

lumbar_rotation arm_flex arm_add angle (rad) angle (rad) angle (rad) -0.5 -0.2 -0.6 2.0 time (s) 2.0 time (s) 2.5 1.0 1.5 time (s) elbow_flex arm_rot pro_sup 2.25 angle (rad) 2.00 angle (rad) angle (rad) 1.5 2.0 1.0 2.0 time (s) time (s) time (s) wrist_flex wrist_dev 0.095 0.02 angle (rad) angle (rad) 0.090 0.00 -0.02 2.5 2.5 2.0 time (s) 1.0 2.0 time (s)

run400_ik.mot (right leg) run400_ik.mot (left leg)