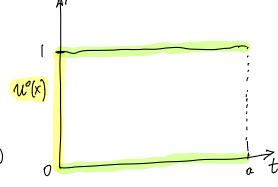
Initial-boundary value problems for parabodic portrol differential equations

 $\frac{\partial f}{\partial n}(x^{i+1}) = \frac{\partial x}{\partial n}\left(D(x^{i+1})\frac{\partial x}{\partial n}(x^{i+1})\right) + d(x^{i+1}) + d(x^{i+1}) + d(x^{i+1}) + d(x^{i+1})$ (ι)

where Digif are given functions and D(xit)70 for all x and t.

Initial condition

 $u(x_1 o) = u^o(x)$ (2) where wo(p) is a given function Boundary conditions



 $u(0(t) = b_0(t))$, $u(1(t) = b_1(t))$ (3)where bo, b, are given fundions.

Example:

(4)
$$\begin{cases} \frac{\partial t}{\partial u}(x_{1}t) = \frac{\partial^{2}u}{\partial x^{2}}(x_{1}t) & x \in (0,1), t > 0, \\ u(x_{1}0) = u^{0}(x), x \in (0,1), \\ u(0,t) = 0, u(1,t) = 0, t > 0, \end{cases}$$

h: step-size in time

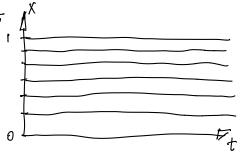
DX: Step-size En space

grid-points:
$$t_n = mh$$
, $m = 0_1 \cdot 1_1 \cdot 2_1 \cdot \cdots \cdot 1_n \cdot 2_n \cdot \cdots \cdot 1_n \cdot 2_n \cdot \cdots \cdot 1_n \cdot 2_n \cdot \cdots \cdot 2_n \cdot 2_n \cdot \cdots \cdot 2_n \cdot 2_n$

Semi-discretization process

We discretore in x keeping continuous t $u(xi,t) \approx u_i(t)$

exact solution approximation



Fruite difference operator

$$\frac{\partial^2 u}{\partial x^2}(x_{i_1}t) \approx \frac{u(x_{i_1},t) - 2u(x_{i_1}t) + u(x_{i_1},t)}{(\Delta x)^2}$$

$$\frac{\partial u}{\partial t}(x_i,t) \approx \frac{u(x_{i+1},t) - 2u(x_i,t) + u(x_{i-1},t)}{(\Delta x)^2}$$

(5)
$$\begin{cases} \frac{du_i}{dt} = \frac{u_{in}(t) - 2u_i(t) + u_{in}(t)}{(\Delta x)^2}, & i = 1, 2, ..., imex-1\\ u_0(t) = 0, & u_{imex}(t) = 0 & (from the boundary conditions)\\ u_i(0) = u^o(xi) \end{cases}$$

If the initial condition (2) is consistent with the boundary conditions (3) , then $u^{\circ}(0) = u^{\circ}(1) = 0$ (so that the exact solution doesn't have discontinuities at (0,0) and (1,0).

We can apply time titegradion methods to (S). For example, if we apply $y_{n+1} = y_n + h f(t_n, y_n)$, where $f = (f_1, f_2) \dots f_{inex-1}$ $f_i(t_1y_1) = f_i(t_1y_1, y_2, \dots, y_{inex-1}) = (bx_1)^2 (y_{i+1} - 2y_i + y_{i-1})$ then we get

(6)
$$\begin{cases} u_{i}^{m+1} = u_{i}^{m} + \frac{h}{(Ax)^{2}} \left(u_{i+1}^{m} - 2u_{i}^{m} + u_{i-1}^{m} \right), & n = 0, 1, 2, \dots \\ u_{i}^{o} = u^{o}(x_{i}), & i = 1, 2, \dots, i \text{max} - 1, \\ u_{i}^{h} = 0, & u_{i}^{m} = 0, & \text{and} \end{cases}$$
where $u_{o}^{h} = 0$, $u_{i}^{m} = 0$, and

with \approx vi(tu) \approx v(xi,tu) approximation exact solution by the time by the semi-discrete integration systems