

walkingTS1_ik.mot (left leg) lumbar_rotation arm_flex arm_add 0.2 angle (rad) angle (rad) angle (rad) 0.0 -0.3 -0.2 -0.4 -0.1 0.5 1.0 time (s) 1.5 1.5 0.5 1.0 0.5 time (s) time (s) elbow_flex arm_rot pro_sup 0.2 1.0 2.100 angle (rad) 2.075 angle 2.075 2.050 angle (rad) 2.025 0.0 1.0 1.5 0.0 time (s)

time (s)

time (s)

walkingTS1_ik.mot (right leg)