

DJ4\_grf\_raw.mot ground\_force\_2\_mx ground\_force\_2\_my ground\_force\_2\_mz 0.05 0.05 10 torque (N-m) torque (N-m) torque (N-m) 0.00 0.00 -0.05 -0.05 2.5 3.2 2.2 2.5 2.5 3.2 time (s) time (s) time (s) ground\_force\_3\_vx ground\_force\_3\_vy ground\_force\_3\_vz 0.05 0.05 0.05 force (N) force (N) force (N) 0.00 0.00 0.00 -0.05 <del>-</del>0.05 -0.05 2.2 2.2 2.5 2.8 3.2 2.5 2.8 3.2 2.2 2.5 2.8 3.2 time (s) time (s) time (s) ground\_force\_3\_py ground\_force\_3\_px ground\_force\_3\_pz 0.05 0.05 0.05 position (m) position (m) position (m) 0.00 0.00 0.00 -0.05 남 -0.05 -0.05 2.2 2.8 3.0 2.2 2.5 3.2 2.5 2.8 3.0 3.2 2.2 2.5 2.8 3.0 3.2 time (s) time (s) time (s) ground force 3 mx ground force 3 my ground\_force\_3\_mz 0.05 0.05 0.05 torque (N-m) torque (N-m) torque (N-m) 0.00 0.00 0.00

-0.05

2.2

2.8

time (s)

2.5

3.0

3.2

3.2

3.0

-0.05

2.2

2.5

2.8

time (s)

-0.05

2.2

2.8

time (s)

3.0

3.2

2.5