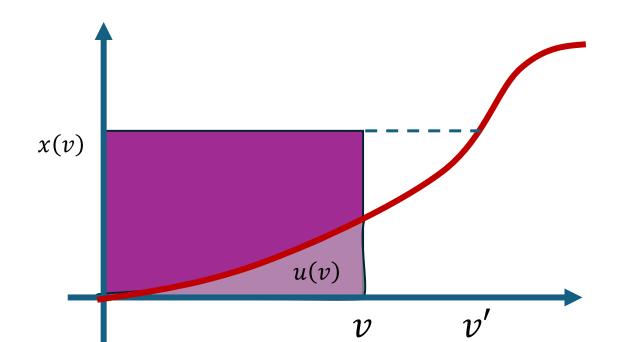
$$u(v) = \int_0^v x(z) dz$$

$$p(v) = v \cdot x(v) - \int_0^v x(z) dz$$



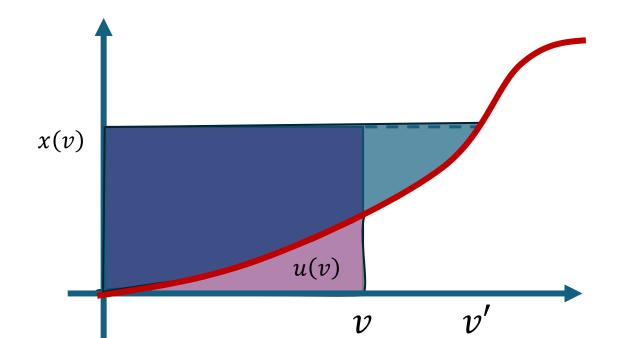
$$u(v) = \int_0^v x(z) \, dz$$

$$p(v) = v \cdot x(v) - \int_0^v x(z) dz$$



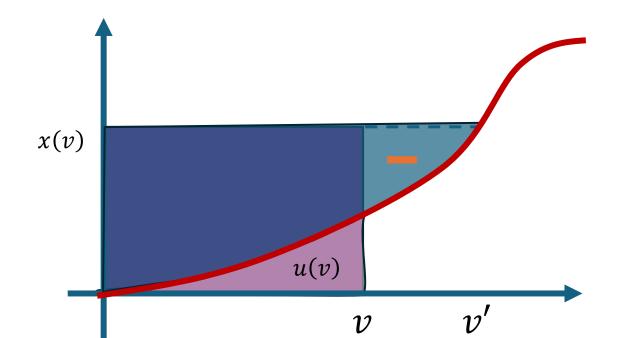
$$u(v) = \int_0^v x(z) dz$$

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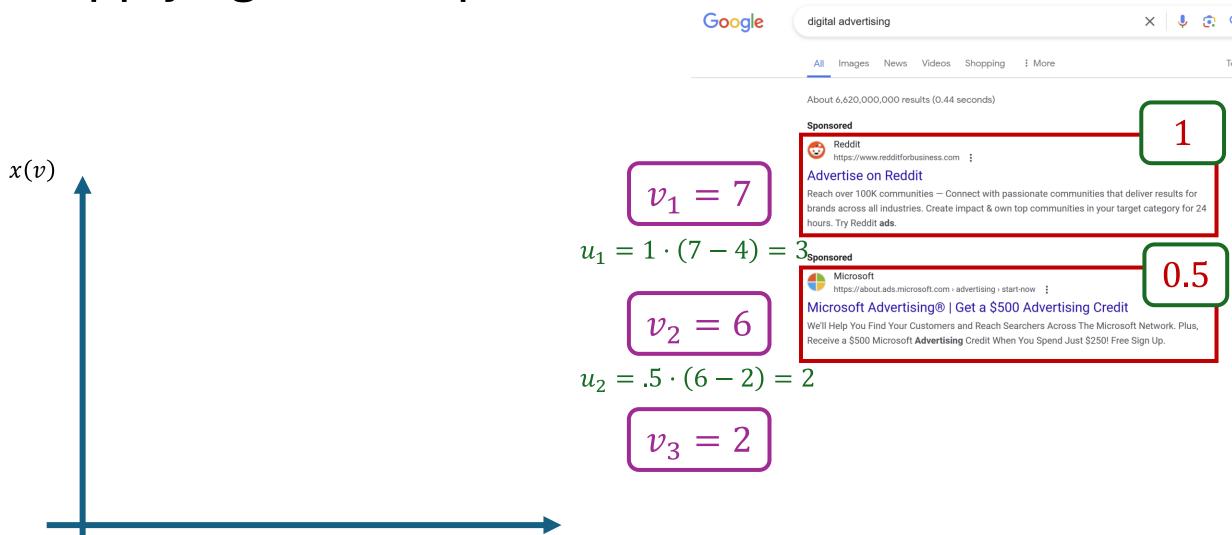


