

lumbar_rotation arm_flex arm_add **-**0.25 -0.2 angle (rad) angle (rad) angle (rad) -0.50 -0.75 -0.4 -1.00 -0.4 1.5 time (s) 1.5 time (s) 2.0 2.0 time (s) elbow_flex arm_rot pro_sup 0.1 angle (rad) angle (rad) angle (rad) 2.0 -0.2 1.5 time (s) 1.5 time (s) 0.5 1.0 2.0 1.0 time (s) wrist_flex wrist_dev -0.01 0.06 angle (rad) angle (rad) -0.02 -0.03 0.02 0.5 2.0 1.5 time (s) 1.5 time (s) 1.0 1.0 2.0

run400_ik.mot (right leg) run400_ik.mot (left leg)