

lumbar\_rotation arm\_flex arm\_add 0.50 0.0 angle (rad) -0.3 0.25 angle (rad) 0.00 -0.25 -0.2 0.5 1.0 0.0 0.5 1.0 time (s) time (s) time (s) elbow\_flex arm\_rot pro\_sup 0.2 angle (rad) angle (rad)

0.5

time (s)

0.0

0.0

time (s)

angle (rad)

angle (rad)

0.0

time (s)

walking2\_ik.mot (right leg)
walking2\_ik.mot (left leg)