

---



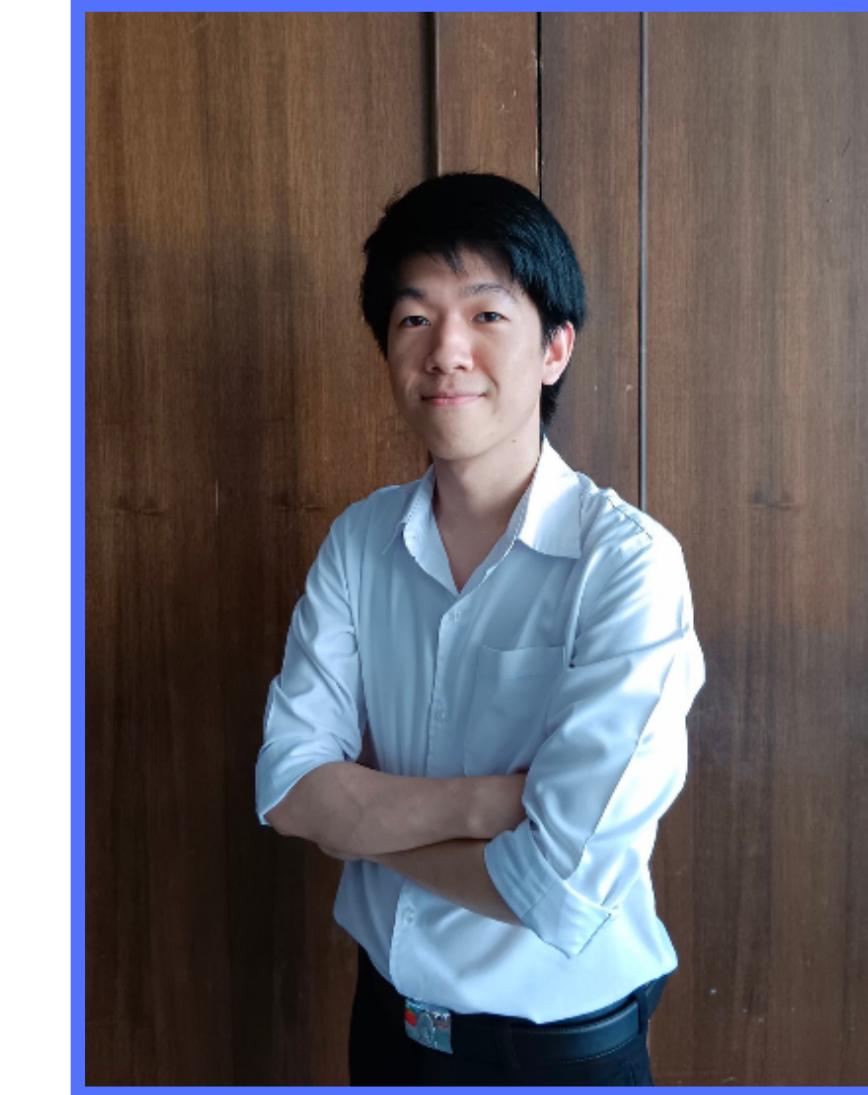
# **PROJECT DIGITAL IMAGE**



# MEMBERS



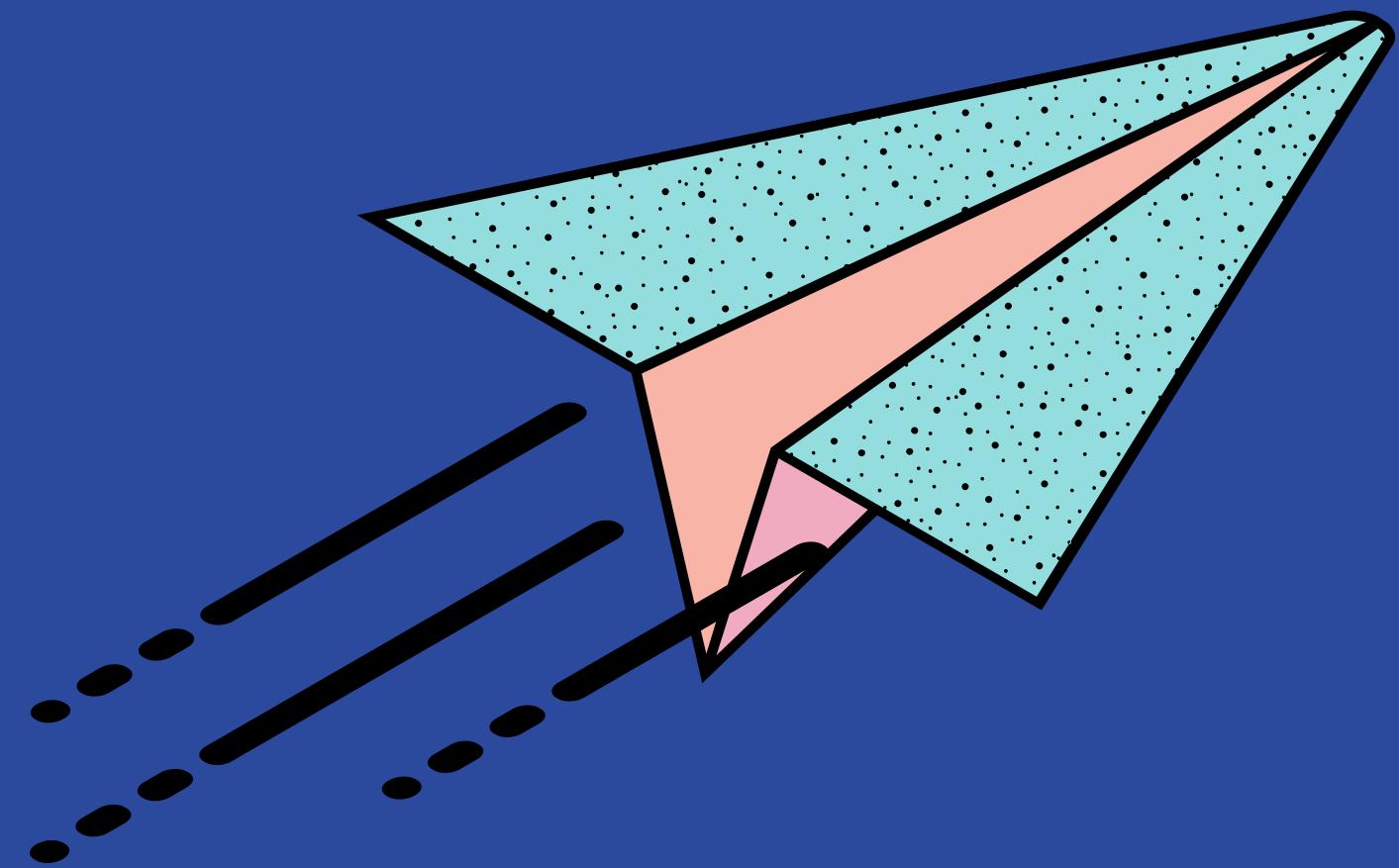
គុរីវិច្ឆិយ តារាបិជ្ជិយ  
MEMBER 6231364021



