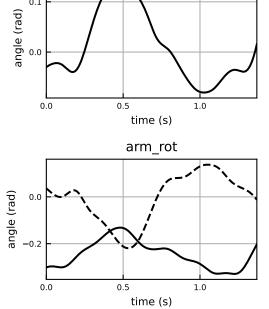
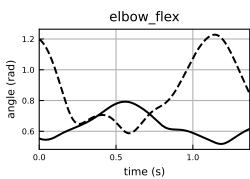


walking4_ik.mot (left leg) arm_flex arm_add -0.15 0.2 angle (rad) angle (rad) 0.0 -0.25 -0.2 -0.30 0.5 0.5 1.0 1.0 time (s) time (s)



lumbar_rotation



walking4_ik.mot (right leg)

