

lumbar_rotation arm_flex arm_add 0.2 0.2 angle (rad) 0.0 0.0 angle (rad) angle (rad) 0.1 -0.2 0.0 -0.4 -0.1 0.5 1.0 1.0 0.5 1.0 0.5 time (s) time (s) time (s) elbow_flex arm_rot pro_sup 1.25 2.2 angle (rad) angle (rad) angle (rad)

0.5

time (s)

0.5

time (s)

1.0

0.50

time (s)

walking3_ik.mot (right leg)
walking3_ik.mot (left leg)