សុន សេវតកិត្តរោម  
MEMBER 6230238421

# INTRODUCTION

1



# **PROJECT TOPIC**

COUNTING ABC BISCUIT



DIG IMAGE

2110431

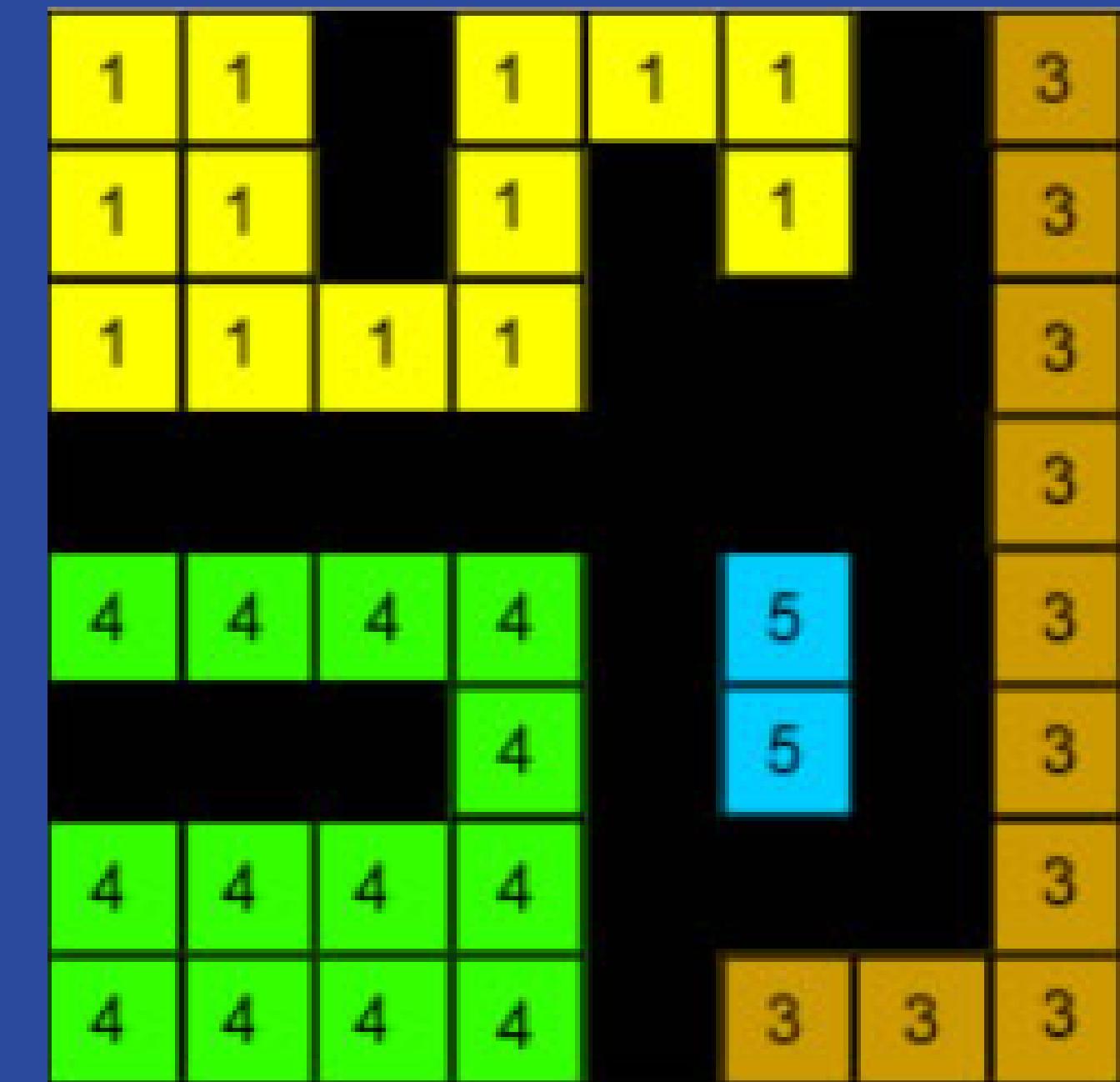
2

# IMAGE PROCESSING TECHNIQUES



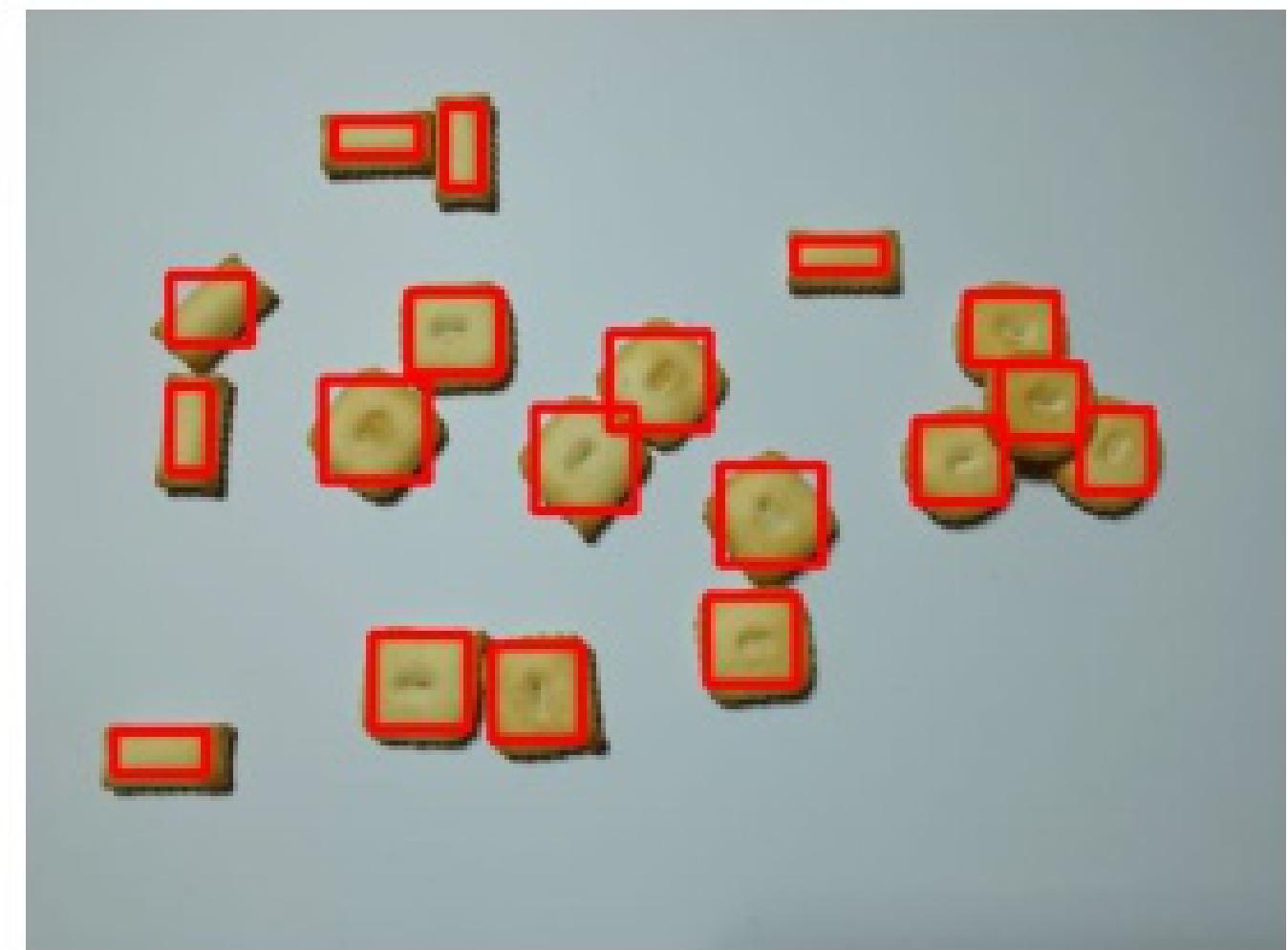
## 2.1

# CONNECTED COMPONENT WITH STAT



# Component

- 1 เป็นหนึ่งใน MORPHOLOGICAL IMAGE PROCESSING โดยใช้หลักการทำงานคณิตศาสตร์ เช่น SET THEORY ในการดึงองค์ประกอบและคุณลักษณะต่างๆ ของรูปภาพที่เราต้องการ
- 2 มีข้อดีคือสามารถนับจำนวน BISCUIT ในรูปภาพได้แม่นยำ ถ้า BISCUIT อยู่ห่างกันพอสมควร แต่ข้อเสียคือตอนที่แปลงรูปภาพเป็น BINARY IMAGE ต้องทำการไล่หาค่า THRESHOLD ที่ทำให้ผลลัพธ์ออกมาดีที่สุด รวมถึงหากมีการ EROSION อาจทำให้ BISCUIT หายไป



# EXAMPLE CODE

```
# HSV threshold to separate object and background
image = cv2.cvtColor(image, cv2.COLOR_BGR2HSV)
for i in range(image.shape[0]):
    for j in range(image.shape[1]):
        if(image[i][j][0] <= 57 and image[i][j][1] >= 20 and image[i][j][2] >= 150):
            image[i][j] = np.array([255, 255, 255])
        else:
            image[i][j] = np.array([0, 0, 0])
```



