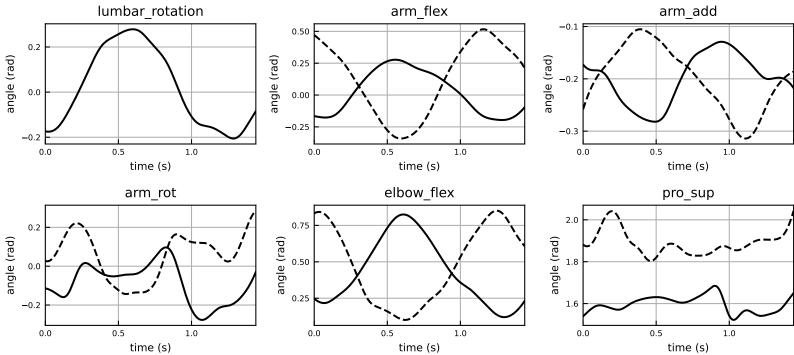


walking3\_ik.mot (left leg) arm\_flex arm\_add -0.1 0.50 angle (rad) angle (rad) 0.25 0.00 -0.25 **-**0.3 0.0 1.0 1.0 time (s) time (s)



walking3\_ik.mot (right leg)