

lumbar_rotation arm_flex arm_add 1.0 angle (rad) 0.5 angle (rad) angle (rad) -0.1 0.0 2.0 2 time (s) 2.5 1.5 1.8 1.8 2.2 1.5 1.8 time (s) time (s) elbow_flex arm_rot pro_sup 0.50 angle (rad) angle (rad) angle (rad)

> 2.0 2 time (s)

2.2

1.8

2.0

time (s)

2.5

1.5

1.5

1.8

2.0

time (s)

DJ3_ik.mot (right leg)
DJ3_ik.mot (left leg)