

# DHINESH RAJASEKARAN

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## Education

<b>Master of Engineering - Robotics</b> University of Maryland, College Park (3.7/4.0 GPA)	Aug. 2022 - Dec. 2023 <i>College Park, MD, USA</i>
<b>Bachelor of Technology - Electronics and Communication Engineering</b> SRM Institute of Science and Technology, Chennai (8.8/10.0 GPA)	Jul. 2017 - Jun. 2021 <i>Chennai, TN, India</i>

## Technical Skills

<b>Areas of Expertise</b>	Developing <b>Robotic Systems</b> , Embedded Systems, Digital logic & Circuit Design
<b>Tools/Technologies</b>	<b>OrCAD</b> , <b>MATLAB</b> , <b>Gazebo</b> , <b>SOLIDWORKS</b> , <b>MoveIt</b> , <b>AWS</b> , <b>PID</b>
<b>Proficient in Frameworks</b>	<b>OpenCV</b> , <b>ROS</b> , <b>Docker</b> , <b>GIT</b>
<b>Programming Languages</b>	<b>Python</b> , <b>C++/C</b> , <b>JavaScript</b> , <b>Linux/Bash</b>
<b>Proficient in Protocols</b>	<b>I2C</b> , <b>I2S</b> , <b>SPI</b> , <b>UART</b> , <b>USART</b> , <b>RS422</b> , <b>PCM</b> , <b>CAN</b>
<b>Hardware Used</b>	<b>Arduino</b> , <b>Rasp Pi</b> , <b>STM</b> , <b>ESP</b> , <b>Jetson</b> , <b>RealSense</b> , <b>TI Sensors</b> , <b>UR5</b> , <b>IMU</b> , <b>LiDAR</b> , <b>Cognex</b>

## Professional Experience

<b>National Institutes of Health, Rockville</b> Robotics Research Associate	Sept. 2023 - Dec. 2023 <i>Rockville, MD, USA</i>
<ul style="list-style-type: none"><li>Developed a <b>robotic chemist</b> utilizing the <b>Omron LD series mobile robot</b>, PF400 robotic arm and an advanced High-Density Storage (HDS) system to seamlessly <b>automate</b> intricate chemical process.</li><li>Utilized <b>OpenCV-based detection algorithms</b> to autonomously track vial movements within the system &amp; designed an <b>electromagnetic door handle</b> for human/robotic access to the HDS.</li><li>Built the <b>hardware, calibrated camera</b> and tested the detection algorithm under various lighting conditions and across multiple <b>industrial cameras</b> in accessing the efficiency and detection robustness.</li></ul>	
<b>Solinas Integrity, IIT Madras Research Park</b> Robotics Engineer	Aug. 2021 - Jul. 2022 <i>Chennai, TN, India</i>
<ul style="list-style-type: none"><li>Developed a <b>pipeline inspection robot</b> which can detect leaks, <b>corrosion</b> and defects on pipelines as small as 4 inch up-to a depth of 300 meters utilizing YOLOv3 and can withstand 5 bar underwater pressure.</li><li>Responsible for <b>embedded firmware, digital circuit, PID tuning</b> and power electronics design for the control PCB based on <b>STM32</b> &amp; DVR PCB based on <b>ATmega 2560</b> along with designing mechanical systems &amp; 3D printed parts.</li></ul>	
<b>FlamencoTech, Bangalore</b> Embedded Engineer	Sept. 2021 - Jul. 2022 <i>Bangalore, KA, India</i>
<ul style="list-style-type: none"><li>Designed <b>Wet Floor Detection Sensor</b> using <b>FLIR</b> thermal camera and <b>ESP32</b>, with custom firmware for precise detection.</li><li>Developed a library for <b>ToF Sensor</b> for <b>3D mapping</b>, people counting &amp; presence detection.</li><li>Designed PCB architecture for <b>mmWave TI</b> sensor, initiated custom wireless sensor platform integrating industrial-grade sensors for <b>IAQ</b>, <b>TVOC</b>, light, and T&amp; RH.</li></ul>	