# EXAMPLE CODE

```
kernel = np.ones((8,8),np.uint8)
image = cv2.morphologyEx(image, cv2.MORPH_OPEN, kernel)

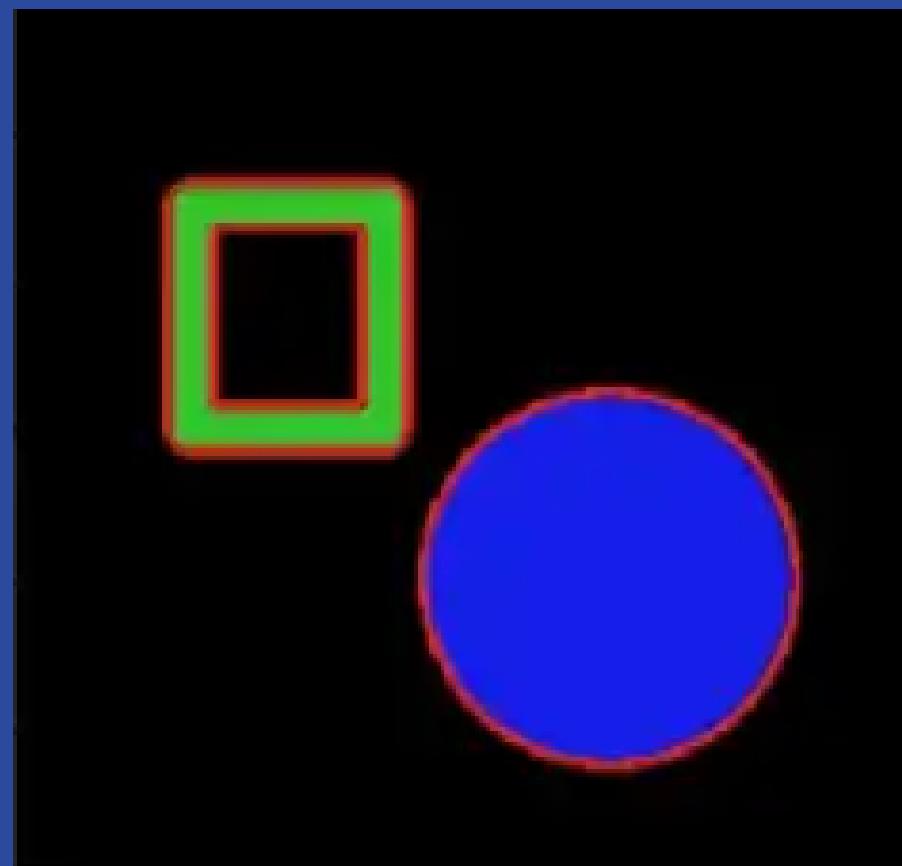
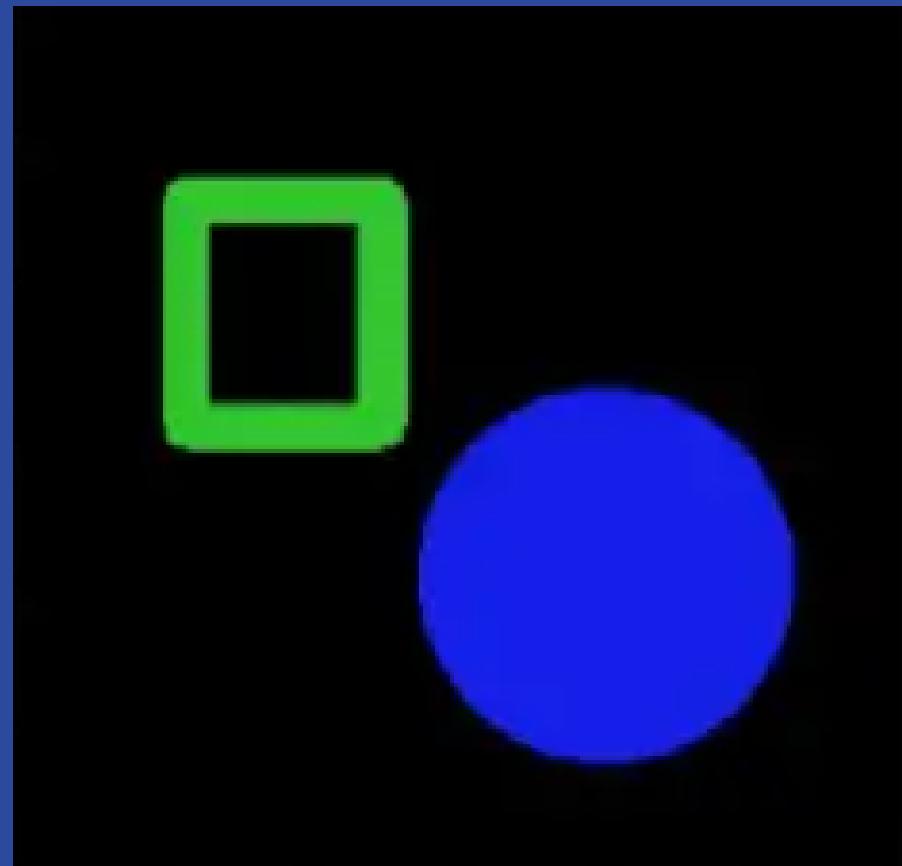
kernel = np.ones((5,5), np.uint8)
image = cv2.erode(image, kernel, iterations=1)
```

```
# count
image2 = image[:, :, 0]
connectivity = 4
output = cv2.connectedComponentsWithStats(image2, connectivity, cv2.CV_16U)
stats = output[2]

res = []
for i in range(len(stats)):
    if stats[i][0] != 0 and stats[i][4] > 150 and stats[i][4] < 3000 :
        res.append(stats[i])
```

## 2.2

# FIND CONTOURS



# Techniques

- 1 ใช้ในการหาเส้นขอบของภาพ โดยสามารถใช้คำสั่ง FIND CONTOURS จาก OPEN CV ซึ่งจะ DETECT การเปลี่ยนแปลงของสีในรูปภาพ
- 2 ข้อดีคือสามารถใช้งานได้ง่าย แต่มีข้อเสียๆ หลักคือเวลา BISCUIT วางใกล้ชิดกันมากๆ หรือมองซ้อนกันจะ DETECT ได้เพียง BISCUTE 1 ชิ้นเท่านั้น



# EXAMPLE CODE

```
# HSV threshold to separate object and background
image = cv2.cvtColor(image, cv2.COLOR_BGR2HSV)
for i in range(image.shape[0]):
    for j in range(image.shape[1]):
        if(image[i][j][0] <= 60 and image[i][j][1] >= 60 and image[i][j][2] >= 100):
            image[i][j] = np.array([255, 255, 255])
        else:
            image[i][j] = np.array([0, 0, 0])
ax1.axis('off')
ax1.imshow(image)
ax1.set_title('HSV threshold')
```

# EXAMPLE CODE

```
h, s, v1 = cv2.split(image)
canny = cv2.Canny(v1, 100, 200, 3)
canny_show = cv2.Canny(v1, 100, 200, 3)
dilation = cv2.dilate(canny,np.ones((5,5),np.uint8),iterations = 1)
erosion = cv2.erode(dilation,np.ones((3,3),np.uint8),iterations = 1)

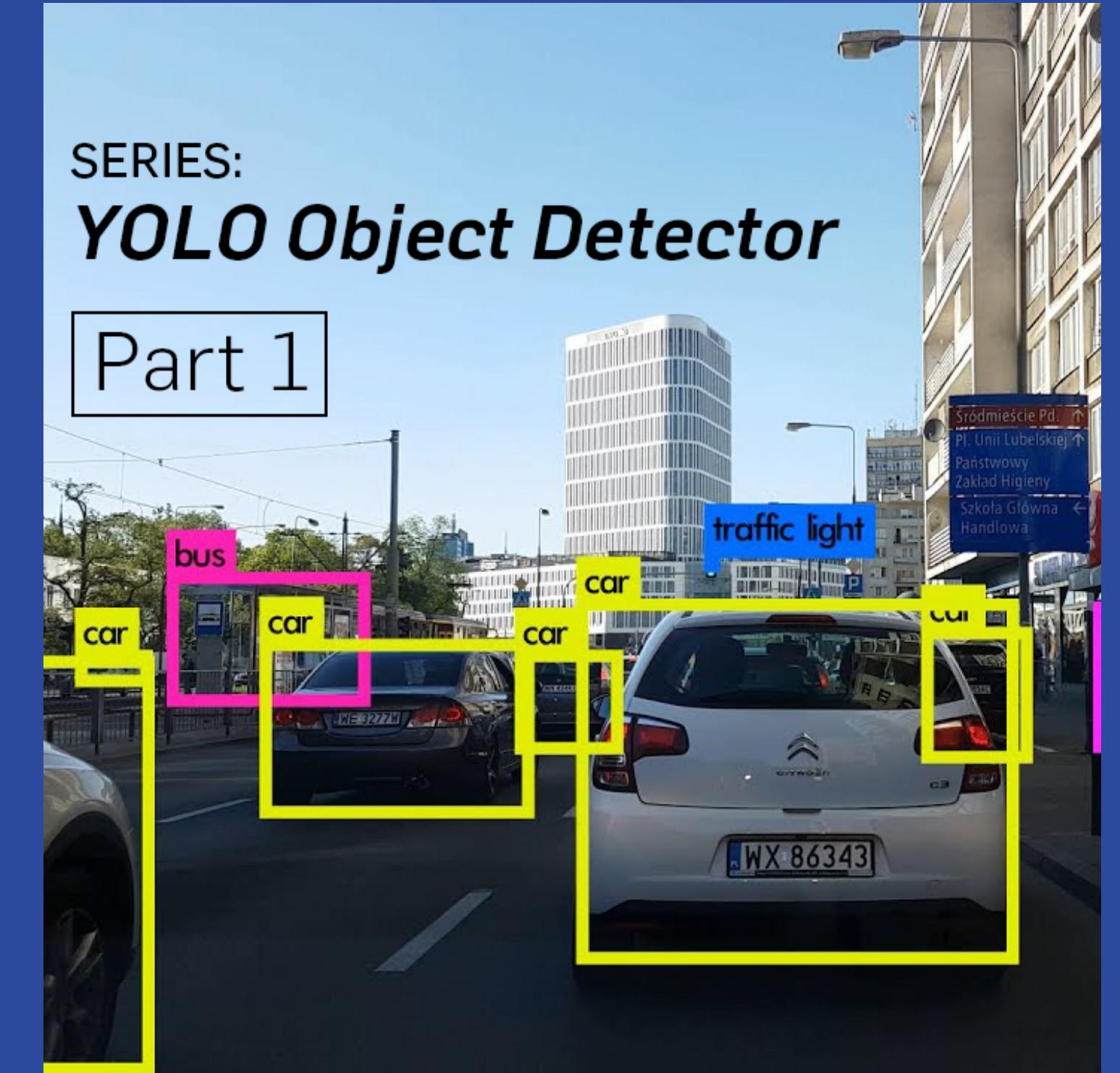
(cnt, hierarchy) = cv2.findContours(
    erosion.copy(), cv2.RETR_EXTERNAL, cv2.CHAIN_APPROX_NONE)
rgb = cv2.cvtColor(img, cv2.COLOR_BGR2RGB)
```

