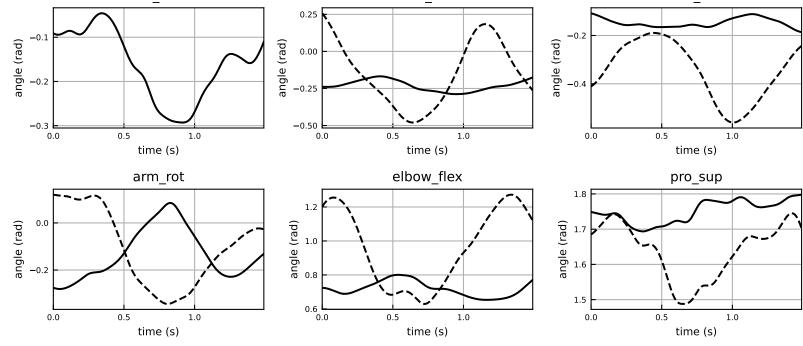


walkingTS1_ik.mot (left leg) lumbar_rotation arm_flex arm_add 0.25 angle (rad) -0.25 angle (rad) -0.50 L 0.5 time (s) time (s) elbow_flex pro_sup



walkingTS1_ik.mot (right leg)