

walking2_ik.mot (left leg) lumbar_rotation arm_flex arm_add 0.1 angle (rad) 0.2 angle (rad) angle (rad) -0.15 0.0 -0.20 0.5 1.0 time (s) time (s) time (s) elbow_flex arm_rot pro_sup 0.2 1.0 angle (rad) 9.0 8.0 angle (rad) 1.9 angle (rad) 0.4 ____ 0.0 0.0 0.5 1.0 1.0

time (s)

time (s)

time (s)

walking2_ik.mot (right leg)