

lumbar\_rotation arm\_flex arm\_add 0.0 angle (rad) angle (rad) angle (rad) -0.1 -0.50 -0.75 -0.3 2.0 time (s) 2.0 time (s) 2.0 time (s) 2.5 1.0 1.5 2.5 1.5 1.0 1.5 elbow\_flex arm\_rot pro\_sup angle (rad) angle (rad) angle (rad) 1.8 2.0 time (s) 2.0 2.5 1.5 time (s) time (s) wrist\_flex wrist\_dev 1e-3 0.00 angle (rad) angle (rad) 1.0 2.5 1.0 2.0 time (s) 2.0 time (s) 1.5 2.5

run200\_ik.mot (right leg) run200\_ik.mot (left leg)