

# DHINESH RAJASEKARAN

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## Education

<b>Master of Engineering - Robotics</b> University of Maryland, College Park (3.7/4.0 GPA)	Aug. 2022 - May. 2024 College Park, MD, USA
<b>Bachelor of Technology - Electrical Engineering</b> SRM Institute of Science and Technology, Chennai (8.8/10.0 GPA)	Jul. 2017 - Jun. 2021 Chennai, TN, India

## Technical Skills

<b>Areas of Expertise</b>	<b>Autonomous Robots</b> , Embedded Systems, <b>Industrial Automation</b>
<b>Robotic Platforms</b>	<b>Omron LD series</b> , <b>PF400</b> , <b>UR Robotic Arms</b> , <b>AMRs</b> , <b>AGVs</b>
<b>Hardware Platforms</b>	<b>AVR</b> , <b>ARM</b> , <b>RealSense</b> , <b>TI Sensors</b> , <b>IMU</b> , <b>LiDAR</b> , <b>Cognex Vision</b>
<b>Programming Languages</b>	<b>Python</b> , <b>C++/C</b> , <b>Linux/Bash</b>
<b>Tools/Technologies</b>	<b>Gazebo</b> , <b>MoveIt</b> , <b>MATLAB</b> , <b>Kalman Filter</b> , <b>SOLIDWORKS</b> , <b>AWS</b>
<b>Proficient in Frameworks</b>	<b>ROS</b> , <b>OpenCV</b> , <b>PyTorch</b> , <b>PID</b> , <b>Docker</b> , <b>GIT</b>
<b>Proficient in Interfaces</b>	I2C, SPI, I2S, UART, RS422, CAN

## Career Highlights

- **Robotics Engineer** with **3 years** of experience, **2 patents**, and expertise in **ROS**, **Industrial Automation**, **Perception**, **Localization**, **Embedded Firmware**, and **Sensor Fusion**.
- Demonstrated **technical expertise**, **attention to detail**, diligence, and **problem-solving** through successful execution of multiple long-term projects, professional experience and research initiatives.

## Professional Experience



<b>Khanjur R&amp;D, Silver Spring</b> Robotics Engineer	Feb. 2024 - Present <i>Silver Spring, MD, USA</i>
• Developed a <b>wearable</b> medical device for <b>Fluorescence-Guided Brain Surgery</b> , integrating high-power UV lights, a <b>camera vision</b> system, and <b>on-board data</b> processing for enhanced surgical precision.	
• Developed schematics and <b>multi-layer control PCBs</b> for a <b>robotic</b> system, integrating <b>Motors</b> , LVDT, Load cells, and various <b>THT</b> and <b>SMD components</b> , adhering to <b>industry</b> best practices in PCB design.	
• Developed an <b>Embedded Application</b> using Qt, Python, and C++ to interface with a <b>multi-sensor automation</b> rig, integrating DATAQ toolbox for data acquisition and generating comprehensive QA reports.	
<b>National Institutes of Health, Rockville</b> Robotics Research Associate	Sept. 2023 - Dec. 2023 <i>Rockville, MD, USA</i>
• Developed a <b>robot chemist</b> utilizing the <b>Omron LD series mobile robot</b> , <b>PF400 robotic arm</b> and an advanced High-Density Storage (HDS) system to seamlessly <b>automate</b> intricate chemical process.	
• Utilized <b>OpenCV-based detection algorithms</b> to <b>autonomously</b> track vial movements within the system and tested under various lighting conditions & multiple <b>industrial cameras</b> in accessing the efficiency and detection robustness.	
• Built the <b>hardware &amp; calibrated camera</b> for a <b>6 DoF</b> robotic actuator using <b>ROS &amp; Intel Realsense</b> and designed an <b>electromagnetic door handle</b> for human/robotic access to the HDS.	
<b>Solinas Integrity, IIT Madras Research Park</b> Robotics Engineer	Aug. 2021 - Jul. 2022 <i>Chennai, TN, India</i>
• Developed a <b>pipeline inspection robot</b> detecting leaks, <b>corrosion</b> , and defects in pipelines as small as 4-inch & up to <b>1000 meters</b> long, utilizing YOLOv3 and withstanding 5 bar underwater pressure.	
• Implemented <b>Sensor Fusion</b> with <b>Kalman Filter</b> , <b>PID</b> motor synchronization, and designed ARM-based Robot <b>Control PCB</b> . Led mechatronic systems development and 3D printing for crucial components.	
• Developed an advanced <b>robot control station</b> featuring ATmega 2560-based infotainment PCB and Arduino Pro Mini control <b>joystick</b> , programmed in C++ for seamless system <b>integration</b> .	
<b>Digital Blanket, Bangalore</b> Embedded Engineer	Sept. 2021 - Jul. 2022 <i>Bangalore, KA, India</i>
• Designed a <b>Wet Floor Detection Sensor</b> using <b>FLIR</b> thermal camera and <b>ESP32</b> , with custom firmware for precise detection.	
• Created a <b>ToF Sensor</b> library for <b>3D mapping</b> , people counting, and presence detection, successfully integrating it with <b>industrial automation</b> circuit boards and IoT nodes.	
• Developed a <b>collision avoidance</b> system using <b>mmWave TI</b> sensor and designed a <b>smart home wireless sensor</b> platform, incorporating <b>industrial-grade</b> sensors for <b>IAQ</b> , TVOC, light, and temperature monitoring.	