# 2.3

# YOLO v3

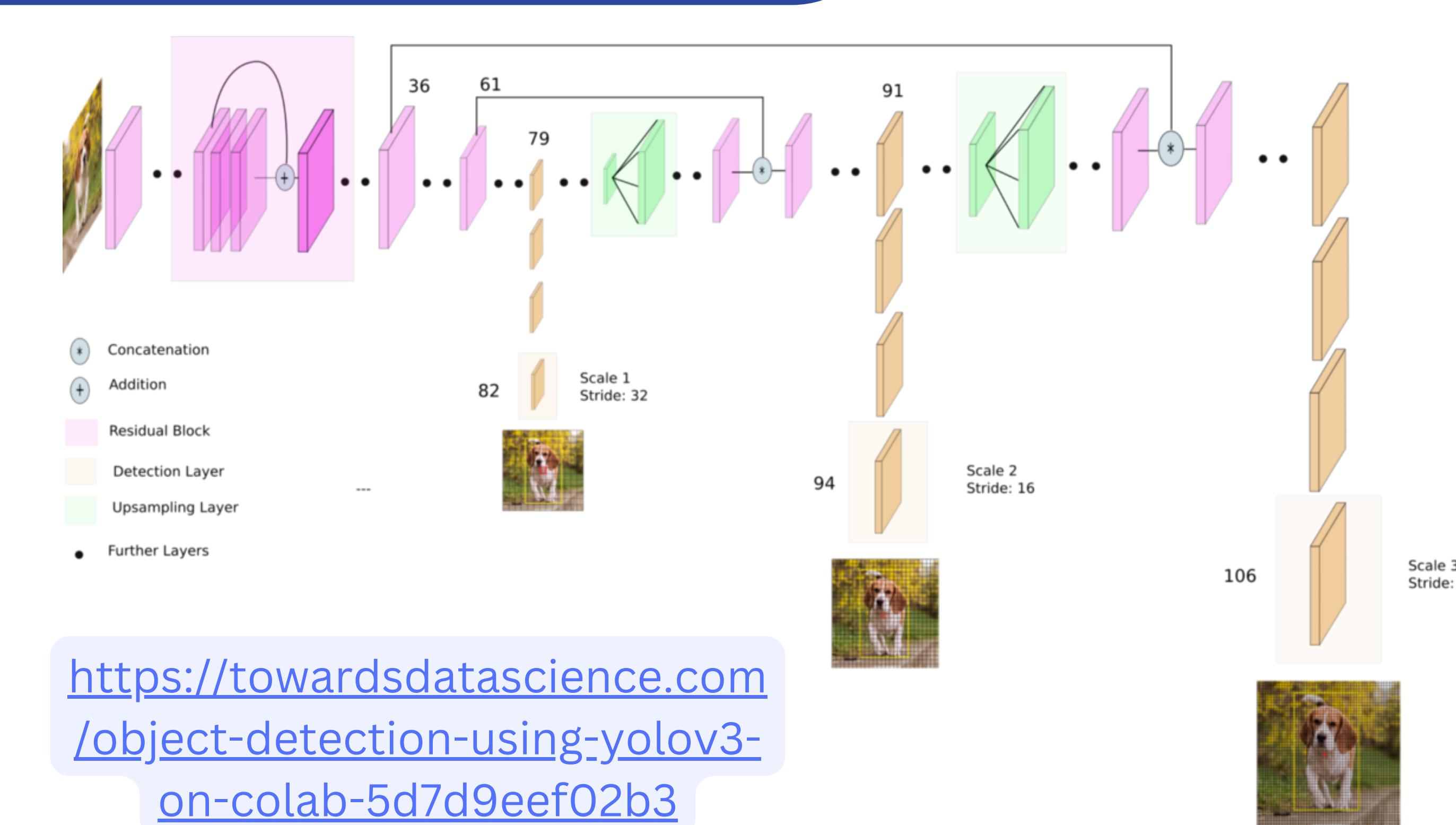
SERIES:  
*YOLO Object Detector*

Part 1

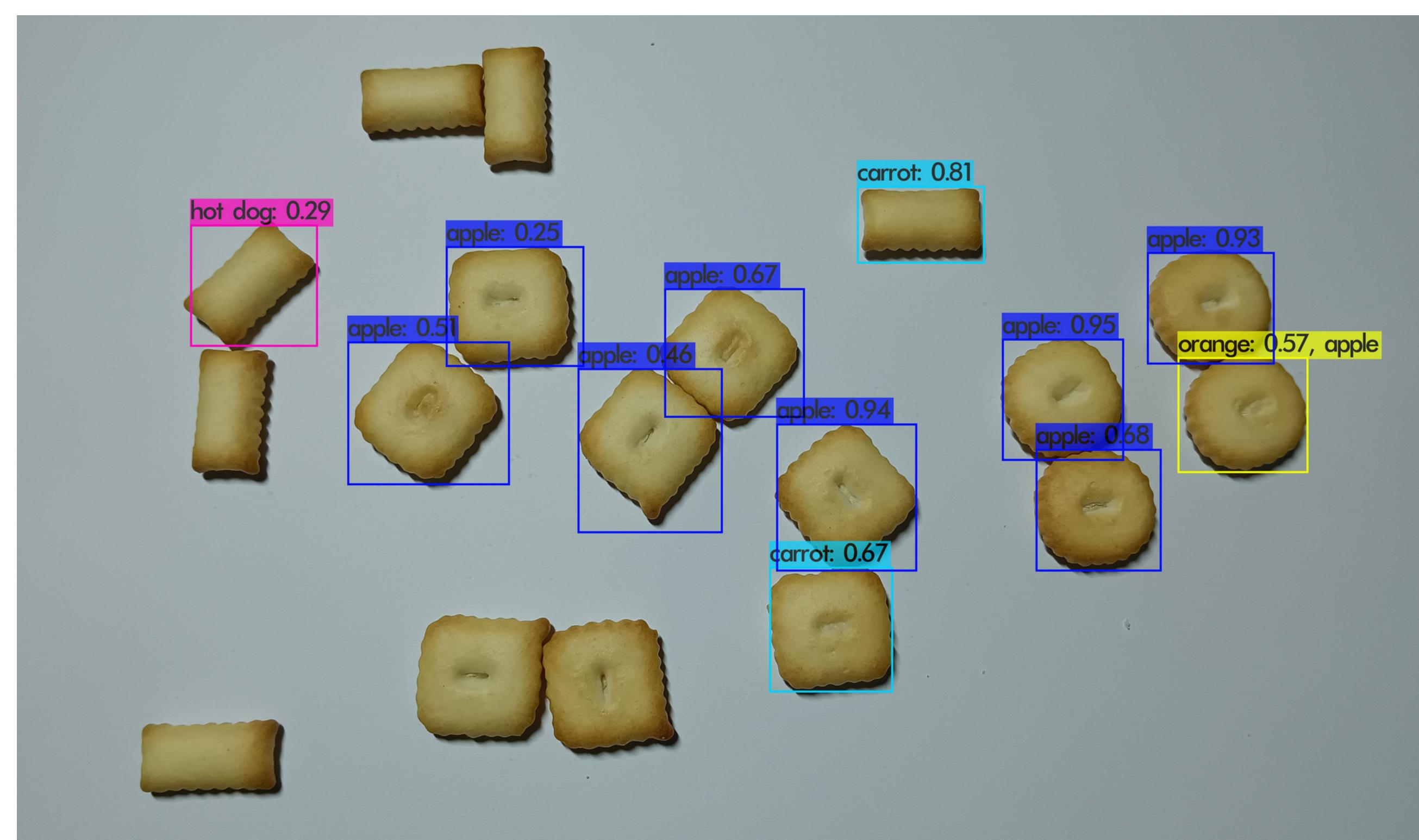


# YOLO v3

YOLO is Convolutional  
Neural Network



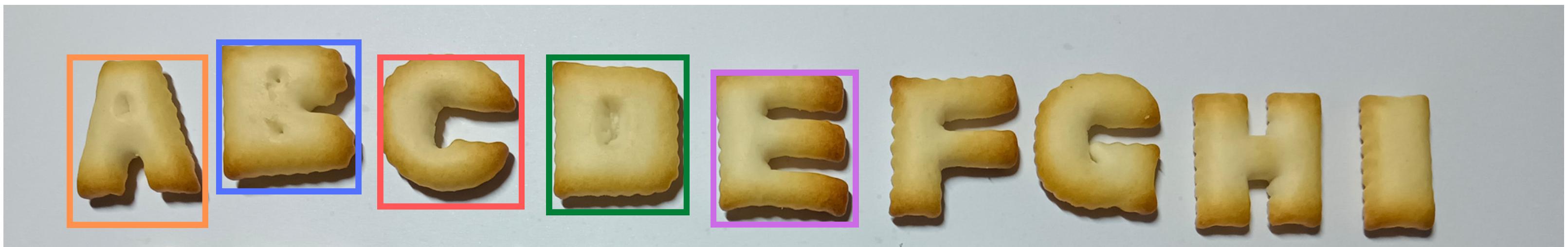
