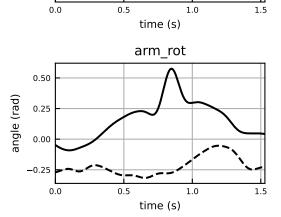


1.5

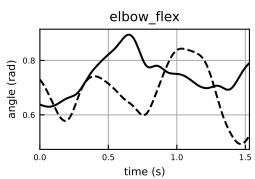


lumbar_rotation

0.1

-0.2

angle (rad) -0.0 -0.1



time (s)

0.5

walkingTS3_ik.mot (right leg)

