

lumbar_rotation arm_flex arm_add 0.2 0.2 angle (rad) angle (rad) -0.30 angle (rad) 0.0 **-**0.35 -0.2 0.0 0.0 0.5 0.5 0.0 time (s) time (s) time (s) elbow_flex arm_rot pro_sup 0.8 1.9 0.4 angle (rad) angle (rad) angle (rad)

0.5

time (s)

0.0

time (s)

0.0

0.0

0.0

0.5

time (s)

walkingTS1_ik.mot (right leg) walkingTS1_ik.mot (left leg)