# YOLO v3



# YOLO v3



data to train model



class: A

class: C

class: E

class: B

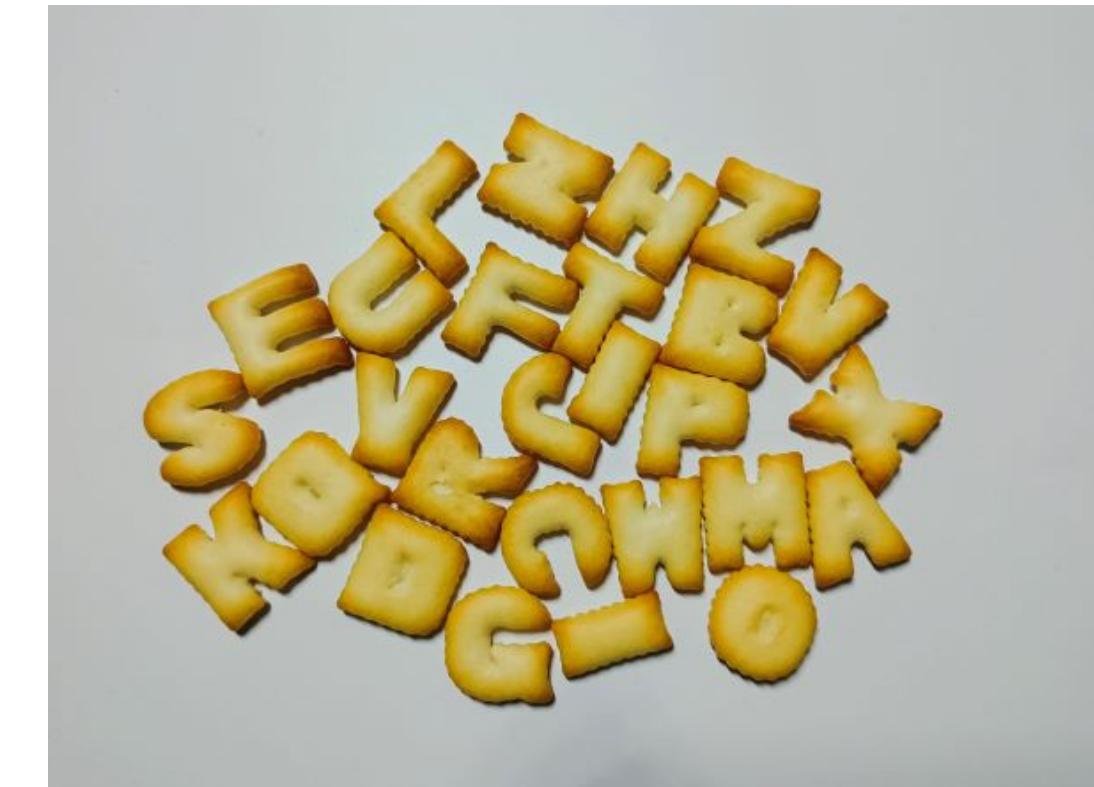
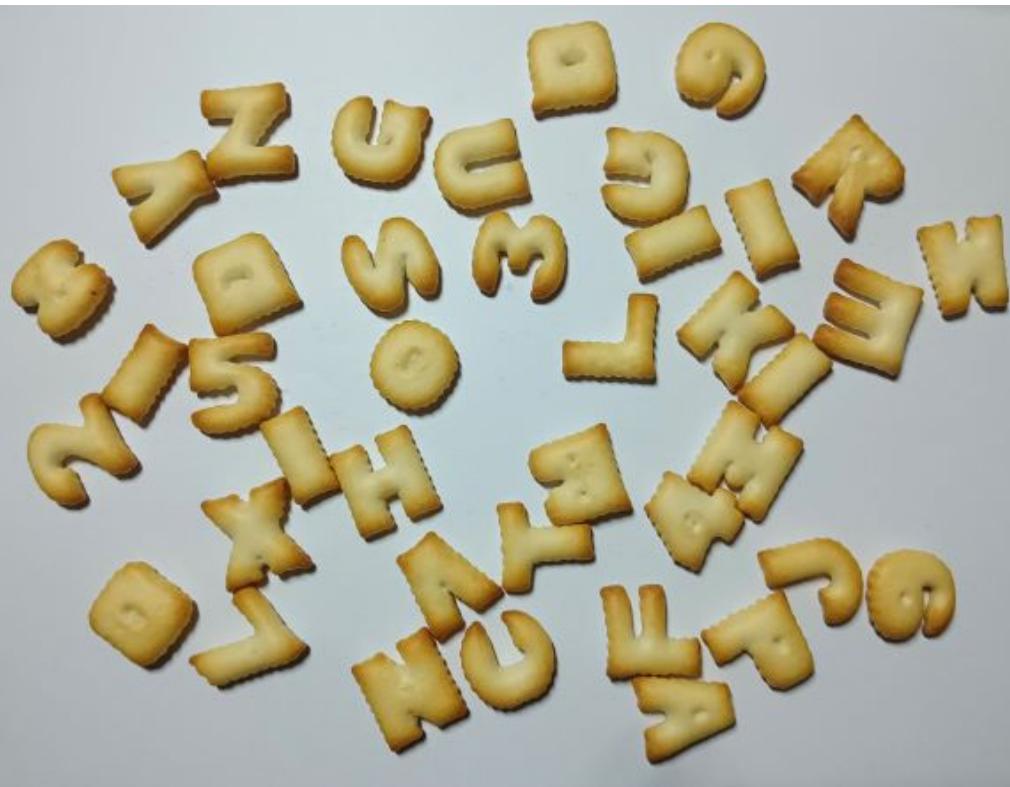
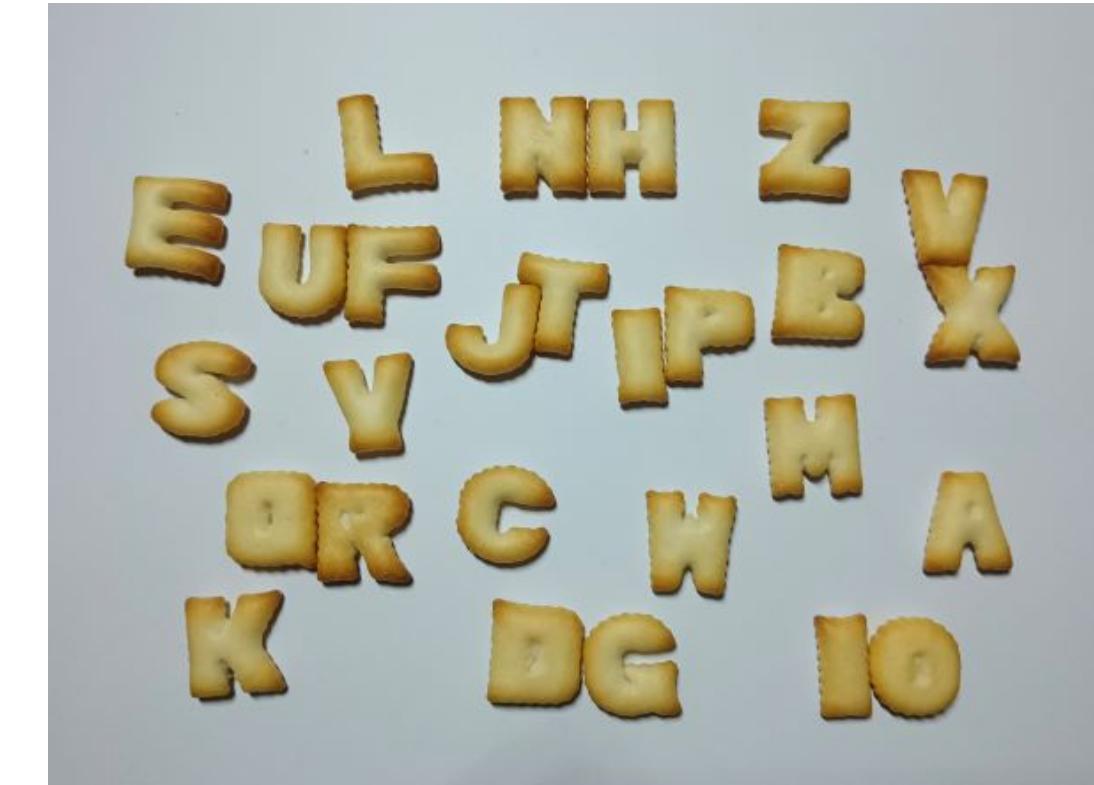
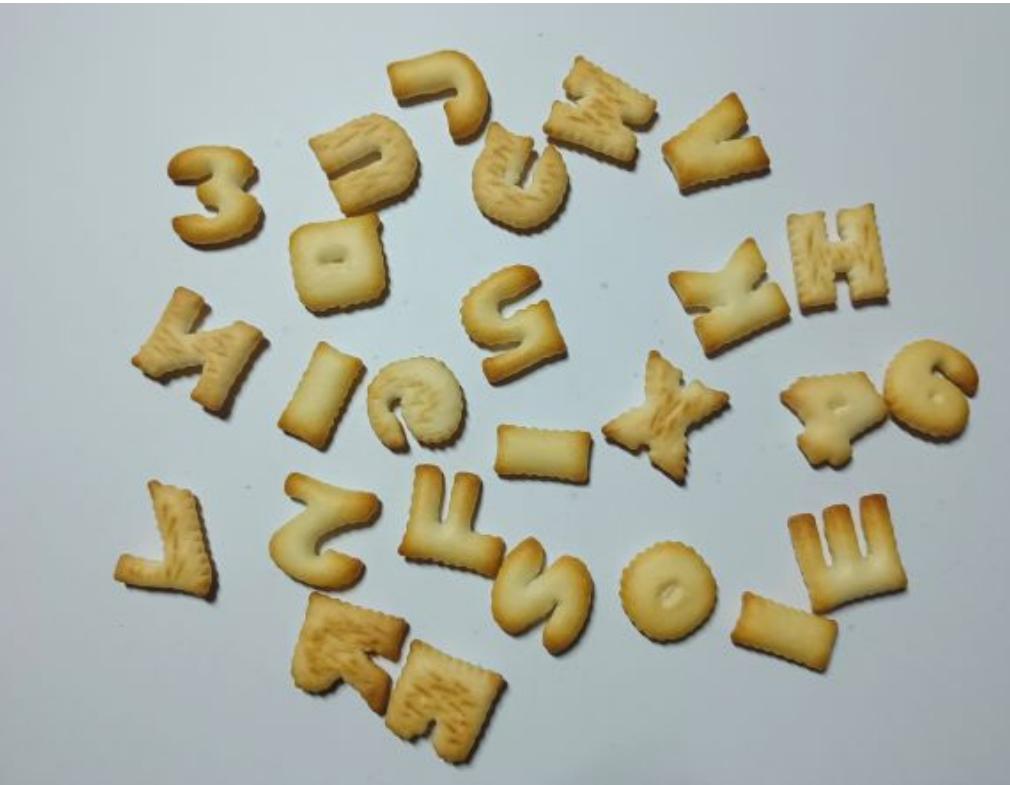
class: D

