

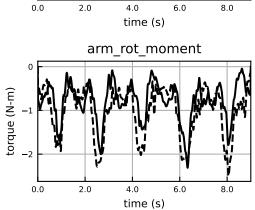
arm_flex_moment

arm_add_moment

(w-N) and of time (s)

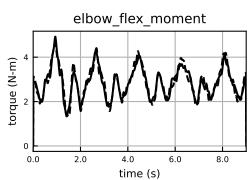
arm_add_moment

output



lumbar_rotation_moment

torque (N-m)



squatsAsym1_id.sto (right leg)

