

lumbar\_rotation arm\_flex arm\_add 0.2 angle (rad) angle (rad) angle (rad) 0.0 -0.6 -0.6 -0.71.0 time (s) 0.5 0.5 2.0 time (s) time (s) elbow\_flex arm\_rot pro\_sup angle (rad) angle (rad) angle (rad) 0.0 -0.2 0.5 time (s) time (s) time (s) wrist\_flex wrist\_dev angle (rad) 0.00 angle (rad) -0.02

> 1.0 time (s)

1.5

2.0

0.5

0.5

1.0 time (s) 2.0

run300\_ik.mot (right leg) run300\_ik.mot (left leg)