



# Virtual Cardiac Surgical Planning Through Hemodynamics Simulation and Design Optimization of Fontan Grafts

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**Abstract.** For complex congenital heart disease (CHD) involving a single functioning ventricle, the Fontan operation is performed which results in a circulation where deoxygenated venous blood passively flows into the pulmonary arteries without a ventricular pump. However, conventional Fontan graft designs may result in suboptimal cardiovascular hemodynamics leading to post-surgical complications. Patient-specific designs are thus promising in the Fontan operation. This paper reports the virtual simulation and designs of patient-specific Fontan grafts with the aid of computational fluid dynamics (CFD). CFD parameters including meshing, wall layers, and solver choices were studied to bolster accuracy while minimizing computational time. CFD simulations of original Fontan design were performed to evaluate three hemodynamic parameters: indexed power loss (iPL), hepatic flow distribution (HFD), and percentage of the non-physiological wall shear stress (%WSS, a novel surrogate marker for clot risk). New designs were then created to target these parameters with iterative optimization technique. This overall approach was utilized to redesign the Fontan grafts of patients ( $n = 2$ ). The re-designed Fontan grafts showed significant improvements in all three hemodynamic parameters when compared to the original designs. Our unique integration of surgical design and flow simulation has the potential to enable cardiac surgeons to effectively simulate patient specific designs for the Fontan operation, potentially improving the surgical outcomes of patients with complex CHD.

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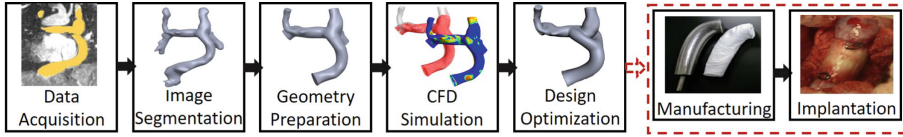
## 1 Introduction

Congenital heart disease (CHD) affects 0.8% of the population, with  $\frac{1}{4}$  of infants requiring life-saving intervention as a neonate [9]. For patients with complex CHD involving a single functioning ventricle, surgeons perform a series of open-heart surgeries to modify the venous circulation. The third surgery, the Fontan operation, connects the inferior vena cava into the superior cavopulmonary anastomosis via intracardiac patch (lateral tunnel Fontan) or a conduit (extracardiac Fontan) [6]. The Fontan graft's geometry influences hemodynamics of blood flow into the pulmonary arteries, and novel designs such as a y-shaped (bifurcated) graft have been previously proposed [11]. Despite significant development in the Fontan operation, graft designs are still constrained by material type and availability, potentially resulting in suboptimal cardiovascular hemodynamics and post-surgical complications including cardiac performance impairment [1], pulmonary arteriovenous malformation [14], and thrombosis [8]. Many studies approached this problem via simulating the blood flow inside Fontan and predicting hemodynamics using the computational fluid dynamics (CFD) [7, 13], none have addressed the risk of thrombosis in a Fontan graft.

The simulation approach can be combined with a manufacturing process using computer-aided design (CAD), CFD and electrospinning of tissue-engineered vascular grafts (TEVGs) to create patient-specific designs as part of virtual surgical planning [13]. With the use of these, patient-specific Fontan graft designs may be the key to improving the quality of surgery and patient outcomes. As patient-specific Fontan grafts become closer to reality, we continue to refine the workflow of virtual surgical planning by identifying an accurate, time-efficient and clinically relevant CFD approach to virtual surgical planning of Fontan grafts. The objective of this study is to investigate and propose the best set of CFD parameters (i.e. meshing strategy, wall layering, and CFD solver choice) for the Fontan circulation simulation. Additionally, along with CFD simulation of conventional hemodynamic parameters such indexed power loss and hepatic flow distribution (CFD), we introduce a novel hemodynamic parameter, non-physiological wall shear stress, that acts as a surrogate for risk of thrombosis.

## 2 Methods

This section summarizes the sequential steps for simulating and optimizing the Fontan designs. Our approach consists of seven steps (see Fig. 1) including two previously reported steps on manufacturing and implanting patient specific 3D printed grafts [5], which we will combine in the future for improving Fontan surgeries. Sections 2.1 and 2.2 entails the methods for MRI data acquisition (i.e. anatomy and boundary flow data), image segmentation, and geometry preparation. Section 2.3 lays out the details of the CFD simulation (i.e. meshing, number



**Fig. 1.** Schematic workflow diagram of the virtual Fontan design optimization.

of wall layers, and solver settings). Based on the calculated hemodynamics, various Fontan design parameters are optimized in three iterations to correct the flow and pressure in the graft, which is explained in Sect. 2.4.

