

walkingTS1\_ik.mot (left leg) lumbar\_rotation arm\_flex arm\_add angle (rad) angle (rad) angle (rad) -0.3 0.0 0.5 0.5 0.5 1.0 1.0 time (s) time (s) time (s) elbow\_flex arm\_rot pro\_sup angle (rad) 9.0 8.0 angle (rad) angle (rad) 0.4 0.0 0.0 0.5 0.5

time (s)

time (s)

time (s)

walkingTS1\_ik.mot (right leg)