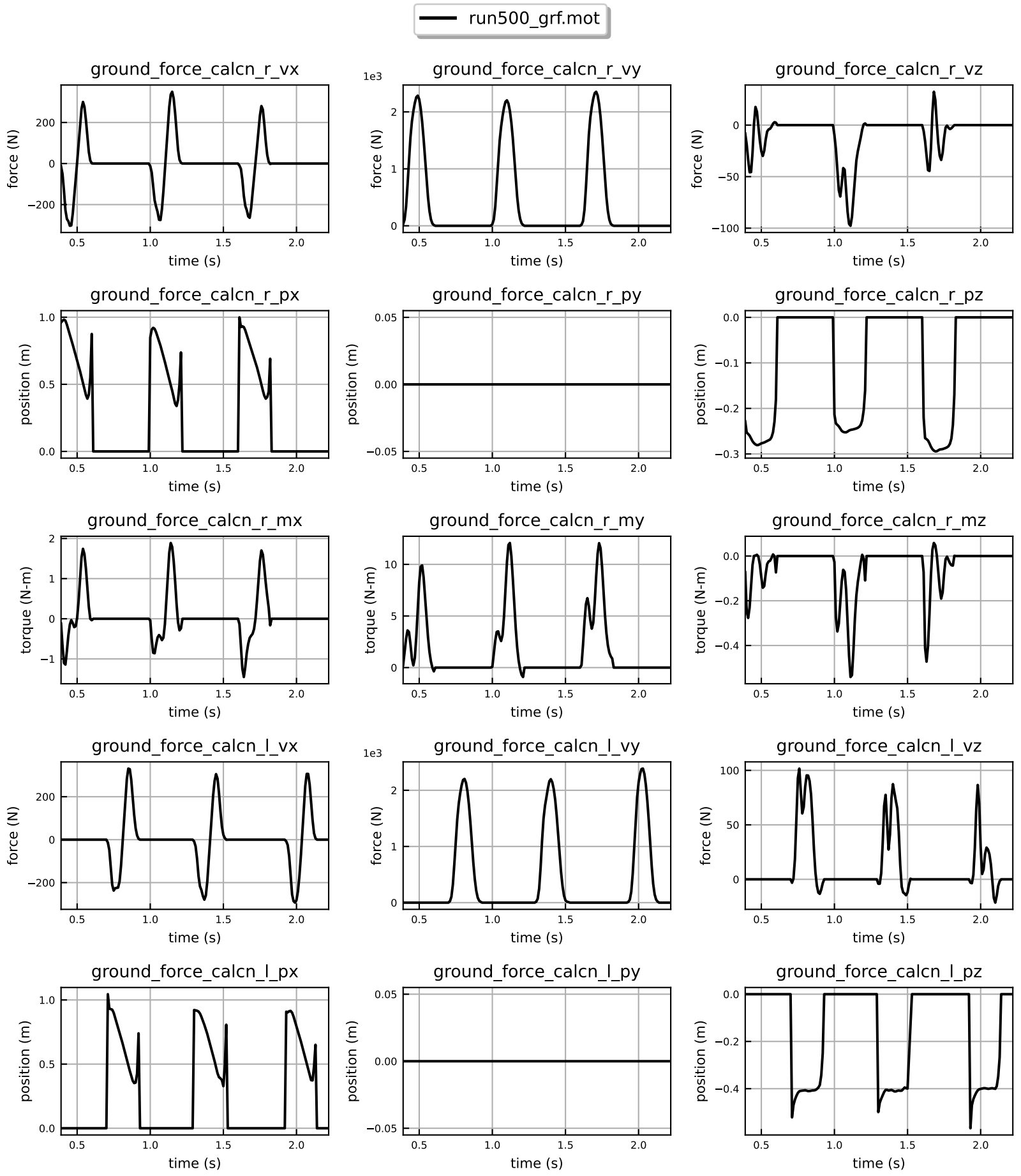
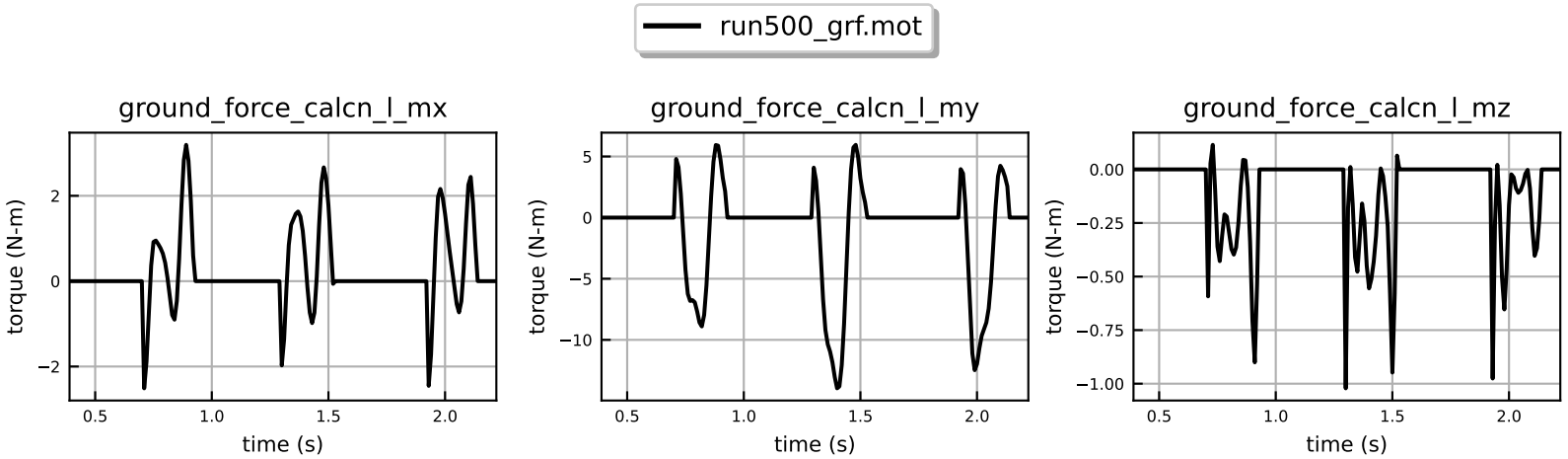

run500_grf.mot
ground_force_calcn_r_vx
force (N)
time (s)
ground_force_calcn_r_vy
1e3
force (N)
time (s)
ground_force_calcn_r_vz
force (N)
time (s)
ground_force_calcn_r_px
position (m)
time (s)
ground_force_calcn_r_py
position (m)
time (s)
ground_force_calcn_r_pz
position (m)
time (s)
ground_force_calcn_r_mx
torque (N-m)
time (s)
ground_force_calcn_r_my
torque (N-m)
time (s)
ground_force_calcn_r_mz
torque (N-m)
time (s)
ground_force_calcn_l_vx
force (N)
time (s)
ground_force_calcn_l_vy
1e3
force (N)
time (s)
ground_force_calcn_l_vz
force (N)
time (s)
ground_force_calcn_l_px
position (m)
time (s)
ground_force_calcn_l_py
position (m)
time (s)
ground_force_calcn_l_pz
position (m)
time (s)


run500_grf.mot
ground_force_calcn_l_mx
ground_force_calcn_l_my
ground_force_calcn_l_mz
torque (N-m)
time (s)
2
0
−2
5
−5
−10
0.00
−0.25
−0.50
−0.75
−1.00
0.5
1.0
1.5
2.0