

lumbar\_rotation arm\_flex arm\_add 0.50 angle (rad) angle (rad) -0.3 angle (rad) 0.25 0.00 0.5 1.0 1.0 time (s) time (s) time (s) elbow\_flex arm\_rot pro\_sup 1.9 angle (rad) angle (rad) angle (rad) -0.2

time (s)

time (s)

0.5

time (s)

1.0

walking3\_ik.mot (right leg)
walking3\_ik.mot (left leg)