

lumbar_rotation arm_flex arm_add 0.2 angle (rad) angle (rad) angle (rad) -0.20 0.0 0.0 **-**0.2 -0.30 -0.1 0.0 0.5 0.5 1.0 time (s) time (s) time (s) elbow_flex arm_rot pro_sup 1.25 angle (rad) 1.95 angle (rad) 0.75 2.00 angle (rad) -0.2 1.90 0.50 0.0 0.5 0.5 1.0 0.0

time (s)

time (s)

time (s)

walking3_ik.mot (right leg)
walking3_ik.mot (left leg)