

lumbar_rotation arm_flex arm_add 0.2 -0.25 angle (rad) -0.50 -0.75 angle (rad) angle (rad) 0.0 -0.1 2.0 time (s) 2.0 time (s) 2.0 time (s) 1.0 2.5 1.5 1.5 elbow_flex arm_rot pro_sup 0.0 angle (rad) angle (rad) angle (rad) 2.0 2.5 time (s) time (s) time (s) wrist_flex wrist_dev 0.10 angle (rad) 80.0 60.0 angle (rad) 0.07

> 2.0 time (s)

1.0

1.5

1.0

2.0 time (s) run400_ik.mot (right leg) run400_ik.mot (left leg)