

lumbar_rotation arm_flex arm_add angle (rad) angle (rad) angle (rad) -0.2 1.0 1.0 1.5 2.0 2.5 time (s) time (s) time (s) elbow_flex arm_rot pro_sup 0.2 1.8 angle (rad) angle (rad) angle (rad) 1.5 time (s) 1.0 time (s) time (s) wrist_flex wrist_dev 0.02 0.03 angle (rad) angle (rad) 0.02 0.01 0.00 1.0 1.5 time (s) 1.0

time (s)

run400_ik.mot (right leg) run400_ik.mot (left leg)