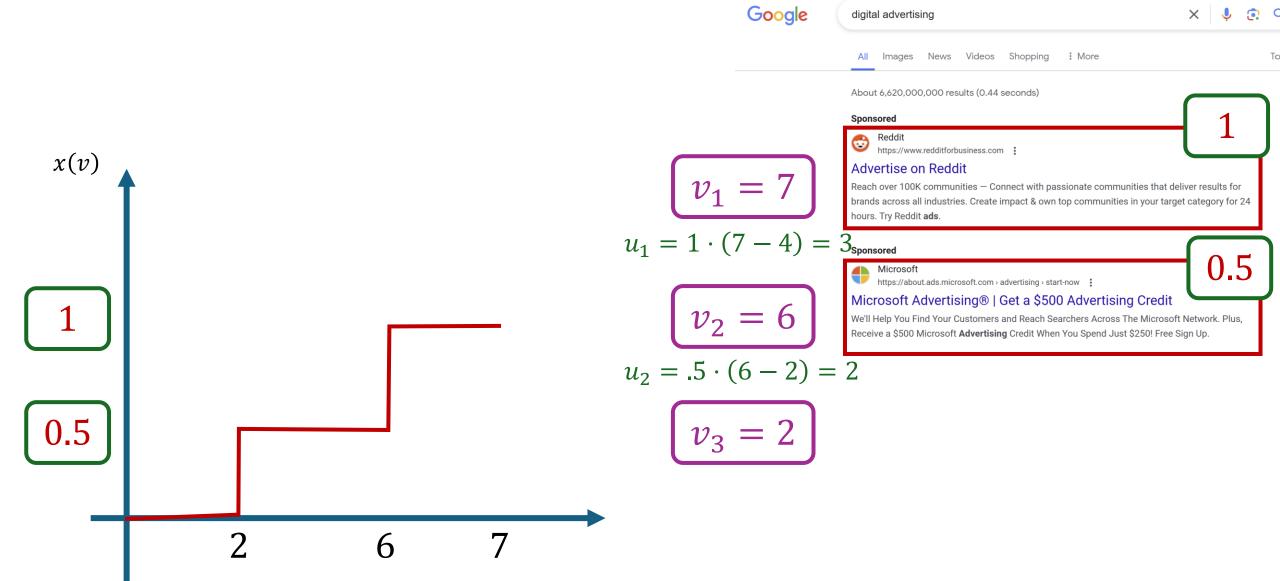
$$u(v) = \int_0^v x(z) \, dz$$

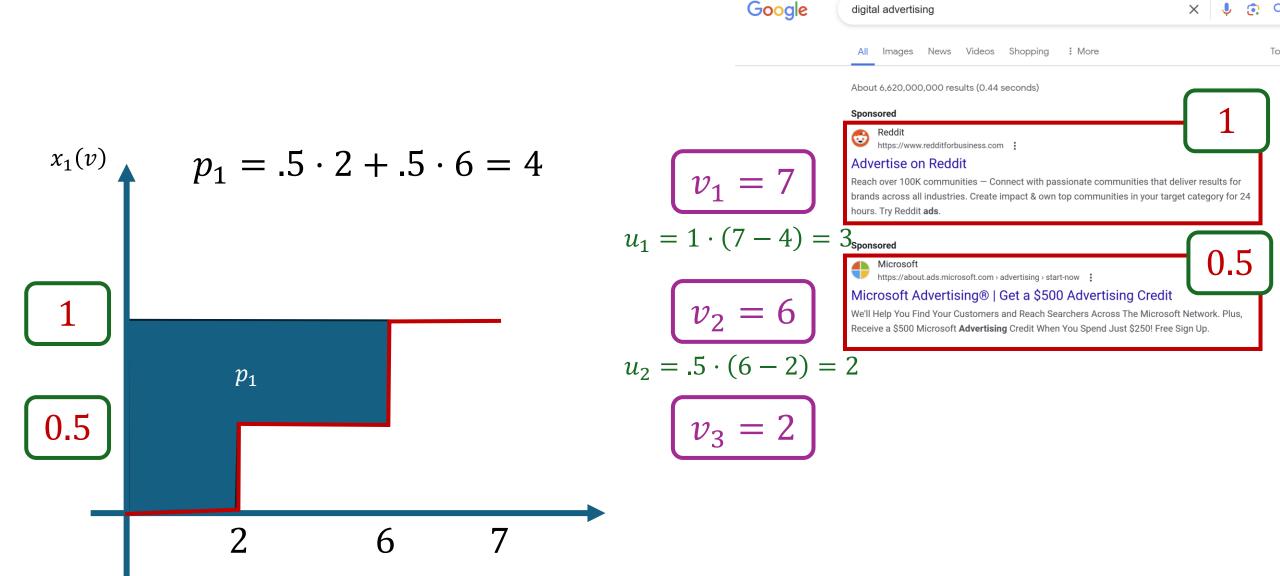
$$p(v) = v \cdot x(v) - \int_0^v x(z) dz$$

