

arm_add lumbar_rotation arm_flex 0.2 angle (rad) -0.1 -0.10 angle (rad) -0.15 -0.20 angle (rad) 0.0 -0.2 -0.25 L 0.0 0.5 1.0 0.5 time (s) time (s) time (s) elbow_flex arm_rot pro_sup 1.0 angle (rad) angle (rad) angle (rad) -0.4 <u>-</u> 0.0 0.0 0.5 0.5

time (s)

time (s)

time (s)

walking4_ik.mot (right leg) walking4_ik.mot (left leg)