

Finite element method - the minimum of the functional \mathcal{J} over a subset $H_E^1(a,b)$

$u \in H_E^1(a,b)$ is a weak solution of the boundary-value problem

$$(7) \begin{cases} -\frac{d}{dt} \left[p(t) \frac{du}{dt} \right] + r(t)u(t) = f(t) \\ u(a) = A, \quad u(b) = B \end{cases}$$

if and only if

$$(8) \quad \mathcal{J}(u) = \min_{w \in H_E^1(a,b)} \mathcal{J}(w)$$

The idea of the finite element method: find u such that

$$\mathcal{J}(u) = \min_{w \in S_E^h} \mathcal{J}(w),$$

where $S_E^h \subset H_E^1(a,b)$.

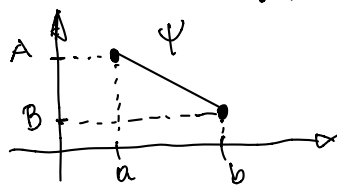
For example,

$$S_E^h = \left\{ w^h \in H_E^1(a,b) : \forall t \in [a,b] \ w^h(t) = \psi(t) + \sum_{i=1}^{n-1} c_i \psi_i(t), \ (c_1, c_2, \dots, c_{n-1}) \in \mathbb{R}^{n-1} \right\}$$

where

$$\psi(t) = \frac{B-A}{b-a} (t-a) + A$$

$$\psi \in H_E^1(a,b)$$



$$\psi(a) = A$$

$$\psi(b) = B$$

and

$\psi_1, \psi_2, \dots, \psi_{n-1} \in H_0^1(a,b)$ are linearly independent.

Then, $S_E^h \subset H_E^1(a,b)$.

Therefore, for (8), we want to find $u^h \in S_E^h$ such that

$$(9) \quad \mathcal{J}(u^h) = \min_{w^h \in S_E^h} \mathcal{J}(w^h)$$

Theorem on equivalence of Ritz and Galerkin methods

$$\text{Ritz method} \left\{ \begin{array}{l} u^h \in S_E^h \text{ is such that} \\ \mathcal{J}(u^h) = \min_{w^h \in S_E^h} \mathcal{J}(w^h) \end{array} \right\} \Leftrightarrow \underbrace{\forall v^h \in S_0^h \quad \mathcal{A}(u^h, v^h) = \langle f, v^h \rangle}_{\text{Galerkin method}},$$

$$\text{where } S_0^h = \{v^h \in H_0^1(a,b) : \forall t \in [a,b] \quad v^h(t) = \sum_{i=1}^{n-1} c_i \varphi_i(t), (c_1, c_2, \dots, c_{n-1}) \in \mathbb{R}^{n-1}\}$$

Proof: similar to the proof of the previous theorem

$$\text{Since } u^h \in S_E^h, \quad u^h = \psi(t) + \underbrace{\sum_{i=1}^{n-1} c_i \varphi_i(t)}_{\text{constants that have to be determined}}$$

Therefore,

$$\begin{aligned} \langle f, \varphi_i \rangle &= \mathcal{A}(u^h, \varphi_i) = \mathcal{A}\left(\psi(t) + \sum_{j=1}^{n-1} c_j \varphi_j(t), \varphi_i(t)\right) = \\ &= \mathcal{A}(\psi, \varphi_i) + \sum_{j=1}^{n-1} c_j \underbrace{\mathcal{A}(\varphi_j, \varphi_i)}_{\substack{\text{definition} \\ \checkmark a_{ji} = a_{ij} = \mathcal{A}(\varphi_i, \varphi_j) \rightarrow \text{because } \mathcal{A} \text{ is symmetric}}} \end{aligned}$$

$$\sum_{j=1}^{n-1} c_j \underbrace{\mathcal{A}(\varphi_j, \varphi_i)}_{= a_{ij}} = \underbrace{\langle f, \varphi_i \rangle - \mathcal{A}(\psi, \varphi_i)}_{b_i}, \quad i=1, 2, \dots, n-1$$

$$c_1 a_{i1} + c_2 a_{i2} + \dots + c_{n-1} a_{in-1} = b_i$$

$$\underbrace{\begin{bmatrix} a_{11} & a_{12} & a_{13} & \dots & a_{1,n-1} \\ a_{21} & a_{22} & a_{23} & \dots & a_{2,n-1} \\ \vdots & \vdots & \vdots & & \vdots \\ a_{n-1,1} & a_{n-1,2} & a_{n-1,3} & \dots & a_{n-1,n-1} \end{bmatrix}}_A \underbrace{\begin{bmatrix} c_1 \\ c_2 \\ \vdots \\ c_{n-1} \end{bmatrix}}_c = \underbrace{\begin{bmatrix} b_1 \\ b_2 \\ \vdots \\ b_{n-1} \end{bmatrix}}_b \quad \Leftrightarrow \quad Ac = b$$

↓
symmetric matrix