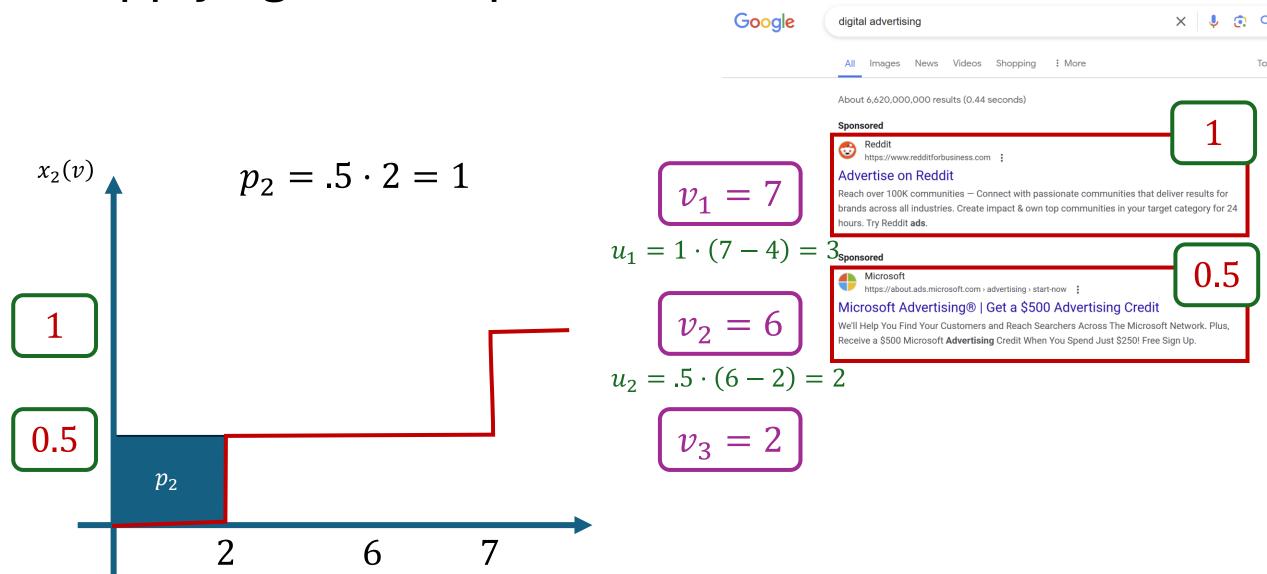


## Back to Sponsored Search





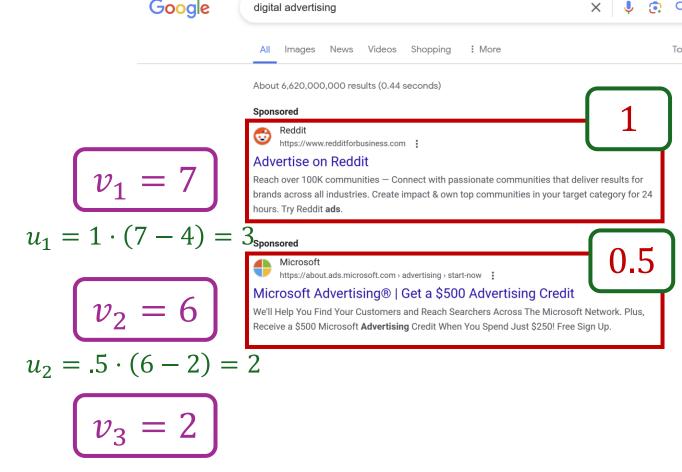




With an arbitrary number of slots, payment of bidder in slot j is:

$$p_{(j)} = \sum_{\ell=j}^{k} (a_{\ell} - a_{\ell+1}) \cdot b_{(\ell+1)}$$

where  $b_{(\ell)}$  is the bid of the player allocated in slot  $\ell$ 



## Optimizing over allocation rules

#### Myerson's Theorem

- Let x, p be any DSIC mechanism
- Suppose each value  $v_i \sim F_i$  independently and let  $v=(v_1,\dots,v_n)$   $E[p_i(v)] = E[x_i(v)\cdot\phi_i(v_i)]$

where  $\phi_i(v_i)$  is bidder i's "virtual value".

