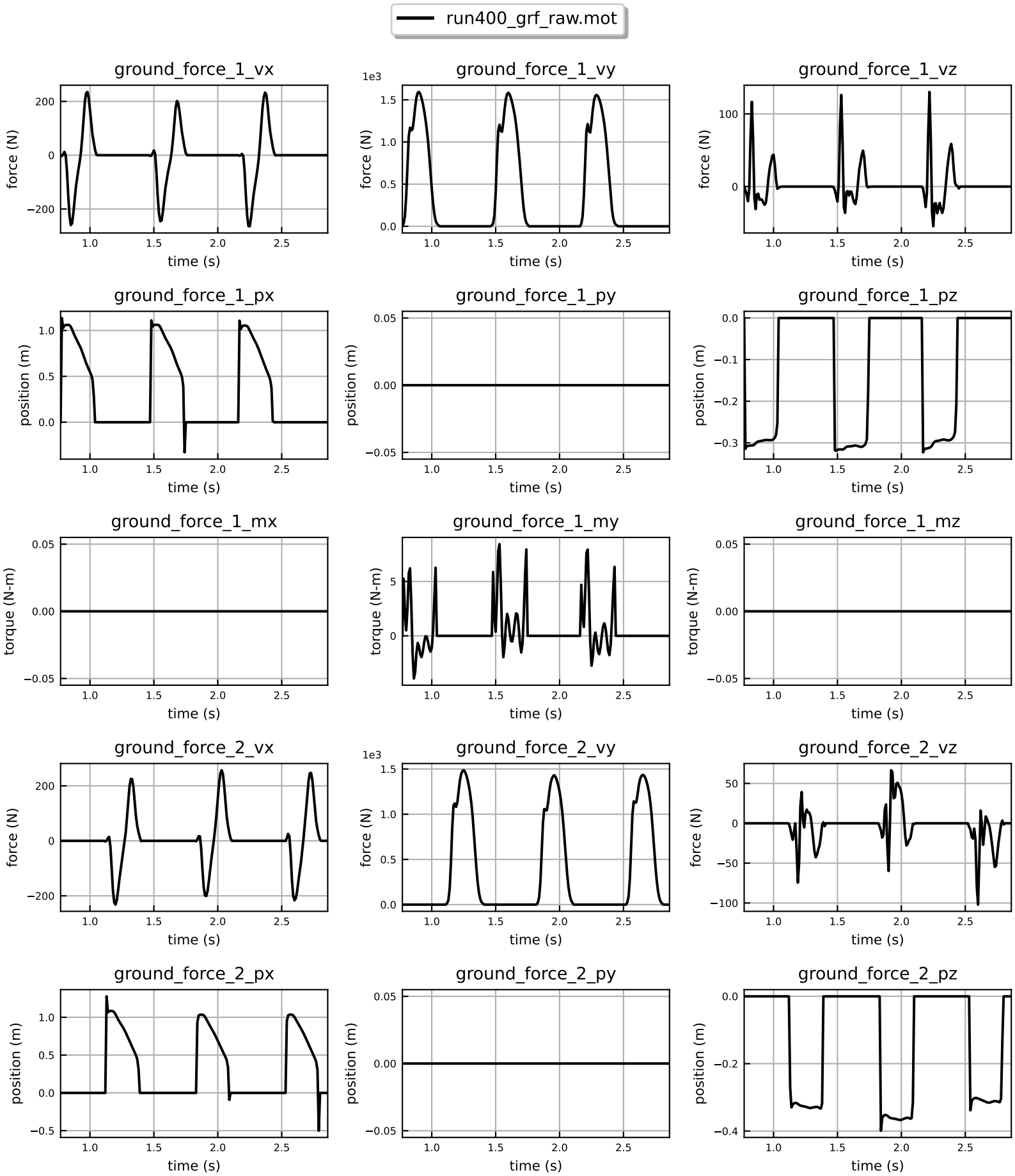
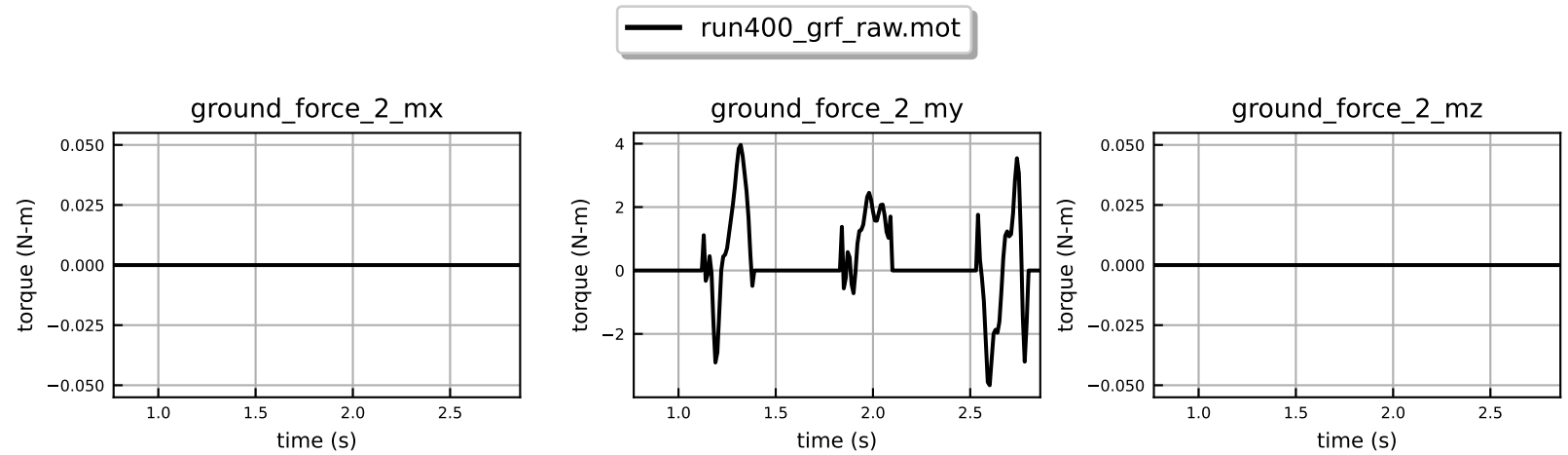

run400_grf_raw.mot
ground_force_1_vx
force (N)
time (s)
ground_force_1_vy
1e3
force (N)
time (s)
ground_force_1_vz
force (N)
time (s)
ground_force_1_px
position (m)
time (s)
ground_force_1_py
position (m)
time (s)
ground_force_1_pz
position (m)
time (s)
ground_force_1_mx
torque (N-m)
time (s)
ground_force_1_my
torque (N-m)
time (s)
ground_force_1_mz
torque (N-m)
time (s)
ground_force_2_vx
force (N)
time (s)
ground_force_2_vy
1e3
force (N)
time (s)
ground_force_2_vz
force (N)
time (s)
ground_force_2_px
position (m)
time (s)
ground_force_2_py
position (m)
time (s)
ground_force_2_pz
position (m)
time (s)


run400_grf_raw.mot
ground_force_2_mx
ground_force_2_my
ground_force_2_mz
torque (N-m)
time (s)
0.050
0.025
0.000
−0.025
−0.050
4
2
0
−2
1.0
1.5
2.0
2.5