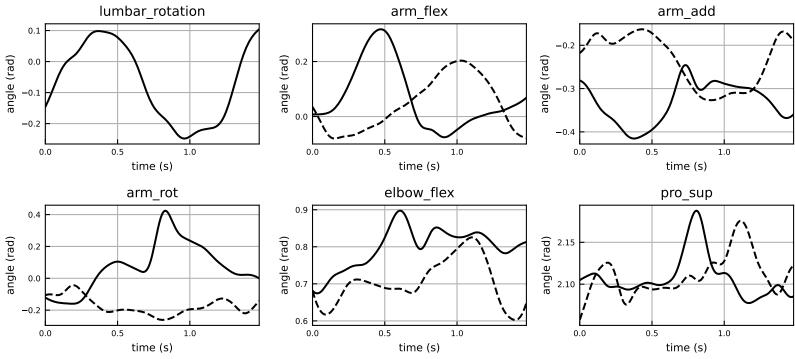


walkingTS2_ik.mot (left leg) arm_flex arm_add angle (rad) angle (rad) -0.3 -0.4 0.5 0.0 0.5 0.0 time (s) time (s) elbow_flex pro_sup 0.9



walkingTS2_ik.mot (right leg)