



ATHABASCA UNIVERSITY

MATH 270

Assignment 3

Stanley Zheng

July 8, 2020

1. (a) We will cofactor expand along row 1.

$$\begin{aligned}
 \det \begin{bmatrix} 3 & 3 & 1 \\ 1 & 0 & -4 \\ 1 & -3 & 5 \end{bmatrix} &= 3 \cdot \det \begin{bmatrix} 0 & -4 \\ -3 & 5 \end{bmatrix} - 3 \cdot \det \begin{bmatrix} 1 & -4 \\ 1 & 5 \end{bmatrix} + 1 \det \begin{bmatrix} 1 & 0 \\ 1 & -3 \end{bmatrix} \\
 &= 3(5 - (-4) \cdot (-3)) - 3(5 \cdot 1 - (-4) \cdot 1) + (1 \cdot (-3) - 0 \cdot 1) \\
 &= 3 \cdot -12 - 9 \cdot 3 - 3 \\
 &= \boxed{-66}
 \end{aligned}$$

- (b) Again, we will cofactor expand along row 1.

$$\begin{aligned}
 \det \begin{bmatrix} k+1 & k-1 & 7 \\ 2 & k-3 & 4 \\ 5 & k+1 & k \end{bmatrix} &= (k+1) \cdot \det \begin{bmatrix} k-3 & 4 \\ k+1 & k \end{bmatrix} - (k-1) \cdot \det \begin{bmatrix} 2 & 4 \\ 5 & k \end{bmatrix} + 7 \cdot \det \begin{bmatrix} 2 & k-3 \\ 5 & k+1 \end{bmatrix} \\
 &= (k+1)(k(k-3) - 4(k+1)) - (k-1)(2k-20) + 7(2(k+1) - 5(k-3)) \\
 &= (k^3 - 6k^2 - 11k - 4) - (2k^2 - 22k + 20) + (-21k + 119) \\
 &= \boxed{k^3 - 8k^2 - 10k + 95}
 \end{aligned}$$

2. (a) We can start by manipulating this matrix into row echelon form by dividing R_1 by 3, adding $2R_1$ to R_3 , and swapping R_2 and R_3 . Finally, we can divide R_2 by 5 and R_3 by -2.

$$\begin{aligned}
 \det A &= \begin{vmatrix} 3 & 6 & -9 \\ 0 & 0 & -2 \\ -2 & 1 & 5 \end{vmatrix} \\
 \frac{\det A}{3} &= \begin{vmatrix} 1 & 2 & -3 \\ 0 & 5 & -1 \\ 0 & 0 & -2 \end{vmatrix} \\
 \frac{\det A}{30} &= \begin{vmatrix} 1 & 2 & -3 \\ 0 & 1 & -\frac{1}{5} \\ 0 & 0 & 1 \end{vmatrix}
 \end{aligned}$$

Finally, we can find the determinant of our row echelon matrix by cofactor expanding on R_3 .

$$\begin{aligned}
 \frac{\det A}{30} &= 1 \det \begin{bmatrix} 1 & 2 \\ 0 & 1 \end{bmatrix} = 1 \\
 \det A &= 30
 \end{aligned}$$

- (b) We can simply manipulate the second matrix using elementary row operations until it is equal to the first, then observe the result. Let $A = \begin{bmatrix} a & b & c \\ d & e & f \\ g & h & i \end{bmatrix}$. Then, we have $\det A = -6$. We can then set this equal to A , then manipulate A into the matrix we are trying to find the determinant of. To do this, we first subtract R_2 from R_1 , then multiply R_2 by -1.

$$\det A = \begin{vmatrix} a & b & c \\ d & e & f \\ g & h & i \end{vmatrix}$$

$$\det A = \begin{vmatrix} a+d & b+e & c+f \\ d & e & f \\ g & h & i \end{vmatrix}$$

$$-\det A = \begin{vmatrix} a+d & b+e & c+f \\ -d & -e & -f \\ g & h & i \end{vmatrix}$$

Therefore, we have $\begin{vmatrix} a+d & b+e & c+f \\ -d & -e & -f \\ g & h & i \end{vmatrix} = \boxed{6}$

- (c) We can use elementary column operations on the first matrix to make it equal to the second matrix since elementary row operations do not change the discriminant of a matrix. First, we can divide C_2 by $t \cdot C_1$ and C_3 by $s \cdot C_1$.

$$\begin{vmatrix} a_1 & b_1 & c_1 \\ a_2 & b_2 & c_2 \\ a_3 & b_3 & c_3 \end{vmatrix} = \begin{vmatrix} a_1 & b_1 & c_1 + rb_1 \\ a_2 & b_2 & c_2 + rb_2 \\ a_3 & b_3 & c_3 + rb_3 \end{vmatrix}$$

Next, we divide C_3 by $r \cdot C_2$.

$$\begin{vmatrix} a_1 & b_1 & c_1 \\ a_2 & b_2 & c_2 \\ a_3 & b_3 & c_3 \end{vmatrix} = \begin{vmatrix} a_1 & b_1 & c_1 \\ a_2 & b_2 & c_2 \\ a_3 & b_3 & c_3 \end{vmatrix}$$

3. (a) We can begin by finding the determinant of A using cofactor expansion.

$$\det A = \begin{vmatrix} 1 & 2 & 0 \\ k & 1 & k \\ 0 & 2 & 1 \end{vmatrix}$$

$$= 1 \begin{vmatrix} 1 & k \\ 2 & 1 \end{vmatrix} - 2 \begin{vmatrix} k & k \\ 0 & 1 \end{vmatrix}$$

$$= 1 - 2k - 2k$$

$$= 1 - 4k$$

Given that a matrix is invertible when its determinant is nonzero and real, we know that

the matrix is invertible when $\boxed{k \neq \frac{1}{4}}$

- (b) i. Recall that $\det(AB) = \det A \cdot \det B$.