## Projects

<b>Smart Kitchen Robot for Making Stuffed Indian Bread Variety:</b>	<a href="#">🔗 GIT</a>
Developed <b>world's first fully automated</b> & compact cooking robot that only requires wheat and water to be filled in containers, aloo parathas are made, <b>stacked</b> and stored in <b>hotboxes</b> with smart <b>IOT</b> control.	
<b>Autonomous Mobile Robot for Shape-Sorting Application:</b>	<a href="#">🔗 GIT</a> <a href="#">📺 Demo</a>
Developed an autonomous mobile robot for a demo construction site capable of <b>identifying &amp; sorting</b> colored shapes by moving them to designated drop-off zone using gripper, <b>planning</b> algorithm, <b>OpenCV</b> & <b>RPi</b> on physical hardware.	
<b>Custom Robotic Arm for Pick &amp; Place Operations using Stereo Vision:</b>	<a href="#">🔗 GIT</a> <a href="#">📺 Demo</a>
Designed a 6-DoF manipulator from scratch with 3D printed design. Programmed it for pick & place tasks using <b>MoveIT</b> , <b>ROS 2</b> , and <b>custom Stereo Depth Estimation pipeline</b> . Conducted a performance comparison against the <b>UR5e</b> arm.	
<b>ARIAC 2023 - Agile Robotics for Industrial Automation:</b>	<a href="#">🔗 GIT</a>
Created <b>ROS2-Gazebo-based Industrial Robotic Manufacturing System</b> mirroring ARIAC 2023 challenge, emphasizing agility and autonomy in <b>Kitting tasks</b> with <b>AGVs</b> , manipulators, and sensors.	
<b>Bone Conduction &amp; Accident Prevention Smart Helmet:</b>	<a href="#">🔗 GIT</a>
Enhancing rider safety, our <b>patented</b> project integrates <b>Advanced Driver Assistance Systems (ADAS)</b> into helmets, offering real-time alerts and distraction-free infotainment, utilizing <b>HUD</b> and bone conduction technology with <b>i2s</b> integration.	

Real-Time Steam Plant Man Hole Cover Detection using Single Shot Detectors:

Implementing YOLOv8, YOLOv5, and YOLOv3 via **transfer learning** on a local GPU, we targeted the detection of steam plant manhole covers. Integration included RGB and **FLIR** thermal cameras alongside GPS.

Black Box Device for Marine Vessels:



Designed **tamper-proof solar-powered** black box for ocean vessels, logging data to coast guard **dashboard**. Features tamper alerts, **Iridium satellite** communication, **AI activity** monitoring, and **environmental** safety measures.

Ferry Smart - All in one Smart commute system:



Designed & implemented a hardware-based solution which bridges the gap between different modes of public transport & act as single source for convenient **commutation planning** providing **ETA**, travel cost, Live tracking & **Carbon footprint tracking** among others.

Patents

HEAD GEAR SYSTEM AND METHOD FOR ENSURING THE SAFETY OF A RIDER OF A VEHICLE  
Patent No: 202141060755  
Dec. 2021  
 Patent

- Patent published for the project "Bone Conduction & Accident Prevention Smart Helmet".

BAKER BOT SYSTEM, SMART KITCHEN ROBOT MACHINE, AND METHOD FOR AUTOMATIC MAKING OF CHAPATI  
Patent No: 202141060759  
Dec. 2021  
 Patent

- Patent published for the project "Smart Kitchen Robot for Making Stuffed Indian Bread".

Achievements

- One among the **Top 100 projects** at **KPIT Sparkle's** i-Innovate contest from **over 2700 submissions**. 2021.
- **Runner Up** at ASEAN-India Hackathon from **over 3600 participants**, **1<sup>st</sup> international hackathon** conducted by AICTE with 10 other Asian countries. 2021.
- **1<sup>st</sup> Prize** at Hackinfinity conducted by SSN collage of Engineering and **Mr.Cooper** company from **over 52 participants**. 2021.
- **1<sup>st</sup> Prize** at National level **Smart India Hackathon** Hardware Edition from **over 20 submissions**. 2020.
- **Gold Medal** Winner in **Research Day** conducted by SRM University from **over 45 submissions**. 2020.
- **Certificate of Distinction** for Introduction to **Robotics** by Prag Robotics, Pvt Ltd, Chennai, India. 2019.

Positions of Responsibility

Team Leader - International ASEAN-India Hackathon  
Jan. 2021 - Feb. 2021

- **Elected as Team lead** among 6 students from **various countries** for 2 months and led the team to **victory** in a 3 day hackathon.
- Played a pivotal role in understanding of problem statement, product design and helped **break the communication barrier**.

Team Leader - Smart India Hackathon  
Jan. 2020 - Dec. 2020

- Team lead for a group of 6 students at SRM University for 12 months and led the team to **victory** in a 5 day hackathon.
- Guided the team members and coordinated with them **during the pandemic and developed a Proof of Concept**.