## 2.1 Data Acquisition and Image Segmentation

The magnetic resonance angiogram (MRA) data, consisting of a late-phase, non-gated, breath-held acquisition with pixel size  $\sim 1.4 \times 1.4$  mm, served as a road-map to build a 3-dimensional (3D) Fontan model, including the proximal cavae and branch pulmonary arteries, using a commercially available image segmentation software (Mimics; Materialise, Leuven, Belgium). Both automatic thresholding and manual methods were used to identify the blood pool of the Fontan in each slice of the angiogram, allowing for the creation of a 3D Fontan model them exported using the stereolithography (STL) file format. This STL file was hollowed and smoothed. Following, retrospectively-gated, through plane phase-encoded velocity maps were acquired across the IVC, SVC, LPA, and RPA using standard sequences, reconstructing 30 phases per cardiac cycle with a velocity encoding threshold of  $150 \frac{\text{cm}}{\text{second}}$ . The time-averaged IVC and SVC flow rates were derived from the phase velocity data and prescribed as inlet boundary conditions to the CFD simulations. The time-averaged RPA and LPA flow rates were prescribed as outlet flow splits (the ratio of LPA to RPA). All patient data was collected with the Institutional Review Board approval.

## 2.2 Geometry Preparation

All models were modified by a “Deform” function which globally smooth out the models’ surfaces, reducing irregular surfaces, using Meshmixer (Autodesk Inc., San Rafael, CA). Deformation of the original model from smoothing was minimized by applying “Shape Preserving” method. Since the smoothed models were extremely fine meshed and caused some software to crash, the mesh size was reduced by 50%, leaving us with around 30,000 triangles per model. Then, 50 mm long extensions were added at the each end of the boundaries for two important purposes. The inlet extensions enabled the velocity profiles to fully develop before the blood enters the computationally interesting areas. The outlet extensions allowed the numerical flow data to stabilize and provide more accurate results [13, 15]. The boundary cuts were adjusted in CAD (SolidWorks, Dassault, France) to ensure smooth extensions of the boundaries. The final model was converted

**Table 1.** Impact of smoothing and cutting on cell quality.

Designed model		Aspect ratio	Max skewness	Min orthogonal
P1	Non-edited	30.303	0.975	2.548e−2
	Smoothed	17.355	0.917	8.310e−2
	Smoothed & cut	16.927	0.802	0.198
P2	Non-edited	32.315	0.927	7.309e−2
	Smoothed	17.602	0.817	0.183
	Smoothed & cut	17.005	0.797	0.203

into the text-based Parasolid file and showed improved cell qualities including aspect ratio, maximum skewness, and minimum orthogonal values (Table 1), the deterministic features for the numerical computation accuracy and stability [4].

### 2.3 CFD Simulation

**Performance Metric.** The blood flow inside the Fontan graft was virtually simulated through CFD (ANSYS, Pennsylvania, USA) to determine its performance by the indexed power loss (iPL), hepatic flow distribution (HFD), and the non-physiological wall shear stress percentage (%WSS). iPL, a deterministic factor of the abrupt blood flow changes causing cardiac performance impairment [1], was calculated using the Eq. 1, derived from power loss (Eq. 2):

$$iPL = \frac{PL}{\rho Q_s^3 / BSA^2} \quad (1)$$

$$PL = \sum_{inlets} \int_A (p + \frac{1}{2} \rho v^2) v \times dA - \sum_{outlets} \int_A (p + \frac{1}{2} \rho v^2) v \times dA \quad (2)$$

where  $p$  being the static pressure,  $\rho$  the density,  $A$  the boundary area,  $v$  the velocity,  $Q_s$  the systemic venous flow, and the BSA the body surface area [7]. Unbalanced HFD overstresses the heart and progresses malformation of pulmonary arteriovenous [14]. HFD was estimated by computing the ratio of the number of particles passed through each outlets from the IVC. The particles at the IVC was evenly spaced with a 0.1 mm marker size and 1 mm spacing factor setting. The percentage of Fontan and outlet areas falling below  $1 \frac{dynes}{cm^2}$  in WSS were estimated since the low WSS represents the low-flow in venous stasis causing deposition of procoagulant [8]. In summary, Fontan models with iPL lower than 0.03, HFD between 40:60 or 60:40, and %WSS below 10% were considered to have healthy hemodynamic performance.

