

Runge-Kutta methods

$$(1) \quad \begin{cases} y_{n+1} = y_n + h(a k_1 + b k_2), & \text{where } k_1 = f(t_n, y_n) \\ & k_2 = f(t_n + \Delta t, y_n + \beta h k_1) \end{cases}$$

$a, b, \Delta, \beta \in \mathbb{R}$ parameters

Here,

$$(2) \quad \Phi(t_n, y_n, h) = a f(t_n, y_n) + b f(t_n + \Delta t, y_n + \beta h k_1)$$

consistency condition

$$\forall t, x \quad \Phi(t, x, 0) \equiv f(t, x)$$

$$a f(t, x) + b f(t + \Delta \cdot 0, x + \beta \cdot 0) = (a + b) f(t, x) \equiv f(t, x)$$

$$\updownarrow$$

$$a + b = 1$$

order of accuracy

$$T_n = \frac{y(t_n + h) - y(t_n)}{h} - \Phi(t_n, y(t_n), h) \quad \left. \begin{array}{l} \text{from the definition of} \\ \text{the truncation error} \end{array} \right\}$$

$$= \frac{1}{h} \left[y(t_n) + \frac{1}{1!} y'(t_n) h + \frac{1}{2!} y''(t_n) h^2 + \frac{1}{3!} y'''(t_n) h^3 + \mathcal{O}(h^4) - y(t_n) \right]$$

$$- \Phi(t_n, y(t_n), h) =$$

$$(3) \quad = y'(t_n) + \frac{h}{2!} y''(t_n) + \frac{h^2}{3!} y'''(t_n) + \mathcal{O}(h^3) - \Phi(t_n, y(t_n), h)$$

Here,

$$y'(t_n) = f(t_n, y(t_n)) = \overbrace{f(t_n, y(t_n))}^{= f(t_n, y(t_n))}$$

$$y''(t_n) = \frac{\partial f}{\partial t}(t_n, y(t_n)) + \frac{\partial f}{\partial y}(t_n, y(t_n)) \cdot y'(t_n) = f_t + f_y \cdot f$$

$$y'''(t_n) = \frac{\partial^2 f}{\partial t^2}(t_n, y(t_n)) + \frac{\partial^2 f}{\partial y \partial t}(t_n, y(t_n)) \cdot y'(t_n) + \left(\frac{\partial^2 f}{\partial y^2}(t_n, y(t_n)) + \right.$$

$$\left. + \frac{\partial^2 f}{\partial t \partial y}(t_n, y(t_n)) \cdot y'(t_n) \right) \cdot y'(t_n) + \frac{\partial f}{\partial y}(t_n, y(t_n)) \cdot y''(t_n) =$$

$$= f_{tt} + \underbrace{f_{ty}} \cdot f + \underbrace{f_{ty}} \cdot f + f_{yy} [f]^2 + f_y [f_t + f_y f]$$

$$= f_{tt} + 2f_{ty} f + f^2 f_{yy} + f_t \cdot f_y + [f_y]^2 f$$

From (2)

$$\begin{aligned}
 \Phi(t_n, y_n, h) &= a f(t_n, y_n) + b f(t_n + \alpha h, y_n + \beta h f(t_n, y_n)) = \\
 &= a f(t_n, y_n) + b \left[f(t_n, y_n) + \frac{\alpha h}{1!} \frac{\partial f}{\partial t}(t_n, y_n) + \frac{(\beta h f(t_n, y_n))}{1!} \frac{\partial f}{\partial y}(t_n, y_n) \right. \\
 &\quad + \frac{(\alpha h)^2}{2!} \frac{\partial^2 f}{\partial t^2}(t_n, y_n) + 2 \frac{(\alpha h)(\beta h f(t_n, y_n))}{2!} \frac{\partial^2 f}{\partial t \partial y}(t_n, y_n) + \\
 &\quad \left. + \frac{[\beta h f(t_n, y_n)]^2}{2!} \frac{\partial^2 f}{\partial y^2}(t_n, y_n) + O(h^3) \right] = \\
 &= a f + b \left[f + \alpha h f_t + \beta h f f_y + \frac{1}{2} \alpha^2 h^2 f_{tt} + \alpha \beta h^2 f f_{ty} + \frac{1}{2} \beta^2 h^2 f^2 f_{yy} \right] \\
 &\quad + O(h^3)
 \end{aligned}$$

Therefore, from (3)

$$\begin{aligned}
 T_n &= \underbrace{f + \frac{1}{2} h [f_t + f f_y]}_{=0 \text{ because } a+b=1} + \frac{1}{6} h^2 [f_{tt} + 2 f f_{ty} + f^2 f_{yy} + f_t f_y + f_y^2 f] \\
 &\quad - \underbrace{a f - b [f + \alpha h f_t + \beta h f f_y + \frac{1}{2} \alpha^2 h^2 f_{tt} + \alpha \beta h^2 f f_{ty} + \frac{1}{2} \beta^2 h^2 f^2 f_{yy}]}_{=0 \text{ because } a+b=1} \\
 &\quad + O(h^3)
 \end{aligned}$$

Conclusion

$$\frac{1}{2} h f_t + \frac{1}{2} h f f_y - b \alpha h f_t - b \beta h f f_y = 0$$

$$\left(\frac{1}{2} - b \alpha \right) f_t + \left(\frac{1}{2} - b \beta \right) f f_y = 0$$

$$b \alpha = \frac{1}{2} \text{ and } b \beta = \frac{1}{2}$$

$$\text{So, } b \alpha = b \beta \text{ and } \alpha = \beta \neq 0$$