

lumbar_rotation arm_flex arm_add angle (rad) angle (rad) -0.10 angle (rad) -0.15-0.20 -0.25 -0.15 L 0.5 0.5 0.5 time (s) time (s) time (s) elbow_flex arm_rot pro_sup angle (rad) angle (rad) 9.0 9.0 0.25 angle (rad) 0.00

time (s)

0.0

time (s)

0.5

-0.25

0.0

time (s)

walkingTS2_ik.mot (right leg) walkingTS2_ik.mot (left leg)