We have $\det(-I \cdot A)$, and we know that $\det I = 1$, so $\det(-I) = -\det(A) = \boxed{2}$

- ii. We know that $\det(AB) = \det A \cdot \det B$ and $A \cdot A^{-1} = I$.

Rearranging this, we get $\det(A \cdot A^{-1}) = \det(I) = 1$.

Finally, we have $\det(A^{-1}) = \frac{1}{\det(A)}$, so $\det(A^{-1}) = \boxed{-\frac{1}{2}}$

- iii. If we cofactor expand A using the first row before A is transposed, it is equivalent to cofactor expanding along the first column after A is transposed. Therefore, we

know that $\det A^T = \det A$.

We can use the property $\det(AB) = \det A \cdot \det B$ to break up the two parts. $\det 2I \cdot \det A = 2 \det A = \boxed{-4}$

- iv. $\det(A^3)$ Similarly to the previous questions, we can use the property $\det(AB) = \det A \cdot \det B$. We have $\det(A^3) = \det A \cdot \det A \cdot \det A = (-2)^3 = \boxed{-8}$

4. (a) We can find if the matrix is invertible by finding its discriminant. We can use cofactor expansion along R_1

$$\det A = 2 \begin{vmatrix} 1 & 0 \\ 3 & 6 \end{vmatrix} = 12$$

The matrix is invertible since its determinant is nonzero. We then need to find the adjugate matrix of A by cofactoring the matrix, then we can multiply by the discriminant to find the inverse.

$$\begin{aligned} A^{-1} &= \frac{1}{12} \text{adj} \begin{bmatrix} 2 & 0 & 0 \\ 8 & 1 & 0 \\ -5 & 3 & 6 \end{bmatrix} \\ &= \frac{1}{12} \begin{bmatrix} \begin{vmatrix} 1 & 0 \\ 3 & 6 \end{vmatrix} & -\begin{vmatrix} 8 & 0 \\ -5 & 6 \end{vmatrix} & \begin{vmatrix} 8 & 1 \\ -5 & 3 \end{vmatrix} \\ -\begin{vmatrix} 0 & 0 \\ 3 & 6 \end{vmatrix} & \begin{vmatrix} 2 & 0 \\ -5 & 6 \end{vmatrix} & -\begin{vmatrix} 2 & 0 \\ -5 & 3 \end{vmatrix} \\ \begin{vmatrix} 0 & 0 \\ 1 & 0 \end{vmatrix} & -\begin{vmatrix} 2 & 0 \\ 8 & 0 \end{vmatrix} & \begin{vmatrix} 2 & 0 \\ 8 & 1 \end{vmatrix} \end{bmatrix}^T \\ &= \frac{1}{12} \begin{bmatrix} 6 & -48 & 29 \\ 0 & 12 & -6 \\ 0 & 0 & 2 \end{bmatrix}^T \\ &= \begin{bmatrix} \frac{1}{2} & 0 & 0 \\ -4 & 1 & 0 \\ \frac{29}{12} & -\frac{1}{2} & \frac{1}{6} \end{bmatrix} \end{aligned}$$

- (b) We can first rewrite this system of equations as three matrices, one for each variable.

$$\begin{aligned} D &= \begin{vmatrix} 1 & -4 & 1 \\ 4 & -1 & 2 \\ 2 & 2 & -3 \end{vmatrix} = 1 \cdot (-1) - (-4) \cdot (-16) + 1 \cdot 10 = -55 \\ D_x &= \begin{vmatrix} 6 & -4 & 1 \\ -1 & -1 & 2 \\ -20 & 2 & -3 \end{vmatrix} = 6 \cdot (-1) - (-4) \cdot (43) + 1 \cdot (-22) = 144 \\ D_y &= \begin{vmatrix} 1 & 6 & 1 \\ 4 & -1 & 2 \\ 2 & -20 & -3 \end{vmatrix} = 1 \cdot (43) - 6 \cdot (-16) + 1 \cdot (-78) = 61 \\ D_z &= \begin{vmatrix} 1 & -4 & 6 \\ 4 & -1 & -1 \\ 2 & 2 & -20 \end{vmatrix} = 1 \cdot (22) - (-4) \cdot (-78) + 6 \cdot (10) = -230 \end{aligned}$$

Cramer's rule states that $x = \frac{D_x}{D}$, $y = \frac{D_y}{D}$, and $z = \frac{D_z}{D}$. Therefore, we have

$$\begin{aligned}x &= \frac{144}{-55} = -\frac{144}{55} \\y &= \frac{61}{-55} = -\frac{61}{55} \\z &= \frac{-230}{-55} = \frac{46}{11}\end{aligned}$$

5. (a) Absolutely no clue.