**3**

# **RESULT & TECHNIQUE COMPARE**

# Test Data (Total 31 pictures)

[https://drive.google.com/drive/folders/13falNJT LY8S3t63YfLXbazQMaCTlCuz?usp=share link](https://drive.google.com/drive/folders/13falNJT LY8S3t63YfLXbazQMaCTlCuz?usp=share_link)



# Result: General Case

All result

[https://drive.google.com/drive/folders/1cLui7lDXmoo1YI0hZNJbr2MrSdnYN9cA?usp=share link](https://drive.google.com/drive/folders/1cLui7lDXmoo1YI0hZNJbr2MrSdnYN9cA?usp=share_link)

HSV threshold



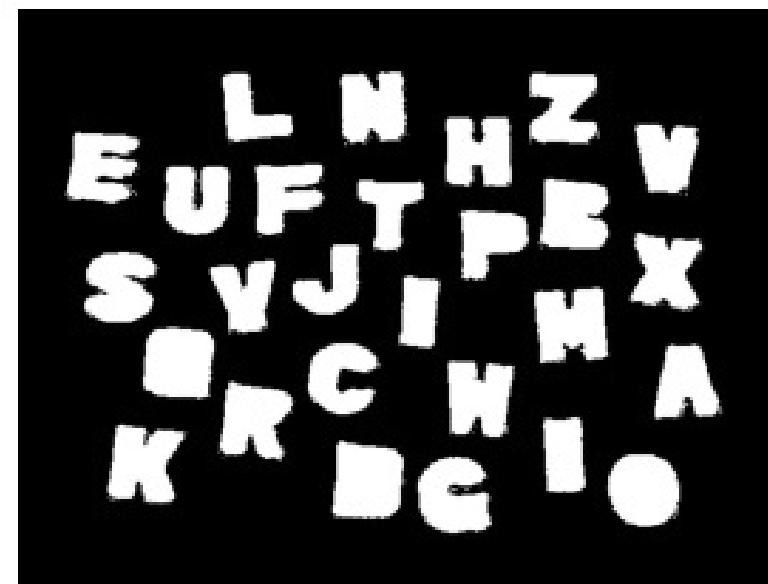
Count by ConnectedComponent



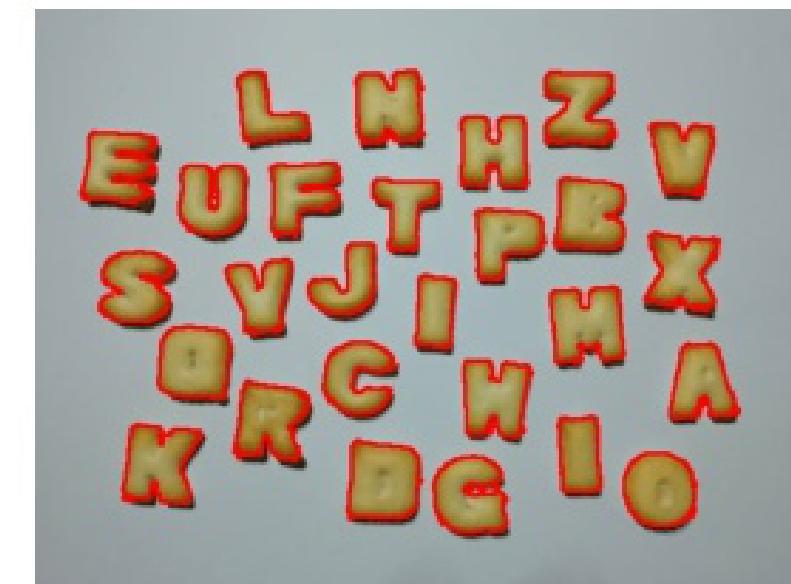
