

walkingTS2_ik.mot (left leg) lumbar_rotation arm_flex arm_add -0.1 0.25 angle (rad) angle (rad) 0.00 -0.25 -0.50 0.5 0.5 0.0 0.5 1.0 0.0 1.0 time (s) time (s) time (s) elbow_flex arm_rot pro_sup 1.25 angle (rad) 1.6 angle (rad) 0.75

time (s)

0.0

0.0

0.5

time (s)

walkingTS2_ik.mot (right leg)

-0.05

angle (rad) angle -0.10

0.0

0.0

-0.4 0.0

time (s)

angle (rad)