**Meshing.** Mesh size was tested to bolster the computation accuracy and time efficiency. The meshing could either be uniform where the elements are roughly the same size or non-uniform with a max element size defined. Our test runs

**Table 2.** Hemodynamics results between non-uniform and uniform meshing.

Simple, 0.7 mm, 5 layers		iPL	HFD (LPA%)	%WSS	Computing time (hr:min)
P1	Non-uniform	0.036	57.68	1.035	15:12
	Uniform	0.036	58.08	1.128	39:21
P2	Non-uniform	0.008	33.25	13.628	14:52
	Uniform	0.008	31.80	13.323	18:02

**Table 3.** Impact of max element size on cell quality.

Original model		Aspect ratio	Max skewness	Min orthogonal
P1	0.70 mm	15.004	0.887	0.114
	1.00 mm	23.259	0.953	4.697e−2
	1.25 mm	19.017	0.944	5.571e−2
	1.50 mm	16.492	0.912	8.844e−2
P2	0.70 mm	18.069	0.883	0.117
	1.00 mm	20.615	0.906	9.384e−2
	1.25 mm	19.197	0.931	6.928e−2
	1.50 mm	19.451	0.937	6.318e−2

confirmed that the CFD results between uniform and non-uniform were similar, but non-uniform meshing performed much faster (see Table 2). Following, the max element sizes, between 0.7 mm to 1.5 mm, were tested to identify the best size for creating mesh around the sharp corners and minimize numerical errors (Table 3). The recommended minimum orthogonal quality is 0.01, and only the 0.7 mm max mesh size was able to get sufficing values. Also considering that the lowest aspect ratio and lowest max skewness was with 0.7 mm, a max element size of 0.7 mm was selected for non-uniform meshing.

**Wall Layer.** The number of wall layers was explored to obtain accurate WSS measurements. Considering previously reported wall layer values, [3,12], the range of three to six was tested. These variations had minimal impact on the Fontan hemodynamics and the computing time (Table 4). Thus, the study concluded to use five layers, which is the default setting in ANSYS.

**Solver.** We compared the pressure-based segregated algorithms including simple, coupled, and PISO. Despite the PISO and coupled algorithms known to be computationally heavy but more accurate, results were close to that of simple algorithm (Table 5). Hence, simple solver was applied to solve the laminar flow, which was confirmed by the Reynolds number. The simulated blood was assumed to be a Newtonian fluid with  $1060 \frac{kg}{m^3}$  density and  $3.71 mPas$  viscosity [13]. Our CFD simulation used the 3D unsteady Navier-Stokes equations with 40 iterations with each iteration timestep lasting 0.001 s. The x, y, z-velocity and mass conservation residual convergence values were set to  $10^{-5}$  [13].

**Table 4.** Hemodynamics results under the varying number of wall layers.

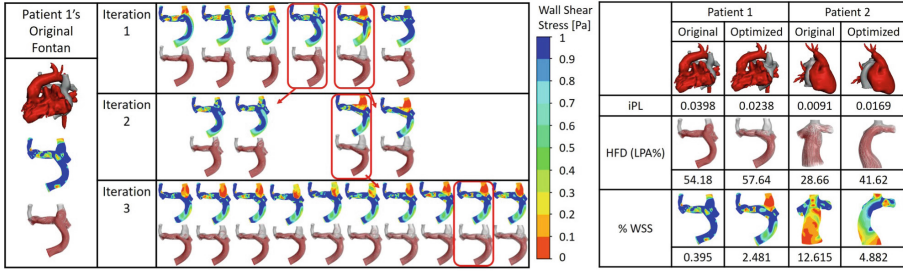
	PISO, 1.25 mm	iPL	HFD (LPA%)	%WSS	Computing time (hr:min)
P1	3	0.0355	57.69	0.90	13:04
	4	0.0357	57.62	0.92	14:11
	5	0.0360	57.90	1.03	15:12
	6	0.0362	58.45	1.06	15:15
P2	3	0.0083	32.74	13.32	14:42
	4	0.0082	32.94	13.51	14:41
	5	0.0082	32.97	13.56	14:51
	6	0.0083	33.08	13.29	14:17