Original



HSV threshold



Count by Contour



Expect: 27

by ConnectedComp: 27

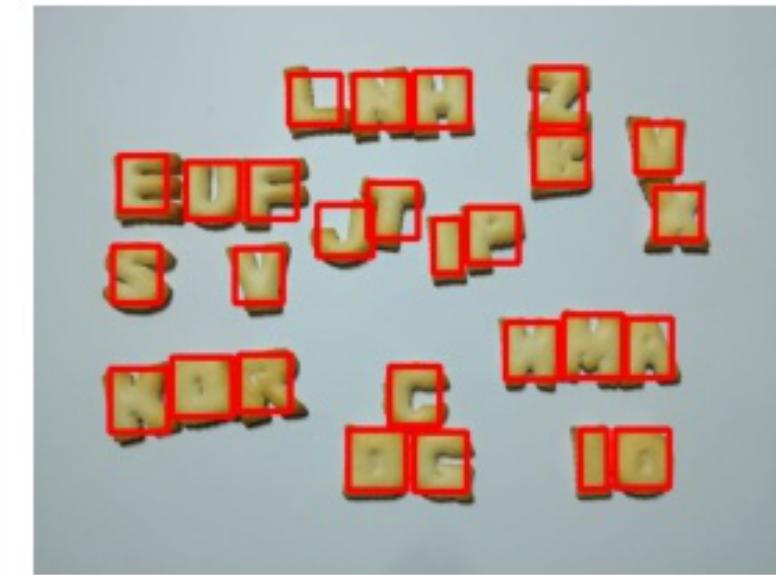
by Contour: 27

# Result: object ชิ้นกัน

HSV threshold



Count by ConnectedComponent



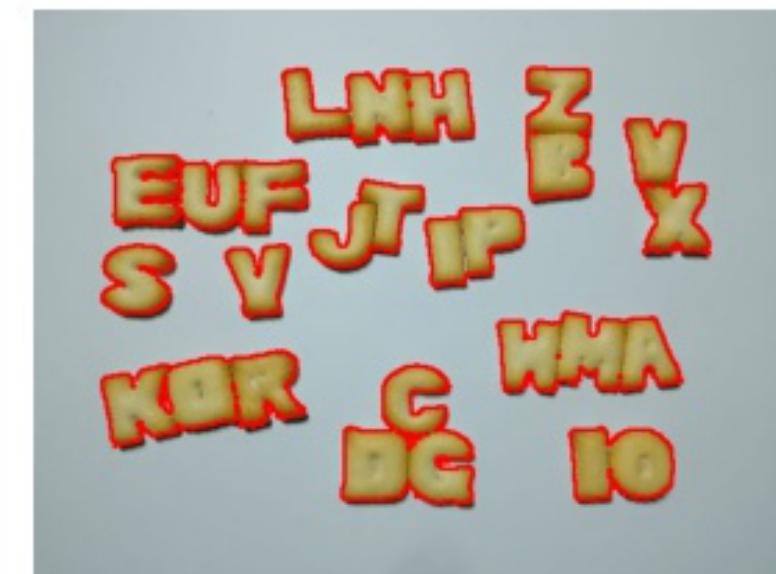
Original



HSV threshold



Count by Contour



Expect: 27

by ConnectedComp: 27

by Contour: 12

# Result: object ชิ้นกันมากๆ

HSV threshold



Count by ConnectedComponent



Original



HSV threshold



Count by Contour

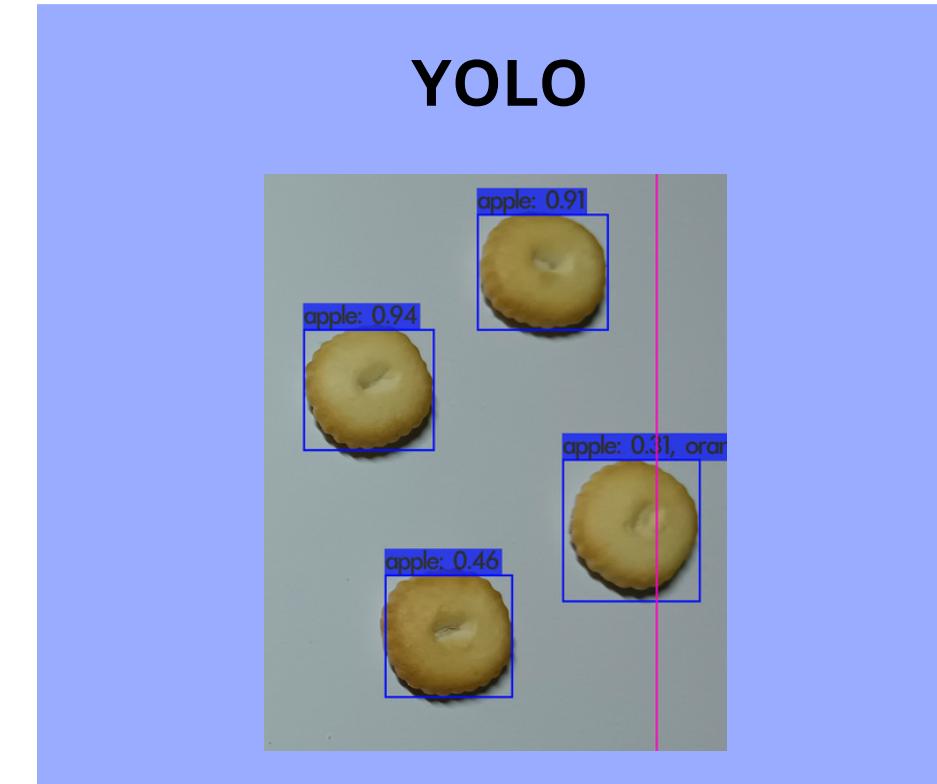
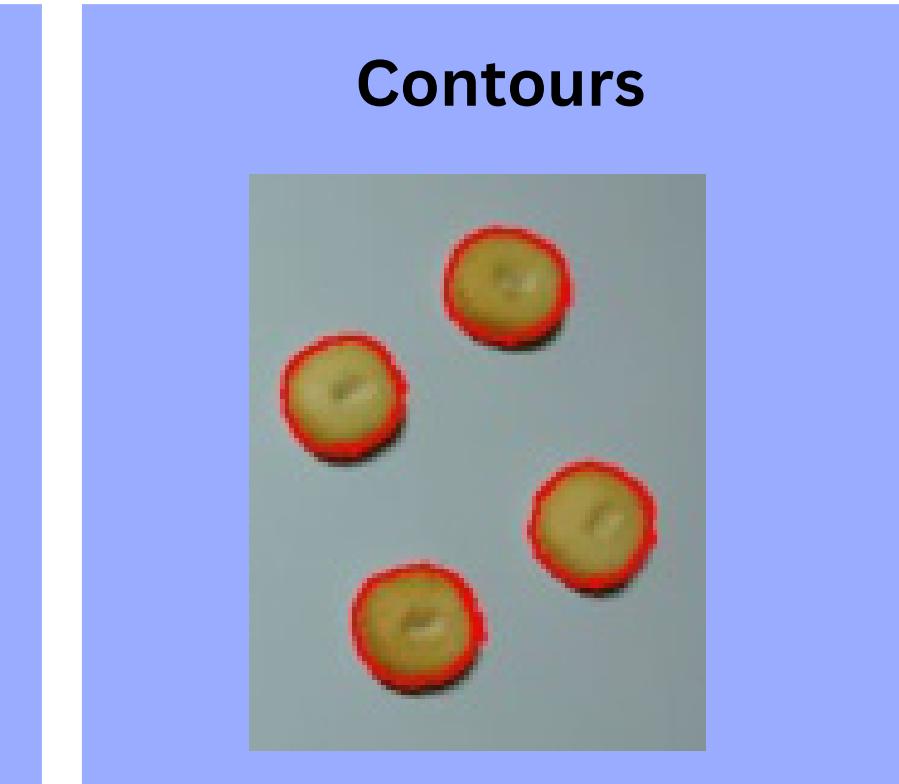
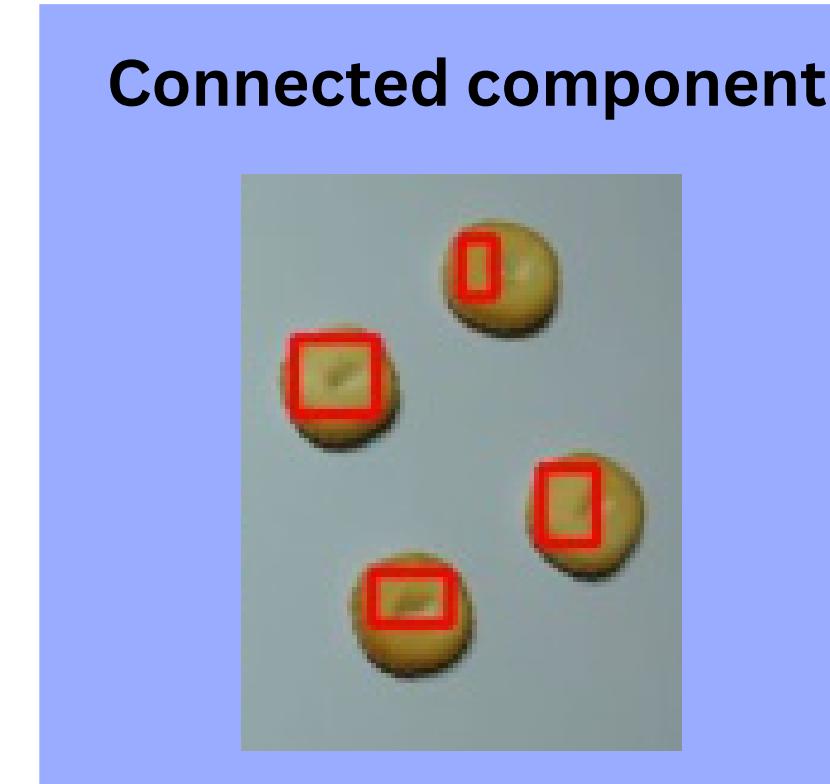


