

DJ1_grf_raw.mot ground_force_2_mx ground_force_2_my ground_force_2_mz 0.05 0.05 torque (N-m) torque (N-m) torque (N-m) 0.00 0.00 -0.05 -0.05 1.2 1.5 2.0 2.2 1.2 1.5 time (s) time (s) time (s) ground_force_3_vx ground_force_3_vy ground_force_3_vz 0.05 0.05 0.05 force (N) force (N) force (N) 0.00 0.00 0.00 -0.05 -0.05 -0.05 1.2 1.8 1.2 1.5 1.8 2.0 2.2 1.2 1.8 2.0 2.2 time (s) time (s) time (s) ground_force_3_px ground_force_3_py ground_force_3_pz 1e-3 1.05 1e-4 0.05 1.60 (m) nosition (m) 1.55 position (m) position (m) 0.00 0.95 -0.05 1.45 1.2 1.5 1.8 1.2 1.8 2.0 2.0 1.5 2.2 1.2 1.5 1.8 2.2 time (s) time (s) time (s) ground_force_3_mx ground_force_3_my ground_force_3_mz 0.05 0.05 0.05 torque (N-m) torque (N-m) torque (N-m) 0.00 0.00 0.00

-0.05

1.2

1.5

1.8

time (s)

2.0

-0.05

1.2

1.5

1.8

time (s)

2.0

-0.05

1.2

1.5

1.8

time (s)

2.0