

lumbar_rotation arm_flex arm_add 0.0 angle (rad) angle (rad) angle (rad) 0.5 1.0 time (s) 0.5 1.0 2.0 time (s) time (s) elbow_flex arm_rot pro_sup angle (rad) angle (rad) angle (rad) 0.5 1.0 2.0 1.0 time (s) time (s) time (s) wrist_flex wrist_dev 0.04 0.02 angle (rad) angle (rad) 0.00 -0.02 0.00 -0.04 2.0 0.5 0.5 1.0 time (s) 1.0 time (s)

run400_ik.mot (right leg) run400_ik.mot (left leg)