**Table 5.** Hemodynamics results under various solver algorithms.

0.7 mm, 5 layers, non-uniform		iPL	HFD (LPA%)	%WSS	Computing time (hr:min)
P1	Simple	0.036	57.68	1.035	13:65
	Coupled	0.036	58.02	0.998	18:51
	PISO	0.035	57.89	1.075	15:12
P2	Simple	0.008	33.25	13.628	08:23
	Coupled	0.008	33.28	13.863	23:54
	PISO	0.008	33.23	13.647	14:52

2.4 Design Optimization

Fontan grafts were optimized by three consecutive iterations of design modifications based on the patient’s anatomy and the performance metric results (Fig. 2). The first iteration included identifying possible paths and anastomoses regions with the assistance of experienced cardiologists. The possible paths avoided colliding with the surrounding anatomy, including heart, major vessels, and spine. Then, the surgically adequate tube-shaped and the y-shaped (bifurcated) Fontan grafts were designed. For a tube-shaped graft, a 3D spline was drawn between 2 points. The starting point was placed at the center of the IVC and the end point was chosen at the center of an ellipse drawn on the identified anatomoses region at the SVC. The IVC’s outline and the ellipse on the SVC with the 3D spline as the centerline were selected for 3D lofting. For easier spline control, 1 or 2 extra points along the intended spline path were added. The bifurcated graft was made with two ellipses on the SVC and connecting it with the IVC using the 2D surface loft function in CAD. Manipulating the curvature of the graft was accomplished by adding an ellipse in between the SVC and IVC, similar to adding 1 or 2 spline points for a tube-shaped graft. The bifurcated Fontan grafts were not always feasible if the identified path was too narrow for two ellipses to be connected. The second iteration involved changing the geometrical parame-



**Fig. 2.** Left: Iterative design for optimizing the first patient's Fontan graft, Right: Comparison of performance for original and optimized Fontan grafts.

ters of the prior designs considering the hemodynamic performance. The entry angle and the center curve of the Fontans were adjusted when the iPL was higher than 0.03. The location, dimensions, and angles of the ellipse on the anastomoses region acted as the manipulator tool of the direction and the amount of the inlet flow heading to Glenn, adjusting the HFD. High %WSS was controlled by reducing the girth of the Fontans. The significance of each geometrical parameter on the hemodynamic performance was summarized and applied for making slight adjustments to further improve Fontan performance during the third iteration. The Fontan grafts were optimized to achieve the lowest iPL, while maintaining below 10% for %WSS and between 40:60 and 60:40 HFD.

### 3 Result

The Fontan grafts were optimized hemodynamically for each patient (Fig. 2) using our approach. The optimized Fontan designs had significant improvements on hemodynamics with 40% decrease in iPL for patient one (P1) with a y-shaped graft and 45% increase in flow distribution to the LPA and 61% reduction in %WSS for the second patient (P2) with a tube-like graft.

### 4 Discussion and Conclusion

We developed 3 benchmark parameters that were based off Haggerty et al.'s larger CFD cohort simulation of 100 patients [7]. This ensured providing patient-specific designs in the hemodynamic optimal when compared to other Fontan patients. %WSS is completely a novel parameter, but is based on relevant clinical data [8] and should be incorporated in all Fontan simulations moving forward. Of note, our method creates a tradeoff between iPL and risk of thrombosis, as larger Fontan grafts will have less power loss but increased risk of thrombosis. This is clinically appropriate given the risk of thrombosis in patients with Fontans [2].

Reducing computational time whilst maintaining accuracy allows more time for feedback from the surgeon and the design team before the Fontan operation.

Inevitable, some adjustments are needed in the initial proposed designs, and shorter computational time allows for more design iterations. Our decisions on CFD simulations were made to balance the accuracy and computational time. Rigid wall was assumed in the current CFD simulations. However, fluid-structure interaction is known to provide higher accuracy in WSS calculation [10] and should be implemented in future studies.

This study introduces the unique virtual simulation workflow and computational fluid dynamics for optimizing the Fontan graft design. The re-designed Fontan grafts of two patients using this approach showed significant improvements in hemodynamic parameters (i.e. iPL, HFD, and %WSS). We believe that our unique integration of surgical design and flow simulation has the potential to enable cardiac surgeons to effectively simulate patient specific designs for the Fontan operation, potentially improving the surgical outcomes of patients with complex CHD. Future studies will entail applying this approach on more patient models and manufacturing the designs for implantation.

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