• Letting  $F_i$  the CDF and  $f_i$  the density:

$$\phi_i(v_i) = v_i - \frac{1 - F_i(v_i)}{f_i(v_i)}$$

- Assuming  $\phi_i(v_i)$  is monotone non-decreasing, then the optimal DSIC mechanism is the mechanism that maximizes virtual welfare  $\sum_i x_i \phi_i(v_i)$
- For a single item auction setting, this is the mechanism that allocates to the highest virtual value bidder (or none if highest virtual value is negative)

#### Back to Uniform Example

- If  $v_i \sim U[0,1]$  then F(v) = v and f(v) = 1
- Virtual value simplifies to

$$\phi_i(v_i) = v_i - (1 - v_i) = 2v_i - 1$$

• We should allocate to the highest virtual value player, as long as the highest virtual value is non-negative

$$v_i \ge 1/2$$

- Since all virtual value functions are the same, allocating to the highest virtual value is the same as allocating to the highest value
- Simply: Second Price with a reserve price of 1/2!

#### Myerson's Theorem

• Consider the revenue contribution of a single bidder i and drop other bids and index from notation

$$E[p(v)] = E\left[v x(v) - \int_0^v x(z)dz\right] = E\left[v \hat{x}(v) - \int_0^v \hat{x}(z)dz\right]$$

- Allocation  $\hat{x}(z)$  is the expected allocation over other bidder values  $\hat{x}(z) = E_{v_{-i}}[x(z,v_{-i})]$
- We can do an exchange of the integrals:

$$E\left[\int_0^v \hat{x}(z) dz\right] = \int_{v=0}^\infty \int_{z=0}^v \hat{x}(z) dz f(v) dv = \int_{z=0}^\infty \hat{x}(z) \int_{v=z}^\infty f(v) dv dz$$
$$= \int_{z=0}^\infty \hat{x}(z) \left(1 - F(z)\right) dz = E\left[\hat{x}(v) \frac{1 - F(v)}{f(v)}\right]$$

#### Myerson's Theorem (cont'd)

 Consider the revenue contribution of a single bidder i and drop other bids and index from notation

$$E[p(v)] = E\left[\hat{x}(v)\left(v - \hat{x}(v)\frac{1 - F(v)}{f(v)}\right)\right] = E[\hat{x}(v)\phi(v)]$$

Re-introducing the bidder index:

$$E[p_i(v)] = E[\hat{x}_i(v_i) \cdot \phi_i(v_i)] = E[x_i(v) \cdot \phi_i(v_i)]$$

Summing across bidders we get:

$$\sum_{i} E[p_i(v)] = \sum_{i} E[x_i(v) \cdot \phi_i(v_i)] = E\left[\sum_{i} x(v) \cdot \phi_i(v_i)\right]$$

Myerson's Optimal Auction. The optimal mechanism is the mechanism that maximizes virtual welfare (and charges the corresponding payments that make this truthful)

$$x(v) = \operatorname{argmax}_{x \in X} \sum_{i} x \cdot \phi_{i}(v_{i}), \qquad p_{i}(v) = v_{i}x_{i}(v) - \int_{0}^{v_{i}} x_{i}(z, v_{-i}) dz$$

$$Rev = E \left[ \max_{x \in X} \sum_{i} x \cdot \phi_i(v_i) \right]$$

#### **Appendix:** Deriving the Optimal Reserve

• Bidders are symmetric. Revenue is twice the revenue we collect from each bidder

$$\begin{aligned} \operatorname{Rev}_{1}(r) &= E[\max(v_{2}, r) \ 1(v_{1} \geq \max(v_{2}, r))] \\ &= E[v_{2} \mid v_{2} \in [r, v_{1}]] \Pr(v_{2} \in [r, v_{1}] | v_{1} \geq r) \Pr(v_{1} \geq r) + r \Pr(v_{2} \leq r) \Pr(v_{1} \geq r) \\ &= \int_{r}^{1} \frac{v + r}{2} (v - r) dv + r^{2} (1 - r) \\ &= \int_{r}^{1} \frac{v^{2} - r^{2}}{2} dv + r^{2} (1 - r) \\ &= \left(\frac{1 - r^{3}}{6} - \frac{r^{2}}{2} (1 - r) + r^{2} (1 - r)\right) \\ &= \frac{1 - r^{3}}{6} + \frac{r^{2} (1 - r)}{2} = \frac{1 - r^{3} + 3r^{2} - 3r^{3}}{6} = \frac{1 + 3r^{2} - 4r^{3}}{6} \end{aligned}$$

The first order condition

$$(\text{Rev}_1(r))' = r(1 - 2r) = 0 \Rightarrow r = 1/2$$