**Expect: 27**

by ConnectedComp: 23

by Contour: 1

# Technique Compare



**pros**

simple to separating adjacent object

can find the object shape and area

can classify the letter

**cons**

some object missing after erosion

problem with separating adjacent object

need a large amount of data to train model

**RMSE**

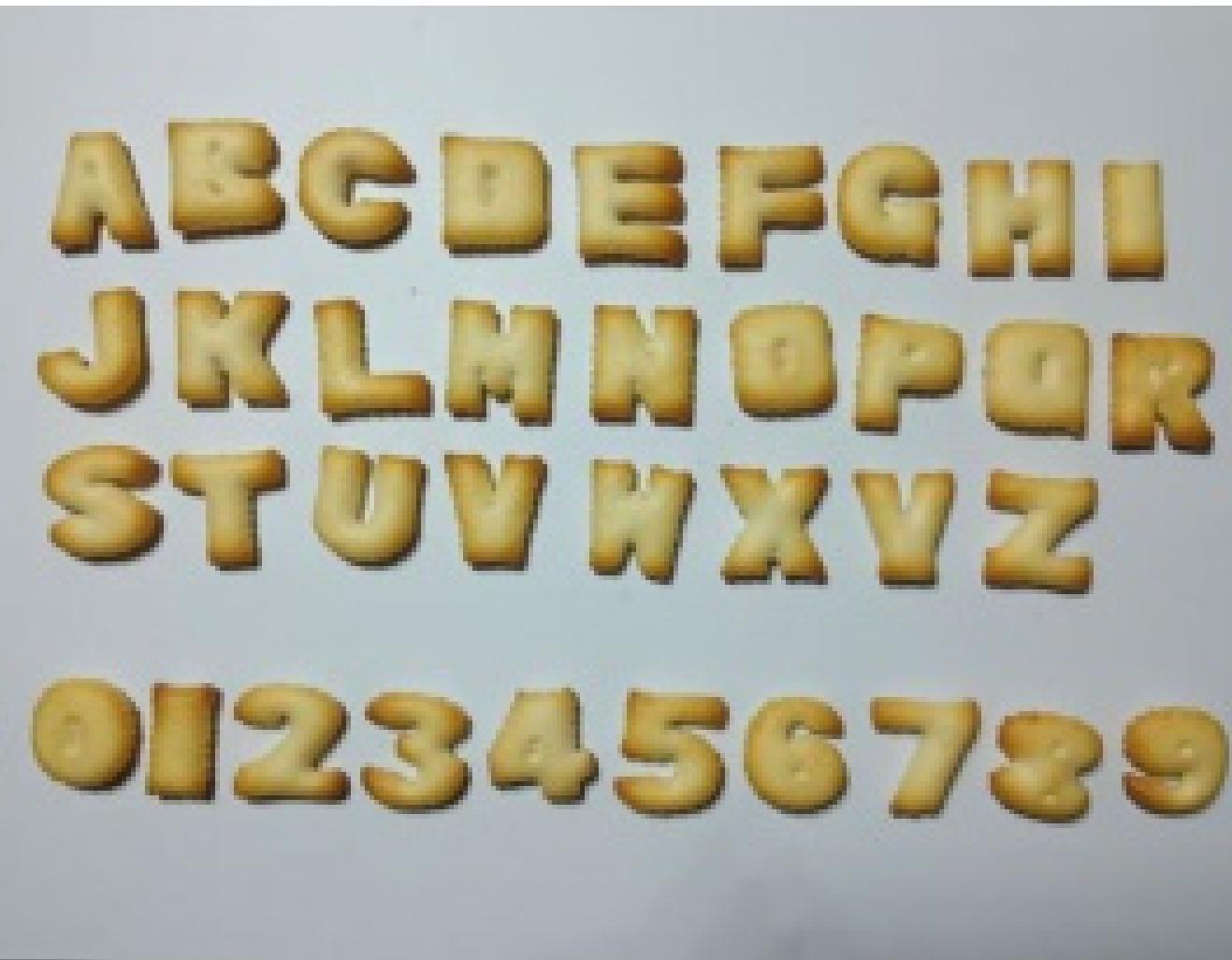
1.0000

9.8078

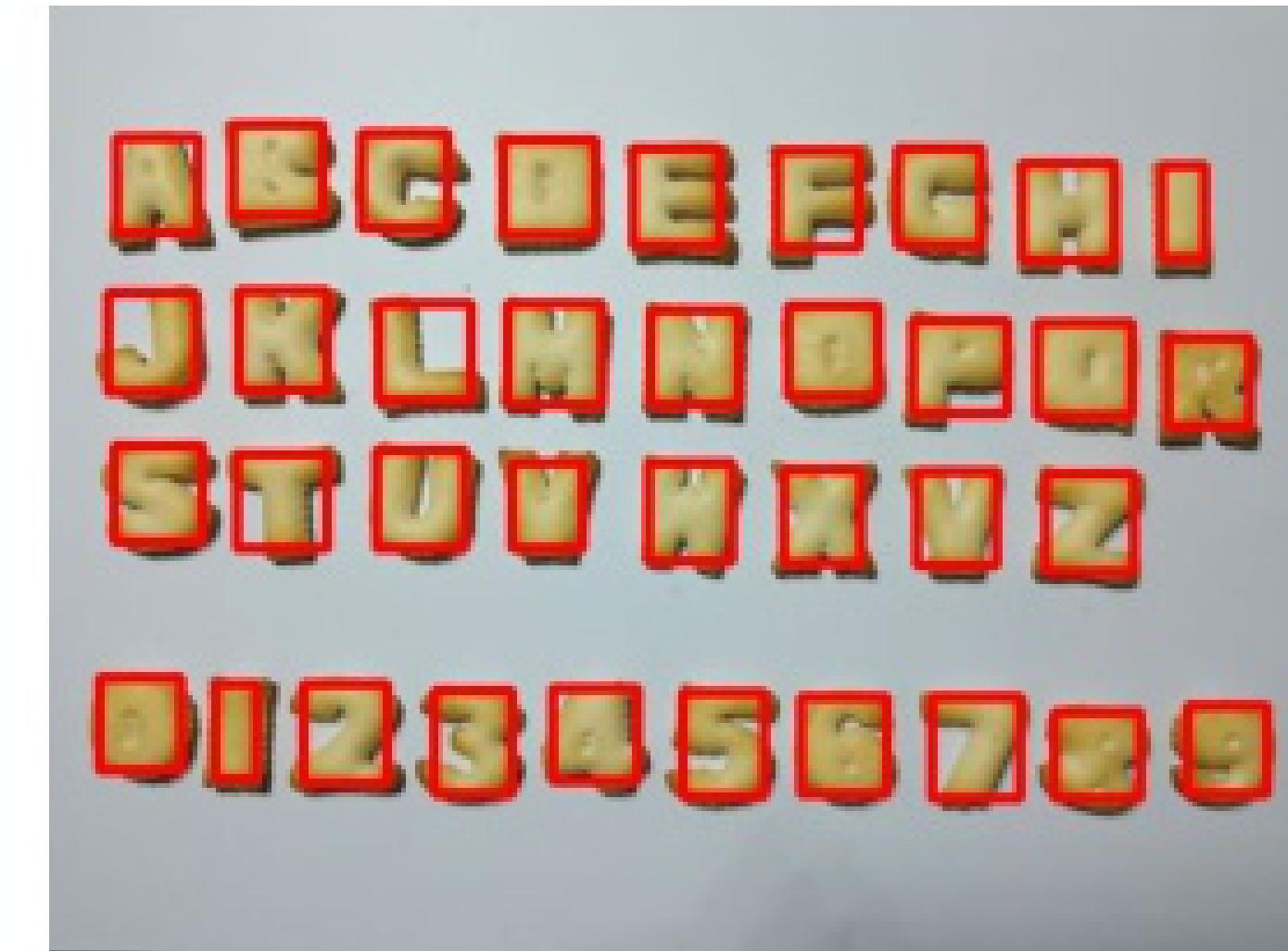
-

# Best Technique

**CONNECTED COMPONENT (RMSE=1.000)**



Expect: 36



Count: 36

---



**THANK YOU  
FOR YOUR ATTENTION**

