

DJ3\_grf\_raw.mot ground\_force\_2\_my ground\_force\_2\_mx ground\_force\_2\_mz 0.05 0.05 torque (N-m) torque (N-m) torque (N-m) 0.00 0.00 -0.05 -0.051.5 2.2 1.5 2.2 1.5 time (s) time (s) time (s) ground\_force\_3\_vx ground\_force\_3\_vy ground\_force\_3\_vz 0.05 0.05 0.05 force (N) force (N) force (N) 0.00 0.00 0.00 -0.05 -0.05 <del>-</del>0.05 1.5 2.0 1.5 2.0 2.2 1.5 2.5 time (s) time (s) time (s) ground\_force\_3\_px ground\_force\_3\_py ground\_force\_3\_pz 0.05 0.05 0.05 position (m) position (m) position (m) 0.00 0.00 0.00 -0.05 -0.05 -0.05 1.5 2.0 2.2 1.8 2.0 1.8 1.8 1.5 2.2 1.5 2.0 2.2 time (s) time (s) time (s) ground\_force\_3\_mx ground\_force\_3\_my ground\_force\_3\_mz 0.05 0.05 0.05 torque (N-m) torque (N-m) torque (N-m) 0.00 0.00 0.00 -0.05 -0.05 1.5 2.2 1.5 1.5 1.8 2.0 1.8 2.0 2.2 2.0 2.2

time (s)

time (s)

time (s)