

lumbar_rotation arm_flex arm_add 0.2 0.50 angle (rad) angle (rad) angle (rad) 0.1 0.25 0.0 0.00 -0.1 -0.25 -0.3 0.5 0.5 0.0 0.0 1.0 0.0 1.0 time (s) time (s) time (s) elbow_flex arm_rot pro_sup 0.2 2.0 angle (rad) 0.75 angle (rad) 0.50 angle (rad) -0.2

time (s)

0.0

0.0

time (s)

0.0

0.5

time (s)

walking2_ik.mot (right leg)
walking2_ik.mot (left leg)