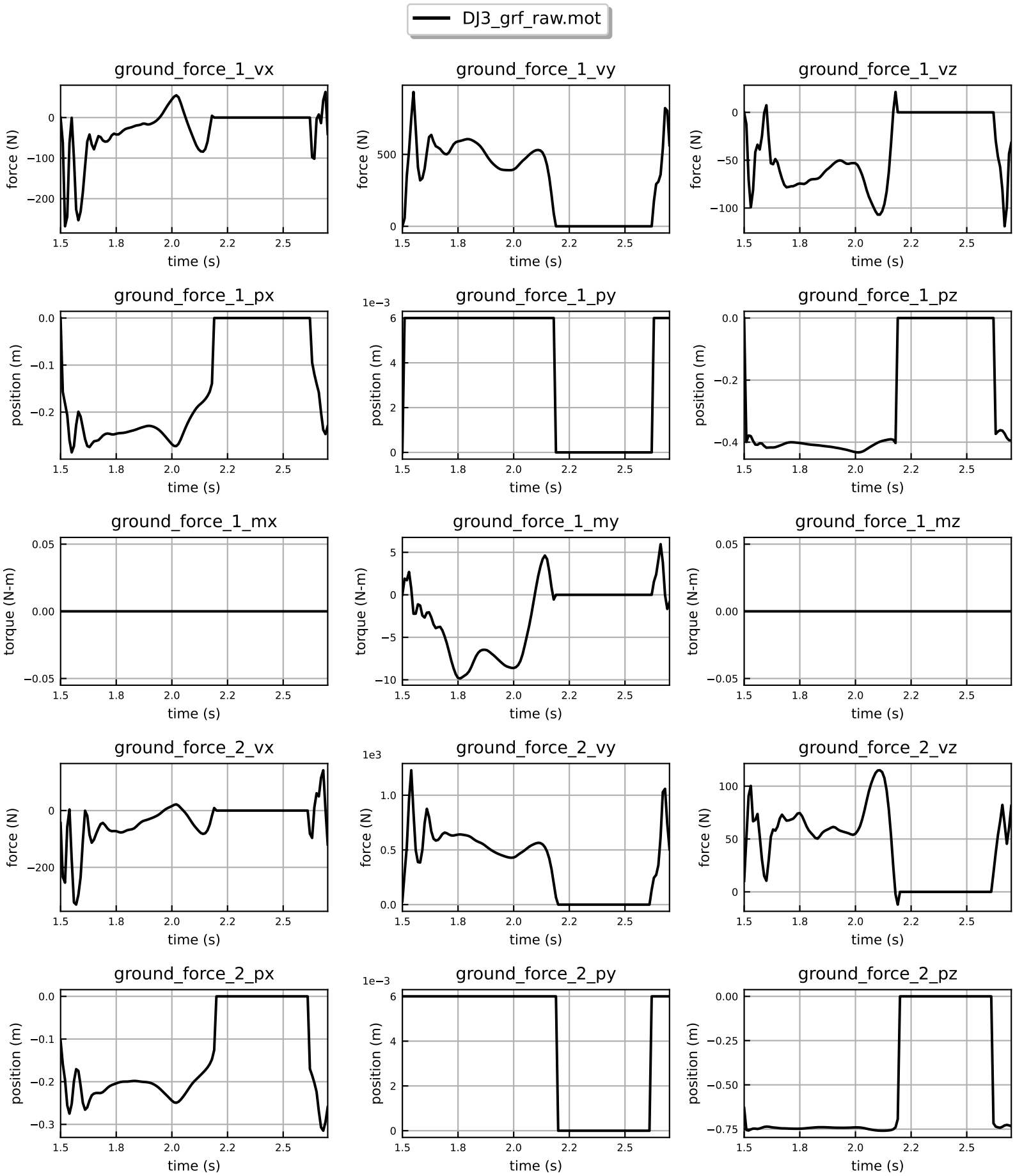
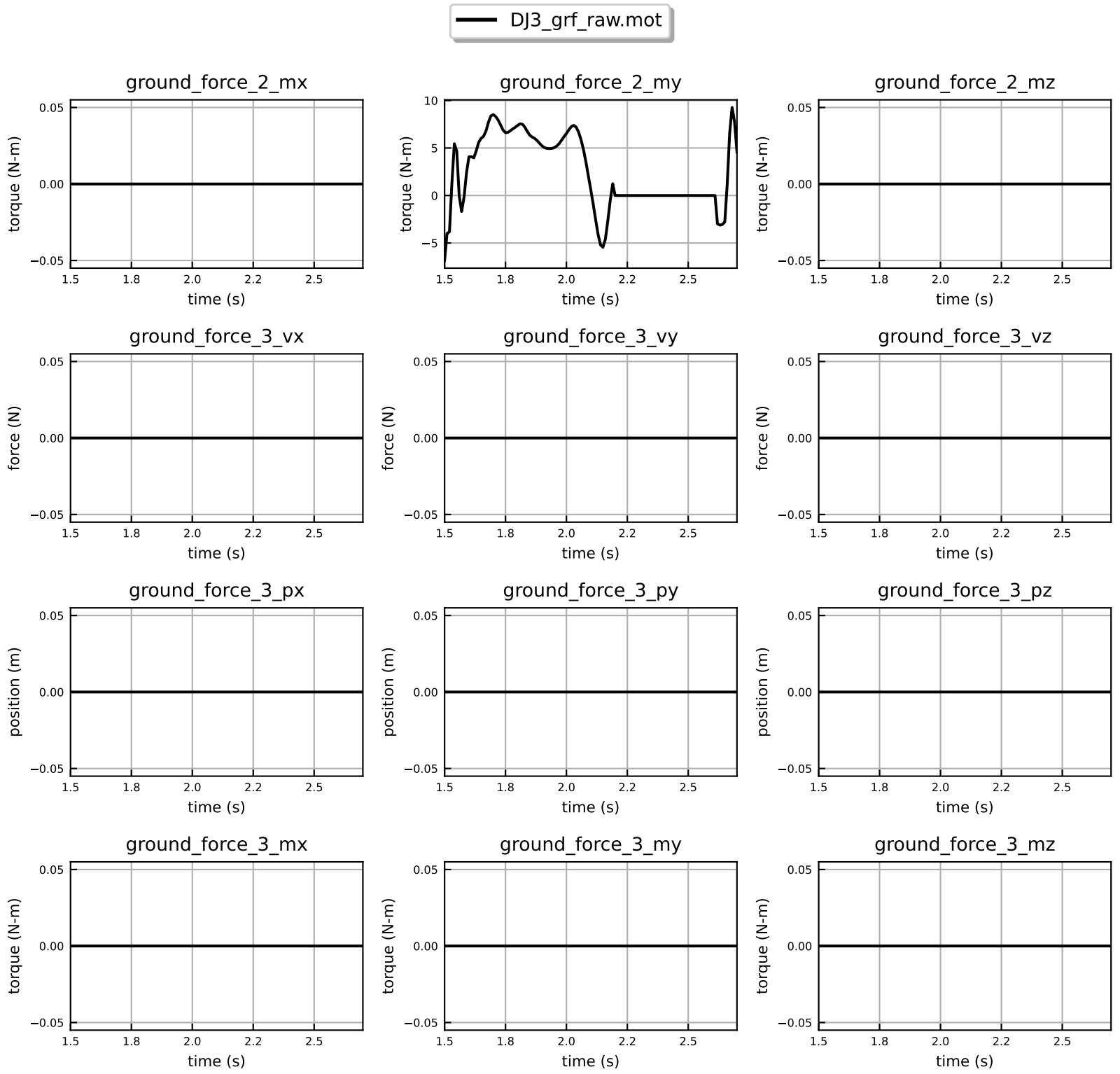

DJ3_grf_raw.mot
ground_force_1_vx
ground_force_1_vy
ground_force_1_vz
ground_force_1_px
ground_force_1_py
ground_force_1_pz
ground_force_1_mx
ground_force_1_my
ground_force_1_mz
ground_force_2_vx
ground_force_2_vy
ground_force_2_vz
ground_force_2_px
ground_force_2_py
ground_force_2_pz
force (N)
position (m)
torque (N-m)
time (s)
1e−3
1e3


DJ3_grf_raw.mot
ground_force_2_mx
ground_force_2_my
ground_force_2_mz
ground_force_3_vx
ground_force_3_vy
ground_force_3_vz
ground_force_3_px
ground_force_3_py
ground_force_3_pz
ground_force_3_mx
ground_force_3_my
ground_force_3_mz
torque (N-m)
force (N)
position (m)
time (s)
0.05
0.00
−0.05
10
5
0
−5
1.5
1.8
2.0
2.2
2.5