

walking2\_ik.mot (left leg) lumbar\_rotation arm\_flex arm\_add 0.4 angle (rad) angle (rad) angle (rad) 0.2 0.0 -0.25 **-**0.2 -0.1 0.5 1.0 0.0 0.5 1.0 time (s) time (s) time (s) elbow\_flex arm\_rot pro\_sup 0.2 1.2 angle (rad) angle (rad) angle (rad) -0.2 0.6 2.00 0.0 0.0 0.0 1.0 0.5

time (s)

time (s)

time (s)

walking2\_ik.mot (right leg)