

lumbar\_rotation arm\_flex arm\_add 1.0 0.05 angle (rad) angle (rad) angle (rad) 0.00 -0.05 0.0 -0.10 2.8 time (s) 2.8 time (s) 2.8 time (s) 2.5 elbow\_flex arm\_rot pro\_sup angle (rad) angle (rad) angle (rad) <del>-</del>0.25

> 2.8 time (s)

2.5

2.8

time (s)

2.8 time (s)

2.2

DJ4\_ik.mot (right leg) DJ4\_ik.mot (left leg)