

DHINESH RAJASEKARAN

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EDUCATION

Master of Engineering - Robotics University of Maryland, College Park	Aug. 2022 - Dec. 2023 <i>College Park, MD, USA</i>
<ul style="list-style-type: none">• CGPA of 3.7/4.0• Key Courses: Perception, 3D Vision, Planning & Software Dev for Autonomous Robots.	
Bachelor of Technology - Electronics and Communication Engineering SRM Institute of Science and Technology, Chennai	Jul. 2017 - Jun. 2021 <i>Chennai, TN, India</i>
<ul style="list-style-type: none">• CGPA of 8.8/10.0• Key Courses: Digital Logic Design, Control Systems, Embedded Systems.	

PROFESSIONAL EXPERIENCE

National Institutes of Health, Rockville Robotics Research Associate	Sept. 2023 - Dec. 2023 <i>Rockville, MD, USA</i>
<ul style="list-style-type: none">• Developed a robotic chemist utilizing the Omron LD series mobile robot, PF400 robotic arm and an advanced High-Density Storage (HDS) system to seamlessly automate the serial/batch evaporation process.• Utilized OpenCV-based detection algorithms to autonomously track vial movements within the system & designed an electromagnetic door handle for human/robotic access to the HDS.• Built the hardware and tested the detection algorithm under various lighting conditions and across multiple industrial cameras in accessing the efficiency and detection robustness.	
Amazon Web Services, New York Solutions Architect Intern	May. 2023 - Aug. 2023 <i>New York, NY, USA</i>
<ul style="list-style-type: none">• Developed an automated tool to facilitate database migration process from a SQL to a No-SQL database.• Tool developed using Python & JavaScript integrates various AWS technologies like DMS, RDS & DynamoDB to deliver a CLI and web based interface automating the entire process.	
Solinas Integrity, IIT Madras Research Park Robotics Engineer	Aug. 2021 - Jul. 2022 <i>Chennai, TN, India</i>
<ul style="list-style-type: none">• Designed & developed Endobot 2.0, a tethered pipeline inspection robot which can detect leaks, corrosion and defects on pipelines as small as 4 inch up-to a depth of 300 meters and can withstand 5 bar underwater pressure. 🔗 Link• Was responsible for embedded firmware, digital circuit & power electronics design, designing & testing the control PCB based on STM32 & DVR PCB based on ESP32 & ATmega 2560, designing mechanical systems & 3D printed parts.	
FlamencoTech, Bangalore Embedded Engineer	Jun. 2021 - Jul. 2022 <i>Bangalore, KA, India</i>
<ul style="list-style-type: none">• Designed & fabricated a "Wet Floor Detection Sensor" using Lepton thermal camera, ESP 32 & custom firmware for detecting wet floor using image processing. 🔗 Link• Developed a library for ToF Sensor for 3D mapping, people counting & presence detection.• Designed basic PCB architecture for IWR6843 mmWave TI sensor and a custom wireless sensor platform capable of automating an entire building.	

PROJECTS

Smart Kitchen Robot for Making Stuffed Indian Bread: 🔗 Link 📄 Patent	Mar. 2020 - Present
Developed world's first fully automated & compact cooking robot that only requires wheat and water to be filled in containers, also parathas are made and stored in hotboxes with smart IOT control. Patent No: 202141060759.	
BlockMover: The Autonomous Shape-Sorting Mobile Robot: 📺 Demo	Jan. 2023 - May. 2023
Developed an autonomous mobile robot for a demo construction site capable of identifying & sorting colored shapes by moving them to designated drop-off zone using gripper, planning algorithm, OpenCV & RPi on physical hardware.	
Custom RoboArm for Pick & Place Operations with Stereo Vision: 🔗 Link 📺 Demo	Oct. 2022 - May. 2023
Designed a 6-DoF manipulator from scratch with 3D printed design. Programmed it for pick & place tasks using MoveIT, ROS 2 , and custom Stereo Depth Estimation pipeline . Conducted a performance comparison against the UR5e arm.	
Training & Testing a NN based on YOLOv3 for Custom Object Detection: 📺 Demo	Apr. 2023 - May. 2023
Trained a NN based on YOLOv3 model using transfer learning with custom dataset to detect humans & deployed on a mobile robot using IP Cam.	
Mono-Camera Human Pose Estimation and Tracking using openCV: 🔗 Link 📺 Demo	Sep. 2022 - Oct. 2022
Developed an algorithm using openCV and laptop web camera for human pose estimation in 3D Cartesian coordinates with depth info. It is capable of tracking humans from frame to frame and assigning unique IDs.	