# Projects



## Smart Kitchen Robot for Making Stuffed Indian Bread Variety:

- Developed the **world's first fully automated** cooking robot requiring only wheat and water inputs.
- Automated aloo paratha making, **stacking**, & storing in **hotboxes** using novel robotic systems, sensors, and smart **IoT** control.

## Custom Robotic Arm for Pick & Place Operations using Stereo Vision:

- Designed a 6-DoF manipulator from scratch with a 3D-printed design for pick and place tasks.
- Programmed it using **MoveIT**, **ROS2**, and a **custom Stereo Depth Estimation pipeline**; compared performance with **UR5e**.

## Autonomous Mobile Robot for Shape-Sorting Application:



- Developed an autonomous mobile robot for a demo site to **identify** and **sort** colored shapes.
- Utilized a gripper, **planning** algorithm, **OpenCV**, and **Raspberry Pi** to move shapes to drop-off zones.

## ARIAC 2023 - Agile Robotics for Industrial Automation:



- Created a ROS2-Gazebo-based **Industrial Robotic Manufacturing System** mirroring the ARIAC 2023 challenge.
- Focused on agility and autonomy in **kitting tasks** using **AGVs**, manipulators, and sensors.

# Patents

## HEAD GEAR SYSTEM AND METHOD FOR ENSURING THE SAFETY OF A RIDER OF A VEHICLE

Dec. 2021

Patent No: 202141060755



- Patent published for the project "Bone Conduction & Accident Prevention Smart Helmet".

## BAKER BOT SYSTEM, SMART KITCHEN ROBOT MACHINE, AND METHOD FOR AUTOMATIC MAKING OF CHAPATI

Dec. 2021

Patent No: 202141060759



- Patent published for the project "Smart Kitchen Robot for Making Stuffed Indian Bread".

# Achievements

- One among the **Top 100 projects** at **KPIT Sparkle's i-Innovate** contest from **over 2700 submissions**. 2021.
- **Runner Up** at ASEAN-India Hackathon from **over 3600 participants**, **1<sup>st</sup> international hackathon** conducted by AICTE with 10 other Asian countries. 2021.
- **1<sup>st</sup> Prize** at Hackinfinity conducted by SSN collage of Engineering and **Mr.Cooper** company from **over 52 participants**. 2021.
- **1<sup>st</sup> Prize** at National level **Smart India Hackathon** Hardware Edition from **over 20 submissions**. 2020.
- **Gold Medal** Winner in **Research Day** conducted by SRM University from **over 45 submissions**. 2020.
- **Certificate of Distinction** for Introduction to **Robotics** by Prag Robotics, Pvt Ltd, Chennai, India. 2019.

# Positions of Responsibility

## Team Leader - International ASEAN-India Hackathon

Jan. 2021 - Feb. 2021

- Elected as **Team lead** among 6 students from **various countries** for 2 months and led the team to **victory** in a 3 day hackathon.
- Played a pivotal role in understanding of problem statement, product design and helped **break the communication barrier**.

## Team Leader - Smart India Hackathon

Jan. 2020 - Dec. 2020

- Team lead for a group of 6 students at SRM University for 12 months and led the team to **victory** in a 5 day hackathon.
- Guided the team members and coordinated with them **during the pandemic and developed a Proof of Concept**.