

lumbar\_rotation arm\_flex arm\_add 0.2 -0.10 angle (rad) -0.2 -0.10 angle (rad) -0.15 angle (rad) -0.25 0.5 0.5 1.0 0.5 time (s) time (s) time (s) elbow\_flex arm\_rot pro\_sup 0.0 angle (rad) 0.8 angle (rad) angle (rad)

0.5

time (s)

0.0

0.5

time (s)

1.0

0.0

0.0

0.5

time (s)

walking3\_ik.mot (right leg)
walking3\_ik.mot (left leg)