

Last time

$$(1) \quad \frac{\partial u}{\partial t}(x,t) = a(t) \frac{\partial^2 u}{\partial x^2}(x,t) + b(t) f(u(x,t)) + g(x,t)$$

$$(4) \quad \frac{du_i}{dt}(t) = \frac{a(t)}{(\Delta x)^2} [u_{i+1}(t) - 2u_i(t) + u_{i-1}(t)] + b(t) f((u_i)_t) + g(i\Delta x, t)$$

Finite difference approximation

$$(7) \quad \frac{d\vec{v}_i}{dt}(t) = a(t) \sum_{j=1}^{N-1} d_{ij} \vec{v}_j(t) + b(t) f((\vec{v}_i)_t) + g_i(t)$$

Error bounds

Systems (4) and (7) can be written in the form

$$(10) \quad \frac{dy}{dt} = a(t)(A+B)y(t) + b(t)F(y_t) + G(t),$$

where $y_t: [-\tau_0, 0] \rightarrow \mathbb{R}^n$, $y_t(\tau) = y(t+\tau)$, $\tau \in [-\tau_0, 0]$,
 $F: C([-\tau_0, 0], \mathbb{R}^n) \rightarrow \mathbb{R}^n$, $F_i(w) = f(w_i)$, $w \in C([-\tau_0, 0], \mathbb{R}^n)$,
 and A, B are n by n square matrices. Here, $n = 2M+1$
 for system (4), and $n = N+1$, for system (7).

Systems (5), (6), (8), (9) can be written in the form

$$(11) \quad \frac{dy^{(k+1)}}{dt}(t) = a(t)A y^{(k+1)}(t) + a(t)B y^{(k)}(t) + b(t)F(y_t^{(k)}) + G(t)$$

Error : $e^{(k)}(t) = y^{(k)}(t) - y(t)$

If F is additive (that is, $F(x + \tilde{x}) = F(x) + F(\tilde{x})$) as in examples (2) and (3), then subtracting (10) from (11), we get

$$\begin{aligned} \frac{de^{(k+1)}}{dt}(t) &= a(t)A e^{(k+1)}(t) + a(t)B e^{(k)}(t) + \underbrace{b(t)F(y_t^{(k)}) - b(t)F(y_t)}_{= b(t)F(y_t^{(k)} - y_t)} \\ &= b(t)F(y_t^{(k)} - y_t) \\ &= b(t)F(e_t^{(k)}) \end{aligned}$$

So,

$$\frac{de^{(k+1)}}{dt}(t) = a(t)A e^{(k+1)}(t) + a(t)B e^{(k)}(t) + b(t)F(e_t^{(k)})$$

Let $\|\cdot\|$ be an arbitrary vector norm or the induced matrix norm.

Then,

$$\|e^{(k+1)}(t+h)\| = \|e^{(k+1)}(t) + h \frac{de^{(k+1)}}{dt}(t)\| + O(h^2)$$

$$= \|\underbrace{e^{(k+1)}(t)}_{I e^{(k)}(t)} + h a(t) A e^{(k+1)}(t) + h a(t) B e^{(k)}(t) + h b(t) F(e_t^{(k)})\| + O(h^2)$$

$$\begin{aligned} & \stackrel{\text{triangle inequality}}{\leq} \| (I + h a(t) A) e^{(k+1)}(t) \| + \overset{\text{positive}}{\| h a(t) B e^{(k)}(t) \|} + \overset{\text{positive}}{\| h b(t) F(e_t^{(k)}) \|} + O(h^2) \\ & \leq \| I + h a(t) A \| \cdot \| e^{(k+1)}(t) \| + h a(t) \| B \| \cdot \| e^{(k)}(t) \| + h \| b(t) F(e_t^{(k)}) \| + O(h^2) \end{aligned}$$

We define $\|F\|_0 = \inf \{ \kappa > 0 : \|F(w)\| \leq \kappa \|w\|_0, w \in C([-r_0, 0], \mathbb{R}^n) \}$

where $\|w\|_0 = \max \{ \|w(r)\| : r \in [-r_0, 0] \}$. Then,

$$\|e^{(k+1)}(t+h)\| \leq \| I + h a(t) A \| \cdot \| e^{(k+1)}(t) \| + h a(t) \| B \| \cdot \| e^{(k)}(t) \| + h |b(t)| \cdot \|F\|_0 \cdot \|e_t^{(k)}\|_0 + O(h^2)$$

So, since $h > 0$, we get

$$(12) \quad \begin{cases} \frac{\|e^{(k+1)}(t+h)\| - \|e^{(k+1)}(t)\|}{h} \leq \frac{\|I + h a(t) A\| - 1}{h} \|e^{(k+1)}(t)\| + \\ + a(t) \|B\| \cdot \|e^{(k)}(t)\| + |b(t)| \cdot \|F\|_0 \cdot \|e_t^{(k)}\|_0 + O(h) \end{cases}$$

We now define the logarithmic norm

$$\mu(C) = \lim_{\varepsilon \rightarrow 0^+} \frac{\|I + \varepsilon C\| - 1}{\varepsilon}, \text{ where } C \text{ is any square matrix.}$$

Properties of the logarithmic norm:

$$\mu(C) \leq \|C\|$$

$$\mu(\lambda C) = \lambda \mu(C), \text{ for any positive scalar } \lambda$$

$$\mu(C_1 + C_2) \leq \mu(C_1) + \mu(C_2)$$

$$\|e^{tC}\| \leq e^{t\mu(C)}, \text{ for any } t \geq 0$$

We now take $h \rightarrow 0^+$ in (12) and get

$$D_+ \|e^{(k+1)}(t)\| \leq \mu(a(t)A) \|e^{(k+1)}(t)\| + a(t) \|B\| \|e^{(k)}(t)\| + \\ + (b(t) \cdot \|F\|_0 \cdot \|e_t^{(k)}\|_0),$$

where D_+ is the right-hand side derivative.