

lumbar_rotation arm_flex arm_add angle (rad) -0.4 angle (rad) angle (rad) **-**0.5 0.0 -1.0 0.5 0.5 1.5 1.0 1.5 2.0 1.0 time (s) time (s) time (s) elbow_flex arm_rot pro_sup angle (rad) 0.0 angle (rad) angle (rad) 1.0 1.0 time (s) time (s) time (s) wrist_flex wrist_dev 0.010 angle (rad) 0.005 0.010 angle (rad) 0.000 0.5 2.0 0.5 1.0 time (s) 1.0 time (s) 1.5

run500_ik.mot (right leg) run500_ik.mot (left leg)