

lumbar_rotation

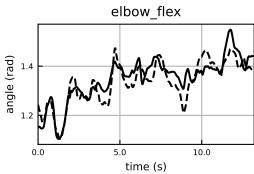
10.0

0.2

0.0

0.0

angle (rad)



squatsAsym1_ik.mot (right leg)

